## 博士論文

# On the Helmholtz decomposition of vector fields with bounded mean oscillation in various domains （諸領域における有界平均振動ベタトル場のヘルムホルツ分解） 

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## Contents

1 Introduction ..... 1
1.1 Purpose of the thesis ..... 1
1.2 Introduction to Chapter 2 ..... 2
1.3 Introduction to Chapter 3 ..... 2
1.4 Introduction to Chapter 4 ..... 3
1.5 Introduction to Chapter 5 ..... 5
1.6 Introduction to Chapter 6 ..... 6
Acknowledgements ..... 8
References ..... 9
2 On the Helmholtz decompositions of vector fields of bounded mean os- cillation and in real Hardy spaces over the half space ..... 10
2.1 Introduction ..... 10
2.2 Definitions and notations ..... 13
2.3 Helmholtz decomposition of vector fields of bounded mean oscillation over the half space ..... 17
2.3.1 Boundedness of projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ from $\mathbf{X}$ to $\mathbf{X}$ ..... 17
2.3.2 Trace problem ..... 21
2.3.3 Validity of $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ as the Helmholtz projection ..... 23
2.3.4 Characterization of the subspace $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}$ ..... 27
2.3.5 Proof of Theorem 2.1.1 ..... 29
2.4 Partial Helmholtz decomposition of vector fields in real Hardy spaces over the half space ..... 29
2.4.1 Boundedness of projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ from $\mathbf{Y}$ to $\mathbf{Y}$ ..... 29
2.4.2 Properties of projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ ..... 31
2.4.3 Characterization of the subspace $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}$ ..... 32
2.4.4 Proof of Theorem 2.1.2 ..... 32
2.5 Duality theorem ..... 33
2.5.1 Duality theorem for the case of odd extension ..... 33
2.5.2 Duality theorem for the case of even extension ..... 39
2.5.3 Proof of Theorem 2.1.3 ..... 44
2.5.4 Comments ..... 45
2.6 Dual operator of the Helmholtz projection ..... 46
2.6.1 Dual operators of $E_{\text {odd }}$ and $r_{\mathbb{R}_{+}^{n}}$ ..... 46
2.6.2 Dual operators of $E_{\text {even }}$ and $r_{\mathbb{R}_{+}^{n}}$ ..... 47
2.6.3 Proof of Theorem 2.1.4 ..... 47
2.6.4 Proof of Corollary 2.1.5 ..... 48
References ..... 49
3 Normal trace for a vector field of bounded mean oscillation ..... 50
3.1 Introduction ..... 50
3.2 Spaces ..... 53
3.3 A variant of Jones' extension theorem ..... 62
3.4 Trace problems ..... 68
3.5 Appendix ..... 74
References ..... 76
4 The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain ..... 77
4.1 Introduction ..... 77
4.2 Construction of volume potential ..... 83
4.2.1 Localization procedure ..... 83
4.2.2 Cut-off and extension ..... 84
4.2.3 Volume potentials ..... 88
4.3 Volume potentials based on normal coordinates ..... 91
4.3.1 A perturbation method keeping parity ..... 91
4.3.2 Laplacian in a normal coordinate system ..... 95
4.3.3 bmo invariant under local $C^{1}$-diffeomorphism ..... 96
4.3.4 Volume potential for tangential component ..... 98
4.3.5 Volume potential for normal component ..... 100
4.4 Neumann problem with bounded data ..... 102
4.4.1 $B M O$ estimate ..... 103
4.4.2 Estimate for normal derivative ..... 104
References ..... 109
5 Extension theorem for bmo in a domain ..... 110
5.1 Introduction ..... 110
5.2 Uniform estimates ..... 113
5.3 Cut-off ..... 118
5.4 Extension ..... 122
5.4.1 Extension to a neighborhood of $\Gamma$ ..... 122
5.4.2 Extension to $\mathbf{R}^{n}$ ..... 125
5.5 Application of the extension theorem ..... 127
5.6 Extension of vector fields in bmo in a domain ..... 128
References ..... 130
6 The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation ..... 131
6.1 Introduction ..... 131
6.2 Volume potential construction in a uniformly $C^{3}$ domain ..... 139
6.2.1 Localization tools ..... 139
6.2.2 Cut-off and extension ..... 141
6.2.3 Volume potentials ..... 142
6.3 Neumann problem with bounded data in a perturbed $C^{2}$ half space with small perturbation ..... 147
6.3.1 $B M O$ estimate ..... 148
6.3.2 Estimate for normal derivative ..... 149
6.3.3 Review of boundary integral equation ..... 152
6.3.4 Solution to the Neumann Problem ..... 154
6.3.5 $\quad L^{2}$ estimate to the solution of the Neumann problem ..... 158
References ..... 164

## Chapter 1

## Introduction

### 1.1 Purpose of the thesis

The purpose of this thesis is to study the Helmholtz decomposition of vector fields with bounded mean oscillation in various domains other than the whole space. Specifically speaking, the Helmholtz decompositions of vector fields with bounded mean oscillation are established in the cases where the domain is a half space, a bounded $C^{3}$ domain and a perturbed $C^{3}$ half space with small perturbation.

The study of Helmholtz decomposition investigates the standard question whether a space of vector fields, which is defined in some domain, can be decomposed into the direct sum of a solenoidal subspace and a subspace that is exactly a gradient field. This decomposition plays a fundamental role in the mathematical theory of the Navier-Stokes equations, see e.g. [9]. This is the reason why we are interested in such problems. For vector fields of $L^{p}$ spaces over domains with $1<p<\infty$, such decompositions are widely studied. It is well-known that by the Hilbert space method, the Helmholtz decomposition of the $L^{2}$ vector fields holds for any arbitrary domain. In the case where $p$ is not equal to 2 , whether the Helmholtz decomposition of the $L^{p}$ vector fields holds or not actually depends on the domain. For bounded domains, the most general result on this decomposition was given by Fujiwara and Morimoto [6]. Their proof was based on the general theory for elliptic partial differential equations by Lions and Magenes [16], [17]. Simader and Sohr [22] generalized this result to both bounded and exterior domains by a variational approach. On the other hand, Bogovskiĭ [5] showed that there exists an unbounded domain in which the Helmholtz decomposition does not hold. However, if one considers the $\tilde{L}^{p}$ vector fields where $\tilde{L}^{p}$ is defined to be $L^{2} \cap L^{p}$ for $2 \leq p<\infty$ and $L^{2}+L^{p}$ for $1<p<2$, then the Helmholtz decomposition holds for arbitrary uniformly $C^{2}$ domain, this is the result due to Farwig, Kozono and Sohr [7]. Their proof was also a variational approach based on duality. In the case when $p$ equals infinity, the Helmholtz decomposition does not hold even in the whole space. The projection mapping to the gradient field in this case is a kind of Riesz operator, which is unbounded in $L^{\infty}$. Hence, we consider vector fields with bounded mean oscillation as an alternate choice for the $L^{\infty}$ vector fields.

In the case of the whole space, the Helmholtz decomposition of the space of vector fields with bounded mean oscillation was established by Miyakawa [19]. In his work, the Helmholtz projection was explicitly presented to prove its boundedness in the space of vector fields with bounded mean oscillation. In the case of the half space, we make use of this projection to construct the Helmholtz projection in the half space case explicitly through extending a vector field, defined in the half space, to the whole space by the trick of even
and odd extensions. In the cases of a bounded $C^{3}$ domain and a perturbed $C^{3}$ half space with small perturbation, we establish the Helmholtz decomposition by directly constructing the volume potential. The ideas in this thesis to establish the Helmholtz decomposition are more of potential-theoretical approaches. Although there is a chance that variational approaches through duality might also be possible to establish the Helmholtz decomposition, that would require a thorough understanding for the predual space of space of vector fields with bounded mean oscillation in domain, i.e., we need to have the theory for spaces of vector fields in real Hardy space in domains in advanced. At this moment, we are not ready to consider a variational approach to establish the Helmholtz decomposition for vector fields with bounded mean oscillation in domains. This would be our future target.

### 1.2 Introduction to Chapter 2

Chapter 2 is devoted to consider the Helmholtz decompositions for vector fields with bounded mean oscillation and vector fields in real Hardy spaces over the half space. We define the space of vector fields with bounded mean oscillation or in real Hardy spaces over the half space in a way such that the even extension of the tangential component and the odd extension of the normal component of a vector field are of bounded mean oscillation or in real Hardy spaces.

By making use of the Helmholtz projection constructed in the whole space case [19], we construct the Helmholtz projection in the half space case directly by considering even and odd extensions and restriction. We show that this projection constructed is bounded linear in both spaces of vector fields with bounded mean oscillation and in real Hardy spaces over the half space. The famous John-Nirenberg inequality, see e.g. [14, Theorem 3.1.6], says that functions of bounded mean oscillation are indeed locally $L^{2}$. Hence, for the space of vector fields with bounded mean oscillation over the half space, the trace can be taken in the sense of distributions. By finally invoking the De Rahm's theorem, see e.g. [9, Lemma III.1.1], we show that our projection that is directly constructed indeed induces the correct Helmholtz decomposition for vector fields with bounded mean oscillation over the half space. On the other hand, we do not know how to take the trace properly for vector fields in real Hardy spaces over the half space, therefore we only obtain a partial decomposition for vector fields in real Hardy spaces over the half space in this chapter.

Moreover, by considering the restrictions of atoms defined in the theory of real Hardy spaces in the whole space, we establish the atomic decomposition theorem for the space of vector fields in real Hardy spaces over the half space defined in this chapter. Following the duality argument due to Fefferman and Stein [8], we prove that the space of vector fields with bounded mean oscillation over the half space defined in this chapter is indeed the dual space of the space of vector fields in real Hardy spaces over the half space defined in this chapter. We develop two sets of theories of real Hardy spaces and spaces of bounded mean oscillation defined in the half space which are compatible with the theory of Miyachi [18], where he established the theory of real Hardy spaces defined in domains.

Chapter 2 is based on the joint work [10] with Professor Yoshikazu Giga.

### 1.3 Introduction to Chapter 3

In Chapter 3, we introduce local bounded mean oscillation spaces in domains. The local bounded mean oscillation space defined in the whole space consists of functions of bounded
mean oscillation that are uniformly locally $L^{1}$ in the whole space. We define different types of local bounded mean oscillation spaces in a domain by allowing functions to be uniformly locally $L^{1}$ only in the $\delta$-neighborhood of the boundary in that domain for $0<\delta \leq \infty$. We give a classification to these different types of spaces according to different values of $\delta$. We then define a local bounded mean oscillation space of vector fields which admits some boundary control on the normal component of every vector field. We call the boundary control as the $b^{\nu}$ estimate. This $b^{\nu}$ estimate was introduced in the previous works [1], [2], [3] and [4].

Due to Jones [20], we see that the bounded mean oscillation space defined in a domain can be extended linearly continuously to the bounded mean oscillation space defined in the whole space if and only if the domain is a uniform domain. Following Jones' argument, we show that if the domain is a uniform domain, then the local bounded mean oscillation space defined in this domain can be extended linearly continuously to the local bounded mean oscillation space defined in the whole space in a way such that the support of every extended function is contained in a small neighborhood of this domain. Since the local bounded mean oscillation space is the dual space of the local real Hardy space and multiplication by a Hölder function is bounded linear in the local real Hardy space, see e.g. [21, Chapter 3], by our extension theorem for the local bounded mean oscillation space defined in a uniform domain, we deduce that the multiplication by a Hölder function is bounded linear in the local bounded mean oscillation space defined in a uniform domain. This means that we can do cut-off to functions of local bounded mean oscillation defined in a uniform domain.

If the domain is the half space. For a vector field of local bounded mean oscillation with boundary control on its normal component, by the formula of integration by parts, we give an estimate on the $L^{\infty}$ norm of the normal component of the vector field on the boundary by the local bounded mean oscillation norm of the vector field in the domain, the $b^{\nu}$ estimate of the normal component of the vector field on the boundary and the uniformly locally $L^{n}$ norm of the divergence of the vector field in the $\delta$-neighborhood of the boundary. This can be done as for a $L^{1}$ function defined on the boundary, there exists a bounded linear lifting operator that maps the $L^{1}$ function to a function that belongs to the TriebelLizorkin space $F_{1,2}^{1}$, see e.g. [24, Section 4.4.3]. Since the gradient of a function in $F_{1,2}^{1}$ is indeed in the local Hardy space, we can apply the duality relation. We can then generalize this result to any uniformly $C^{2+\beta}$ domain with $0<\beta<1$ by localizing the problem to small neighborhoods of points on the boundary and then flatten the boundary by invoking the normal coordinate change in each of these small neighborhoods. When the boundary is flattened, the problem locally reduces to the half space case. We therefore obtain a trace theorem that holds for any uniformly $C^{2+\beta}$ domain.

Chapter 3 is based on the joint work [11] with Professor Yoshikazu Giga.

### 1.4 Introduction to Chapter 4

Chapter 4 is devoted to the Helmholtz decomposition of the space of vector fields of bounded mean oscillation defined in a bounded $C^{3}$ domain that requires the normal component of every vector field to be $b^{\nu}$ bounded. As we have shown in Chapter 3, in the case of a bounded $C^{2}$ domain, the space of vector fields of bounded mean oscillation that requires the normal component of every vector field to be $b^{\nu}$ bounded is indeed $L^{1}$. Hence, we do not need to assume the space of vector fields to be of local bounded mean oscillation. In the case of a bounded $C^{3}$ domain, multiplication by a Hölder function is bounded linear in the space of vector fields of bounded mean oscillation that implements the $b^{\nu}$ condition
on the normal component of every vector field, i.e., we can do cut-off to vector fields with bounded mean oscillation whose normal components are controlled on the boundary.

Our strategy to establish the Helmholtz decomposition is a potential-theoretic approach. Simply speaking, we construct the volume potential corresponding to the divergence of a vector field directly and then solve a Neumann problem with bounded data. The idea of constructing the volume potential is simply applying the minus Laplacian to the divergence of a vector field. However, if we apply the minus Laplacian directly to the divergence of a vector field, we would get a volume potential whose gradient has normal component that is not necessarily $b^{\nu}$ bounded on the boundary. We construct the volume potential in a delicate way. We do cut-off to split a vector field into the sum of a vector field supported away from the boundary and a vector field supported in a small neighborhood of the boundary. For the vector field supported away from the boundary, we construct the corresponding volume potential by applying the minus Laplacian to the divergence of the vector field directly. We can estimate the $L^{\infty}$ norm of the gradient of this volume potential in a small neighborhood of the boundary, thus this gradient certainly has $b^{\nu}$ bounded normal component. For the vector field supported in a small neighborhood of the boundary, we extend this vector field in a way such that the tangential component of the extended vector field is even with respect to the boundary whereas the normal component of the boundary is odd with respect to the boundary. Then we consider a finite partition of unity to localize the extended vector field to finitely many compact small neighborhoods of points on the boundary. In each of these compact small neighborhoods, we consider the normal coordinate change so that the boundary becomes flattened. Thus locally the problem can be viewed as in the half space. Applying the minus Laplacian in normal coordinate to the localized extended vector field, we construct the corresponding volume potential by Neumann series. Our parity setting for the extended vector field ensures that the gradient of the volume potential constructed from each of the compact small neighborhoods has $b^{\nu}$ bounded normal component. Adding up all volume potentials constructed from each of the compact small neighborhoods together with the volume potential constructed from the vector field supported away from the boundary, we obtain our desired volume potential.

Finally, we solve the Neumann problem with bounded data. Since the domain is a bounded $C^{3}$ domain, we recall the Green's function from [13]. For a bounded data defined on the boundary, the unique solution (up to an additive constant) to the Neumann problem is given by the convolution of the Green's function with bounded data on the boundary. In the case of a bounded domain, the Green's function contains two parts, the first part is the usual Newton potential $E(x-y)$, the second part $h(x, y)$ has gradient $L^{1}$ with respect to the $y$ variable on the boundary for any point $x$ in the bounded domain (see [13, Lemma 3.1]). The gradient of the convolution of this second part with boundary data on the boundary is thus estimated directly by the $L^{\infty}$ norm of the boundary data on the boundary. It is sufficient to consider only the Newton potential part. The BMO estimate for the Newton potential part follows from the standard $L^{\infty}-B M O$ estimate, see e.g. [14, Theorem 4.2.7]. By a direct calculation, we show that the normal derivative of the Newton potential is $L^{1}$ with respect to the $y$ variable on the boundary. Hence, the normal derivative of the convolution of the Newton potential with bounded data on the boundary is uniformly bounded by the $L^{\infty}$ norm of the boundary data on the boundary. The $b^{\nu}$ estimate of the normal component of our solution to the Neumann problem follows naturally. Therefore, we solve our Neumann problem.

Chapter 4 is based on the joint work [12] with Professor Yoshikazu Giga.

### 1.5 Introduction to Chapter 5

In Chapter 5, we generalize the extension result in Chapter 3 for local bounded mean oscillation functions defined in a domain. In Chapter 3, we follow the idea of Jones [20] and establish an extension theorem for local bounded mean oscillation functions defined in a uniform domain. In this chapter, we invoke the extension introduced in Chapter 4 which extends a function supported in a small neighborhood of the boundary evenly with respect to the boundary, in order to establish an extension theorem for local bounded mean oscillation functions defined in arbitrary uniformly $C^{2}$ domain. Although we requires the boundary to be uniformly $C^{2}$, our extension theorem extends Jones' result [20] in the sense that local bounded mean oscillation functions defined in a non-uniform domain can also be extended linearly continuously.

Our strategy is to firstly decompose a function into the sum of a function supported away from the boundary and a function supported in a small neighborhood of the boundary in our domain. We can achieve this by multiplying a cut-off test function supported in our domain. At this stage, multiplication is not necessarily bounded linear as the domain is not necessarily uniform. However, we can still uniformly estimate the mean oscillation of the function supported in a small neighborhood of the boundary over all balls in the domain with sufficiently small radius. This is because for a small ball close to the boundary, we may find a bounded $C^{2}$ subdomain that is contained in our domain such that the small ball is contained in this bounded $C^{2}$ subdomain, hence we can perform the multiplication rule for local bounded mean oscillation functions inside this bounded $C^{2}$ subdomain. For a small ball lying sufficiently away from the boundary, then the function supported in a small neighborhood of the boundary is actually zero in this small ball. We then even extend this function with respect to the boundary, the idea of even extension with respect to the boundary is introduced in Chapter 4. Since the extended function in this case is supported in a small neighborhood of the boundary in the whole space, by invoking the normal coordinate we can also uniformly estimate the mean oscillation of the extended function over all balls in the whole space with sufficiently small radius. As we have shown in Chapter 3, if a function is uniformly locally $L^{1}$, then being able to uniformly estimate the mean oscillation of the function over all balls with sufficiently small radius is equivalent to prove that the function is of bounded mean oscillation. Hence, the extended function is of local bounded mean oscillation in the whole space. For the function supported away from the boundary, we extend it to the whole space by simply considering its zero extension. Since we can also uniformly estimate the mean oscillation of its zero extension over all balls in the whole space with sufficiently small radius, this zero extended function is of local bounded mean oscillation in the whole space. Add up these two extended function together, we extend our original function to the whole space.

By our extension theorem, we further deduce that the multiplication by any Hölder function is bounded linear in the local bounded mean oscillation space defined in a uniformly $C^{2}$ domain. Moreover, we also obtain several uniform estimates regarding to a uniformly $C^{2}$ domain. We show that for each point on the boundary, the gradient of the normal coordinate change in a small neighborhood of that point with fixed size is uniformly controlled by a constant depending only on the size of the small neighborhood of that point. We also obtain a locally finite partition of unity for a small neighborhood of the boundary such that the $C^{1}$ norm of each partition function is uniformly controlled. These uniform estimates will also be used in the next chapter.

### 1.6 Introduction to Chapter 6

Chapter 6 is devoted to the Helmholtz decomposition of a space of vector fields with bounded mean oscillation defined in a perturbed $C^{3}$ half space with small perturbation. A perturbed $C^{3}$ half space is the region above a compactly supported $C^{3}$ function. By small perturbation we require the $C^{2}$ norm of the boundary function to be small and the support of the boundary function to be not too big. In Chapter 4, since we consider the Helmholtz decomposition for vector fields defined in a bounded $C^{3}$ domain, the space of vector fields of bounded mean oscillation, in which boundary control is implemented on the normal component of each vector field, is indeed $L^{1}$ in the bounded domain. We do not need to assume the vector fields to be of local bounded mean oscillation in order to allow cut-off by multiplication. In the case of a perturbed $C^{3}$ half space, in order to allow cut-off by multiplication we need some extra integrability, other than requiring the vector fields to be of bounded mean oscillation and to have $b^{\nu}$ bounded normal components. We consider the space of $L^{2}$ vector fields that is of bounded mean oscillation having bounded $b^{\nu}$ normal components. This is in some sense compatible with the result of Farwig, Kozono and Sohr [7] where the Helmholtz decomposition of the $L^{p} \cap L^{2}$ vector fields ( $2 \leq p<\infty$ ) was established.

Our strategy follows from the potential theoretical approach introduced in Chapter 4. We firstly construct the volume potential and then solve a Neumann problem. In the case of a bounded $C^{3}$ domain, the construction of the volume potential works as the boundary is compact. There exist finitely many points on the boundary such that small neighborhoods of these points provide an open cover of a small neighborhood of the boundary. Thus, the gradient of the normal coordinate change in each of these small neighborhoods is uniformly controlled. In addition, since we have a finite partition of unity for a small neighborhood of the boundary, the $C^{1}$ norm of each partition function is uniformly controlled. In Chapter 5 , we see that in the case of a uniformly $C^{2}$ domain, although the boundary is not compact, the gradient of the normal coordinate change in a small neighborhood of every point on the boundary is uniformly controlled regardless of where the point is. Moreover, in the case of a uniformly $C^{2}$ domain, there exist countably many points on the boundary such that small neighborhoods of these points provide a locally finite open cover of a small neighborhood of the boundary. By considering the normal coordinate change in each of these small neighborhood in this locally finite open cover, we can construct a partition of unity for a small neighborhood of the boundary such that the $C^{1}$ norm of each partition function is uniformly controlled. Hence by following the argument of constructing volume potential in Chapter 4, we can generalize the volume potential construction to arbitrary uniformly $C^{3}$ domain instead of just to a perturbed $C^{3}$ half space.

At the end of Chapter 4, we solve the Neumann problem with bounded data. In this case of a perturbed $C^{3}$ half space, since we consider the $L^{2}$ vector fields that are of bounded mean oscillation, the normal trace is actually $L^{\infty} \cap H^{-\frac{1}{2}}$ on the boundary. In this chapter, our target is to solve the Neumann problem under $L^{\infty} \cap H^{-\frac{1}{2}}$ data. For a $L^{\infty} \cap H^{-\frac{1}{2}}$ boundary data, we consider its double layer potential on the boundary. By separating the boundary into the straight part and the curved part and then viewing the straight part as part of the half space boundary and the curved part as part of the boundary of a bounded $C^{2}$ domain, the trace of this double layer potential on the boundary is indeed an bounded linear operator in $L^{\infty}$ of the form $\left(\frac{1}{2} I-S\right)$ acting on the boundary data. By considering Neumann series, we can construct the inverse to the operator $(I-2 S)$. The Neumann series converges if the operator norm of $S$ is small enough. That is why we need the perturbation
to be small. The unique solution (up to an additive constant) to our Neumann problem is then given by the single layer potential of $2(I-2 S)^{-1}$ acting on the boundary data. Similar as in the case of a bounded domain, the $B M O$ estimate of the gradient of our solution follows from the standard $L^{\infty}-B M O$ estimate, see e.g. [14, Theorem 4.2.7]. The $L^{\infty}$ norm of the normal component of the gradient of our solution in a small neighborhood of the boundary is estimated by the $L^{\infty} \cap H^{-\frac{1}{2}}$ norm of the boundary data. In the case of a half space, the solution to the Neumann problem is explicitly given by twice of the single layer potential of the boundary data. The standard theory says that the $L^{2}$ estimate of the gradient of this solution in the half space is estimated by the $H^{-\frac{1}{2}}$ norm of the boundary data, see e.g. [23, Remark 1.2 and Remark 1.3], [15, Section 1.7]. In our problem, we again separate the boundary into the straight part and the curved part. We view the straight part as part of the boundary of the half space, hence we can invoke the standard theory of the half space case to estimate the contribution of the straight part in the $L^{2}$ estimate. The contribution of the curved part in the $L^{2}$ estimate can be calculated directly as the curved part is compact. Therefore, we have our desired $L^{2}$ estimate for the gradient of our solution to the Neumann problem.

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## Chapter 2

## On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space


#### Abstract

This chapter is concerned with the Helmholtz decompositions of vector fields of bounded mean oscillation over the half space and vector fields in real Hardy spaces over the half space. It proves the Helmholtz decomposition for vector fields of bounded mean oscillation over the half space whereas a partial Helmholtz decomposition for vector fields in real Hardy spaces over the half space. Meanwhile, it also establishes two sets of theories of real Hardy spaces over the half space which are compatible with the theory of Miyachi (1990).


### 2.1 Introduction

In this chapter, we investigate the Helmholtz decompositions of vector fields of bounded mean oscillation over the half space and vector fields in real Hardy spaces over the half space. The subject of studying Helmholtz decompositions asks the standard question whether a vector field, in some specific function spaces over some specific domains, can be decomposed into the direct sum of a solenoidal subspace and a subspace which is exactly a gradient field. The reason why we are interested in this subject is due to the well known fact that Helmholtz decomposition plays an important role in constructing mild solutions of the Navier-Stokes equations.

Helmholtz decompositions are widely studied for vector fields of $L^{p}$ spaces over many kinds of different domains when $1<p<\infty$. For example, we have the result that for every open domain $\Omega \subset \mathbb{R}^{n}$ the Helmholtz decomposition holds for vector fields of $L^{2}(\Omega)$. When $p$ does not equal to 2 , we also know that the Helmholtz decompositions of vector fields of $L^{p}$ spaces hold for some domains while there exists other domains where the Helmholtz decompositions of vector fields of $L^{p}$ spaces fail to hold, e.g. see [4]. Although problems when $p$ does not equal to 2 are much more difficult than the case when $p$ equals to 2 , we still had various results. However, this subject is poorly studied for vector fields of other function spaces. In the case for vector fields of bounded mean oscillation and vector fields in real Hardy spaces, we only have a single piece of result, obtained by Miyakawa [8], states that the Helmholtz decompositions of vector fields of bounded mean oscillation over $\mathbb{R}^{n}$ and
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
vector fields in real Hardy spaces over $\mathbb{R}^{n}$ hold. This lack of study is due to the fact that the theories of real Hardy spaces and $B M O$ spaces over domains other than $\mathbb{R}^{n}$ are harder to deal with and moreover, the proper definitions of the space of vector fields of bounded mean oscillation and the space of vector fields in real Hardy spaces over other domains are not known perfectly. The purpose of this chapter seeks to extend the result of Miyakawa $[8]$ from $\mathbb{R}^{n}$ to $\mathbb{R}_{+}^{n}=\left\{\left(\mathbf{x}^{\prime}, x_{n}\right) \in \mathbb{R}^{n-1} \times \mathbb{R} \mid x_{n}>0\right\}$. In the meantime, we show that our definitions of the space of vector fields of bounded mean oscillation over $\mathbb{R}_{+}^{n}$ and the space of vector fields in real Hardy spaces over $\mathbb{R}_{+}^{n}$ are valid, in the sense that they admit a duality relation.

In order to define the space of vector fields of bounded mean oscillation over $\mathbb{R}_{+}^{n}$, we need to define two types of $B M O$ spaces over $\mathbb{R}_{+}^{n}$ firstly, one corresponds to the function space for the tangent direction while the other one corresponds to the function space for the normal direction. The $B M O$ space over $\mathbb{R}_{+}^{n}$ for the tangent direction we define is the space $B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$. In Section 2.5, we prove that $B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ is equivalent to $B M O\left(\mathbb{R}_{+}^{n}\right):=r_{\mathbb{R}_{+}^{n}} B M O$, the restriction of functions of $B M O$ to $\mathbb{R}_{+}^{n}$. The $B M O$ space over $\mathbb{R}_{+}^{n}$ for the normal direction we define is the space $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$. In [1], it is proved that $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ is equivalent to $B M O_{M}\left(\mathbb{R}_{+}^{n}\right)$ where $B M O_{M}\left(\mathbb{R}_{+}^{n}\right)$ is the $B M O$ space defined by Miyachi in [7]. Therefore the space of vector fields of bounded mean oscillation over $\mathbb{R}_{+}^{n}$, denoted by $\mathbf{X}$, can be defined as $\mathbf{X}:=\left(B M O\left(\mathbb{R}_{+}^{n}\right)\right)^{n-1} \times B M O_{M}\left(\mathbb{R}_{+}^{n}\right)$. The first main theorem of this chapter reads as follows. Let $\mathbf{n}$ be the exterior unit normal of the boundary of $\mathbb{R}_{+}^{n}$, i.e., $\mathbf{n}=(0,0,-1)$ so that the inner product $\mathbf{v} \cdot \mathbf{n}$ denotes the normal trace to $\partial \mathbb{R}_{+}^{n}$ of a vector field $\mathbf{v}$ on $\mathbb{R}_{+}^{n}$.

Theorem 2.1.1. Let $\mathbf{X}$ be the space of vector fields of bounded mean oscillation over the half space $\mathbb{R}_{+}^{n}$, then $\mathbf{X}$ admits the Helmholtz decomposition

$$
\mathbf{X}=\mathbf{X}_{\sigma} \oplus \mathbf{X}_{\pi}
$$

with the Helmholtz projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ where

$$
\begin{aligned}
& \mathbf{X}_{\sigma}=\left\{\mathbf{v} \in \mathbf{X} \mid \operatorname{div} \mathbf{v}=0 \text { in } \mathbb{R}_{+}^{n} \quad \mathcal{G} \mathbf{v} \cdot \mathbf{n}=0 \text { on } \partial \mathbb{R}_{+}^{n}\right\}, \\
& \mathbf{X}_{\pi}=\left\{\nabla p \in \mathbf{X} \mid p \in L_{l o c}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)\right\} .
\end{aligned}
$$

The key idea of the proof of Theorem 2.1.1 is to consider extension and restriction. When Miyakawa [8] established the Helmholtz decomposition of vector fields of bounded mean oscillation over $\mathbb{R}^{n}$ and vector fields in real Hardy spaces over $\mathbb{R}^{n}$, he considered the Helmholtz projection $\mathbb{P}$ where $\mathbb{P}_{i, j}:=\delta_{i, j}+R_{i} R_{j}$ and $R_{i}$ is the $i$-th Riesz transform for $1 \leq i, j \leq n$. Here we make use of this idea. We define our projection by $\mathbb{P}_{\mathbb{R}_{+}^{n}}:=r_{\mathbb{R}_{+}^{n}} \mathbb{P} E$ where $E$ is the extension operator which extends vectors in $\mathbf{X}$ to vectors in $B M O$ and $r_{\mathbb{R}_{+}^{n}}$ is the restriction operator which restricts vectors in $B M O$ back to vectors in $\mathbf{X}$. Then we prove that our projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ is actually a bounded linear map from $\mathbf{X}$ to $\mathbf{X}$. Hence through this projection we have a natural decomposition of our space $\mathbf{X}$ of the form

$$
\mathbf{X}=\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X} \oplus\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X} .
$$

Then we prove that the subspace $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X}$ is actually the solenoidal part and the subspace $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}$ is actually the gradient part. As for the trace problem, we can make use of the theory of Temam [10] since $\mathbf{X} \subset \mathbf{L}_{l o c}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)$. Notice that the space $\mathbf{X}$ is not a proper Banach space due to the fact that the $B M O$-type norm is just a seminorm. Therefore, in order to avoid any ambiguity, we mean the Helmholtz decomposition not for $\mathbf{X}$ in the usual
sense but for the quotient space $\mathbf{X} /\left(\mathbb{R}^{n-1} \times\{0\}\right)$. Here we direct the readers to Section 2.2 for the precise definitions of the extension $E$, the restriction $r_{\mathbb{R}_{+}^{n}}$, the space $B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ and the space $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$.

By similar ideas as above, we need to define two types of real Hardy spaces over $\mathbb{R}_{+}^{n}$ in order to define the space of vector fields in real Hardy spaces over $\mathbb{R}_{+}^{n}$. For the real Hardy space over $\mathbb{R}_{+}^{n}$ in the tangent direction, denoted by $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, is defined to be the restriction of all even functions in the real Hardy space over $\mathbb{R}^{n}$ to the half space $\mathbb{R}_{+}^{n}$. For the real Hardy space over $\mathbb{R}_{+}^{n}$ in the normal direction, denoted by $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, is defined to be the restriction of all odd functions in the real Hardy space over $\mathbb{R}^{n}$ to the half space $\mathbb{R}_{+}^{n}$. In Section 2.5, we also prove that $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ is equivalent to $\mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$ where $\mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$ is the real Hardy space defined by Miyachi in [7]. Hence the space of vector fields in real Hardy spaces over $\mathbb{R}_{+}^{n}$, denoted by $\mathbf{Y}$, can be defined as $\mathbf{Y}:=\left(\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)\right)^{n-1} \times \mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Let $\mathbf{Y}_{\sigma}=\left\{\mathbf{v} \in \mathbf{Y} \mid \operatorname{div} \mathbf{v}=0\right.$ in $\mathbb{R}_{+}^{n} \& \mathbf{v} \cdot \mathbf{n}=0$ on $\left.\partial \mathbb{R}_{+}^{n}\right\}$, the second main theorem in this chapter reads as follows.

Theorem 2.1.2. Let $\mathbf{Y}$ be the vector field in real Hardy spaces over the half space $\mathbb{R}_{+}^{n}$, then $\mathbf{Y}$ admits a decomposition of the form

$$
\mathbf{Y}=\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y} \oplus \mathbf{Y}_{\pi}
$$

with a bounded linear projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}: \mathbf{Y} \rightarrow \mathbf{Y}$ where

$$
\begin{aligned}
& \mathbf{Y}_{\sigma} \subset \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y} \subset\left\{\mathbf{v} \in \mathbf{Y} \mid \operatorname{div} \mathbf{v}=0 \text { in } \mathbb{R}_{+}^{n}\right\}, \\
& \mathbf{Y}_{\pi}=\left\{\nabla p \in \mathbf{Y} \mid p \in L_{l o c}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)\right\} .
\end{aligned}
$$

Similar to the proof of Theorem 2.1.1, we consider the same projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}:=r_{\mathbb{R}_{+}^{n}} \mathbb{P} E$ and we prove that $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ is also a bounded linear map from $\mathbf{Y}$ to $\mathbf{Y}$. Using the same idea, we can see that $\mathbf{Y}$ also admits a natural decomposition of the form

$$
\mathbf{Y}=\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y} \oplus\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}
$$

Although the later theory is basically the same as the previous case for vector fields of bounded mean oscillation, in this case we do not know how to solve the trace problem. Hence for the subspace $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y}$ we can only say that it is divergence free, we cannot say that it is the right solenoidal part in the Helmholtz decomposition. We have no problems in characterizing the subspace $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}$. Indeed, $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}$ is the right gradient part, just like the previous case. For the precise definitions of the spaces $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, we direct the readers to Section 2.2. Notice that if we can solve the trace problem, then this decomposition turns into the full Helmholtz decomposition immediately. Hence for this decomposition, we call it a partial Helmholtz decomposition.

By the standard theory of real Hardy spaces, we can see that the space of vector fields of bounded mean oscillation over $\mathbb{R}^{n}$ is exactly the dual space of the space of vector fields in real Hardy spaces $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. In order to make the theory over $\mathbb{R}_{+}^{n}$ to be compatible with the theory over $\mathbb{R}^{n}$, it is necessary to consider the relation between the spaces $\mathbf{X}$ and $\mathbf{Y}$. Fortunately, we have a positive answer to this question.

Theorem 2.1.3. Suppose $\mathbf{v} \in \mathbf{X}$. Then the linear functional l defined on $\mathbf{Y}$ by

$$
l(\mathbf{u})=\int_{\mathbb{R}_{+}^{n}} \mathbf{u} \cdot \mathbf{v} \mathrm{~d} \mathbf{x}
$$

for $\mathbf{u} \in \mathbf{Y}$ is a bounded linear functional which satisfies $\|l\| \leq c \cdot\|\mathbf{v}\| \mathbf{x}$ with some constant c. Conversely, every bounded linear functional on $\mathbf{Y}$ can be written in the form of

$$
l(\mathbf{u})=\int_{\mathbb{R}_{+}^{n}} \mathbf{u} \cdot \mathbf{v} \mathrm{~d} \mathbf{x} \text { for all } \mathbf{u} \in \mathbf{Y}
$$

with $\mathbf{v} \in \mathbf{X}$ and $\|\mathbf{v}\| \mathbf{X} \leq c \cdot\|l\|$ with some constant $c$. Here $\|l\|$ means the norm of $l$ as a bounded linear functional on $\mathbf{Y}$.

In short, the above theorem states the simple fact that $\mathbf{X}$ is the dual space of $\mathbf{Y}$. To prove the above theorem, we prove that $B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ is the dual space of $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ is the dual space of $\mathscr{H}_{o d d}^{1}\left(\mathbb{R}_{+}^{n}\right)$. The key idea in showing these two duality relations is again to consider extensions and restrictions. By the theories in the previous part, we see that the even extension of elements in $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ produce elements in $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and the odd extension of elements in $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ also produce elements in $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. Since elements in $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ admit atomic decompositions, by taking the restrictions we can get the half space version of atomic decompositions of elements in $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Then by similar arguments of Fefferman and Stein [3] in proving that $B M O$ is the dual space of $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$, we can prove the two duality relations concerning $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. The proof of Theorem 2.1.3 establishes two sets of complete theories for our two types of real Hardy spaces over $\mathbb{R}_{+}^{n}$. These two sets of theories are indeed compatible with the theory of Miyachi [7] where he established the theory of real Hardy spaces over arbitrary open subsets of $\mathbb{R}^{n}$. As a result, Theorem 2.1.3 verifies the validity of the definitions of $\mathbf{X}$ and Y.

In the work of Miyakawa [8], he also found the fact that the dual operator of the whole space Helmholtz projection $\mathbb{P}$ is indeed $\mathbb{P}$ itself. In this chapter we also investigate the dual operator of our half space Helmholtz projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ and we obtain the following result.

Theorem 2.1.4. The dual operator of $\mathbb{P}_{\mathbb{R}_{+}^{n}}: \mathbf{Y} \rightarrow \mathbf{Y}$ is $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ itself as a map from $\mathbf{X}$ to $\mathbf{X}$, i.e., $\mathbb{P}_{\mathbb{R}_{+}^{n}}{ }^{*}=\mathbb{P}_{\mathbb{R}_{+}^{n}}$ as a map from $\mathbf{X}$ to $\mathbf{X}$.

The key idea lies in the proof of Theorem 2.1.3. This theorem can be easily deduced by simply considering the dual operators of $E, \mathbb{P}$ and $r_{\mathbb{R}_{+}^{n}}$. By making use of this theorem, we can further deduce the following important corollary.

Corollary 2.1.5. $\mathbf{X}_{\sigma}=\mathbf{Y}_{\pi}{ }^{\perp}$ and $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y}=\mathbf{X}_{\pi}{ }^{\perp}$.
Notice that here because we do not know how to take the trace of elements in $\mathbf{Y}$ properly, we can only say that $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y}$ is the annihilator of $\mathbf{X}_{\pi}$. If the trace problem is settled, this relation turns into $\mathbf{Y}_{\sigma}=\mathbf{X}_{\pi}{ }^{\perp}$ immediately.

This chapter is organized as follow. In section 2.2 , we give out the basic definitions. In section 2.3, we investigate the Helmholtz decomposition of $\mathbf{X}$. In section 2.4, we investigate the Helmholtz decomposition of $\mathbf{Y}$. In section 2.5 , we study the duality relationship between $\mathbf{X}$ and $\mathbf{Y}$. In section 2.6 , we study the dual operator of our Helmholtz projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ : $\mathbf{Y} \rightarrow \mathbf{Y}$.

### 2.2 Definitions and notations

Let $\mathbb{R}_{+}^{\mathrm{n}}:=\left\{\mathbf{x} \in \mathbb{R}^{n} \mid x_{n}>0\right\}$ be the half space where $x_{n}$ here is the $n$-th component of $\mathbf{x}$ and let $\partial \mathbb{R}_{+}^{\mathrm{n}}:=\left\{\mathbf{x} \in \mathbb{R}^{n} \mid x_{n}=0\right\}$ be the boundary of the half space $\mathbb{R}_{+}^{\mathrm{n}}$. The space $L_{\text {loc }}^{1}\left(\mathbb{R}_{+}^{\mathrm{n}}\right)$ is
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
defined in the usual way as the set

$$
\left\{f: \mathbb{R}_{+}^{n} \rightarrow \mathbb{R} \text { measurable } \mid\|f\|_{L^{1}(\Omega)}<\infty \text { for any open subsets } \Omega \subset \subset \mathbb{R}_{+}^{\mathrm{n}}\right\}
$$

and $\mathbf{L}_{\text {loc }}^{1}\left(\mathbb{R}_{+}^{\mathrm{n}}\right):=\left(L_{\text {loc }}^{1}\left(\mathbb{R}_{+}^{\mathrm{n}}\right)\right)^{n}$.
Definition 2.2.1. Let $f \in L_{l o c}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $B_{r}(\mathbf{x})$ be the open ball of radius $r$ centered at $\mathbf{x}$, we define three types of $B M O$-type seminorms as the following:

- $[f]_{B M O \infty}\left(\mathbb{R}_{+}^{n}\right):=\sup _{B \subset \mathbb{R}_{+}^{n}} \frac{1}{B \mid} \int_{B}\left|f(\mathbf{y})-f_{B}\right| \mathrm{d} \mathbf{y}$
where $f_{B}:=\frac{1}{|B|} \int_{B} f(\mathbf{y}) \mathrm{d} \mathbf{y}$ and $B$ is an open ball.
- $[f]_{b \infty\left(\mathbb{R}_{+}^{n}\right)}:=\sup _{\substack{r>0 \\ \mathbf{x} \in \partial \mathbb{R}_{+}^{n}}} \frac{1}{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}+} \int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}|f(\mathbf{y})| \mathrm{d} \mathbf{y}$.
- $[f]_{b a^{\infty}\left(\mathbb{R}_{+}^{n}\right)}:=\sup _{\substack{r>0 \\ \mathbf{x} \partial \mathbb{R}^{n}}} \frac{1}{\left|B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}\right|} \int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\left|f(\mathbf{y})-f_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\right| \mathrm{d} \mathbf{y}$ $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$
where $f_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}:=\frac{1}{\left|B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}\right|} \int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}} f(\mathbf{y}) \mathrm{d} \mathbf{y}$.
The seminorm $[\cdot]_{b^{\infty}\left(\mathbb{R}_{+}^{n}\right)}$ is already introduced in [1] with a more general form. In [1], the definition of this seminorm is of the form $[\cdot]_{b^{\nu} p(\Omega)}$ where $\nu$ could be any real number including $\infty$ and $p \in[1, \infty)$. In our case, when $\nu$ is equal to $\infty$ and $p=1$, an easy check quickly shows that this seminorm is indeed a norm. Therefore it is unambiguous to replace $[\cdot]_{b^{\infty}\left(\mathbb{R}_{+}^{n}\right)}$ by $\|\cdot\|_{b^{\infty}\left(\mathbb{R}_{+}^{n}\right)}$.
Definition 2.2.2. We define two types of $B M O$ spaces over the half space $\mathbb{R}_{+}^{n}$ in the following way:
- $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right):=\left\{f \in L_{\text {loc }}^{1}\left(\mathbb{R}_{+}^{n}\right) \mid\|f\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}<\infty\right\}$
where $\|f\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}:=[f]_{B M O \infty\left(\mathbb{R}_{+}^{n}\right)}+\|f\|_{b \infty\left(\mathbb{R}_{+}^{n}\right)}$.
- $B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right):=\left\{f \in L_{l o c}^{1}\left(\mathbb{R}_{+}^{n}\right) \mid[f]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}<\infty\right\}$
where $[f]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}:=[f]_{B M O \infty\left(\mathbb{R}_{+}^{n}\right)}+[f]_{b a \infty\left(\mathbb{R}_{+}^{n}\right)}$.
Since $\|\cdot\|_{b \infty\left(\mathbb{R}_{+}^{n}\right)}$ is indeed a norm, $\|\cdot\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}$ is also a norm. However, $[\cdot]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}$ is simply a seminorm.

Definition 2.2.3. The space of vector fields of bounded mean oscillation over the half space $\mathbb{R}_{+}^{n}$ is defined in the following way:

$$
\mathbf{X}\left(\mathbb{R}_{+}^{n}, \mathbb{R}^{n}\right):=\left\{\left(\mathbf{v}^{\prime}, v^{n}\right) \mid \mathbf{v}^{\prime} \in\left(B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)\right)^{n-1}, v^{n} \in B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)\right\}
$$

where $\mathbf{v}^{\prime}:=\left(v^{1}, \ldots, v^{n-1}\right)$ and $\mathbf{v}:=\left(v^{1}, \ldots, v^{n-1}, v^{n}\right)$. We define the seminorm $[\cdot] \mathbf{X}$ on the space of vector fields $\mathbf{X}\left(\mathbb{R}_{+}^{n}, \mathbb{R}^{n}\right)$ as follow:

$$
[\mathbf{v}]_{\mathbf{X}}:=\sum_{i=1}^{n-1}\left[v^{i}\right]_{B M O_{b a}^{\infty}, \infty}\left(\mathbb{R}_{+}^{n}\right)+\left\|v^{n}\right\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)} .
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

From now on, without any ambiguity, we shall denote $(\mathbf{X},[\cdot] \mathbf{x})$ simply by $\mathbf{X}$ for abbreviation.

Next we would like to define two extension operators which extend functions over the half space $\mathbb{R}_{+}^{n}$ to functions over the whole space $\mathbb{R}^{n}$.

Definition 2.2.4. Let $f: \mathbb{R}_{+}^{n} \rightarrow \mathbb{R}$, we say that $E_{\text {odd }} f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is the odd extension of $f$ if

$$
E_{o d d} f\left(\mathbf{x}^{\prime}, x_{n}\right)= \begin{cases}f\left(\mathbf{x}^{\prime}, x_{n}\right) & \text { if } x_{n}>0 \\ -f\left(\mathbf{x}^{\prime},-x_{n}\right) & \text { if } x_{n}<0\end{cases}
$$

a.e. (almost everywhere).

Definition 2.2.5. Let $f: \mathbb{R}_{+}^{n} \rightarrow \mathbb{R}$, we say that $E_{\text {even }} f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is the even extension of $f$ if

$$
E_{\text {even }} f\left(\mathbf{x}^{\prime}, x_{n}\right)= \begin{cases}f\left(\mathbf{x}^{\prime}, x_{n}\right) & \text { if } x_{n}>0, \\ f\left(\mathbf{x}^{\prime},-x_{n}\right) & \text { if } x_{n}<0\end{cases}
$$

a.e. (almost everywhere).

Based on these two definitions of extension, we are able to define an extension operator for vector fields of functions over the half space $\mathbb{R}_{+}^{n}$.
Definition 2.2.6. Let $f^{i}: \mathbb{R}_{+}^{n} \rightarrow \mathbb{R}$ for $1 \leq i \leq n$ and let $\mathbf{f}=\left(f^{1}, \ldots, f^{n-1}, f^{n}\right)$, we define the extension of $f$ by

$$
E \mathbf{f}=\left\{\begin{array}{l}
(E \mathbf{f})^{i}:=E_{\text {even }} f^{i} \quad \text { for } 1 \leq i \leq n-1, \\
(E \mathbf{f})^{n}:=E_{\text {odd }} f^{n} .
\end{array}\right.
$$

After we defined the extension operator, we shall now define the restriction operator, for functions and vector fields.

Definition 2.2.7. The restriction operator is defined as follow in two cases:

- Let $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$, we define the restriction $r_{\mathbb{R}_{+}^{n}} f$ by $r_{\mathbb{R}_{+}^{n}} f:=\left.f\right|_{\mathbb{R}_{+}^{n}}: \mathbb{R}_{+}^{n} \rightarrow \mathbb{R}^{n}$.
- Let $\mathbf{f}=\left(f^{1}, \ldots, f^{n-1}, f^{n}\right)$ and $f^{i}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ with $1 \leq i \leq n$, we define the $i$-th component of the restriction $r_{\mathbb{R}_{+}^{n}} \mathbf{f}$ by $\left(r_{\mathbb{R}_{+}^{n}} \mathbf{f}\right)^{i}:=r_{\mathbb{R}_{+}^{n}} f^{i}$.
Now we have done enough preparations for defining our vector field of real Hardy space $\mathscr{H}^{1}$ over $\mathbb{R}_{+}^{n}$.

Definition 2.2.8. We define two types of real Hardy space $\mathscr{H}^{1}$ over the half space $\mathbb{R}_{+}^{n}$ in the following way:

- $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right):=\left\{f \in L^{1}\left(\mathbb{R}_{+}^{n}\right) \mid\|f\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)}<\infty\right\}$
where $\|f\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)}:=\left\|\sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}} e^{t \Delta} E_{\text {odd }} f\right|(\mathbf{x})\right\|_{L^{1}\left(\mathbb{R}_{+}^{n}\right)}$.
- $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right):=\left\{f \in L^{1}\left(\mathbb{R}_{+}^{n}\right) \mid\|f\|_{\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)}<\infty\right\}$
where $\|f\|_{\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)}:=\left\|\sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}} e^{t \Delta} E_{\text {even }} f\right|(\mathbf{x})\right\|_{L^{1}\left(\mathbb{R}_{+}^{n}\right)}$.

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Here $e^{t \Delta}$ is the heat semigroup. In other words, $\left(e^{t \Delta} f\right)(\mathbf{x})=\int_{\mathbb{R}^{n}} G_{t}(\mathbf{x}-\mathbf{y}) f(\mathbf{y}) \mathrm{d} \mathbf{y}$ where $G_{t}(\mathbf{x})=\frac{1}{(4 \pi t)^{n}} e^{-\frac{|\mathbf{x}|^{2}}{4 t}}$ denotes the heat kernel. We also write as $\left(G_{t} * f\right)(\mathbf{x})$ by using the notation of convolution.

Definition 2.2.9. The space of vector fields in real Hardy spaces over the half space $\mathbb{R}_{+}^{n}$ is defined in the following way:

$$
\mathbf{Y}\left(\mathbb{R}_{+}^{n}, \mathbb{R}^{n}\right):=\left\{\left(\mathbf{u}^{\prime}, u^{n}\right) \mid \mathbf{u}^{\prime} \in\left(\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)\right)^{n-1}, u^{n} \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)\right\}
$$

where $\mathbf{u}^{\prime}:=\left(u^{1}, \ldots, u^{n-1}\right)$ and $\mathbf{u}:=\left(u^{1}, \ldots, u^{n-1}, u^{n}\right)$. We define the norm $\|\cdot\|_{\mathbf{Y}}$ on $\mathbf{Y}$ by

$$
\|\mathbf{u}\|_{\mathbf{Y}}:=\sum_{i=1}^{n-1}\left\|u^{i}\right\|_{\mathscr{H}_{e v e n}^{1}\left(\mathbb{R}_{+}^{n}\right)}+\left\|u^{n}\right\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)} .
$$

From now on, without any ambiguity, we shall denote $\left(\mathbf{Y},\|\cdot\|_{\mathbf{Y}}\right)$ simply by $\mathbf{Y}$ for abbreviation.

Definition 2.2.10. We define $\mathbb{P}$ by $(\mathbb{P})_{i j}:=\delta_{i j}+R_{i} R_{j}$ with $1 \leq i, j \leq n$ where $R_{i}$ is the $i$-th Riesz transform.

Here $\mathbb{P}$ is an $n \times n$ matrix whose entries are transforms. This $\mathbb{P}$ is exactly the Helmholtz projection established by Miyakawa in [8].

Definition 2.2.11. We define the half space projection operator $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ by $\mathbb{P}_{\mathbb{R}_{+}^{n}}:=r_{\mathbb{R}_{+}^{n}} \mathbb{P} E$, that means for $\mathbf{v} \in \mathbf{X}$ (or $\mathbf{Y}$ ) we have that $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v}:=r_{\mathbb{R}_{+}^{n}} \mathbb{P} E \mathbf{v}$.

Before we end this section, let us recall the real Hardy space and the $B M O$ space defined by Miyachi in [7] when the domain $\Omega=\mathbb{R}_{+}^{n}$ and $p=1$. Let $\varphi \in C_{0}^{\infty}(B(0,1))$ such that $\int_{\mathbb{R}^{n}} \varphi(\mathbf{x}) \mathrm{d} \mathbf{x}=1$. For $\mathbf{x} \in \mathbb{R}_{+}^{n}$, let $d_{\mathbb{R}_{+}^{n}}(\mathbf{x}):=\operatorname{dist}\left(\mathbf{x},\left(\mathbb{R}_{+}^{n}\right)^{c}\right)$.

Definition 2.2.12. We denote by $\mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$ the set of those $f \in L^{1}\left(\mathbb{R}_{+}^{n}\right)$ such that

$$
\left\|\sup _{0<t<d_{\mathbb{R}_{+}^{n}}(\mathbf{x})}\left|\varphi_{t} * f\right|(\mathbf{x})\right\|_{L^{1}\left(\mathbb{R}_{+}^{n}\right)}<\infty .
$$

Definition 2.2.13. Let $f \in L_{l o c}^{1}\left(\mathbb{R}_{+}^{n}\right)$, we say $f \in B M O_{M}\left(\mathbb{R}_{+}^{n}\right)$ if

$$
\|f\|_{B M O_{M}\left(\mathbb{R}_{+}^{n}\right)}:=[f]_{B M O\left(\mathbb{R}_{+}^{n}\right)}+[f]_{b\left(\mathbb{R}_{+}^{n}\right)}<\infty
$$

where

$$
\begin{aligned}
& {[f]_{B M O\left(\mathbb{R}_{+}^{n}\right)}:=\sup \left\{\left.\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|f-f_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} \right\rvert\, B_{2 r}(\mathbf{x}) \subset \mathbb{R}_{+}^{n}\right\},} \\
& {[f]_{b\left(\mathbb{R}_{+}^{n}\right)}:=\sup \left\{\left.\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}|f| \mathrm{d} \mathbf{y} \right\rvert\, B_{2 r}(\mathbf{x}) \subset \mathbb{R}_{+}^{n} \text { and } B_{5 r}(\mathbf{x}) \cap\left(\mathbb{R}_{+}^{n}\right)^{c} \neq \emptyset\right\}}
\end{aligned}
$$

### 2.3 Helmholtz decomposition of vector fields of bounded mean oscillation over the half space

### 2.3.1 Boundedness of projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ from X to X

Let $\mathbf{v} \in \mathbf{X}$ and $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v}:=r_{\mathbb{R}_{+}^{n}} \mathbb{P} E \mathbf{v}$.
Lemma 2.3.1. Let $f \in B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$, then we have that $E_{\text {odd }} f \in B M O\left(\mathbb{R}^{n}, \mathbb{R}\right)$ and there exists a constant $C$ which only depends on $n$ such that

$$
\left[E_{o d d} f\right]_{B M O} \leq C \cdot\|f\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)} .
$$

Proof. This lemma has already been established in [1, Lemma 7].
Lemma 2.3.2. Let $f \in B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$, then we have that $E_{\text {even }} f \in B M O\left(\mathbb{R}^{n}, \mathbb{R}\right)$ and there exists a constant $C$ which only depends on $n$ such that

$$
\left[E_{\text {even }} f\right]_{B M O} \leq C \cdot[f]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}
$$

Proof. For simplicity let us denote $E_{\text {even }} f$ by $\tilde{f}$, let $\mathbf{x} \in \mathbb{R}^{n}$ and $r>0$. If $B_{r}(\mathbf{x}) \subset \mathbb{R}_{+}^{n}$ or $B_{r}(\mathbf{x}) \subset\left(\mathbb{R}_{+}^{n}\right)^{c}$, we can easily verify that

$$
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} \leq[f]_{B M O^{\infty}\left(\mathbb{R}_{+}^{n}\right)}
$$

(1). If $B_{r}(\mathbf{x}) \cap \partial \mathbb{R}_{+}^{n} \neq \varnothing$ and $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$, then due to the fact that $\tilde{f}$ is even with respect to $x_{n}$, we have

$$
\begin{aligned}
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} & \leq \frac{2}{\left|B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}\right|} \int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\left|f(\mathbf{y})-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} \\
& \leq \frac{2}{\left|B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}\right|}\left(\int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\left|f(\mathbf{y})-f_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\right| \mathrm{d} \mathbf{y}\right. \\
& \left.+\int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\left|f_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y}\right) \cdots \cdots(* 1) .
\end{aligned}
$$

Here $f_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}:=\frac{1}{\left|B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}\right|} \int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}} f(\mathbf{y}) \mathrm{d} \mathbf{y}$. By simple check we can further notice that

$$
\tilde{f}_{B_{r}(\mathbf{x})}=\frac{1}{\left|B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}\right|} \int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}} f(\mathbf{y}) \mathrm{d} \mathbf{y} .
$$

Therefore $f_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}=\tilde{f}_{B_{r}(\mathbf{x})}$ if $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$ and hence

$$
\int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\left|f_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y}=0 .
$$

By continuing the calculation we can deduce that

$$
(* 1)=\frac{2}{\left|B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}\right|} \int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\left|f(\mathbf{y})-f_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}\right| \mathrm{d} \mathbf{y} \leq 2 \cdot[f]_{b_{a} \infty\left(\mathbb{R}_{+}^{n}\right)} .
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Thus if $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$, then for any $r>0$ we have that

$$
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} \leq 2 \cdot[f]_{b_{a} \infty\left(\mathbb{R}_{+}^{n}\right)} .
$$

(2). If $B_{r}(\mathbf{x}) \cap \partial \mathbb{R}_{+}^{n} \neq \varnothing$ and $\mathbf{x} \notin \partial \mathbb{R}_{+}^{n}$, then $\exists \mathbf{x}^{*} \in B_{r}(\mathbf{x}) \cap \partial \mathbb{R}_{+}^{n}$ and $B_{r}(\mathbf{x}) \subset B_{2 r}\left(\mathbf{x}^{*}\right)$.

Notice that

$$
\begin{aligned}
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{2 r}\left(\mathbf{x}^{*}\right)}\right| \mathrm{d} \mathbf{y} & \leq \frac{\left|B_{2 r}\left(\mathbf{x}^{*}\right)\right|}{\left|B_{r}(\mathbf{x})\right|} \cdot \frac{1}{\left|B_{2 r}\left(\mathbf{x}^{*}\right)\right|} \cdot \int_{B_{2 r}\left(\mathbf{x}^{*}\right)}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{2 r}\left(\mathbf{x}^{*}\right)}\right| \mathrm{d} \mathbf{y} \\
& \leq \frac{\left|B_{2 r}\left(\mathbf{x}^{*}\right)\right|}{\left|B_{r}(\mathbf{x})\right|} \cdot 2 \cdot[f]_{b a \infty\left(\mathbb{R}_{+}^{n}\right)} \\
& =2^{n+1} \cdot[f]_{b a^{\infty}\left(\mathbb{R}_{+}^{n}\right)} .
\end{aligned}
$$

The second inequality here holds because of (1). Notice that

$$
\begin{aligned}
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} & \leq\left(\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{2 r}\left(\mathbf{x}^{*}\right)}\right| \mathrm{d} \mathbf{y}\right. \\
& \left.+\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}_{B_{2 r}\left(\mathbf{x}^{*}\right)}-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y}\right) \cdots \cdots(* 2) .
\end{aligned}
$$

and

$$
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}_{B_{2 r}\left(\mathbf{x}^{*}\right)}-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} \leq \frac{1}{\left|B_{r}(\mathbf{x})\right|} \cdot \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{2 r}\left(\mathbf{x}^{*}\right)}\right| \mathrm{d} \mathbf{y} .
$$

Therefore

$$
(* 2) \leq \frac{2}{\left|B_{r}(\mathbf{x})\right|} \cdot \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{2 r}\left(\mathbf{x}^{*}\right)}\right| \mathrm{d} \mathbf{y} \leq 2^{n+2} \cdot[f]_{b_{a} \infty\left(\mathbb{R}_{+}^{n}\right)} .
$$

As a result, for any $\mathbf{x} \in \mathbb{R}_{+}^{n}$ and $r>0$, we have that

$$
\begin{aligned}
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|\tilde{f}(\mathbf{y})-\tilde{f}_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} & \leq\left([f]_{B M O^{\infty}\left(\mathbb{R}_{+}^{n}\right)}+2^{n+2} \cdot[f]_{b a^{\infty}\left(\mathbb{R}_{+}^{n}\right)}\right) \\
& =2^{n+2} \cdot[f]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}
\end{aligned}
$$

by (1) and (2). Therefore it is true that

$$
[\tilde{f}]_{B M O} \leq 2^{n+2} \cdot[f]_{B M O_{b a}^{\infty}, \infty}\left(\mathbb{R}_{R}^{n}\right) .
$$

Lemma 2.3.3. Let $f \in B M O\left(\mathbb{R}^{n}, \mathbb{R}\right)$ and $f$ be odd with respect to $x_{n}$, i.e., $f\left(\mathbf{x}^{\prime}, x_{n}\right)=$ $-f\left(\mathbf{x}^{\prime},-x_{n}\right)$, then we have that $r_{\mathbb{R}_{+}^{n}} f \in B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ and there exists a universal constant $C$ such that

$$
\left\|r_{\mathbb{R}_{+}^{n}} f\right\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)} \leq C \cdot[f]_{B M O} .
$$

Proof. (1). Notice that

$$
\left[r_{\mathbb{R}_{+}^{n}} f\right]_{B M O^{\infty}\left(\mathbb{R}_{+}^{n}\right)} \leq \sup _{\substack{\mathbf{x} \in \mathbb{R}^{n} \\ r>0}} \frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|f(\mathbf{y})-f_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y}=[f]_{B M O} .
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
(2). Let $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$ and $r>0$. Let $B_{r}^{+}(\mathbf{x}):=B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}$ and $B_{r}^{-}(\mathbf{x}):=B_{r}(\mathbf{x}) \cap\left(\mathbb{R}_{+}^{n}\right)^{c}$. We have that

$$
f_{B_{r}(\mathbf{x})}=\frac{1}{\left|B_{r}(\mathbf{x})\right|}\left(\int_{B_{r}^{+}(\mathbf{x})} f(\mathbf{y}) \mathrm{d} \mathbf{y}+\int_{B_{r}^{-}(\mathbf{x})} f(\mathbf{y}) \mathrm{d} \mathbf{y}\right) .
$$

Notice that by change of variables we can easily deduce that

$$
\int_{B_{r}^{-}(\mathbf{x})} f(\mathbf{y}) \mathrm{d} \mathbf{y}=-\int_{B_{r}^{+}(\mathbf{x})} f(\mathbf{y}) \mathrm{d} \mathbf{y} .
$$

Hence

$$
f_{B_{r}(\mathbf{x})}=\frac{1}{\left|B_{r}(\mathbf{x})\right|} \cdot\left(\int_{B_{r}^{+}(\mathbf{x})} f(\mathbf{y}) \mathrm{d} \mathbf{y}-\int_{B_{r}^{+}(\mathbf{x})} f(\mathbf{y}) \mathrm{d} \mathbf{y}\right)=0 .
$$

Therefore in this case, we have that

$$
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|f(\mathbf{y})-f_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y}=\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}|f(\mathbf{y})| \mathrm{d} \mathbf{y} .
$$

By taking the supremum, we can deduce that

$$
\begin{aligned}
\sup _{\substack{r>0 \\
\mathbf{x} \in \partial \mathbb{R}_{+}^{n}}} r^{-n} \int_{B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}}|f(\mathbf{y})| \mathrm{d} \mathbf{y} & \leq \sup _{\substack{r>0 \\
\mathbf{x} \in \partial \mathbb{R}_{+}^{n}}} \frac{C}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|f(\mathbf{y})-f_{B_{r}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} \\
& \leq C \cdot[f]_{B M O} .
\end{aligned}
$$

Thus

$$
\left\|r_{\mathbb{R}_{+}^{n}} f\right\|_{b^{\infty}\left(\mathbb{R}_{+}^{n}\right)} \leq C \cdot[f]_{B M O} .
$$

Therefore by (1) and (2), we have that

$$
\left\|r_{\mathbb{R}_{+}^{n}} f\right\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)} \leq C \cdot[f]_{B M O} .
$$

Lemma 2.3.4. Let $f \in B M O\left(\mathbb{R}_{+}^{n}, \mathbb{R}\right)$, then we have that $r_{\mathbb{R}_{+}^{n}} f \in B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ and there exists a universal constant $C$ such that

$$
\left[r_{\mathbb{R}_{+}^{n}} f\right]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)} \leq C \cdot[f]_{B M O} .
$$

Proof. Firstly let us recall the fact that in defining the $B M O$-seminorm it is equivalent to consider the supremum over all balls and all squares. Here we make use of this idea. Let $f \in B M O\left(\mathbb{R}_{+}^{n}, \mathbb{R}\right), \mathbf{x} \in \partial \mathbb{R}_{+}^{n}$ and $r>0$, let $B_{r}^{+}(\mathbf{x})$ be the intersection of the ball $B_{r}(\mathbf{x})$ and the half space $\mathbb{R}_{+}^{n}$. Let $\tilde{Q}_{c}$ be the set of squares whose centers are on the boundary $\partial \mathbb{R}_{+}^{n}$ with sides parallel to the coordinate system. Notice that a simple triangle inequality would give us the fact that if for each half ball $B_{r}^{+}(\mathbf{x})$ there exists a constant $c_{B_{r}^{+}(\mathbf{x})}$ such that

$$
\begin{equation*}
\sup _{\substack{\mathbf{x} \in \partial \mathbb{R}_{+}^{n} \\ r>0}} \frac{1}{\left|B_{r}^{+}(\mathbf{x})\right|} \int_{B_{r}^{+}(\mathbf{x})}\left|f(\mathbf{y})-c_{B_{r}^{+}(\mathbf{x})}\right| \mathrm{d} \mathbf{y}<\infty, \tag{2.3.1}
\end{equation*}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
then $[f]_{b a^{\infty}}<\infty$. Now we let $Q_{*} \in \tilde{Q}_{c}$ be the smallest square that contains $B_{r}(\mathbf{x})$, then we can easily deduce that

$$
\begin{aligned}
\frac{1}{\left|B_{r}^{+}(\mathbf{x})\right|} \int_{B_{r}^{+}(\mathbf{x})}\left|f(\mathbf{y})-f_{Q_{*}^{+}}\right| \mathrm{d} \mathbf{y} & \leq \frac{\left|Q_{*}^{+}\right|}{\left|B_{r}^{+}(\mathbf{x})\right|} \cdot \frac{1}{\left|Q_{*}^{+}\right|} \int_{Q_{*}^{+}}\left|f(\mathbf{y})-f_{Q_{*}^{+}}\right| \mathrm{d} \mathbf{y} \\
& \leq c \cdot \sup _{Q \in \tilde{Q}_{c}} \frac{1}{\left|Q^{+}\right|} \int_{Q^{+}}\left|f(\mathbf{y})-f_{Q^{+}}\right| \mathrm{d} \mathbf{y}
\end{aligned}
$$

where $c$ is a constant independent of the radius $r$ and $Q^{+}$is the intersection of $Q$ and $\mathbb{R}_{+}^{n}$. Hence by (2.3.1) there exists a constant $c$ such that

$$
[f]_{b a^{\infty}\left(\mathbb{R}_{+}^{n}\right)} \leq c \cdot \sup _{Q \in \tilde{Q}_{c}} \frac{1}{\left|Q^{+}\right|} \int_{Q^{+}}\left|f(\mathbf{y})-f_{Q^{+}}\right| \mathrm{d} \mathbf{y} .
$$

For the opposite direction let $Q^{*} \in \tilde{Q}_{c}$ be the largest square that is contained in the ball $B_{r}(\mathrm{x})$, then we have

$$
\frac{1}{\left|Q^{*+}\right|} \int_{Q^{*+}}\left|f(\mathbf{y})-f_{B_{r}^{+}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} \leq \frac{\left|B_{r}^{+}(\mathbf{x})\right|}{\left|Q^{*+}\right|} \cdot \frac{1}{\left|B_{r}^{+}(\mathbf{x})\right|} \int_{B_{r}^{+}(\mathbf{x})}\left|f(\mathbf{y})-f_{B_{r}^{+}(\mathbf{x})}\right| \mathrm{d} \mathbf{y} .
$$

By similar arguments as proving (2.3.1), if we take the supremum over all squares, we have that

$$
\sup _{Q \in \tilde{Q}_{c}} \frac{1}{\left|Q^{+}\right|} \int_{Q^{+}}\left|f(\mathbf{y})-f_{Q^{+}}\right| \mathrm{d} \mathbf{y} \leq c \cdot[f]_{b a^{\infty}\left(\mathbb{R}_{+}^{n}\right)} .
$$

Therefore the seminorm $[f]_{b_{a} \infty\left(\mathbb{R}_{+}^{n}\right)}$ is equivalent to the seminorm $\left.\sup _{Q \in \tilde{Q}_{c}} \frac{1}{\left|Q^{+}\right|} \int_{Q^{+}} \right\rvert\, f(\mathbf{y})-$ $f_{Q^{+}} \mid$dy. To prove Lemma 2.3.4, we only need to check that the seminorm $\left.\sup _{Q \in \tilde{Q}_{c}} \frac{1}{\left|Q^{+}\right|} \int_{Q^{+}} \right\rvert\, f(\mathbf{y})-$ $f_{Q^{+}} \mid \mathrm{d} \mathbf{y}$ is less than infinity. This is indeed since we always have that

$$
\begin{aligned}
\frac{1}{\left|Q^{+}\right|} \int_{Q^{+}}\left|f(\mathbf{y})-f_{Q}\right| \mathrm{d} \mathbf{y} & \leq \frac{|Q|}{\left|Q^{+}\right|} \cdot \frac{1}{|Q|} \cdot \int_{Q}\left|f(\mathbf{y})-f_{Q}\right| \mathrm{d} \mathbf{y} \\
& =c \cdot[f]_{B M O} \\
& <\infty
\end{aligned}
$$

By applying the argument of the square version of (2.3.1) again, we can deduce that

$$
\frac{1}{\left|Q^{+}\right|} \int_{Q^{+}}\left|f(\mathbf{y})-f_{Q^{+}}\right| \mathrm{d} \mathbf{y} \leq c \cdot[f]_{B M O}<\infty .
$$

Therefore by taking the supremum, we are done.
Now we are ready to prove the main lemma in this subsection.
Lemma 2.3.5. $\mathbb{P}_{\mathbb{R}_{+}^{n}}: \mathbf{X} \rightarrow \mathbf{X}$ is a bounded linear operator.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Proof. (1). Let $\mathbf{v} \in \mathbf{X}$, by Lemma 2.3.1 and Lemma 2.3.2, we can deduce that there exists a constant $C$ such that

$$
\begin{aligned}
{[E \mathbf{v}]_{B M O} } & =\sum_{i=1}^{n-1}\left[E_{\text {even }} v^{i}\right]_{B M O}+\left[E_{\text {odd }} v^{n}\right]_{B M O} \\
& \leq C \cdot\left(\sum_{i=1}^{n-1}\left[v^{i}\right]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}+\left\|v^{n}\right\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}\right) \\
& \leq C \cdot[\mathbf{v}]_{\mathbf{X}} .
\end{aligned}
$$

Therefore $E: \mathbf{X} \rightarrow B M O\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$ is a bounded linear operator.
(2). Since the Riesz transform $R_{i}$ is a bounded linear operator from $B M O\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$ to $B M O\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$ for each $i$, we can easily deduce that the projection $\mathbb{P}:=I+R \otimes R$ is also a bounded linear operator from $B M O\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$ to $B M O\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$. As for the boundedness of Riesz transforms from $B M O$ to $B M O$, please refer to Fefferman and Stein [3].
(3). Notice the fact that $(\mathbb{P} E \mathbf{v})^{i}$ is even with respect to $x_{n}$ for $i$ such that $1 \leq i \leq n-1$ whereas $(\mathbb{P} E \mathbf{v})^{n}$ is odd with respect to $x_{n}$. This fact will be proved in subsection 2.3.3. Then by Lemma 2.3.3 and Lemma 2.3.4, we can deduce that there exists a constant $C$ such that

$$
\left[\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v}\right]_{\mathbf{x}} \leq C \cdot[\mathbf{v}]_{\mathbf{x}}
$$

### 2.3.2 Trace problem

Let $\mathbf{u} \in \mathbf{X}$, then by Lemma 2.3.1 and Lemma 2.3 .2 we know that $E \mathbf{u} \in B M O\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$. Let $\mathbf{L}_{l o c}^{2}(\Omega):=\left(L_{l o c}^{2}(\Omega)\right)^{n}$ where $\Omega \subseteq \mathbb{R}^{n}$.

Lemma 2.3.6. Let $\mathbf{u} \in \mathbf{X}$, then we have that $\mathbf{u} \in \mathbf{L}_{\text {loc }}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)$.
Proof. Let $u \in L_{\text {loc }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $E u \in L_{\text {loc }}^{1}\left(\mathbb{R}^{n}\right)$ be an extension of $u$.
(1). $E u \in B M O$ implies that $E u \in L_{l o c}^{2}\left(\mathbb{R}^{n}\right)$. This is indeed true since if we let $B$ be any open ball in $\mathbb{R}^{n}$, by the John-Nirenberg inequality we have that

$$
\begin{aligned}
\|E u\|_{L^{2}(B)}^{2} & =2 \cdot \int_{0}^{\infty} \alpha \mu\left(\left\{\mathbf{x} \in B| | E u(\mathbf{x})-E u_{B} \mid>\alpha\right\}\right) \mathrm{d} \alpha \\
& \leq C_{1} \cdot|B| \cdot \int_{0}^{\infty} \alpha \cdot \exp \left(-\frac{C_{2} \alpha}{[E u]_{B M O}}\right) \mathrm{d} \alpha \\
& <\infty .
\end{aligned}
$$

The first equality above is due to $\|f\|_{L^{p}}^{p}=p \int_{0}^{\infty} \alpha^{p-1} d_{f}(\alpha) \mathrm{d} \alpha$ where $d_{f}(\alpha)$ is the distribution function of $f$, for this fact please refer to L.Grafakos [5].
(2). Let $K \subset \subset \overline{\mathbb{R}_{+}^{n}}$, it is certainly that $K \subset B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}$ for some $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$ and $r>0$, then we have that

$$
\|u\|_{L^{2}(K)} \leq\|u\|_{L^{2}\left(B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}\right)} \leq\|E u\|_{L^{2}\left(B_{r}(\mathbf{x})\right)}<\infty .
$$

Therefore $u \in L^{2}(K)$ for any $K \subset \subset \overline{\mathbb{R}_{+}^{n}}$, that means $u \in L_{\text {loc }}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)$.
For $\mathbf{u} \in \mathbf{X}$, we have that $E_{\text {even }} u^{i} \in B M O$ for $1 \leq i \leq n-1$ and $E_{\text {odd }} u^{n} \in B M O$, hence by (1) and (2) $u^{i} \in L_{l o c}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ for $1 \leq i \leq n$.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Since we have proved that $\mathbf{u} \in \mathbf{X}$ implies that $\mathbf{u} \in \mathbf{L}_{l o c}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)$, we are able to make use of the theory of R.Temam [10] to define the trace.

Definition 2.3.7. We define the space $E_{l o c}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ in the following way:

- $E_{l o c}\left(\overline{\mathbb{R}_{+}^{n}}\right):=\left\{\mathbf{u} \in \mathbf{L}_{l o c}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right) \mid \operatorname{div} \mathbf{u} \in L_{l o c}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)\right\}$.

Here div $\mathbf{u}$ means the divergence of $\mathbf{u}$, i.e., $\operatorname{div} \mathbf{u}:=\sum_{i=1}^{n} \partial_{x_{i}} u^{i}$.

- Let $\mathbf{u} \in E_{l o c}\left(\overline{\mathbb{R}_{+}^{n}}\right)$, we define a family of seminorms $\|\cdot\|_{E\left(\Omega_{i}\right)}$ for all $i \in \mathbb{N}$ on $E_{\text {loc }}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ by

$$
\|\mathbf{u}\|_{E\left(\Omega_{i}\right)}^{2}:=\int_{\Omega_{i}}|\operatorname{div} \mathbf{u}|^{2}+|\mathbf{u}|^{2} \mathrm{~d} \mathbf{x}
$$

where $\Omega_{i}$ is an open domain in $\mathbb{R}_{+}^{n}$ with $C^{2}$ boundary $\partial \Omega_{i}$ for each $i \in \mathbb{N}$, moreover we require that $B_{i}(0)^{\prime} \subset \partial \Omega_{i}$ for all $i \in \mathbb{N}$ where $B_{i}(0)^{\prime}:=\left\{\mathbf{x} \in B_{i}(0) \mid x_{n}=0\right\}$ and $\Omega_{i} \uparrow \mathbb{R}_{+}^{n}$ as $i \rightarrow \infty$.

Definition 2.3.8. (Trace space)

- We denote the interior of the region $\overline{\Omega_{i}} \cap \partial \mathbb{R}_{+}^{n}$ in $\mathbb{R}^{n-1}$ by $\Omega_{i}^{\prime}$.
- $\Gamma\left(\mathbb{R}^{n-1}\right):=\left\{T \in \mathscr{D}^{\prime}\left(\mathbb{R}^{n-1}\right)| |<T, \phi>\left\lvert\, \leq C_{i} \cdot\|\phi\|_{H^{\frac{1}{2}\left(\Omega_{i}^{\prime}\right)}}\right.\right.$ for any $\phi \in \mathscr{D}\left(\mathbb{R}^{n-1}\right)$ with $\operatorname{supp} \phi \subset$ $\left.\Omega_{i}^{\prime}\right\}$
- We define a family of seminorms $\left\{\|\cdot\|_{\Omega_{i}^{\prime}} \mid i \in \mathbb{N}\right\}$ on $\Gamma\left(\mathbb{R}^{n-1}\right)$ by:

$$
\|T\|_{\Omega_{i}^{\prime}}:=\sup _{\substack{\phi \in \mathscr{O}\left(\mathbb{R}^{n-1}\right), \operatorname{supp} \phi \subset \Omega_{i}^{\prime}, \left.\|\phi\|_{H^{\frac{1}{2}\left(\Omega_{i}^{\prime}\right)},} \right\rvert\,}}|<T, \phi>| .
$$

It is not hard to verify the fact that these two spaces $E_{l o c}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ and $\Gamma\left(\mathbb{R}^{n-1}\right)$ are indeed Frechet spaces, thus we omit the details here and proceed directly to define the trace.
Lemma 2.3.9. Let $\gamma: E_{l o c}\left(\overline{\mathbb{R}_{+}^{n}}\right) \rightarrow \Gamma\left(\mathbb{R}^{n-1}\right)$ by $\mathbf{u} \mapsto \gamma_{\mathbf{u}}$, where for $\phi \in \mathscr{D}\left(\mathbb{R}^{n-1}\right)$ with $\operatorname{supp} \phi \subset \Omega_{i}^{\prime}$ we have the map

$$
\gamma_{\mathbf{u}}(\phi):=\int_{\Omega_{i}} \operatorname{div} \mathbf{u} \cdot \omega+\mathbf{u} \cdot \nabla \omega \mathrm{d} \mathbf{x} .
$$

Here we choose $\omega \in H^{1}\left(\Omega_{i}\right)$ with the trace operator $\gamma_{0}: H^{1}\left(\Omega_{i}\right) \rightarrow H^{\frac{1}{2}}\left(\partial \Omega_{i}\right)$ such that the trace of $\omega$ is $\phi$. Then we have that the map $\gamma$ is a bounded linear operator.

Proof. Here we make use of the theory of R.Temam [10]. Notice that for each $\phi \in \mathscr{D}\left(\mathbb{R}^{n-1}\right)$ with supp $\phi \subset \Omega_{i}^{\prime}$, we can actually find an $\omega \in H^{1}\left(\Omega_{i}\right)$ such that its trace $\gamma_{0} \omega=\phi$. Let $\phi \in \mathscr{D}\left(\mathbb{R}^{n-1}\right)$ with $\operatorname{supp} \phi \subset \Omega_{i}^{\prime}$, notice that by definition we have that $\Omega_{i}^{\prime} \subset \Omega_{i}$. We define a function $g$ on $\partial \Omega_{i}$ by

$$
g(\mathbf{x}):= \begin{cases}\phi\left(\mathbf{x}^{\prime}\right) & \text { if } \quad x_{n}=0 \\ 0 & \text { else }\end{cases}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Since $\phi \in \mathscr{D}\left(\mathbb{R}^{n-1}\right)$, an easy check quickly tells us that this function $g \in H^{\frac{1}{2}}\left(\partial \Omega_{i}\right)$ and $\|g\|_{H^{\frac{1}{2}}\left(\partial \Omega_{i}\right)}=\|\phi\|_{H^{\frac{1}{2}\left(\Omega_{i}^{\prime}\right)}}$. Then by R.Temam [10], there exists an $\omega \in H^{1}\left(\Omega_{i}\right)$ such that its trace $\gamma_{0} \omega=g$. Therefore by the definition of our $\gamma_{\mathbf{u}}$, we have that

$$
\begin{aligned}
\left|\gamma_{\mathbf{u}}(\phi)\right| & \leq\|\operatorname{div} \mathbf{u}\|_{L^{2}\left(\Omega_{i}\right)} \cdot\|\omega\|_{L^{2}\left(\Omega_{i}\right)}+\|\mathbf{u}\|_{\mathbf{L}^{2}\left(\Omega_{i}\right)} \cdot\|\nabla \omega\|_{\mathbf{L}^{2}\left(\Omega_{i}\right)} \\
& \leq C \cdot\left(\|\operatorname{div} \mathbf{u}\|_{L^{2}\left(\Omega_{i}\right)}+\|\mathbf{u}\|_{\mathbf{L}^{2}\left(\Omega_{i}\right)}\right) \cdot\|\omega\|_{H^{1}\left(\Omega_{i}\right)} \\
& \leq C \cdot\|\mathbf{u}\|_{E\left(\Omega_{i}\right)} \cdot\|\omega\|_{H^{1}\left(\Omega_{i}\right)}
\end{aligned}
$$

by the triangle inequality and Hölder's inequality. Since by R.Temam [10], there exists $l_{\Omega_{i}} \in \mathcal{L}\left(H^{1 / 2}\left(\partial \Omega_{i}\right), H^{1}\left(\Omega_{i}\right)\right)$ where $l_{\Omega_{i}}$ is the lifting operator such that $l_{\Omega_{i}} g=\omega$, hence by above we have that

$$
\begin{aligned}
\left|\gamma_{\mathbf{u}}(\phi)\right| & \leq C \cdot\|\mathbf{u}\|_{E\left(\Omega_{i}\right)} \cdot\left\|l_{\Omega_{i}} g\right\|_{H^{1}\left(\Omega_{i}\right)} \\
& \leq C_{i} \cdot\|\mathbf{u}\|_{E\left(\Omega_{i}\right)} \cdot\|g\|_{H^{1 / 2}\left(\partial \Omega_{i}\right)} \\
& =C_{i} \cdot\|\mathbf{u}\|_{E\left(\Omega_{i}\right)} \cdot\|\phi\|_{H^{1 / 2}\left(\Omega_{i}^{\prime}\right)} .
\end{aligned}
$$

The last equality holds since $g(\mathbf{x})=0$ for $\mathbf{x} \notin \Omega_{i}^{\prime}$. Therefore, we can deduce that

$$
\left\|\gamma_{\mathbf{u}}\right\|_{\Omega_{i}^{\prime}} \leq C_{i} \cdot\|\mathbf{u}\|_{E\left(\Omega_{i}\right)}
$$

where $C_{i}$ is simply a constant which depends on $i$. As a result, we see that

$$
\gamma: E_{l o c}\left(\overline{\mathbb{R}_{+}^{n}}\right) \rightarrow \Gamma\left(\mathbb{R}^{n-1}\right)
$$

is indeed a bounded linear operator in the sense of Frechet spaces.
By Lemma 2.3.6 we know that $\mathbf{X} \subset \mathbf{L}_{\text {loc }}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ and by Lemma 2.3.9 there exists a bounded linear operator $\gamma$ which maps $E_{\text {loo }}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ to $\Gamma\left(\mathbb{R}^{n-1}\right)$. For the subspace $\{\mathbf{u} \in \mathbf{X} \mid \operatorname{div} \mathbf{u} \in$ $\left.L_{\text {loc }}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)\right\} \subset \mathbf{X}$, it is trivial to see that the map $\gamma$ is also a bounded linear operator from $\left\{\mathbf{u} \in \mathbf{X} \mid \operatorname{div} \mathbf{u} \in L_{\text {loc }}^{2}\left(\overline{\mathbb{R}_{+}^{n}}\right)\right\}$ to $\Gamma\left(\mathbb{R}^{n-1}\right)$. This is how we take the trace for elements in $\mathbf{X}$.

### 2.3.3 Validity of $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ as the Helmholtz projection

Lemma 2.3.10. Let $\mathbf{v} \in \mathbf{X}$, then div $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v}=0$ in $\mathbb{R}_{+}^{n}$ in the sense of distributions.
Proof. Let $\phi \in C_{0}^{\infty}\left(\mathbb{R}_{+}^{n}\right)$. By the definition of distributions, we have that

$$
\int_{\mathbb{R}_{+}^{n}} \operatorname{div} \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v} \cdot \phi \mathrm{~d} \mathbf{x}=-\int_{\mathbb{R}_{+}^{n}} \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v} \cdot \nabla \phi \mathrm{~d} \mathbf{x} .
$$

Since $\operatorname{supp} \phi \subset \subset \mathbb{R}_{+}^{n}$, we can easily deduce that supp $\partial_{x_{i}} \phi \subset \subset \mathbb{R}_{+}^{n}$ for any $1 \leq i \leq n$, therefore

$$
\int_{\mathbb{R}_{+}^{n}} \mathbb{P}_{\mathbb{R}_{+}^{n} \mathbf{v}} \cdot \nabla \phi \mathrm{~d} \mathbf{x}=\int_{\mathbb{R}^{n}} \mathbb{P} E \mathbf{v} \cdot \nabla \phi \mathrm{~d} \mathbf{x}=-\int_{\mathbb{R}^{n}} \operatorname{div}(\mathbb{P} E \mathbf{v}) \cdot \phi \mathrm{d} \mathbf{x} .
$$

Because div $(\mathbb{P} E \mathbf{v})=0$ in the sense of distributions, we have that

$$
\int_{\mathbb{R}^{n}} \operatorname{div}(\mathbb{P} E \mathbf{v}) \cdot \phi \mathrm{d} \mathbf{x}=0
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Thus

$$
\int_{\mathbb{R}_{+}^{n}} \operatorname{div} \mathbb{P}_{\mathbb{R}_{+}^{n} \mathbf{v}} \cdot \phi \mathrm{~d} \mathbf{x}=-\int_{\mathbb{R}_{+}^{n}} \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v} \cdot \nabla \phi \mathrm{~d} \mathbf{x}=\int_{\mathbb{R}^{n}} \operatorname{div}(\mathbb{P} E \mathbf{v}) \cdot \phi \mathrm{d} \mathbf{x}=0 .
$$

Notice that the above equality holds for any $\phi \in C_{0}^{\infty}\left(\mathbb{R}_{+}^{n}\right)$, hence

$$
\operatorname{div} \mathbb{P}_{\mathbb{R}_{+}^{n} \mathbf{v}}=0 \quad \text { in } \mathbb{R}_{+}^{n}
$$

in the sense of distributions. As for the reason why div $\mathbb{P} E \mathbf{v}=0$ in the sense of distributions, by considering Fourier transforms we can quickly prove it through simple calculations.

Let us recall some facts about Riesz transforms. Notice that the $j$-th Riesz transform $R_{j}$ is defined as

$$
R_{j}(f)(\mathbf{x}):=\text { p.v. } \int_{\mathbb{R}^{n}} \frac{x_{j}-y_{j}}{|\mathbf{x}-\mathbf{y}|^{n+1}} \cdot f(\mathbf{y}) \mathrm{d} \mathbf{y} .
$$

By [9, p.232], we have that $R_{j}(f)$ is well-defined for any $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and $1 \leq j \leq n$. By [3], we have that for $f \in B M O$ and $1 \leq j \leq n, R_{j}(f) \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)^{*}$. Hence by the fact that $B M O=\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)^{*}$, there exists $h \in B M O$ such that $R_{j}(f)=h$ in the sense of bounded linear functionals on $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. Therefore for any $f \in B M O$ and $1 \leq j \leq n, R_{j}(f)$ is defined by its corresponding $h$. Based on these facts, we have the next lemma which proves an interesting property about Riesz transforms.

Lemma 2.3.11. Let $f$ belongs to $B M O$ or $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$,
(1). If $f$ is even with respect to $x_{n}$, then

$$
\left\{\begin{array}{l}
R_{j}(f) \text { is even with respect to } x_{n} \text { for } j \text { satisfying } 1 \leq j \leq n-1, \\
R_{n}(f) \text { is odd with respect to } x_{n} .
\end{array}\right.
$$

(2). If $f$ is odd with respect to $x_{n}$, then

$$
\left\{\begin{array}{l}
R_{j}(f) \text { is odd with respect to } x_{n} \text { for } j \text { satisfying } 1 \leq j \leq n-1, \\
R_{n}(f) \text { is even with respect to } x_{n} .
\end{array}\right.
$$

Proof. For $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$, since $R_{j}(f)$ is well-defined for each $1 \leq j \leq n$, we can prove this lemma directly through change of variables. Let $g \in B M O$ be odd with respect to $x_{n}$ and $1 \leq j \leq n-1$, let $w \in B M O$ such that $R_{j}(g)=w$. Let $\tilde{w}\left(\mathbf{x}^{\prime}, x_{n}\right):=w\left(\mathbf{x}^{\prime},-x_{n}\right)$ and $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$, then by change of variables we have that

$$
<\tilde{w}, f>=<w, \tilde{f}>=-<g, R_{j}(\tilde{f})>.
$$

Notice that the second equality above holds since $\tilde{f} \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ if $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. Again by change of variables, we can further deduce that

$$
R_{j}(\tilde{f})\left(\mathbf{x}^{\prime}, x_{n}\right)=R_{j}(f)\left(\mathbf{x}^{\prime},-x_{n}\right) .
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Then,

$$
\begin{aligned}
-<g, R_{j}(\tilde{f})> & =-\int_{\mathbb{R}^{n}} g \cdot R_{j}(\tilde{f}) \mathrm{d} \mathbf{x} \\
& =-\int_{\mathbb{R}^{n}} g\left(\mathbf{x}^{\prime}, x_{n}\right) \cdot R_{j}(f)\left(\mathbf{x}^{\prime},-x_{n}\right) \mathrm{d} \mathbf{x} \\
& =-\int_{\mathbb{R}^{n}} g\left(\mathbf{x}^{\prime},-x_{n}\right) \cdot R_{j}(f)\left(\mathbf{x}^{\prime}, x_{n}\right) \mathrm{d} \mathbf{x} \\
& =\int_{\mathbb{R}^{n}} g\left(\mathbf{x}^{\prime}, x_{n}\right) \cdot R_{j}(f)\left(\mathbf{x}^{\prime}, x_{n}\right) \mathrm{d} \mathbf{x} \\
& =<g, R_{j}(f)> \\
& =-<w, f>.
\end{aligned}
$$

Hence $<\tilde{w}+w, f>=0$ for any $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and thus $w$ is odd with respect to $x_{n}$. The other three cases can be proved by similar arguments.

Lemma 2.3.12. Let $\mathbf{v} \in \mathbf{X}$, then we have that

$$
\left\{\begin{array}{l}
(\mathbb{P} E \mathbf{v})^{i} \text { is even with respect to } x_{n} \text { for } i \text { satisfying } 1 \leq i \leq n-1, \\
(\mathbb{P E} \mathbf{v})^{n} \text { is odd with respect to } x_{n} .
\end{array}\right.
$$

Proof. This is a direct application of Lemma 2.3.11.
Lemma 2.3.13. Let $\mathbf{v} \in \mathbf{X}$, then the trace $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v} \cdot \mathbf{n}=0$ on $\partial \mathbb{R}_{+}^{n}$ in the sense of distributions.
Proof. Let $B_{R}$ be the ball $B_{R}(0)$. Let $B_{R}^{+}:=B_{R} \cap \mathbb{R}_{+}^{n}$ and $B_{R}^{-}:=B_{R} \cap\left(\mathbb{R}_{+}^{n}\right)^{c}$. Let $\mathbf{v} \in \mathbf{X}$ and let $\mathbf{u}:=\mathbb{P} E \mathbf{v}$. By the above lemma we can see that $u^{n}$ is odd with respect to $x_{n}$. Let

$$
\mathbf{u}_{1}\left(\mathbf{x}^{\prime}, x_{n}\right):= \begin{cases}\mathbf{u}\left(\mathbf{x}^{\prime}, x_{n}\right) & \text { if } x_{n}>0 \\ 0 & \text { if } x_{n}<0\end{cases}
$$

and

$$
\mathbf{u}_{2}\left(\mathbf{x}^{\prime}, x_{n}\right):= \begin{cases}0 & \text { if } x_{n}>0 \\ \mathbf{u}\left(\mathbf{x}^{\prime}, x_{n}\right) & \text { if } x_{n}<0\end{cases}
$$

Let $\phi \in C_{0}^{\infty}\left(B_{R}\right)$, then we have that

$$
\begin{aligned}
<\operatorname{div} \mathbf{u}_{1}, \phi> & \left.:=-<\mathbf{u}_{1}, \nabla \phi\right\rangle \\
& =\int_{B_{R}^{+}} \operatorname{div} \mathbf{u}_{1} \cdot \phi \mathrm{~d} \mathbf{x}+\int_{\left\{x_{n}=0\right\} \cap B_{R}}\left(\mathbf{u}_{1} \cdot \mathbf{n}_{1}\right) \phi \mathrm{d} \mathscr{H}^{n-1}
\end{aligned}
$$

where $\mathbf{n}_{1}$ is the normal vector on $\partial \mathbb{R}_{+}^{n}$ which points outward $B_{R}^{+}$. In the mean time, we also have that

$$
\begin{aligned}
<\operatorname{div} \mathbf{u}_{2}, \phi> & \left.:=-<\mathbf{u}_{2}, \nabla \phi\right\rangle \\
& =\int_{B_{R}^{-}} \operatorname{div} \mathbf{u}_{2} \cdot \phi \mathrm{~d} \mathbf{x}+\int_{\left\{x_{n}=0\right\} \cap B_{R}}\left(\mathbf{u}_{2} \cdot \mathbf{n}_{2}\right) \phi \mathrm{d} \mathscr{H}^{n-1}
\end{aligned}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
where $\mathbf{n}_{2}$ is the normal vector on $\partial \mathbb{R}_{+}^{n}$ which points outward $B_{R}^{-}$. By similar arguments as in the proof of Lemma 2.3.10, we can see that div $\mathbf{u}=0$ in $B_{R}$, div $\mathbf{u}_{1}=0$ in $B_{R}^{+}$and div $\mathbf{u}_{2}=0$ in $B_{R}^{-}$. Therefore

$$
\begin{aligned}
0 & =<\operatorname{div} \mathbf{u}_{1}, \phi>+\left\langle\operatorname{div} \mathbf{u}_{2}, \phi\right\rangle \\
& =\int_{B_{R}^{+}} \operatorname{div} \mathbf{u}_{1} \cdot \phi \mathrm{~d} \mathbf{x}+\int_{B_{R}^{-}} \operatorname{div} \mathbf{u}_{2} \cdot \phi \mathrm{~d} \mathbf{x}+\int_{\left\{x_{n}=0\right\} \cap B_{R}}\left(\mathbf{u}_{1} \cdot \mathbf{n}_{1}+\mathbf{u}_{2} \cdot \mathbf{n}_{2}\right) \phi \mathrm{d} \mathscr{H}^{n-1} \\
& =\int_{\left\{x_{n}=0\right\} \cap B_{R}}\left(\mathbf{u}_{1} \cdot \mathbf{n}_{1}-\mathbf{u}_{2} \cdot \mathbf{n}_{1}\right) \phi \mathrm{d} \mathscr{H}^{n-1} .
\end{aligned}
$$

Thus we see that on $\left\{x_{n}=0\right\} \cap B_{R},\left(\mathbf{u}_{1} \cdot \mathbf{n}_{1}-\mathbf{u}_{2} \cdot \mathbf{n}_{1}\right)=0$ in the sense of distributions. Notice that if $x_{n}<0$, then

$$
u_{2}^{n}\left(\mathbf{x}^{\prime}, x_{n}\right)=-u_{1}^{n}\left(\mathbf{x}^{\prime},-x_{n}\right) .
$$

At $\left\{x_{n}=0\right\} \cap B_{R}$, we have that

$$
\mathbf{u}_{1} \cdot \mathbf{n}_{1}=u_{1}^{n}\left(\mathbf{x}^{\prime}, 0\right) \quad \text { and } \quad \mathbf{u}_{2} \cdot \mathbf{n}_{2}=-u_{1}^{n}\left(\mathbf{x}^{\prime}, 0\right) .
$$

and thus $u_{1}^{n}\left(\mathbf{x}^{\prime}, 0\right)=0$ in the sense of distributions. Notice that

$$
u_{1}^{n}\left(\mathbf{x}^{\prime}, 0\right)=\left.\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v} \cdot \mathbf{n}\right|_{\left\{x_{n}=0\right\} \cap B_{R}} .
$$

Since $\left\{x_{n}=0\right\} \cap B_{R} \uparrow \partial \mathbb{R}_{+}^{n}$ as $R \rightarrow \infty$, we can easily deduce that the trace

$$
\left.\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v} \cdot \mathbf{n}\right|_{\mathbb{R}_{+}^{n}}=0
$$

in the sense of distributions.
Lemma 2.3.14. Let $\mathbf{v} \in \mathbf{X}$ such that

$$
\begin{cases}\operatorname{div} \mathbf{v}=0 & \text { in } \mathbb{R}_{+}^{n} \\ \mathbf{v} \cdot \mathbf{n}=0 & \text { on } \partial \mathbb{R}_{+}^{n}\end{cases}
$$

Then we have that $\mathbf{v} \in \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X}$. Notice that both equalities above hold in the sense of distributions.

Proof. Let $\mathbf{v} \in \mathbf{X}$ such that

$$
\begin{cases}\operatorname{div} \mathbf{v}=0 & \text { in } \mathbb{R}_{+}^{n} \\ \mathbf{v} \cdot \mathbf{n}=0 & \text { on } \partial \mathbb{R}_{+}^{n}\end{cases}
$$

in the sense of distributions and let $E$ be our extension operator. Throughout the proof of this lemma we mean equal to 0 in the sense of distributions.
(1). Here we prove that div $E \mathbf{v}=0$ in $\mathbb{R}^{n}$. Let $B_{R}$ be the ball $B_{R}(0)$. Let $B_{R}^{+}:=B_{R} \cap \mathbb{R}_{+}^{n}$ and $B_{R}^{-}:=B_{R} \cap\left(\mathbb{R}_{+}^{n}\right)^{c}$. If $x_{n}>0$, then $E \mathbf{v}\left(\mathbf{x}^{\prime}, x_{n}\right)=\mathbf{v}\left(\mathbf{x}^{\prime}, x_{n}\right)$ and $\operatorname{div} E \mathbf{v}=\operatorname{div} \mathbf{v}=0$ in $\mathbb{R}_{+}^{n}$ by our assumptions. If $x_{n}<0$, then $E \mathbf{v}\left(\mathbf{x}^{\prime}, x_{n}\right)=\left(\mathbf{v}^{\prime}\left(\mathbf{x}^{\prime},-x_{n}\right),-v^{n}\left(\mathbf{x}^{\prime},-x_{n}\right)\right)$ and

$$
\operatorname{div} E \mathbf{v}=\sum_{i=1}^{n-1} \partial_{x_{i}} v^{i}\left(\mathbf{x}^{\prime},-x_{n}\right)+\partial_{-x_{n}} v^{n}\left(\mathbf{x}^{\prime},-x_{n}\right)=0
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
since div $\mathbf{v}=0$ in $\mathbb{R}_{+}^{n}$. Let $\phi \in C_{0}^{\infty}\left(B_{R}\right)$, then

$$
\begin{aligned}
\langle\operatorname{div} E \mathbf{v}, \phi\rangle & :=-\langle E \mathbf{v}, \nabla \phi\rangle \\
& =\int_{B_{R}^{+}} \operatorname{div} E \mathbf{v} \cdot \phi \mathrm{~d} \mathbf{x}+\int_{B_{R}^{-}} \operatorname{div} E \mathbf{v} \cdot \phi \mathrm{~d} \mathbf{x} \\
& -\int_{B_{R} \cap\left\{x_{n}=0\right\}}\left\{\left((E \mathbf{v})_{+}-(E \mathbf{v})_{-}\right) \cdot \mathbf{n}_{+}\right\} \phi \mathrm{d} \mathscr{H}^{n-1} .
\end{aligned}
$$

The first two terms in the last equality equal to 0 since div $E \mathbf{v}=0$ in both $B_{R}^{+}$and $B_{R}^{-}$. The third term equals to 0 since $(E \mathbf{v})_{+} \cdot \mathbf{n}_{+}=v^{n}\left(\mathbf{x}^{\prime}, 0\right),(E \mathbf{v})_{-} \cdot \mathbf{n}_{+}=-v^{n}\left(\mathbf{x}^{\prime}, 0\right)$ and $v^{n}\left(\mathbf{x}^{\prime}, 0\right)=0$ by our assumptions. Hence div $E \mathbf{v}=0$ in $\mathbb{R}^{n}$.
(2). Notice that by simply considering Fourier transforms it is easy to verify that $R_{i} \sum_{j} R_{j} u^{j}=0$ for any $1 \leq i \leq n$ if div $\mathbf{u}=0$ in $\mathbb{R}^{n}$. Therefore if div $\mathbf{u}=0$ in $\mathbb{R}^{n}$, then $(\mathbb{P} \mathbf{u})^{i}=u^{i}$ for any $1 \leq i \leq n$.

Now let $\mathbf{u}:=E \mathbf{v}$, by (1) and (2) we have that $\mathbb{P} \mathbf{u}=\mathbf{u}$. Then by applying the restriction on both sides of this equality, we get that $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v}=\mathbf{v}$.

Definition 2.3.15. We define the solenoidal subspace $\mathbf{X}_{\sigma}$ of $\mathbf{X}$ by

$$
\mathbf{X}_{\sigma}:=\left\{\mathbf{v} \in \mathbf{X} \mid \operatorname{div} \mathbf{v}=0 \text { in } \mathbb{R}_{+}^{n} \& \mathbf{v} \cdot \mathbf{n}=0 \text { on } \partial \mathbb{R}_{+}^{n}\right\} .
$$

Here the two equalities hold in the sense of distributions.
By Lemma 2.3.10 and Lemma 2.3.13 we can see that $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X} \subseteq \mathbf{X}_{\sigma}$. And by Lemma 2.3.14 we can see that $\mathbf{X}_{\sigma} \subseteq \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X}$. Therefore $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X}=\mathbf{X}_{\sigma}$. This fact justifies the validity of $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ as the Helmholtz projection.

### 2.3.4 Characterization of the subspace $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathrm{X}$

Lemma 2.3.16. Let $\mathbf{v} \in \mathbf{X}$, then there exists $p \in L_{\text {loc }}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ such that $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{v}=\nabla p$.
Proof. We seek to make use of De Rham's theorem [4] here. In order to make use of De Rham's theorem, it is sufficient to show that

$$
<(I-\mathbb{P}) E \mathbf{v}, \phi>=0 \quad \forall \phi \in C_{0, \sigma}^{\infty}\left(\mathbb{R}^{n}\right) .
$$

Let $\phi \in C_{0, \sigma}^{\infty}\left(\mathbb{R}^{n}\right)$ and $\mathbf{u}:=E \mathbf{v}$, notice that

$$
\{(I-\mathbb{P}) \mathbf{u}\}^{i}=-R_{i} \sum_{j} R_{j} u^{j} .
$$

Therefore by substitution $<(I-\mathbb{P}) \mathbf{u}, \phi\rangle=\sum_{i}\left\langle-R_{i} \sum_{j} R_{j} u^{j}, \phi^{i}\right\rangle$. Let $f:=\sum_{j} R_{j} u^{j}$, notice that

$$
<-R_{i}(f), \phi^{i}>=<f, R_{i}\left(\phi^{i}\right)>.
$$

Therefore

$$
\begin{aligned}
<(I-\mathbb{P}) \mathbf{u}, \phi> & =\sum_{i}<\sum_{j} R_{j} u^{j}, R_{i} \phi^{i}> \\
& =<\sum_{j} R_{j} u^{j}, \sum_{i} R_{i} \phi^{i}>.
\end{aligned}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

By div $\phi=0$ we can easily deduce that $\sum_{i} R_{i} \phi^{i}=0$ by considering Fourier transforms. Thus

$$
<(I-\mathbb{P}) \mathbf{u}, \phi>=0 \quad \forall \phi \in C_{0, \sigma}^{\infty}\left(\mathbb{R}^{n}\right) .
$$

Therefore by De Rham [4], there exists $p \in L_{l o c}^{1}\left(\mathbb{R}^{n}\right)$ such that $(I-\mathbb{P}) \mathbf{u}=\nabla p$. By applying the restriction operator we have that

$$
r_{\mathbb{R}_{+}^{n}}(I-\mathbb{P}) E \mathbf{v}=\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{v}=r_{\mathbb{R}_{+}^{n}} \nabla p
$$

Notice that we can further deduce that $r_{\mathbb{R}_{+}^{n}} \nabla p=\nabla\left(r_{\mathbb{R}_{+}^{n}} p\right)$. Indeed since for any $\phi \in$ $C_{0}^{\infty}\left(\mathbb{R}_{+}^{n}\right)$ we have that

$$
\begin{aligned}
\left\langle r_{\mathbb{R}_{+}^{n}} \nabla p, \phi>\right. & :=\int_{\mathbb{R}_{+}^{n}} r_{\mathbb{R}_{+}^{n}} \nabla p \cdot \phi \mathrm{~d} \mathbf{x}=\int_{\mathbb{R}^{n}} \nabla p \cdot \phi \mathrm{~d} \mathbf{x} \\
& =-\int_{\mathbb{R}^{n}} p \cdot \operatorname{div} \phi \mathrm{~d} \mathbf{x}=-\int_{\mathbb{R}_{+}^{n}} p \cdot \operatorname{div} \phi \mathrm{~d} \mathbf{x} \\
& =-\int_{\mathbb{R}^{n}}\left(r_{\mathbb{R}_{+}^{n}} p\right) \cdot \operatorname{div} \phi \mathrm{d} \mathbf{x}=\int_{\mathbb{R}_{+}^{n}} \nabla\left(r_{\mathbb{R}_{+}^{n}} p\right) \cdot \phi \mathrm{d} \mathbf{x} \\
& =\left\langle\nabla\left(r_{\mathbb{R}_{+}^{n}} p\right), \phi\right\rangle .
\end{aligned}
$$

Therefore we have that $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{v}=\nabla\left(r_{\mathbb{R}_{+}^{n}} p\right)$. Since $p \in L_{l o c}^{1}\left(\mathbb{R}^{n}\right)$, it is easy to deduce that $r_{\mathbb{R}_{+}^{n}} p \in L_{\text {loc }}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)$.

Lemma 2.3.17. Let $p \in L_{\text {loc }}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ such that $\nabla p \in \mathbf{X}$, then $\nabla p \in\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}$.
Proof. Let $p \in L_{l o c}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ such that $\nabla p \in \mathbf{X}$, it is sufficient to prove that $\mathbb{P}_{\mathbb{R}_{+}^{n}} \nabla p=0$. Then by this fact we can see that

$$
\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \nabla p=\nabla p-\mathbb{P}_{\mathbb{R}_{+}^{n}} \nabla p=\nabla p
$$

and thus $\nabla p \in\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}$. Let $q$ be defined as follow:

$$
q\left(\mathbf{x}^{\prime}, x_{n}\right):= \begin{cases}p\left(\mathbf{x}^{\prime}, x_{n}\right) & \text { if } x_{n}>0, \\ p\left(\mathbf{x}^{\prime},-x_{n}\right) & \text { if } x_{n}<0 .\end{cases}
$$

Since $q$ is the even extension of $p, p \in L_{l o c}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ would imply $q \in L_{l o c}^{1}\left(\mathbb{R}^{n}\right)$. Moreover, simple calculations would tell us $\nabla q=E \nabla p$. This is indeed since for $x_{n}<0$ we have that

$$
\frac{\partial}{\partial x_{n}} q\left(\mathbf{x}^{\prime}, x_{n}\right)=\frac{\partial}{\partial x_{n}} p\left(\mathbf{x}^{\prime},-x_{n}\right)=-\frac{\partial}{\partial\left(-x_{n}\right)} p\left(\mathbf{x}^{\prime},-x_{n}\right)=-\frac{\partial}{\partial z_{n}} p\left(\mathbf{x}^{\prime}, z_{n}\right)
$$

where $z_{n}>0$. Again by considering Fourier transforms, it is easy to verify that $(\mathbb{P} \nabla q)^{i}=0$ for any $1 \leq i \leq n$. As a result,

$$
\mathbb{P}_{\mathbb{R}_{+}^{n}} \nabla p=r_{\mathbb{R}_{+}^{n}} \mathbb{P} E \nabla p=r_{\mathbb{R}_{+}^{n}} \mathbb{P} \nabla q=0 .
$$

Hence $\nabla p=\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \nabla p$ and we are done.
Definition 2.3.18. We define the subspace $\mathbf{X}_{\pi}$ of $\mathbf{X}$ by

$$
\mathbf{X}_{\pi}:=\left\{\nabla p \in \mathbf{X} \mid p \in L_{l o c}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)\right\} .
$$

By Lemma 2.3 .16 we can see that $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X} \subseteq \mathbf{X}_{\pi}$ and by Lemma 2.3.17 we can see that $\mathbf{X}_{\pi} \subseteq\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}$. Therefore $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}=\mathbf{X}_{\pi}$. This fact gives the characterisation of the subspace $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}$.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

### 2.3.5 Proof of Theorem 2.1.1

Proof. By Lemma 2.3.5 we see that $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ is a bounded linear operator which maps $\mathbf{X}$ to $\mathbf{X}$. By this bounded linear map we can easily see that the vector field $\mathbf{X}$ admits a natural decomposition

$$
\mathbf{X}=\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X} \oplus\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}
$$

where both $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X}$ and $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}$ are linear subspaces of $\mathbf{X}$. Since this natural decomposition is induced by the projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$, this decomposition is certainly unique. Moreover, we have already proved that

$$
\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{X}=\mathbf{X}_{\sigma}
$$

and

$$
\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{X}=\mathbf{X}_{\pi} .
$$

As a result, Theorem 2.1.1 holds and we are done.
Remark 2.3.19. Although the Helmholtz decomposition we established for $\mathbf{X}$ is true, due to the fact that $[\cdot]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}$ is a seminorm, it is inevitable to think about the question where constant vectors are mapped to under this Helmholtz projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$. Unfortunately, this question is not answered in this research, in order to avoid this ambiguity, we shall consider our Helmholtz decomposition not for the space $\mathbf{X}$ but for the quotient space $\mathbf{X} /\left(\mathbb{R}^{n-1} \times\{0\}\right)$. From now on, without causing any ambiguity, we shall denote $\mathbf{X} /\left(\mathbb{R}^{n-1} \times\right.$ $\{0\})$ simply by $\mathbf{X}$.

### 2.4 Partial Helmholtz decomposition of vector fields in real Hardy spaces over the half space

### 2.4.1 Boundedness of projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ from Y to Y

Let $\mathbf{v} \in \mathbf{Y}$ and $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v}:=r_{\mathbb{R}_{+}^{n}} \mathbb{P} E \mathbf{v}$.
Lemma 2.4.1. Let $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, then we have that $E_{\text {odd }} f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and

$$
\left\|E_{o d d} f\right\|_{\mathscr{H}^{1}}=2 \cdot\|f\|_{\mathscr{H}_{\text {odd }}^{1}}\left(\mathbb{R}_{+}^{n}\right) .
$$

Proof. For simplicity we denote $E_{\text {odd }} f$ by $\bar{f}$. Let $G_{t}$ be the heat kernel on $\mathbb{R}^{n}$ so that $\left(e^{t \Delta} g\right)(\mathbf{x})=\left(G_{t} * g\right)(\mathbf{x})$ for a function $g$ on $\mathbb{R}^{n}$. By Definition 2.2.8, we have that

$$
\begin{aligned}
\|\bar{f}\|_{\mathscr{H}}{ }^{1} & =\int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|G_{t} * \bar{f}\right|(\mathbf{x}) \mathrm{d} \mathbf{x}+\int_{\mathbb{R}_{-}^{n}} \sup _{t>0}\left|G_{t} * \bar{f}\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =(1)+(2) .
\end{aligned}
$$

(1). For $\mathbf{x} \in \mathbb{R}_{+}^{n}$ and $t>0$, we have that $\left(G_{t} * \bar{f}\right)(\mathbf{x}, t)=\left(r_{\mathbb{R}_{+}^{n}}\left(G_{t} * \bar{f}\right)\right)(\mathbf{x}, t)$. Since this is true for all $t>0$, by taking the supremum over all $t>0$, we have that

$$
\sup _{t>0}\left|G_{t} * \bar{f}\right|(\mathbf{x})=\sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}}\left(G_{t} * \bar{f}\right)\right|(\mathbf{x}) .
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Since the above equality holds for all $\mathbf{x} \in \mathbb{R}_{+}^{n}$, we can see that

$$
\begin{aligned}
(1) & =\int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}}\left(G_{t} * \bar{f}\right)\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =\int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}} e^{t \Delta} \bar{f}\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =\|f\|_{\mathscr{O _ { o d d }} 1}^{1\left(\mathbb{R}_{+}^{n}\right)} .
\end{aligned}
$$

(2). Notice that $\left(G_{t} * \bar{f}\right)(\mathbf{x}, t)$ is actually odd with respect to $x_{n}$ since $\bar{f}$ is odd with respect to $x_{n}$, hence

$$
\left|G_{t} * \bar{f}\right|\left(\mathbf{x}^{\prime}, x_{n}, t\right)=\left|-\left(G_{t} * \bar{f}\right)\left(\mathbf{x}^{\prime},-x_{n}, t\right)\right|=\left|G_{t} * \bar{f}\right|\left(\mathbf{x}^{\prime},-x_{n}, t\right) .
$$

Let $\bar{f}_{G_{t}}^{+}(\mathbf{x}):=\sup _{t>0}\left|G_{t} * \bar{f}\right|(\mathbf{x}), \bar{f}_{G_{t}}^{+}$is even with respect to $x_{n}$. Hence,

$$
(2)=\int_{\mathbb{R}_{+}^{n}} \bar{f}_{G_{t}}^{+}\left(\mathbf{z}^{\prime},-z_{n}\right) \mathrm{d} \mathbf{z}^{\prime} \mathrm{d} z_{n}=\int_{\mathbb{R}_{+}^{n}} \bar{f}_{G_{t}}^{+}\left(\mathbf{z}^{\prime}, z_{n}\right) \mathrm{d} \mathbf{z}^{\prime} \mathrm{d} z_{n}=(1) .
$$

Lemma 2.4.2. Let $f \in \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, then we have that $E_{\text {even }} f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and

$$
\left\|E_{\text {even }} f\right\|_{\mathscr{H}}{ }_{\left(\mathbb{R}^{n}\right)}=2 \cdot\|f\|_{\mathscr{e _ { e v e n }} 1}\left(\mathbb{R}_{+}^{n}\right) .
$$

Proof. For simplicity we denote $E_{\text {even }} f$ by $\tilde{f}$. Let $G_{t}$ be the heat kernel. By Definition 2.2.8, we have that

$$
\begin{aligned}
\|\tilde{f}\|_{\mathscr{H}}{ }^{1} & =\int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|G_{t} * \tilde{f}\right|(\mathbf{x}) \mathrm{d} \mathbf{x}+\int_{\mathbb{R}_{-}^{n}} \sup _{t>0}\left|G_{t} * \tilde{f}\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =(1)+(2) .
\end{aligned}
$$

(1). For $\mathbf{x} \in \mathbb{R}_{+}^{n}$ and $t>0$, we have that $\left(G_{t} * \tilde{f}\right)(\mathbf{x}, t)=\left(r_{\mathbb{R}_{+}^{n}}\left(G_{t} * \tilde{f}\right)\right)(\mathbf{x}, t)$. Since this is true for all $t>0$, by taking the supremum over all $t>0$, we have that

$$
\sup _{t>0}\left|G_{t} * \tilde{f}\right|(\mathbf{x})=\sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}}\left(G_{t} * \tilde{f}\right)\right|(\mathbf{x}) .
$$

Since the above equality holds for all $\mathbf{x} \in \mathbb{R}_{+}^{n}$, we can see that

$$
(1)=\|f\|_{\mathscr{H} \mathscr{e v e n}_{1}^{1}\left(\mathbb{R}_{+}^{n}\right) .} .
$$

(2). Notice that $\left(G_{t} * \tilde{f}\right)(\mathbf{x}, t)$ is even with respect to $x_{n}$ since $\tilde{f}$ is even with respect to $x_{n}$. We have that $\tilde{f}_{G_{t}}^{+}(\mathbf{x}):=\sup _{t>0}\left|G_{t} * \tilde{f}\right|(\mathbf{x})$ is even with respect to $x_{n}$. Therefore,

$$
(2)=\int_{\mathbb{R}_{+}^{n}} \tilde{f}_{G_{t}}^{+}\left(\mathbf{z}^{\prime},-z_{n}\right) \mathrm{d} \mathbf{z}^{\prime} \mathrm{d} z_{n}=\int_{\mathbb{R}_{+}^{n}} \tilde{f}_{G_{t}}^{+}\left(\mathbf{z}^{\prime}, z_{n}\right) \mathrm{d} \mathbf{z}^{\prime} \mathrm{d} z_{n}=(1)
$$

Lemma 2.4.3. Let $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and $f$ be odd with respect to $x_{n}$, i.e., $f\left(\mathbf{x}^{\prime}, x_{n}\right)=$ $-f\left(\mathbf{x}^{\prime},-x_{n}\right)$, then we have that $r_{\mathbb{R}_{+}^{n}} f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and

$$
\left\|r_{\mathbb{R}_{+}^{n}} f\right\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)} \leq\|f\|_{\mathscr{H}^{1}} .
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Proof. Let $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ such that $f$ is odd with respect to $x_{n}$, then

$$
\begin{aligned}
\left\|r_{\mathbb{R}_{+}^{n}} f\right\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)} & :=\int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}} e^{t \Delta} E_{\text {odd }} r_{\mathbb{R}_{+}^{n}} f\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =\int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}} e^{t \Delta} f\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& \leq \int_{\mathbb{R}^{n}} \sup _{t>0}\left|e^{t \Delta} f\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =\|f\|_{\mathscr{H}}\left(\mathbb{R}^{n}\right)
\end{aligned}
$$

Lemma 2.4.4. Let $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and $f$ be even with respect to $x_{n}$, i.e., $f\left(\mathbf{x}^{\prime}, x_{n}\right)=$ $f\left(\mathbf{x}^{\prime},-x_{n}\right)$, then we have that $r_{\mathbb{R}_{+}^{n}} f \in \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and

$$
\left\|r_{\mathbb{R}_{+}^{n}} f\right\|_{\mathscr{H}_{e v e n}^{1}\left(\mathbb{R}_{+}^{n}\right)} \leq\|f\|_{\mathscr{H}^{1}}
$$

Proof. Let $f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ such that $f$ is even with respect to $x_{n}$, then

$$
\begin{aligned}
\left\|r_{\mathbb{R}_{+}^{n}} f\right\|_{\mathscr{C}_{\text {even }}^{1}}\left(\mathbb{R}_{+}^{n}\right) & :=\int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}} e^{t \Delta} E_{\text {even }} r_{\mathbb{R}_{+}^{n}} f\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =\int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|r_{\mathbb{R}_{+}^{n}} e^{t \Delta} f\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& \leq \int_{\mathbb{R}^{n}} \sup _{t>0}\left|e^{t \Delta} f\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =\|\left. f\right|_{\mathscr{H}}\left(\mathbb{R}^{n}\right)
\end{aligned}
$$

Lemma 2.4.5. $\mathbb{P}_{\mathbb{R}_{+}^{n}}: \mathbf{Y} \rightarrow \mathbf{Y}$ is a bounded linear operator.
Proof. The proof is basically identical to the proof of Lemma 2.3.5.

### 2.4.2 Properties of projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$

Except some places due to the fact that we cannot take the trace properly, the theory in this subsection is completely identical to the theory in subsection 2.3.3. This is due to the fact that all properties hold not because of the space where $\mathbf{v}$ belongs to, but the properties of projection $\mathbb{P}$ itself has.

Lemma 2.4.6. Let $\mathbf{v} \in \mathbf{Y}$, then $\operatorname{div} \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{v}=0$ in $\mathbb{R}_{+}^{n}$ in the sense of distributions.
Proof. The proof is completely identical to the proof of Lemma 2.3.10.
Lemma 2.4.7. Let $\mathbf{v} \in \mathbf{Y}$ such that

$$
\begin{cases}\operatorname{div} \mathbf{v}=0 & \text { in } \mathbb{R}_{+}^{n} \\ \mathbf{v} \cdot \mathbf{n}=0 & \text { on } \partial \mathbb{R}_{+}^{n}\end{cases}
$$

Then we have that $\mathbf{v} \in \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y}$. Notice that both equalities above hold in the sense of distributions.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Proof. The proof is completely identical to the proof of Lemma 2.3.14.
Definition 2.4.8. We define the subspace $\mathbf{Y}_{\sigma}$ of $\mathbf{Y}$ by

$$
\mathbf{Y}_{\sigma}:=\left\{\mathbf{v} \in \mathbf{Y} \mid \operatorname{div} \mathbf{v}=0 \text { in } \mathbb{R}_{+}^{n} \& \mathbf{v} \cdot \mathbf{n}=0 \text { on } \partial \mathbb{R}_{+}^{n}\right\} .
$$

Lemma 2.4.9. In the case for the space $\mathbf{Y}$, we have that

$$
\mathbf{Y}_{\sigma} \subset \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y} \subset\left\{\mathbf{v} \in \mathbf{Y} \mid \operatorname{div} \mathbf{v}=0 \text { in } \mathbb{R}_{+}^{n}\right\}
$$

Proof. By Lemma 2.4.6 and Lemma 2.4.7, we are done.

### 2.4.3 Characterization of the subspace $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}$

Due to the fact that the theory in this section depends only on the properties of projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ and the trace problem which we do not know how to deal with is not involved in any sense, it is completely identical to the theory in subsection 2.3.4.

Lemma 2.4.10. Let $\mathbf{v} \in \mathbf{Y}$, then there exists $p \in L_{\text {loc }}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ such that $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{v}=\nabla p$.
Proof. The proof is completely identical to the proof of Lemma 2.3.16.
Lemma 2.4.11. Let $p \in L_{\text {loc }}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)$ such that $\nabla p \in \mathbf{Y}$, then $\nabla p \in\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}$.
Proof. The proof is completely identical to the proof of Lemma 2.3.17.
Definition 2.4.12. We define the subspace $\mathbf{Y}_{\pi}$ of $\mathbf{Y}$ by

$$
\mathbf{Y}_{\pi}:=\left\{\nabla p \in \mathbf{Y} \mid p \in L_{l o c}^{1}\left(\overline{\mathbb{R}_{+}^{n}}\right)\right\} .
$$

Lemma 2.4.13. $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}=\mathbf{Y}_{\pi}$.
Proof. By Lemma 2.4.10 and Lemma 2.4.11, we are done.

### 2.4.4 Proof of Theorem 2.1.2

Proof. By Lemma 2.4.5 we see that $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ is a bounded linear operator which maps $\mathbf{Y}$ to $\mathbf{Y}$. By this bounded linear map we can easily see that the vector field $\mathbf{Y}$ admits a natural decomposition

$$
\mathbf{Y}=\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y} \oplus\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}
$$

where both $\mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y}$ and $\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}$ are linear subspaces of $\mathbf{Y}$. Since this natural decomposition is induced by the projection $\mathbb{P}_{\mathbb{R}_{+}^{n}}$, this decomposition is certainly unique. Moreover, we have already proved that

$$
\mathbf{Y}_{\sigma} \subset \mathbb{P}_{\mathbb{R}_{+}^{n}} \mathbf{Y} \subset\left\{\mathbf{v} \in \mathbf{Y} \mid \operatorname{div} \mathbf{v}=0 \text { in } \mathbb{R}_{+}^{n}\right\}
$$

and

$$
\left(I-\mathbb{P}_{\mathbb{R}_{+}^{n}}\right) \mathbf{Y}=\mathbf{Y}_{\pi}
$$

As a result, Theorem 2.1.2 holds and we are done.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

### 2.5 Duality theorem

Before we start this section we would like to recall the definition that a function $h \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ is called a 2-atom if $\operatorname{supp} h \subset B,\|h\|_{L^{2}\left(\mathbb{R}^{n}\right)} \leq|B|^{-1 / 2}$ and $\int_{B} h \mathrm{dx}=0$. Here $B \subset \mathbb{R}^{n}$ is an open ball.

### 2.5.1 Duality theorem for the case of odd extension

Throughout this subsection, we denote the odd extension operator $E_{\text {odd }}$ by $E$.
Definition 2.5.1. We define the set of symmetric 2 -atoms by the set

$$
\begin{array}{r}
\left\{E r_{\mathbb{R}_{+}^{n}} \alpha \mid \alpha \text { is a 2-atom s.t. } \operatorname{supp} \alpha \subset B \text { and } B \cap \partial \mathbb{R}_{+}^{n} \neq \varnothing\right\} \\
\bigcup\left\{E r_{\mathbb{R}_{+}^{n}} \beta \mid \beta \text { is a 2-atom s.t. } \operatorname{supp} \beta \subset B \subset \mathbb{R}_{+}^{n}\right\} .
\end{array}
$$

Let $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right):=\left\{E \mathbf{v} \mid \mathbf{v} \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)\right\}$. Then $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right) \subset \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ is a linear subspace.

Lemma 2.5.2. The norm

$$
\inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all symmetric 2-atomic decompositions }\right\}
$$

is equivalent to the norm $\|\cdot\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)}$ on the subspace $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Proof. Let $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, then $E f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$.
(1). By the atomic decompositions of functions of the real Hardy space $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$, we see that $E f$ admits 2-atomic decompositions. Let

$$
E f=\sum_{i} \lambda_{i} \alpha_{i}+\sum_{j} \mu_{j} \beta_{j}
$$

be a 2-atomic decomposition of $E f$. Apply $r_{\mathbb{R}_{+}^{n}}$ firstly and then $E$ secondly on both sides of this 2 -atomic decomposition, we can deduce that

$$
E f=E r_{\mathbb{R}_{+}^{n}} E f=\sum_{i} \lambda_{i} E r_{\mathbb{R}_{+}^{n}} \alpha_{i}+\sum_{j} \mu_{j} E r_{\mathbb{R}_{+}^{n}} \beta_{j} .
$$

This is a symmetric 2-atomic decomposition of $E f$ with exactly the same coefficients just as the original 2 -atomic decomposition. Hence we see that every 2 -atomic decomposition of $E f$ gives rise to a symmetric 2 -atomic decomposition of $E f$ with exactly the same coefficients. Therefore,

$$
\begin{aligned}
\|E f\|_{\mathscr{H} 1}\left(\mathbb{R}^{n}\right) & =\inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all } 2 \text {-atomic decompositions }\right\} \\
& \geq \inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all symmetric 2-atomic decompositions }\right\} .
\end{aligned}
$$

(2). Let $E f=\sum_{i} \lambda_{i} E r_{\mathbb{R}_{+}^{n}} \alpha_{i}+\sum_{j} \mu_{j} E r_{\mathbb{R}_{+}^{n}} \beta_{j}$ be a symmetric 2-atomic decomposition. Pick an $i$, suppose that $\operatorname{supp} \alpha_{i} \subset B_{i}$ where $B_{i}$ is a ball in $\mathbb{R}^{n}$ such that $B_{i} \cap \partial \mathbb{R}_{+}^{n} \neq \varnothing$.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Then there exists $\mathbf{x}^{*} \in B_{i} \cap \partial \mathbb{R}_{+}^{n}$ such that $\operatorname{supp} E r_{\mathbb{R}_{+}^{n}} \alpha_{i} \subset B_{2 i}\left(\mathbf{x}^{*}\right)$. Moreover, we have that

$$
\left\|E r_{\mathbb{R}_{+}^{n}} \alpha_{i}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \leq 2 \cdot\left\|\alpha_{i}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}=2^{\frac{n}{2}+1} \cdot\left|B_{2 i}\left(\mathbf{x}^{*}\right)\right|^{-1 / 2}
$$

Since $E$ is the odd extension, we certainly have that

$$
\int_{B_{2 i}\left(\mathbf{x}^{*}\right)} E r_{\mathbb{R}_{+}^{n}} \alpha_{i} \mathrm{dx}=0 .
$$

Therefore, $\frac{1}{2^{\frac{n}{2}+1}} \cdot E r_{\mathbb{R}_{+}^{n}} \alpha_{i}$ is a 2 -atom in $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ for any $i$. In addition, since $\operatorname{supp} \beta_{j} \subset$ $B_{j} \subset \mathbb{R}_{+}^{n}$ for some ball $B_{j}$, for any $j$ we can decompose $E r_{\mathbb{R}_{+}^{n}} \beta_{j}$ into the form $\beta_{j}+\beta_{j}^{-}$where $\beta_{j}^{-}$is a 2 -atom which is contained in $\left(\mathbb{R}_{+}^{n}\right)^{c}$. Hence we can rewrite the symmetric 2-atomic decomposition in the following way:

$$
E f=\sum_{i}\left(\lambda_{i} 2^{\frac{n}{2}+1}\right) \cdot\left(\frac{1}{2^{\frac{n}{2}+1}} E r_{\mathbb{R}_{+}^{n}} \alpha_{i}\right)+\sum_{j} \mu_{j} \cdot \beta_{j}+\sum_{j} \mu_{j} \cdot \beta_{j}^{-} .
$$

Here $\left(\frac{1}{2^{\frac{n}{2}+1}} E r_{\mathbb{R}_{+}^{n}} \alpha_{i}\right), \beta_{j}$ and $\beta_{j}^{-}$are all 2 -atoms for any $i, j$. Therefore we can get a 2 -atomic decomposition of $E f$ from each symmetric 2-atomic decomposition of $E f$ with coefficients $\left\{\lambda_{i}^{\prime}\right\}_{i=1}^{\infty}$ and $\left\{\mu_{j}^{\prime}\right\}_{j=1}^{\infty}$ where $\lambda_{i}^{\prime}=\lambda_{i} \cdot 2^{\frac{n}{2}+1}$ for all $i$ and $\mu_{j}^{\prime}=2 \cdot \mu_{j}$ for all $j$. Notice that

$$
\begin{aligned}
\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| & \geq \frac{1}{2^{\frac{n}{2}+1}} \cdot\left(\sum_{i}\left(\left|\lambda_{i}\right| \cdot 2^{\frac{n}{2}+1}\right)+\sum_{j} 2 \cdot\left|\mu_{j}\right|\right) \\
& =\frac{1}{2^{\frac{n}{2}+1}} \cdot\left(\sum_{i}\left|\lambda_{i}^{\prime}\right|+\sum_{j}\left|\mu_{j}^{\prime}\right|\right) .
\end{aligned}
$$

Therefore we have that

$$
\begin{aligned}
& \inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all symmetric } 2 \text {-atomic decompositions }\right\} \\
\geq & \frac{1}{2^{\frac{n}{2}+1}} \cdot \inf \left\{\sum_{i}\left|\lambda_{i}^{\prime}\right|+\sum_{j}\left|\mu_{j}^{\prime}\right| \mid \text { all } 2 \text {-atomic decompositions }\right\} .
\end{aligned}
$$

Since the norm $\inf \left\{\sum_{i}\left|\lambda_{i}^{\prime}\right|+\sum_{j}\left|\mu_{j}^{\prime}\right| \mid\right.$ all 2-atomic decompositions $\}$ is equivalent to the norm $\|\cdot\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)}$ by the standard theory of real Hardy spaces, we can deduce that

$$
\inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all symmetric } 2 \text {-atomic decompositions }\right\} \geq C\|\cdot\|_{\mathscr{C}\left(\mathbb{R}^{n}\right)}
$$

for some constant $C$.
By making use of Lemma 2.5.2 we can deduce the half space atomic decomposition for elements of $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.

Theorem 2.5.3. Let $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, then there exists sequences of non-negative numbers $\left\{\lambda_{i}\right\}_{i=1}^{\infty} \&\left\{\mu_{j}\right\}_{j=1}^{\infty}$, a sequence of 2-atoms $\left\{\alpha_{i}\right\}_{i=1}^{\infty}$ where for each $i \operatorname{supp} \alpha_{i} \subset B_{i}$ for some
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
ball $B_{i}$ and $B_{i} \cap \partial \mathbb{R}_{+}^{n} \neq \varnothing$ and a sequence of 2-atoms $\left\{\beta_{j}\right\}_{j=1}^{\infty}$ where for each $j \operatorname{supp} \beta_{j} \subset$ $B_{j} \subset \mathbb{R}_{+}^{n}$ for some ball $B_{j}$ such that

$$
f=\left.\sum_{i} \lambda_{i} \cdot \alpha_{i}\right|_{r_{\mathbb{R}_{+}^{n}}}+\sum_{j} \mu_{j} \cdot \beta_{j} .
$$

We refer such a decomposition of $f$ as a half space atomic decomposition of $f$ and moreover, the norm

$$
\inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all half space atomic decompositions }\right\}
$$

is equivalent to the norm $\|\cdot\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)}$ on $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Proof. By Lemma 2.5.2, we have that

$$
\begin{aligned}
f \in \mathscr{H}_{o d d}^{1}\left(\mathbb{R}_{+}^{n}\right) . & \Longrightarrow E f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right) . \\
& \Longrightarrow E f \text { admits } 2 \text {-atomic decompositions. } \\
& \Longrightarrow E f \text { admits symmetric 2-atomic decompositions. } \\
& \Longrightarrow f \text { admits half space atomic decompositions by taking } \\
& \text { restrictions of symmetric 2-atomic decompositions. }
\end{aligned}
$$

By Lemma 2.4.1 and Lemma 2.4.3, there exists constants $C_{1}$ and $C_{2}$ such that

$$
C_{1} \cdot\|f\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)} \leq\|E f\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)} \leq C_{2} \cdot\|f\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)}
$$

Moreover, the norm $\|\cdot\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)}$ is equivalent to the norm

$$
\inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all symmetric 2-atomic decompositions }\right\}
$$

on $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ by Lemma 2.5.2. Since each of the half space atomic decomposition of $f$ gives rise naturally to a symmetric 2 -atomic decomposition of $E f$ with exactly the same coefficients by odd extension, we have that

$$
\inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all half space atomic decompositions }\right\} \approx\|\cdot\|_{\mathscr{\ell _ { \text { odd } } ^ { 1 }}\left(\mathbb{R}_{+}^{n}\right)}
$$

on $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Definition 2.5.4. We denote the set of all finite linear combinations of symmetric 2 -atoms by $\mathscr{H}_{0, s}^{1}\left(\mathbb{R}^{n}\right)$.

Notice that $\mathscr{H}_{0, s}^{1}\left(\mathbb{R}^{n}\right) \subset \mathscr{H}_{0}^{1}\left(\mathbb{R}^{n}\right) \cap E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ where $\mathscr{H}_{0}^{1}\left(\mathbb{R}^{n}\right)$ is the set of all finite linear combinations of 2 -atoms.

Lemma 2.5.5. $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ is a closed subspace of $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$.
Proof. Let $F \in \overline{E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)} \|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)} \backslash E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, then there exists a sequence $\left\{u_{n}\right\}_{n=1}^{\infty} \subset$ $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ such that $E u_{n} \rightarrow F$ in $\|\cdot\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)}$ as $n \rightarrow \infty$. Since $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right) \subset L^{1}\left(\mathbb{R}^{n}\right)$, we have that

$$
\left\|E u_{n}-F\right\|_{L^{1}\left(\mathbb{R}^{n}\right)} \leq\left\|E u_{n}-F\right\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)} \rightarrow 0 .
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

This means that $E u_{n}(\mathbf{x}) \rightarrow F(\mathbf{x})$ a.e.. Notice that for $\mathbf{x} \in \mathbb{R}^{n}$,

$$
F\left(\mathbf{x}^{\prime}, x_{n}\right) \leftarrow E u_{n}\left(\mathbf{x}^{\prime}, x_{n}\right)=-E u_{n}\left(\mathbf{x}^{\prime},-x_{n}\right) \rightarrow-F\left(\mathbf{x}^{\prime},-x_{n}\right) .
$$

Therefore, $F$ is odd with respect to $x_{n}$ a.e. and $F \in E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Lemma 2.5.6. $\mathscr{H}_{0, s}^{1}\left(\mathbb{R}^{n}\right)$ is dense in $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Proof. Through the proof of Lemma 2.5 .2 we know that every element of $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ admits symmetric 2 -atomic decompositions and by Lemma 2.5 .5 we see that $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ is closed in $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. We are done.

Theorem 2.5.7. Suppose $g \in B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$. Then the linear functional $l$ defined on $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ by

$$
l(f)=\int_{\mathbb{R}_{+}^{n}} f \cdot g \mathrm{~d} \mathbf{x}
$$

for $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ is a bounded linear functional which satisfies $\|l\| \leq c \cdot\|g\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}$ with some constant c. Conversely, every bounded linear functional l on $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ can be written in the form of

$$
l(f)=\int_{\mathbb{R}_{+}^{n}} f \cdot g \mathrm{dx} \text { for all } f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)
$$

with $g \in B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ and $\|g\|_{B M O_{b}^{\infty, \infty}{ }_{\left(\mathbb{R}_{+}^{n}\right)} \leq c \cdot\|l\| \text { with some constant } c \text {. Here }\|l\|}$ means the norm of $l$ as a bounded linear functional on $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.

Proof. (1). Let $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $g \in B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$. Then we have the estimates

$$
\begin{aligned}
\left|\int_{\mathbb{R}_{+}^{n}} f \cdot g \mathrm{~d} \mathbf{x}\right| & =\frac{1}{2} \cdot\left|\int_{\mathbb{R}^{n}} E f \cdot E g \mathrm{~d} \mathbf{x}\right| \\
& \leq \frac{1}{2} \cdot\|E f\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)} \cdot\|E g\|_{B M O} \\
& \leq c \cdot\|f\|_{\mathscr{O}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)} \cdot\|g\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)} .
\end{aligned}
$$

Therefore, $l: f \mapsto \int_{\mathbb{R}_{+}^{n}} f \cdot g \mathrm{~d} \mathbf{x} \in \mathscr{H}_{o d d}^{1}\left(\mathbb{R}_{+}^{n}\right)^{*}$ and the above inequalities imply that $\|l\| \leq c \cdot\|g\|_{B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}$ with some constant $c$.
(2). Let $l \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)^{*}$. We define $\tilde{l}(E f):=2 \cdot l(f)$ for all $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Fix a ball $B \subset \mathbb{R}_{+}^{n}$, let $L_{0}^{2}(B)$ be the subspace $\left\{f \in L^{2}(B) \mid \int_{B} f \mathrm{~d} \mathbf{x}=0\right\}$, notice that $L_{0}^{2}(B) \subset$ $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Let $u \in L_{0}^{2}(B)$ be a 2-atom, i.e., we require that $\operatorname{supp} u \subset B \subset \mathbb{R}_{+}^{n}$ for some ball $B, \int_{B} u \mathrm{~d} \mathbf{x}=0$ and $\|u\|_{L^{2}(B)} \leq|B|^{-1 / 2}$. We then have that

$$
\begin{aligned}
|\tilde{l}(E u)| & : \\
& =2 \cdot|l(u)| \leq c \cdot\|u\|_{\mathscr{H}_{o d}^{1}\left(\mathbb{R}_{+}^{n}\right)} \\
& \leq c \cdot\|E u\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)}=c \cdot\left\|u^{+}+u^{-}\right\| \mathscr{H}^{1}\left(\mathbb{R}^{n}\right) \\
& \leq c \cdot\left(\left\|u^{+}\right\| \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)+\left\|u^{-}\right\| \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)\right) \leq c \cdot|B|^{1 / 2} \cdot\|u\|_{L_{0}^{2}(B)} \\
& \leq c \cdot|B|^{1 / 2} \cdot\|E u\|_{E L_{0}^{2}(B)} .
\end{aligned}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Here $\|\cdot\|_{L_{0}^{2}(B)}:=\left(\int_{B}|\cdot|^{2} \mathrm{~d} \mathbf{x}\right)^{\frac{1}{2}}$ and $\|\cdot\|_{E L_{0}^{2}(B)}:=\left(\int_{B \cup B^{-}}|\cdot|^{2} \mathrm{dx}\right)^{\frac{1}{2}}$ with $B^{-}:=\left\{\left(\mathbf{x}^{\prime},-x_{n}\right) \mid\right.$ $\left.\left(\mathbf{x}^{\prime}, x_{n}\right) \in B\right\}$. For general $w \in L_{0}^{2}(B)$, we have that $w=\lambda \cdot u$ where $u \in L_{0}^{2}(B)$ is a 2 -atom, then

$$
|\tilde{l}(E w)|:=2 \cdot|l(w)|=2 \cdot|\lambda| \cdot|l(u)| \leq c \cdot|B|^{1 / 2} \cdot\|E w\|_{E L_{0}^{2}(B)} .
$$

Thus $\left.\tilde{l}\right|_{E L_{0}^{2}(B)}$ is a bounded linear functional on $E L_{0}^{2}(B)$.
Claim 1: EL $L_{0}^{2}(B)^{*}=E L_{0}^{2}(B)$.
Proof of $\operatorname{Claim} 1$ : Let $\tilde{T} \in E L_{0}^{2}(B)^{*}$, by definition we have that $|\tilde{T}(E u)| \leq c$. $\|E u\|_{E L_{0}^{2}(B)}$. Let's define $T(u)$ for each $u \in L_{0}^{2}(B)$ by $T(u)=\frac{1}{2} \cdot \tilde{T}(E u)$, thus

$$
|T(u)|=\frac{1}{2} \cdot|\tilde{T}(E u)| \leq c \cdot\|E u\|_{E L_{0}^{2}(B)} \leq c \cdot\|u\|_{L_{0}^{2}(B)}
$$

Hence $T \in L_{0}^{2}(B)^{*}$. By the Riesz representation theorem for the Hilbert space $L_{0}^{2}(B)$, we deduce that there exists $g^{B} \in L_{0}^{2}(B)$ such that

$$
T(u)=\int_{B} u \cdot g^{B} \mathrm{~d} \mathbf{x} \text { for all } u \in L_{0}^{2}(B)
$$

Notice that

$$
\tilde{T}(E u)=2 \cdot T(u)=2 \cdot \int_{B} u \cdot g^{B} \mathrm{~d} \mathbf{x}=\int_{B \cup B^{-}} E u \cdot E g^{B} \mathrm{~d} \mathbf{x}
$$

and $E g^{B} \in E L_{0}^{2}(B)$, hence $E L_{0}^{2}(B)^{*}=E L_{0}^{2}(B)$ and the proof of Claim 1 is finished.
By Claim 1, $\left.\tilde{l}\right|_{E L_{0}^{2}(B)} \in E L_{0}^{2}(B)^{*}=E L_{0}^{2}(B)$ implies that there exists $g^{B} \in L_{0}^{2}(B)$ such that $\left.\tilde{l}\right|_{E L_{0}^{2}(B)}=E g^{B}$ as a bounded linear functional on $E L_{0}^{2}(B)$, i.e.,

$$
\tilde{l}(E u)=\int_{B \cup B^{-}} E u \cdot E g^{B} \mathrm{~d} \mathbf{x} \text { for all } E u \in E L_{0}^{2}(B) .
$$

Since $B$ is any ball in $\mathbb{R}_{+}^{n}$, we can find $E g^{B}$ for any $B \subset \mathbb{R}_{+}^{n}$. If $B_{1} \subset B_{2} \subset \mathbb{R}_{+}^{n}$, then we can easily see that $E g^{B_{2}}-E g^{B_{1}}$ is a constant on $B_{1} \cup B_{1}^{-}$.

Consider the ball $B_{r}(\mathbf{x})$ where $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$ and $r>0$. Let $B_{r}^{+}(\mathbf{x}):=B_{r}(\mathbf{x}) \cap \mathbb{R}_{+}^{n}$. For simplicity, we denote $B_{r}(\mathbf{x})$ by $B_{r}$. Let $u \in B_{r}^{+}$, notice that $E u \in L^{2}\left(B_{r}\right)$ and $\int_{B_{r}} E u \mathrm{dx}=0$ as $E$ is the odd extension. Since $E u \in E L_{0}^{2}\left(B_{r}\right)$ and $E u$ is odd with respect to $x_{n}$, we have that $L^{2}\left(B_{r}^{+}\right) \subset \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. By similar arguments as above, we see that $\left.\tilde{l}\right|_{E L^{2}\left(B_{r}^{+}\right)}$is a bounded linear functional on $E L^{2}\left(B_{r}^{+}\right)$. By the same proof of Claim 1, we have that $E L^{2}\left(B_{r}^{+}\right)^{*}=E L^{2}\left(B_{r}^{+}\right)$. Hence $\left.\tilde{l}\right|_{E L^{2}\left(B_{r}^{+}\right)} \in E L^{2}\left(B_{r}^{+}\right)^{*}=E L^{2}\left(B_{r}^{+}\right)$implies that $\left.\tilde{l}\right|_{E L^{2}\left(B_{r}^{+}\right)}=$ $E g^{B_{r}^{+}} \in E L^{2}\left(B_{r}^{+}\right)$as a bounded linear functional on $E L^{2}\left(B_{r}^{+}\right)$for some $g^{B_{r}^{+}} \in L^{2}\left(B_{r}^{+}\right)$. For any ball $B_{r}(\mathbf{x})$ where $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$, we can find $E g^{B_{r}^{+}}$. If $B_{r_{1}} \subset B_{r_{2}}$, then $E g^{B_{r_{2}}^{+}}-E g^{B_{r_{1}}^{+}}$ is a constant on $B_{r_{1}}$.

Now we seek to find a uniform $E g(\mathbf{x})$ defined on $\mathbb{R}^{n}$. We define that

$$
E g(\mathbf{x}):=E g^{B_{r}^{+}(0)}-\frac{1}{\left|B_{1}(0)\right|} \cdot \int_{B_{1}(0)} E g^{B_{r}^{+}(0)} \mathrm{d} \mathbf{x}=E g^{B_{r}^{+}(0)}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

The last equality holds as $\underset{B_{1}(0)}{A v g} E g^{B_{r}^{+}(0)}=0$. For $B \subset \mathbb{R}_{+}^{n}$, we have $E g^{B}(\mathbf{x})$ defined on $B$, then there exists $B_{R}(0)$ for some $R$ large enough such that $B \subset B_{R}^{+}(0)$. Hence

$$
\begin{aligned}
E g^{B}(\mathbf{x}) & =E g^{B}(\mathbf{x})-E g^{B_{R}^{+}(0)}(\mathbf{x})+E g^{B_{R}^{+}(0)}(\mathbf{x}) \\
& =c_{B}+E g(\mathbf{x})
\end{aligned}
$$

where $c_{B}:=E g^{B}(\mathbf{x})-E g^{B_{R}^{+}(0)}(\mathbf{x})$ is a constant which depends on $B$.
Next we prove that the function $g(\mathbf{x})$ defined by $g(\mathbf{x}):=r_{\mathbb{R}_{+}^{n}} E g(\mathbf{x})$ belongs to the space $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$.
$1^{*}$. If $B \subset \mathbb{R}_{+}^{n}$, we have that

$$
\begin{aligned}
\frac{1}{|B|} \int_{B}\left|E g(\mathbf{x})-\left(-c_{B}\right)\right| \mathrm{d} \mathbf{x} & =\frac{1}{|B|} \int_{B}\left|E g^{B}(\mathbf{x})\right| \mathrm{d} \mathbf{x} \\
& \leq \frac{1}{|B|}\left(\int_{B}\left|E g^{B}\right|^{2} \mathrm{~d} \mathbf{x}\right)^{\frac{1}{2}} \cdot|B|^{\frac{1}{2}} \\
& =|B|^{-\frac{1}{2}} \cdot\left\|E g^{B}\right\|_{E L_{0}^{2}(B)}
\end{aligned}
$$

where the second inequality above is by the Hölder inequality. Since

$$
\left|\int_{B \cup B^{-}} E g^{B} \cdot E u \mathrm{dx}\right|=|\tilde{l}(E u)| \leq c \cdot|B|^{\frac{1}{2}} \cdot\|E u\|_{E L_{0}^{2}(B)}
$$

we can deduce that

$$
\left\|E g^{B}\right\|_{E L_{0}^{2}(B)}=\|\tilde{l}\| \leq c \cdot|B|^{\frac{1}{2}}
$$

where $\|\tilde{l}\|$ is the operator norm of $\tilde{l}$. Therefore we have that

$$
\frac{1}{|B|} \int_{B}\left|E g(\mathbf{x})-\left(-c_{B}\right)\right| \mathrm{d} \mathbf{x} \leq|B|^{-\frac{1}{2}} \cdot c \cdot|B|^{\frac{1}{2}}=c .
$$

By taking the supremum over all balls in $\mathbb{R}_{+}^{n}$, we can deduce that

$$
\sup _{B \subset \mathbb{R}_{+}^{n}} \frac{1}{|B|} \int_{B}\left|E g(\mathbf{x})-\left(-c_{B}\right)\right| \mathrm{d} \mathbf{x} \leq c .
$$

Then by the triangle inequality, we can easily get that

$$
[g]_{B M O \infty\left(\mathbb{R}_{+}^{n}\right)} \leq 2 \cdot \sup _{B \subset \mathbb{R}_{+}^{n}} \frac{1}{|B|} \int_{B}\left|g(\mathbf{x})-\left(-c_{B}\right)\right| \mathrm{d} \mathbf{x} \leq 2 \cdot c .
$$

$2^{*}$. For balls of the form $B_{r}(\mathbf{x})$ where $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$, we have that

$$
E g(\mathbf{x})=E g^{B_{r}^{+}(\mathbf{x})}-c_{B_{r}} .
$$

Now we integrate this equality over the ball $B_{r}(\mathbf{x})$, we have that

$$
\int_{B_{r}(\mathbf{x})} E g(\mathbf{y}) \mathrm{d} \mathbf{y}=\int_{B_{r}(\mathbf{x})} E g^{B_{r}^{+}(\mathbf{x})} \mathrm{d} \mathbf{y}-\int_{B_{r}(\mathbf{x})} c_{B_{r}} \mathrm{~d} \mathbf{y}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Notice that $E g$ and $E g^{B_{r}^{+}(\mathbf{x})}$ are both odd with respect to $x_{n}$, we certainly have

$$
\int_{B_{r}(\mathbf{x})} E g(\mathbf{y}) \mathrm{d} \mathbf{y}=\int_{B_{r}(\mathbf{x})} E g^{B_{r}^{+}(\mathbf{x})} \mathrm{d} \mathbf{y}=0 .
$$

Hence $c_{B_{r}}$ must equal 0. By making use of this fact and similar arguments as the previous part, we also have that

$$
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}\left|E g(\mathbf{y})-\left(-c_{B_{r}}\right)\right| \mathrm{d} \mathbf{y} \leq c .
$$

Therefore,

$$
\frac{1}{\left|B_{r}(\mathbf{x})\right|} \int_{B_{r}(\mathbf{x})}|E g| \mathrm{d} \mathbf{y}=\frac{1}{\left|B_{r}^{+}(\mathbf{x})\right|} \int_{B_{r}^{+}(\mathbf{x})}|E g| \mathrm{d} \mathbf{y} \leq c .
$$

As $E g(\mathbf{y})=g(\mathbf{y})$ in $B_{r}^{+}(\mathbf{x})$, we have that

$$
\frac{1}{\left|B_{r}^{+}(\mathbf{x})\right|} \int_{B_{r}^{+}(\mathbf{x})}|g(\mathbf{y})| \mathrm{d} \mathbf{y} \leq c .
$$

By taking the supremum over all balls centered at $\partial \mathbb{R}_{+}^{n}$, we can easily deduce that

$$
\|g\|_{b^{\infty}\left(\mathbb{R}_{+}^{n}\right)}=\sup _{\substack{r>0 \\ \mathbf{x} \in \partial \mathbb{R}_{+}^{n}}} \frac{1}{\left|B_{r}^{+}(\mathbf{x})\right|} \int_{B_{r}^{+}(\mathbf{x})}|g(\mathbf{y})| \mathrm{d} \mathbf{y} \leq c<\infty
$$

Hence by $1^{*}$ and $2^{*}, g \in B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$.
Let $E u$ be a (2, s)-atom, we have that

$$
\int_{\mathbb{R}_{+}^{n}} g \cdot u \mathrm{~d} \mathbf{x}=\frac{1}{2} \cdot \int_{\mathbb{R}^{n}} E g \cdot E u \mathrm{~d} \mathbf{x}=\frac{1}{2} \cdot \tilde{l}(E u)=l(u) .
$$

Since this representation has been established for the subspace $\mathscr{H}_{0, s}^{1}\left(\mathbb{R}^{n}\right)$ and $\mathscr{H}_{0, s}^{1}\left(\mathbb{R}^{n}\right)$ is dense in $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, therefore $E g=\tilde{l} \in E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)^{*}$ and thus $g=l \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)^{*}$.

Notice that in the proof of Theorem 2.5.7, there is a step where we proved that for $B \subset \mathbb{R}_{+}^{n}$ and $u \in L_{0}^{2}(B)$ we have that

$$
|\tilde{l}(E u)| \leq c \cdot|B|^{\frac{1}{2}} \cdot\|E u\|_{E L_{0}^{2}(B)} .
$$

For the ball $B_{r}(\mathbf{x})$ with $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$ we also have the same estimates. By L.Grafakos [6], the constant $c$ depends only on the dimension $n$ and it is independent of the ball $B$ or $B_{r}(\mathbf{x})$, hence the later arguments in the proof are valid.

### 2.5.2 Duality theorem for the case of even extension

Throughout this subsection, we denote the even extension operator $E_{\text {even }}$ by $E$.
Definition 2.5.8. We define the set of symmetric 2 -atoms by
$\left\{E r_{\mathbb{R}_{+}^{n}} \alpha \mid \alpha\right.$ is a 2-atom such that $\operatorname{supp} \alpha \subset B \& B \cap \partial \mathbb{R}_{+}^{n} \neq \varnothing$
$\left.\& \int_{\mathbb{R}_{+}^{n}} \alpha \mathrm{~d} \mathbf{x}=\int_{\mathbb{R}_{-}^{n}} \alpha \mathrm{~d} \mathbf{x}=0\right\}$
$\cup\left\{E r_{\mathbb{R}_{+}^{n}} \beta \mid \beta\right.$ is a 2 -atom such that $\left.\operatorname{supp} \beta \subset B \subset \mathbb{R}_{+}^{n}\right\}$.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Let $E \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right):=\left\{E \mathbf{v} \mid \mathbf{v} \in \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)\right\}$. Then $E \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right) \subset \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ is a linear subspace.

Lemma 2.5.9. The norm

$$
\inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all symmetric 2-atomic decompositions }\right\}
$$

is equivalent to the norm $\|\cdot\|_{\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)}$ on the subspace $E \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Proof. Let $f \in \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, then $E f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$.
(1). By the atomic decompositions of functions of the real Hardy space $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$, we see that $E f$ admits 2-atomic decompositions. Let

$$
E f=\sum_{i} \lambda_{i} \alpha_{i}+\sum_{j} \mu_{j} \beta_{j}
$$

be a 2 -atomic decomposition of $E f$. Notice that

$$
f=r_{\mathbb{R}_{+}^{n}} E f=\sum_{i} \lambda_{i} r_{\mathbb{R}_{+}^{n}} \alpha_{i}+\sum_{j} \mu_{j} r_{\mathbb{R}_{+}^{n}} \beta_{j} .
$$

Without loss of generality, assume that $\operatorname{supp} \alpha_{i} \subset B_{i}$ for some ball $B_{i}$ and $B_{i} \cap \partial \mathbb{R}_{+}^{n} \neq \varnothing$, assume further that $\operatorname{supp} \beta_{j} \subset B_{j} \subset \mathbb{R}_{+}^{n}$ or $\mathbb{R}_{-}^{n}$. Therefore we have that

$$
f=\sum_{i} \lambda_{i} r_{\mathbb{R}_{+}^{n}} \alpha_{i}+\sum_{j} \mu_{j} \beta_{j} .
$$

Let $B_{i}^{+}:=B_{i} \cap \mathbb{R}_{+}^{n}$ and $B_{i}^{-}:=B_{i} \cap \mathbb{R}_{-}^{n}$. Since $\alpha_{i}$ can be any 2 -atom, we know that $\int_{B_{i}} \alpha_{i} \mathrm{~d} \mathbf{x}=0$ but $\int_{B_{i}^{+}} \alpha_{i} \mathrm{~d} \mathbf{x}$ and $\int_{B_{i}^{-}} \alpha_{i} \mathrm{~d} \mathbf{x}$ are not necessarily zero. Here we need to do some tricks to $\int_{B_{i}^{+}} \alpha_{i} \mathrm{~d} \mathbf{x}$ and $\int_{B_{i}^{-}} \alpha_{i} \mathrm{~d} \mathbf{x}$. Since $E$ is the even extension, except

$$
E f=E r_{\mathbb{R}_{+}^{n}} E f=\sum_{i} \lambda_{i} E r_{\mathbb{R}_{+}^{n}} \alpha_{i}+\sum_{j} \mu_{j} E r_{\mathbb{R}_{+}^{n}} \beta_{j}
$$

we also have that

$$
E f=E r_{\mathbb{R}_{-}^{n}} E f=\sum_{i} \lambda_{i} E r_{\mathbb{R}_{-}^{n}} \alpha_{i}+\sum_{j} \mu_{j} E r_{\mathbb{R}_{-}^{n}} \beta_{j} .
$$

Therefore,

$$
\begin{aligned}
2 E f & =E r_{\mathbb{R}_{+}^{n}} E f+E r_{\mathbb{R}_{-}^{n}} E f \\
& =\sum_{i} \lambda_{i} \cdot\left(E r_{\mathbb{R}_{+}^{n}} \alpha_{i}+E r_{\mathbb{R}_{-}^{n}} \alpha_{i}\right)+\sum_{j} \mu_{j} \cdot\left(E r_{\mathbb{R}_{+}^{n}} \beta_{j}+E r_{\mathbb{R}_{-}^{n}} \beta_{j}\right) .
\end{aligned}
$$

Suppose that $\operatorname{supp} \alpha_{i} \subset B_{i}(\mathbf{x})$ and $B_{i}(\mathbf{x}) \cap \partial \mathbb{R}_{+}^{n} \neq \varnothing$, there exists $\mathbf{x}^{*} \in B_{i}(\mathbf{x}) \cap \partial \mathbb{R}_{+}^{n}$ such that supp $E r_{\mathbb{R}_{+}^{n}} \alpha_{i} \subset B_{2 r_{i}}\left(\mathbf{x}^{*}\right)$ and $\operatorname{supp} E r_{\mathbb{R}_{-}^{n}} \alpha_{i} \subset B_{2 r_{i}}\left(\mathbf{x}^{*}\right)$. Therefore we have that $\operatorname{supp}\left(E r_{\mathbb{R}_{+}^{n}} \alpha_{i}+E r_{\mathbb{R}_{-}^{n}} \alpha_{i}\right) \subset B_{2 r_{i}}\left(\mathbf{x}^{*}\right)$. Notice that $E r_{\mathbb{R}_{+}^{n}} \alpha_{i}+E r_{\mathbb{R}_{-}^{n}} \alpha_{i}$ is also even with respect
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
to $x_{n}$. Let's consider $r_{\mathbb{R}_{+}^{n}}\left(E r_{\mathbb{R}_{+}^{n}} \alpha_{i}+E r_{\mathbb{R}_{-}^{n}} \alpha_{i}\right)=r_{\mathbb{R}_{+}^{n}} \alpha_{i}+r_{\mathbb{R}_{+}^{n}} E r_{\mathbb{R}_{-}^{n}} \alpha_{i}$. There is no doubt that $\operatorname{supp}\left(r_{\mathbb{R}_{+}^{n}} \alpha_{i}+r_{\mathbb{R}_{+}^{n}} E r_{\mathbb{R}_{-}^{n}} \alpha_{i}\right) \subset B_{2 r_{i}}\left(\mathbf{x}^{*}\right) \cap \mathbb{R}_{+}^{n}$ and

$$
\begin{aligned}
\int_{\mathbb{R}_{+}^{n}} r_{\mathbb{R}_{+}^{n}} \alpha_{i}+r_{\mathbb{R}_{+}^{n}} E r_{\mathbb{R}_{-}^{n}} \alpha_{i} \mathrm{~d} \mathbf{x} & =\int_{\mathbb{R}_{+}^{n}} r_{\mathbb{R}_{+}^{n}} \alpha_{i} \mathrm{~d} \mathbf{x}+\int_{\mathbb{R}_{-}^{n}} E r_{\mathbb{R}_{-}^{n}} \alpha_{i} \mathrm{~d} \mathbf{x} \\
& =\int_{\mathbb{R}^{n}} \alpha_{i} \mathrm{~d} \mathbf{x} \\
& =0
\end{aligned}
$$

Let $\alpha_{i}^{*}:=r_{\mathbb{R}_{+}^{n}} \alpha_{i}+r_{\mathbb{R}_{+}^{n}} E r_{\mathbb{R}_{-}^{n}} \alpha_{i}$, notice that

$$
\begin{aligned}
\left\|\alpha_{i}^{*}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} & =\left\|r_{\mathbb{R}_{+}^{n}} \alpha_{i}+r_{\mathbb{R}_{+}^{n}} E r_{\mathbb{R}_{-}^{n}} \alpha_{i}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \\
& \leq\left\|\alpha_{i}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|E r_{\mathbb{R}_{-}^{n}} \alpha_{i}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \\
& \leq\left\|\alpha_{i}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+2 \cdot\left\|\alpha_{i}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \\
& \leq 3 \cdot 2^{\frac{n}{2}} \cdot\left|B_{2 r_{i}}\left(\mathrm{x}^{*}\right)\right|^{-1 / 2} .
\end{aligned}
$$

Let $c_{3,2}:=3 \cdot 2^{\frac{n}{2}}$. Therefore $c_{3,2}^{-1} \cdot \alpha_{i}^{*}$ is a 2 -atom and more importantly, we have that

$$
\int_{\mathbb{R}_{-}^{n}} c_{3,2}^{-1} \cdot \alpha_{i}^{*} \mathrm{~d} \mathbf{x}=\int_{\mathbb{R}_{+}^{n}} c_{3,2}^{-1} \cdot \alpha_{i}^{*} \mathrm{~d} \mathbf{x}=0 .
$$

Hence $E\left(c_{3,2}^{-1} \cdot \alpha_{i}^{*}\right)=c_{3,2}^{-1} \cdot E \alpha_{i}^{*}$ is a symmetric 2 -atom. We have that

$$
2 \cdot E f=\sum_{i} \lambda_{i}^{\prime} \cdot\left(c_{3,2}^{-1} \cdot E \alpha_{i}^{*}\right)+\sum_{j} \mu_{j} \cdot E r_{\mathbb{R}_{+}^{n}} \beta_{j}+\sum_{j} \mu_{j} \cdot E r_{\mathbb{R}_{-}^{n}} \beta_{j}
$$

where $\lambda_{i}^{\prime}:=\lambda_{i} \cdot c_{3,2}$. Therefore from a 2-atomic decomposition of $E f$ we can get a symmetric 2 -atomic decomposition of $E f$. In addition, for a 2 -atomic decomposition $E f=\sum_{i} \lambda_{i} \alpha_{i}+\sum_{j} \mu_{j} \beta_{j}$ such that $\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right|<\infty$, the corresponding symmetric 2-atomic decomposition of this 2-atomic decomposition is $E f=\sum_{i} \frac{\lambda_{i}^{\prime}}{2} \cdot\left(c_{3,2}^{-1} \cdot E \alpha_{i}^{*}\right)+$ $\sum_{j} \frac{\mu_{j}}{2} \cdot E r_{\mathbb{R}_{+}^{n}} \beta_{j}+\sum_{j} \frac{\mu_{j}}{2} \cdot E r_{\mathbb{R}_{-}^{n}} \beta_{j}$. In this case we have that

$$
\sum_{i} \frac{\left|\lambda_{i}^{\prime}\right|}{2}+\sum_{j} \frac{\left|\mu_{j}\right|}{2}+\sum_{j} \frac{\left|\mu_{j}\right|}{2} \leq 3 \cdot 2^{\frac{n}{2}-1} \cdot\left(\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right|\right)<\infty .
$$

Therefore,

$$
\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \geq \frac{1}{3 \cdot 2^{\frac{n}{2}-1}} \cdot\left(\sum_{i}\left|\lambda_{i}^{\prime \prime}\right|+\sum_{j}\left|\mu_{j}^{\prime \prime}\right|\right)
$$

where $\lambda_{i}^{\prime \prime}:=\frac{\lambda_{i}^{\prime}}{2}$ for all $i$ and $\mu_{j}^{\prime \prime}:=\frac{\mu_{j}}{2}$ for all $j$. $\lambda_{i}^{\prime \prime}$ and $\mu_{j}^{\prime \prime}$ are the coefficients of the corresponding symmetric 2 -atomic decomposition induced by the original 2 -atomic decomposition. As a result, we have that

$$
\begin{aligned}
& \inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all 2-atomic decompositions }\right\} \\
\geq & C_{1} \cdot \inf \left\{\sum_{i}\left|\lambda_{i}^{\prime \prime}\right|+\sum_{j}\left|\mu_{j}^{\prime \prime}\right| \mid \text { all symmetric 2-atomic decompositions }\right\}
\end{aligned}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
where $C_{1}:=\frac{1}{3 \cdot 2 \frac{n}{2}-1}$.
(2). Let $E f=\sum_{i} \lambda_{i} \cdot E r_{\mathbb{R}_{+}^{n}} \alpha_{i}+\sum_{j} \mu_{j} \cdot E r_{\mathbb{R}_{+}^{n}} \beta_{j}$ be a symmetric 2-atomic decomposition. Since $\alpha_{i}$ is a 2 -atom, we have that

$$
\left\|E r_{\mathbb{R}_{+}^{n}} \alpha_{i}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \leq 2^{\frac{n}{2}+1} \cdot\left|B_{2 r_{i}}\left(\mathrm{x}^{*}\right)\right|^{-1 / 2} .
$$

Therefore

$$
E f=\sum_{i}\left(\lambda_{i} \cdot 2^{\frac{n}{2}+1}\right) \cdot\left(\frac{1}{2^{\frac{n}{2}+1}} \cdot E r_{\mathbb{R}_{+}^{n}} \alpha_{i}\right)+\sum_{j} \mu_{j} \beta_{j}^{+}+\sum_{j} \mu_{j} \beta_{j}^{-}
$$

is a 2-atomic decomposition of $E f$. Thus every symmetric 2-atomic decomposition of $E f$ gives rise to a 2 -atomic decomposition. For this symmetric 2-atomic decomposition of $E f$ where $\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right|<\infty$, the coefficients of the corresponding 2-atomic decomposition of $E f$ satisfies

$$
\sum_{i}\left(\left|\lambda_{i}\right| \cdot 2^{\frac{n}{2}+1}\right)+\sum_{j} 2 \cdot\left|\mu_{j}\right| \leq 2^{\frac{n}{2}+1} \cdot\left(\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right|\right) .
$$

Therefore,

$$
\begin{aligned}
& \inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all symmetric 2-atomic decompositions }\right\} \\
\geq & C_{2} \cdot \inf \left\{\sum_{i}\left|\lambda_{i}^{\prime}\right|+\sum_{j}\left|\mu_{j}^{\prime}\right| \mid \text { all 2-atomic decompositions }\right\}
\end{aligned}
$$

where $C_{2}:=\frac{1}{2^{\frac{n}{2}+1}}$.
Theorem 2.5.10. Let $f \in \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, then there exists sequences of non-negative numbers $\left\{\lambda_{i}\right\}_{i=1}^{\infty}$ and $\left\{\mu_{j}\right\}_{j=1}^{\infty}$, a sequence of 2-atoms $\left\{\alpha_{i}\right\}_{i=1}^{\infty}$ where for each $i \operatorname{supp} \alpha_{i} \subset B_{i} छ B_{i} \cap$ $\partial \mathbb{R}_{+}^{n} \neq \varnothing \varepsilon \int_{\mathbb{R}_{+}^{n}} \alpha_{i} \mathrm{~d} \mathbf{x}=0$ for some ball $B_{i}$ and a sequence of 2 -atoms $\left\{\beta_{j}\right\}_{j=1}^{\infty}$ where for each $j \operatorname{supp} \beta_{j} \subset B_{j} \subset \mathbb{R}_{+}^{n}$ for some ball $B_{j}$ such that

$$
f=\left.\sum_{i} \lambda_{i} \cdot \alpha_{i}\right|_{\mathbb{R}_{+}^{n}}+\sum_{j} \mu_{j} \cdot \beta_{j} .
$$

We refer such a decomposition of $f$ as a half space atomic decomposition of $f$ and moreover, the norm

$$
\inf \left\{\sum_{i}\left|\lambda_{i}\right|+\sum_{j}\left|\mu_{j}\right| \mid \text { all half space atomic decompositions }\right\}
$$

is equivalent to the norm $\|\cdot\|_{\mathscr{H}_{e v e n}^{1}\left(\mathbb{R}_{+}^{n}\right)}$ on $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Proof. By Lemma 2.5.9 we are done.
Definition 2.5.11. We denote the set of all finite linear combinations of symmetric 2-atoms by $\mathscr{H}_{0, s}^{1}\left(\mathbb{R}^{n}\right)$.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

By similar arguments as in the previous subsection, we can easily deduce that $\mathscr{H}_{0, s}^{1}\left(\mathbb{R}^{n}\right) \subset$ $\mathscr{H}_{0}^{1}\left(\mathbb{R}^{n}\right) \cap E \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right), E \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ is a closed subspace of $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and $\mathscr{H}_{0, s}^{1}\left(\mathbb{R}^{n}\right)$ is dense in $E \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Then by making use of these facts, we can prove our duality theorem for the case of even extension.

Theorem 2.5.12. Suppose $g \in B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$. Then the linear functional l defined on $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ by

$$
l(f)=\int_{\mathbb{R}_{+}^{n}} f \cdot g \mathrm{~d} \mathbf{x}
$$

for $f \in \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ is a bounded linear functional which satisfies $\|l\| \leq c \cdot[g]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)}$ with some constant $c$. Conversely, every bounded linear functional $l$ on $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ can be written in the form of

$$
l(f)=\int_{\mathbb{R}_{+}^{n}} f \cdot g \mathrm{dx} \text { for all } f \in \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)
$$

with $g \in B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ and $[g]_{B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)} \leq c \cdot\|l\|$ with some constant $c$. Here $\|l\|$ means the norm of $l$ as a bounded linear functional on $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.

Proof. The only difference from the proof of Theorem 2.5.7 is the last part where here we prove that the unified function $g(\mathbf{x}) \in B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ instead of $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$. For the rest of the details, please refer to the proof of Theorem 2.5.7.

We define the unified function $E g(\mathbf{x})$ on $\mathbb{R}^{n}$ by

$$
\begin{aligned}
E g(\mathbf{x}) & :=E g^{B_{r}^{+}(0)}-\frac{1}{\left|B_{1}(0)\right|} \int_{B_{1}(0)} E g^{B_{r}^{+}(0)} \mathrm{d} \mathbf{x} \\
& =E g^{B_{r}^{+}(0)}-\underset{B_{1}(0)}{A v g E g^{B_{r}^{+}(0)}} .
\end{aligned}
$$

For $B \subset \mathbb{R}_{+}^{n}$ we have $E g^{B}(\mathbf{x})$ defined on the ball $B$, then there exists $B_{r}(0)$ for some $r$ large enough such that $B \subset B_{r}(0)$. We can rewrite $E g^{B}(\mathbf{x})$ as

$$
E g^{B}(\mathbf{x})=E g^{B}(\mathbf{x})-E g^{B_{r}^{+}(0)}(\mathbf{x})+E g^{B_{r}^{+}(0)}(\mathbf{x})-\underset{B_{1}(0)}{A v g E g^{B_{r}^{+}(0)}}+\underset{B_{1}(0)}{A v g} E g^{B_{r}^{+}(0)} .
$$

Notice that $E g^{B}(\mathbf{x})-E g^{B_{r}^{+}(0)}(\mathbf{x})$ and $\operatorname{Avg} E g^{B_{r}^{+}(0)}$ are both constants which depend on $B$, hence let $c_{B}:=E g^{B}(\mathbf{x})-E g^{B_{r}^{+}(0)}(\mathbf{x})+\underset{B_{1}(0)}{\operatorname{Avg} E g^{B_{r}^{+}(0)}}$, we have that $E g^{B}(\mathbf{x})=c_{B}+E g(\mathbf{x})$.
Next we prove that the function $g(\mathbf{x})$ defined by $g(\mathbf{x}):=r_{\mathbb{R}_{+}^{n}} E g(\mathbf{x}) \in B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$.
$* 1$. If $B \subset \mathbb{R}_{+}^{n}$, we have that

$$
\frac{1}{|B|} \int_{B}\left|E g(\mathrm{x})-\left(-c_{B}\right)\right| \mathrm{d} \mathrm{x} \leq c \cdot|B|^{-1 / 2} \cdot\left\|E g^{B}\right\|_{E L_{0}^{2}(B)}
$$

by the Hölder inequality. Since

$$
\left.\left|\int_{B \cup B^{-}} E g^{B} \cdot E u \mathrm{~d} \mathbf{x}=|\tilde{l}(E u)| \leq c \cdot\right| B\right|^{-1 / 2} \cdot\|E u\|_{E L_{0}^{2}(B)},
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space
we have that

$$
\left\|E g^{B}\right\|_{E L_{0}^{2}(B)}=\|\tilde{\eta}\| \leq c \cdot|B|^{1 / 2} .
$$

Therefore we can deduce that

$$
\frac{1}{|B|} \int_{B}\left|E g(\mathbf{x})-\left(-c_{B}\right)\right| \mathrm{d} \mathbf{x} \leq c .
$$

Notice that the $c$ here is just a number which is independent of $B$. Therefore by taking the supremum over all balls contained in $\mathbb{R}_{+}^{n}$, we can see that

$$
\sup _{B \subset \mathbb{R}_{+}^{n}} \frac{1}{|B|} \int_{B}\left|E g(\mathbf{x})-\left(-c_{B}\right)\right| \mathrm{d} \mathbf{x} \leq c
$$

and thus,

$$
\left[r_{\mathbb{R}_{+}^{n}} E g\right]_{B M O \infty\left(\mathbb{R}_{+}^{n}\right)}=[g]_{B M O \infty\left(\mathbb{R}_{+}^{n}\right)} \leq 2 \cdot c .
$$

$* 2$. If $B_{r}(\mathbf{x})$ is a ball where $\mathbf{x} \in \partial \mathbb{R}_{+}^{n}$ and $r>0$, we have that $E g(\mathbf{x})=E g^{B_{r}^{+}}(\mathbf{x})-c_{B_{r}}$. Therefore we have the following calculations:

$$
\begin{aligned}
2 \cdot \int_{B_{r}^{+}} g(\mathbf{x}) \mathrm{d} \mathbf{x} & =\int_{B_{r}} E g(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =\int_{B_{r}} E g^{B_{r}^{+}}(\mathbf{x}) \mathrm{d} \mathbf{x}-\int_{B_{r}} c_{B_{r}} \mathrm{~d} \mathbf{x} \\
& =0-c_{B_{r}} \cdot\left|B_{r}\right| .
\end{aligned}
$$

Hence $c_{B_{r}}=-g_{B_{r}^{+}}$and we have that

$$
\begin{aligned}
\frac{1}{\left|B_{r}\right|} \int_{B_{r}}\left|E g(\mathbf{x})-\left(-c_{B_{r}}\right)\right| \mathrm{d} \mathbf{x} & =\frac{1}{\left|B_{r}\right|} \int_{B_{r}}\left|E g(\mathbf{x})-g_{B_{r}^{+}}\right| \mathrm{d} \mathbf{x} \\
& =\frac{1}{\left|B_{r}^{+}\right|} \int_{B_{r}^{+}}\left|g(\mathbf{x})-g_{B_{r}^{+}}\right| \mathrm{d} \mathbf{x} \leq c .
\end{aligned}
$$

Take the supremum over all balls centered on $\mathbb{R}_{+}^{n}$, we have that

$$
[g]_{b a^{\infty}\left(\mathbb{R}_{+}^{n}\right)}=\sup _{\substack{r>0 \\ \mathbf{x} \in \partial \mathbb{R}_{+}^{n}}} \frac{1}{\left|B_{r}^{+}\right|} \int_{B_{r}^{+}}\left|g(\mathbf{x})-g_{B_{r}^{+}}\right| \mathrm{d} \mathbf{x} \leq c
$$

and hence $g \in B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$.

### 2.5.3 Proof of Theorem 2.1.3

Proof. By Theorem 2.5.7 and Theorem 2.5.12, we are done.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

### 2.5.4 Comments

Remark 2.5.13. If we look at the proof of Lemma 2.4.1 and Lemma 2.4.2, we can see that it is completely all right for us to replace the heat kernel $e^{t \Delta}$ in the definition of $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ by any radial symmetric function $\varphi \in \mathscr{S}\left(\mathbb{R}^{n}\right)$ such that $\int_{\mathbb{R}^{n}} \varphi \mathrm{dx}=1$. Therefore, the definitions of the norms $\|\cdot\|_{\mathscr{H}_{e v e n}^{1}\left(\mathbb{R}_{+}^{n}\right)}$ and $\|\cdot\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)}$ are independent of the choice of $\varphi$ if $\varphi$ is radial symmetric with integral over $\mathbb{R}^{n}$ equals 1 .

Remark 2.5.14. When we established the half space atomic decompositions for $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, we made use of the 2 -atomic decomposition of $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ in order to carry out the arguments of Fefferman and Stein [3] to prove the duality theorem. However, if we carry out the arguments using the p-atomic decomposition of $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ instead where $p \geq 1$, then we get the half space atomic decompositions for $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ in the form of symmetric p-atomic decompositions.

In [1], it is proved that $B M O_{M}\left(\mathbb{R}_{+}^{n}\right)$ and $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ are actually the same space. Since $B M O_{M}\left(\mathbb{R}_{+}^{n}\right)$ is the dual space of $\mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ is the dual space of $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, it is natural to ask the question about the relation between $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $\mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Here we give an answer to this question.

Lemma 2.5.15. $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)=\mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Proof. (1). By the theory of Miyachi [7], $f \in \mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$ implies that $f$ admits the half space atomic decomposition of the form

$$
f=\sum_{i} \lambda_{i} \alpha_{i}+\sum_{j} \mu_{j} \beta_{j}
$$

where $\left\{\beta_{j}\right\}_{j=1}^{\infty}$ is a sequence of 1 -atom such that $\beta_{j}$ is supported on some ball $B_{j}$ with $2 B_{j} \subset \mathbb{R}_{+}^{n}$ for each $j$ and $\left\{\alpha_{i}\right\}_{i=1}^{\infty}$ is a sequence of $\left(1, \mathbb{R}_{+}^{n}\right)$-atom such that $\alpha_{i}$ is supported on some ball $B_{i}$ with $2 B_{i} \subset \mathbb{R}_{+}^{n}$ but $5 B_{i} \cap\left(\mathbb{R}_{+}^{n}\right)^{c} \neq \varnothing$ for each $i$. Let $B_{i}=B_{r}\left(\mathbf{x}_{i}\right)$ and $\mathrm{x}^{*}:=\left(\mathbf{x}_{i}^{\prime}, 0\right)$. Since $2 B_{i} \subset \mathbb{R}_{+}^{n}$ but $5 B_{i} \cap\left(\mathbb{R}_{+}^{n}\right)^{c} \neq \varnothing$, we can easily deduce that $B_{i} \subset B_{6 r}\left(\mathrm{x}^{*}\right)$. Notice that $\alpha_{i}=r_{\mathbb{R}_{+}^{n}} E_{\text {odd }} \alpha_{i}$ and $\int_{B_{6 r}\left(\mathbf{x}^{*}\right)} E_{\text {odd }} \alpha_{i} \mathrm{~d} \mathbf{x}=0$, therefore we have that

$$
\begin{equation*}
E_{\text {odd }} f=\sum_{i}\left(\lambda_{i} \cdot 6^{n}\right) \cdot\left(\frac{1}{6^{n}} \cdot E_{\text {odd }} \alpha_{i}\right)+\sum_{j} \mu_{j} E_{\text {odd }} \beta_{j} . \tag{2.5.1}
\end{equation*}
$$

Here $\frac{1}{6^{n}} \cdot E_{\text {odd }} \alpha_{i}$ is a 1 -atom for any $i$, hence by (2.5.1) we see that $E_{\text {odd }} f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ and thus by Remark 2.5.14 $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
(2). Let $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, let $\eta$ be the standard mollifier. For $\mathbf{x} \in \mathbb{R}_{+}^{n}$ and $0<t<$ $\operatorname{dist}\left(\mathbf{x}, \partial \mathbb{R}_{+}^{n}\right)$, we have that $\left(\eta_{t} * f\right)(\mathbf{x})=\left(\eta_{t} * E_{\text {odd }} f\right)(\mathbf{x})$ since $\operatorname{supp} \eta_{t} \subset B_{t}(0)$. Hence for $\mathrm{x} \in \mathbb{R}_{+}^{n}$,

$$
\begin{aligned}
\sup _{0<t<\operatorname{dist}\left(\mathbf{x}, \partial \mathbb{R}_{+}^{n}\right)}\left|\eta_{t} * f\right|(\mathbf{x}) & =\sup _{0<t<\operatorname{dist}\left(\mathbf{x}, \partial \mathbb{R}_{+}^{n}\right)}\left|\eta_{t} * E_{\text {odd }} f\right|(\mathbf{x}) \\
& \leq \sup _{t>0}\left|\eta_{t} * E_{\text {odd }} f\right|(\mathbf{x}) .
\end{aligned}
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Thus

$$
\begin{aligned}
\|f\|_{\mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)} & :=\int_{\mathbb{R}_{+}^{n}} \sup _{0<t<\operatorname{dist}\left(\mathbf{x}, \partial \mathbb{R}_{+}^{n}\right)}\left|\eta_{t} * f\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& \leq \int_{\mathbb{R}_{+}^{n}} \sup _{t>0}\left|\eta_{t} * E_{\text {odd }} f\right|(\mathbf{x}) \mathrm{d} \mathbf{x} \\
& =\|f\|_{\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)}
\end{aligned}
$$

and therefore $f \in \mathscr{H}_{M}^{1}\left(\mathbb{R}_{+}^{n}\right)$.
Remark 2.5.16. Let us consider a function $f \in L^{2}\left(B_{r}^{+}(0)\right)$ with integral over $B_{r}^{+}(0)$ not equals to 0 . Notice that although $\int_{B_{r}^{+}(0)} f \mathrm{~d} \mathbf{x} \neq 0$, the odd extension $E_{\text {odd }} f$ has integral zero over the ball $B_{r}(0)$. Hence we have that $E_{\text {odd }} f \in L^{2}\left(B_{r}(0)\right), \int_{B_{r}(0)} E_{\text {odd }} f \mathrm{dx}=0$ and thus $E_{\text {odd }} f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. Then $f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. However, $\int_{B_{r}^{+}(0)} f \mathrm{dx} \neq 0$ implies that $\int_{B_{r}(0)} E_{\text {even }} f \mathrm{dx} \neq 0$ and thus $E_{\text {even }} f \notin \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. Hence $f \notin \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Therefore $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $\mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ are two different spaces.

Remark 2.5.17. Let us consider the function $\log |\mathbf{x}|$, by the standard theory of $B M O$ spaces we see that $\log |\mathbf{x}| \in B M O$. Then $\left.\log |\mathbf{x}|\right|_{\mathbb{R}_{+}^{n}} \in B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$. However, $\left.\log |\mathbf{x}|\right|_{\mathbb{R}_{+}^{n}} \notin$ $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ since the integral

$$
\frac{1}{B_{r}^{+}(0)} \int_{B_{r}^{+}(0)}|\log | \mathbf{x}| | \mathrm{d} \mathbf{x} \rightarrow \infty \quad \text { as } r \rightarrow \infty .
$$

Therefore $B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ and $B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ are also two different spaces.
Remark 2.5.18. Notice that by Theorem 2.5 .3 we can easily see that $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)=\mathscr{H}^{1}\left(\mathbb{R}_{+}^{n}\right)$ where $\mathscr{H}^{1}\left(\mathbb{R}_{+}^{n}\right):=\left\{r_{\mathbb{R}_{+}^{n}} f \mid f \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)\right\}$. Moreover, by Lemma 2.3.2 and Lemma 2.3.4, we can also see that $B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)=B M O\left(\mathbb{R}_{+}^{n}\right)$ where $B M O\left(\mathbb{R}_{+}^{n}\right):=\left\{r_{\mathbb{R}_{+}^{n}} f \mid f \in B M O\left(\mathbb{R}^{n}\right)\right\}$. As a result, we can clarify the relationship between various function spaces in this chapter as follow:

$$
\begin{gathered}
B M O\left(\mathbb{R}_{+}^{n}\right)=B M O_{b a}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)={ }^{*} \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right) \\
\cup \\
B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)={ }^{*} \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)=\mathscr{H}^{1}\left(\mathbb{R}_{+}^{n}\right) \\
\|
\end{gathered}
$$

Here $A={ }^{*} B$ means that $A$ is the dual space of $B$.

### 2.6 Dual operator of the Helmholtz projection

### 2.6.1 Dual operators of $E_{\text {odd }}$ and $r_{\mathbb{R}_{+}^{n}}$

In this subsection, for simplicity, we shall denote the odd extension operator $E_{\text {odd }}$ by $E$. Since $E: \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right) \rightarrow E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, we have that $E^{*}: E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)^{*} \rightarrow \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)^{*}$. By the theories in section 2.5 we have that $E^{*}: E B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right) \rightarrow B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$.
Lemma 2.6.1. The dual operator of $E$ is indeed $2 \cdot r_{\mathbb{R}_{+}^{n}}$, i.e., $E^{*}=2 \cdot r_{\mathbb{R}_{+}^{n}}$.
2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

Proof. Let $f \in \mathscr{H}_{o d d}^{1}\left(\mathbb{R}_{+}^{n}\right)$ and $g \in B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$, by the definition of dual operator, we can deduce that

$$
<E^{*} E g, f>:=<E g, E f>=2<g, f>.
$$

Therefore, we have that

$$
<E^{*} E g-2 g, f>=0 \text { for all } f \in \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)
$$

Let $B_{r}(0)$ be the ball centered at 0 with radius $r$ and $B_{r}^{+}(0):=B_{r}(0) \cap \mathbb{R}_{+}^{n}$. For simplicity, we denote $B_{r}^{+}(0)$ by $B_{r}^{+}$. Notice that from the previous chapter, we see that $L^{2}\left(B_{r}^{+}\right) \subset$ $\mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Hence fix $r>0$, we have that

$$
<E^{*} E g-2 g, f>=0 \text { for all } f \in L^{2}\left(B_{r}^{+}\right) .
$$

Since $C_{0}^{\infty}\left(B_{r}^{+}\right) \subset L^{2}\left(B_{r}^{+}\right)$, by the fundamental lemma of variational calculus, we see that

$$
E^{*} E g-2 g=0 \quad \text { a.e. in } B_{r}^{+} .
$$

This means $E^{*}=2 \cdot r_{\mathbb{R}_{+}^{n}}$ and we are done.
By similar arguments as above, we can also deduce that $r_{\mathbb{R}_{+}^{n}}{ }^{*}: B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right) \rightarrow$ $E B M O_{b}^{\infty, \infty}\left(\mathbb{R}_{+}^{n}\right)$ and the dual operator of $r_{\mathbb{R}_{+}^{n}}$, where $r_{\mathbb{R}_{+}^{n}}$ corresponds to the restriction of $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, is indeed $\frac{1}{2} \cdot E$.

### 2.6.2 Dual operators of $E_{\text {even }}$ and $r_{\mathbb{R}_{+}^{n}}$

We denote the even extension operator $E_{\text {even }}$ by $E$. By similar arguments as in the previous subsection, we have that the dual operator of $E$ is indeed $2 \cdot r_{\mathbb{R}_{+}^{n}}$ and the dual operator of $r_{\mathbb{R}_{+}^{n}}$, which corresponds to the restriction of $E \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$, is indeed $\frac{1}{2} \cdot E$.

### 2.6.3 Proof of Theorem 2.1.4

Proof. Since $\mathbb{P}_{\mathbb{R}_{+}^{n}}$ is a bounded linear operator from $\mathbf{Y}$ to $\mathbf{Y}$ and $\mathbf{X}$ is the dual space of $\mathbf{Y}$, we have that

$$
\mathbb{P}_{\mathbb{R}_{+}^{n}}: \mathbf{X} \rightarrow \mathbf{X}
$$

Then let $\mathbf{v} \in \mathbf{X}$ and $\mathbf{u} \in \mathbf{Y}$, we have that

$$
\left.<\mathbb{P}_{\mathbb{R}_{+}^{n}} * \mathbf{v}, \mathbf{u}>=\sum_{i=1}^{n-1}<v^{i}, r_{\mathbb{R}_{+}^{n}}(\mathbb{P} E \mathbf{u})^{i}\right\rangle+\left\langle v^{n}, r_{\mathbb{R}_{+}^{n}}(\mathbb{P} E \mathbf{u})^{n}\right\rangle
$$

Notice that $(\mathbb{P} E \mathbf{u})^{i}$ is even with respect to $x_{n}$ for $1 \leq i \leq n-1$ and $(\mathbb{P} E \mathbf{u})^{n}$ is odd with respect to $x_{n}$. Hence for $1 \leq i \leq n-1$, the $r_{\mathbb{R}_{+}^{n}}$ in $r_{\mathbb{R}_{+}^{n}}(\mathbb{P} E \mathbf{u})^{i}$ corresponds to the restriction of $E \mathscr{H}_{\text {even }}^{1}\left(\mathbb{R}_{+}^{n}\right)$ whereas for $i=n$, the $r_{\mathbb{R}_{+}^{n}}$ in $r_{\mathbb{R}_{+}^{n}}(\mathbb{P} E \mathbf{u})^{n}$ corresponds to the restriction of $E \mathscr{H}_{\text {odd }}^{1}\left(\mathbb{R}_{+}^{n}\right)$. Therefore,

$$
<\mathbb{P}_{\mathbb{R}_{+}^{n}} * \mathbf{v}, \mathbf{u}>=\frac{1}{2}<E \mathbf{v}, \mathbb{P} E \mathbf{u}>\cdots \cdots(*) .
$$

2. On the Helmholtz decompositions of vector fields of bounded mean oscillation and in real Hardy spaces over the half space

By [8], we see that the dual operator of $\mathbb{P}: \mathscr{H}^{1}\left(\mathbb{R}^{n}\right) \rightarrow \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$ is itself as a map from $B M O$ to BMO. Therefore

$$
\begin{aligned}
(*) & =\frac{1}{2}\langle\mathbb{P} E \mathbf{v}, E \mathbf{u}\rangle \\
& \left.=\frac{1}{2}\left(\sum_{i=1}^{n-1}<(\mathbb{P} E \mathbf{v})^{i}, E_{\text {even }} u^{i}\right\rangle+<(\mathbb{P} E \mathbf{v})^{n}, E_{\text {odd }} u^{n}>\right) \\
& =\frac{1}{2}\left(\sum_{i=1}^{n-1}<2 r_{\mathbb{R}_{+}^{n}}(\mathbb{P} E \mathbf{v})^{i}, u^{i}>+<2 r_{\mathbb{R}_{+}^{n}}(\mathbb{P} E \mathbf{v})^{n}, u^{n}>\right) \\
& =<\mathbb{P}_{\left.\mathbb{R}_{+}^{n} \mathbf{v}, \mathbf{u}\right\rangle .} .
\end{aligned}
$$

Remark 2.6.2. When we are considering the dual operator of $\mathbb{P}_{\mathbb{R}_{+}^{n}}$, notice that the space $\mathbf{X}$ must be viewed as $\mathbf{X} /\left(\mathbb{R}^{n-1} \times\{0\}\right)$ !

### 2.6.4 Proof of Corollary 2.1.5

Proof. By [2, Th 2.19] and Theorem 2.1.4 in this chapter, we are done.

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## Chapter 3

## Normal trace for a vector field of bounded mean oscillation

We introduce various spaces of vector fields of bounded mean oscillation (BMO) defined in a domain so that normal trace of a vector field on the boundary is bounded when its divergence is well controlled. The behavior of "normal" component and "tangential" component may be different for our $B M O$ vector fields. As a result the zero extension of the normal component stays in $B M O$ although such property may not hold for tangential components.

### 3.1 Introduction

One of basic questions on vector fields defined on a domain $\Omega$ in $\mathbf{R}^{n}(n \geq 2)$ is whether the normal trace is well controlled without estimating all partial derivatives when the divergence is well controlled. Such a type of estimates is well known when a vector field is $L^{p}(1<p<\infty)$ or $L^{\infty}$. Here are examples. Let $\Omega$ be a bounded domain with smooth boundary $\Gamma$. Let $\mathbf{n}$ denotes its exterior unit normal vector field on $\Gamma$. For simplicity, we assume that a vector field $v$ satisfies $\operatorname{div} v=0$. Then there is a constant $C$ independent of $v$ such that

$$
\begin{align*}
\|v \cdot \mathbf{n}\|_{W^{-1 / p, p}(\Gamma)} & \leq C\|v\|_{L^{p}(\Omega)}  \tag{3.1.1}\\
\|v \cdot \mathbf{n}\|_{L^{\infty}(\Gamma)} & \leq C\|v\|_{L^{\infty}(\Omega)} . \tag{3.1.2}
\end{align*}
$$

Here $W^{s, p}$ denotes the Sobolev space which is actually a Besov space $B_{p, p}^{s}$ for non-integer $s$. The first estimate is a key to establish the Helmholtz decomposition of an $L^{p}$ vector field; see e.g. [6]. The second estimate is important to study, for example, a total variation flow; see e.g. [1, Appendix C1]. These estimates (3.1.1), (3.1.2) hold for various domains including the case that $\Omega$ is a half space $\mathbf{R}_{+}^{n}$, i.e.,

$$
\mathbf{R}_{+}^{n}=\left\{\left(x_{1}, \ldots, x_{n}\right) \mid x_{n}>0\right\} .
$$

Our goal in this chapter is to extend (3.1.2) by replacing $\|v\|_{L^{\infty}(\Omega)}$ by some $B M O$ type norm. However, it turns out that the normal trace on $\Gamma=\partial \mathbf{R}_{+}^{n}$ of divergence free $B M O$ vector fields in $\mathbf{R}^{n}$ may not be bounded. Indeed, consider

$$
v=\left(v^{1}, v^{2}\right), \quad v^{1}(x)=v^{2}(x)=\log \left|x_{1}-x_{2}\right| . \quad x=\left(x_{1}, x_{2}\right) \in \mathbf{R}^{2} .
$$

This vector field is in $B M O\left(\mathbf{R}^{2}\right)$ and it is divergence free in distribution sense. Indeed,

$$
\begin{gathered}
\int_{\mathbf{R}^{2}} v \cdot \nabla \varphi d x=\frac{1}{2} \int_{\mathbf{R}^{2}} \log |\zeta|\left(\left(\partial_{\zeta}-\partial_{\zeta}\right) \tilde{\varphi}+\left(\partial_{\eta}+\partial_{\eta}\right) \tilde{\varphi}\right) d \zeta d \eta=0, \\
\zeta=x_{1}-x_{2}, \quad \eta=x_{1}+x_{2}
\end{gathered}
$$

for all compactly supported smooth function $\varphi$, i.e., $\varphi \in C_{c}^{\infty}\left(\mathbf{R}^{2}\right)$. Here, $\tilde{\varphi}(\zeta, \eta)=\varphi((\zeta+$ $\eta) / 2,(\eta-\zeta) / 2)$. However, if we consider $\Omega=\mathbf{R}_{+}^{2}$ and $\Gamma=\left\{x_{2}=0\right\}$, then $v \cdot \mathbf{n}=-v_{2}$ on $\Gamma$ is clearly unbounded. This example indicates that we need some control near the boundary. Such a control is introduced in [?BG], [?BGS], [?BGMST], [?BGST]. More precisely, for $f \in L_{\text {loc }}^{1}(\Omega)$ and $\nu \in(0, \infty]$, they introduced a seminorm

$$
[f]_{b^{\nu}}:=\sup \left\{r^{-n} \int_{\Omega \cap B_{r}(x)}|f(y)| d y \mid x \in \Gamma, 0<r<\nu\right\}
$$

where $B_{r}(x)$ denotes the closed ball of radius $r$ centered at $x$. For $\mu \in(0, \infty]$, they define

$$
[f]_{B M O^{\mu}}:=\sup \left\{\left.\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f-f_{B_{r}(x)}\right| d y \right\rvert\, B_{r}(x) \subset \Omega, r<\mu\right\}
$$

where $f_{B}=\frac{1}{|B|} \int_{B} f(y) d y$, the average over $B$; here $|B|$ denotes the Lebesgue measure of $B$. The $B M O$ type space $B M O_{b}^{\mu, \nu}$ introduced in these papers is the space of $f \in L_{\mathrm{loc}}^{1}(\Omega)$ having finite

$$
\|f\|_{B M O_{b}^{\mu, \nu}}:=[f]_{B M O^{\mu}}+[f]_{b^{\nu}}
$$

This space is very convenient to study the Stokes semigroup in [2], [4], [3], [5] as well as the heat semigroup [5]. One of our main results (Theorem 3.4.7) yields

$$
\begin{equation*}
\|v \cdot \mathbf{n}\|_{L^{\infty}(\Gamma)} \leq C\|v\|_{B M O_{b}^{\mu, \nu}} \tag{3.1.3}
\end{equation*}
$$

for any $\mu, \nu \in(0, \infty]$ for any uniformly $C^{1+\beta}$ domain with $\beta \in(0,1)$.
However, for applications, especially to establish the Helmholtz decomposition, requiring all components to be $B M O_{b}^{\mu, \nu}$ bounded is too strong so we would like to estimate by a weaker norm. We only use $b^{\nu}$ seminorm for normal component of a vector field $v$. To decompose the vector field, let $d_{\Omega}(x)$ be the distance of $x \in \Omega$ from the boundary $\Gamma$, i.e.,

$$
d_{\Omega}(x):=\inf \{|x-y| \mid y \in \Gamma\} .
$$

If $\Omega$ is uniformly $C^{2}$, then $d_{\Omega}$ is $C^{2}$ in a $\delta$-tubular neighborhood $\Gamma_{\delta}$ of $\Gamma$ for some $\delta<R_{*}$, where $R_{*}$ is the reach of $\Gamma$ [10, Chapter 14, Appendix], [11, §4.4]; here

$$
\Gamma_{\delta}:=\left\{x \in \Omega \mid d_{\Omega}(x)<\delta\right\} .
$$

Instead of (3.1.3), our main results (Theorem 3.4.2, 3.4.3) together with Theorem 3.2.9 read as

$$
\begin{equation*}
\|v \cdot \mathbf{n}\|_{L^{\infty}(\Gamma)} \leq C\left([v]_{B M O^{\mu}}+\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu}}\right) \tag{3.1.4}
\end{equation*}
$$

for $\nu \leq \delta, \mu \in(0, \infty]$ provided that $\Omega$ is a bounded $C^{2+\beta}$ domain with $\beta \in(0,1)$. The quantity $\nabla d_{\Omega} \cdot v$ is a kind of a normal component of $v$.

Our main strategy is to use the formula

$$
\int_{\Gamma}(v \cdot \mathbf{n}) \psi d \mathcal{H}^{n-1}=\int_{\Omega}(\operatorname{div} v) \varphi d x-\int_{\Omega} v \cdot \nabla \varphi d x
$$

for any $\varphi \in C_{c}^{\infty}(\bar{\Omega})$ with $\left.\varphi\right|_{\Gamma}=\psi$, where $d \mathcal{H}^{n-1}$ denotes the surface element. This formula is obtained by integration by parts. If $\operatorname{div} v=0$, then it reads

$$
\begin{equation*}
\int_{\Gamma}(v \cdot \mathbf{n}) \psi d \mathcal{H}^{n-1}=-\int_{\Omega} v \cdot \nabla \varphi d x \tag{3.1.5}
\end{equation*}
$$

Our estimate (3.1.4) follows from localization, flattening the boundary and duality argument. To get the flavor, we explain the case when $\Omega$ is the half space $\mathbf{R}_{+}^{n}$. For $\psi \in L^{1}(\Gamma)$ it is known that there is $\varphi \in F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$ such that its trace to the boundary equals to $\psi$; see e.g. [19, Section 4.4.3]. Here $F_{1,2}^{1}$ denotes the Triebel-Lizorkin space which means that $\nabla \varphi \in h^{1}$, a local Hardy space. We may assume that $\varphi$ is even in $x_{n}$. We extend $v=\left(v^{\prime}, v_{n}\right)$ even in $x_{n}$ for tangential part $v^{\prime}$ and odd in $x_{n}$ for the normal part $v_{n}=\nabla d_{\Omega} \cdot v$. Although extended $v^{\prime}$ is still in $B M O^{\infty}\left(\mathbf{R}^{n}\right)$, the extended $v_{n}$ may not be in $B M O^{\infty}\left(\mathbf{R}^{n}\right)$ unless we assume $\left[v_{n}\right]_{b^{\nu}}<\infty$. Here we invoke $\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu}}<\infty$. By these extensions, our (3.1.5) yields

$$
\begin{equation*}
\int_{\Gamma}(v \cdot \mathbf{n}) \psi d \mathcal{H}^{n-1}=-\frac{1}{2} \int_{\mathbf{R}^{n}} v \cdot \nabla \varphi d x \tag{3.1.6}
\end{equation*}
$$

where $v$ denotes the extended vector field. We apply $h^{1}$-bmo duality [16, Theorem 3.22] for (3.1.6) to get

$$
\left|\int_{\Gamma}(v \cdot \mathbf{n}) \psi d \mathcal{H}^{n-1}\right| \leq C\|v\|_{b m o}\|\varphi\|_{F_{1,2}^{1}},
$$

where $b m o=B M O \cap L_{\mathrm{ul}}^{1}$ a localized $B M O$ space. Here $L_{\mathrm{ul}}^{1}$ denotes a uniformly local $L^{1}$ space; see Section 3.2 for details. Since $\|\varphi\|_{F_{1,2}^{1}} \leq C\|\psi\|_{L^{1}}$, this implies

$$
\begin{align*}
\|v \cdot \mathbf{n}\|_{L^{\infty}(\Gamma)} & \leq C\|v\|_{b m o\left(\mathbf{R}^{n}\right)} \\
& \leq C\left([v]_{B M O^{\infty}(\Omega)}+[v]_{L_{\mathrm{ul}}^{1}(\Omega)}+\left[\nabla d_{\Omega} \cdot v\right]_{b^{\infty}}\right) . \tag{3.1.7}
\end{align*}
$$

Here and hereafter $C$ denotes a constant independent of $v$ and its numerical value may be different line by line.

In the case of a curved domain we need localization and flattening procedure by using a normal (principal) coordinate system. The localized space $b m o_{\delta}^{\mu}=B M O^{\mu} \cap L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)$ is convenient for this purpose. Again we have to handle normal component $\nabla d_{\Omega} \cdot v$ separately. If the domain has a compact boundary, we are able to remove $L_{\mathrm{ul}}^{1}$ term in (3.1.7) and we deduce the estimate (3.1.4). Note that in this trace estimate only the behavior of $v$ near $\Gamma$ is important so one may use finite exponents in $B M O^{\mu}$ and $b^{\nu}$.

As a byproduct we notice the extension problem of $B M O$ functions. In general, zero extension of $v \in B M O^{\mu}(\Omega)$ may not belong to $B M O^{\mu}\left(\mathbf{R}^{n}\right)$ but if $v$ is in $B M O_{b}^{\mu, \nu}$, as noticed in [5], its zero extension belongs to $B M O^{\mu}\left(\mathbf{R}^{n}\right)$ for $\nu \geq 2 \mu$. We also note that it is possible to extend general $b m o_{\delta}^{\mu}(\Omega)$ to $B M O^{\mu}$ whose support is near $\bar{\Omega}$. We develop such a theory to explain the role of $b^{\nu}$.

This chapter is organized as follows. In Section 3.2 we introduce several localized BMO spaces and compared these spaces. Some of them are discussed in [5]. We introduce a new space $v b m o_{\delta}^{\mu, \nu}$ which requires that the $b^{\nu}$ seminorm of the normal component is bounded in
$\left(b m o_{\delta}^{\mu}\right)^{n}$. A key observation is that if the boundary of the domain is compact, i.e., either a bounded or an exterior domain, the requirement in $L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)$ is redundant in the definition of $v b m o_{\delta}^{\mu, \nu}$. In Section 3.3 we discuss extension problem as well as localization problem. In Section 3.4 we shall prove our main results. In Appendix we discuss coordinate change of vector fields by normal coordinates for the reader's convenience.

### 3.2 Spaces

In this section we fix notation of important function spaces. Let $L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)$ be a uniformly $L^{1}$ space, i.e., for a fixed $r_{0}>0$

$$
L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right):=\left\{f \in L_{\mathrm{loc}}^{1}\left(\mathbf{R}^{n}\right)\left|\|f\|_{L_{\mathrm{ul}}^{1}}:=\sup _{x \in \mathbf{R}^{n}} \int_{B_{r_{0}}(x)}\right| f(y) \mid d y<\infty\right\}
$$

The space is independent of the choice of $r_{0}$. For a domain $\Omega$, the space $L_{\mathrm{ul}}^{1}$ is the space of all $L_{\mathrm{loc}}^{1}$ functions $f$ in $\Omega$ whose zero extension belongs to $L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)$. In other words,

$$
L_{\mathrm{ul}}^{1}(\Omega):=\left\{f \in L_{\mathrm{loc}}^{1}(\Omega)\left|\|f\|_{L_{\mathrm{ul}}^{1}(\Omega)}:=\sup _{x \in \mathbf{R}^{n}} \int_{B_{r_{0}}(x) \cap \Omega}\right| f(y) \mid d y<\infty\right\} .
$$

As in [2], we set

$$
B M O^{\mu}(\Omega):=\left\{f \in L_{\mathrm{loc}}^{1}(\Omega) \mid[f]_{B M O^{\mu}}<\infty\right\}
$$

For $\delta \in(0, \infty]$, we set
$b m o_{\delta}^{\mu}(\Omega):=B M O^{\mu}(\Omega) \cap L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)=\left\{f \in B M O^{\mu}(\Omega) \mid\right.$ restriction of $f$ on $\Gamma_{\delta}$ is in $\left.L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)\right\}$.
This is a Banach space equipped with the norm

$$
\|f\|_{b m o_{\delta}^{\mu}}:=[f]_{B M O^{\mu}(\Omega)}+[f]_{\Gamma_{\delta}}, \quad[f]_{\Gamma_{\delta}}:=\|f\|_{L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)}
$$

where the restriction of $f$ on $\Gamma_{\delta}$ is still denoted by $f$. If there is no boundary, we set

$$
b m o\left(\mathbf{R}^{n}\right):=B M O^{\infty}\left(\mathbf{R}^{n}\right) \cap L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)
$$

which is a local $B M O$ space and it agrees with the Triebel-Lizorkin space $F_{\infty, 2}^{0}$; see e.g. [19, Section 1.7.1], [16, Theorem 3.26].

For vector-valued function spaces, we still write $B M O^{\mu}$ instead of $\left(B M O^{\mu}\right)^{n}$. For example, for vector field $v$, by $v \in b m o_{\delta}^{\mu}(\Omega)$ we mean that

$$
v=\left(v_{1}, \ldots, v_{n}\right), \quad v_{i} \in b m o_{\delta}^{\mu}(\Omega), \quad 1 \leq i \leq n .
$$

We next introduce the space of vector fields whose normal component has finite $b^{\nu}$ of the form

$$
v b m o_{\delta}^{\mu, \nu}(\Omega):=\left\{v \in b m o_{\delta}^{\mu}(\Omega) \mid\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu}}<\infty\right\}
$$

for $\nu \in(0, \infty]$. This space is a Banach space equipped with the norm

$$
\|v\|_{v b m o_{\delta}^{\mu, \nu}}:=\|v\|_{b m o_{\delta}^{\mu}}+\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu}} .
$$

Similarly, we introduce another space

$$
v B M O^{\mu, \nu}(\Omega):=\left\{v \in B M O^{\mu}(\Omega) \mid\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu}}<\infty\right\}
$$

equipped with a seminorm

$$
[v]_{v B M O^{\mu, \nu}}:=[v]_{B M O^{\mu}}+\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu}} .
$$

Of course, this is strictly larger than the Banach space

$$
B M O_{b}^{\mu, \nu}(\Omega):=\left\{v \in B M O^{\mu}(\Omega) \mid[v]_{b^{\nu}}<\infty\right\}
$$

equipped with the norm

$$
\|v\|_{B M O_{b}^{\mu, \nu}}:=[v]_{B M O^{\mu}}+[v]_{b^{\nu}}
$$

introduced essentially in [2]. Indeed, in the case when $\Omega$ is the half space $\mathbf{R}_{+}^{n}$,

$$
\begin{equation*}
v B M O^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right)=\left(B M O^{\mu}\left(\mathbf{R}_{+}^{n}\right)\right)^{n-1} \times B M O_{b}^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right), \tag{3.2.1}
\end{equation*}
$$

where in the right-hand side the each space denotes the space of scalar functions not of vector fields. This shows that $v B M O^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right)$ is strictly larger than $B M O_{b}^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right)$ for $n \geq 2$.

Although there are many exponents, the spaces may be the same for different exponents. By definition, for $0<\mu_{1} \leq \mu_{2} \leq \infty, 0<\nu_{1} \leq \nu_{2} \leq \infty, 0<\delta_{1} \leq \delta_{2} \leq \infty$,

$$
[f]_{B M O^{\mu_{1}}} \leq[f]_{B M O^{\mu_{2}}}, \quad[f]_{b^{\nu_{1}}} \leq[f]_{b^{\nu_{2}}}, \quad[f]_{\Gamma_{\delta_{1}}} \leq[f]_{\Gamma_{\delta_{2}}}
$$

Proposition 3.2.1. Let $\Omega$ be an arbitrary domain in $\mathbf{R}^{n}$.
(i) Let $0<\mu_{1}<\mu_{2}<\infty$. Then seminorms $[\cdot]_{B M O^{\mu_{1}}}$ and $[\cdot]_{B M O^{\mu_{2}}}$ are equivalent. If $\Omega$ is bounded, one may take $\mu_{2}=\infty$.
(ii) Let $0<\delta_{1}<\delta_{2}<\infty$ and $\mu \in(0, \infty]$. Then there exists a constant $C>0$ depending only on $n, \mu, \delta_{1}, \delta_{2}$ and $\Omega$ such that

$$
[f]_{\Gamma_{\delta_{2}}} \leq C\left([f]_{B M O^{\mu}}+[f]_{\Gamma_{\delta_{1}}}\right) .
$$

In particular, the norms $\|\cdot\|_{b m o_{\delta_{1}}^{\mu}}$ and $\|\cdot\|_{b m o_{\delta_{2}}^{\mu}}$ are equivalent. If $\Omega$ is bounded, one may take $\delta_{2}=\infty$.

Proof. (i) This is [5, Theorem 4] which follows from [5, Theorem 3].
(ii) Since the space $L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)$ is independent of the radius $r_{0}$ in its definition, without loss of generality, we may assume that $r_{0}>\delta_{1}$. Let us firstly consider the case where the dimension $n>1$. Let $k$ be the smallest integer such that $2^{-k}<\frac{\delta_{1}}{\sqrt{n}}$ and $x \in \mathbf{R}^{n}$. Notice that

$$
\int_{B_{r_{0}}(x) \cap \Gamma_{\delta_{2}}}|f| d y=\int_{B_{r_{0}}(x) \cap \Gamma_{\delta_{1}}}|f| d y+\int_{B_{r_{0}}(x) \cap\left(\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}}\right)}|f| d y,
$$

we can estimate $\|f\|_{L^{1}\left(B_{r_{0}}(x) \cap \Gamma_{\delta_{1}}\right)}$ directly by $[f]_{\Gamma_{\delta_{1}}}$. Assume that $\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}} \neq \emptyset$. Let $D_{k}(x)$ be the set of dyadic cubes of side length $2^{-k}$ that intersect with $B_{r_{0}}(x) \cap\left(\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}}\right)$. For a
dyadic cube $Q_{j} \in D_{k}(x)$, we define $B_{j}$ to be the ball which has radius $\frac{\sqrt{n}}{2} \cdot 2^{-k}$ and shares the same center with $Q_{j}$. Let $C_{k}(x):=\left\{B_{j} \mid Q_{j} \in D_{k}(x)\right\}$ and $\Sigma:=\left\{x \in \Omega \mid d_{\Omega}(x)=\delta_{1}\right\}$.

For $Q_{j} \in D_{k}(x)$ that intersects $\Sigma$, we seek to estimate $\|f\|_{L^{1}\left(B_{j}\right)}$. Let $c_{j}$ be a point on $\Sigma \cap Q_{j}$, we have that $B_{\delta_{1}}\left(c_{j}\right) \subset \Omega$. Indeed as otherwise, there exists $z \in B_{\delta_{1}}\left(c_{j}\right) \cap \Omega^{c}$. Then the line segment joining $c_{j}$ and $z$ must intersect $\Gamma$ at some point, say $z^{*}$. Then $\left|z^{*}-c_{j}\right| \leq\left|z-c_{j}\right|<\delta_{1}$. This contradicts the fact that $d_{\Omega}\left(c_{j}\right)=\delta_{1}$. For $y \in B_{j}$, $\left|y-c_{j}\right|<\sqrt{n} \cdot \ell\left(Q_{j}\right)=\sqrt{n} \cdot 2^{-k}<\delta_{1}$. So $B_{j} \subset B_{\delta_{1}}\left(c_{j}\right)$. Let $d_{j} \in \Gamma$ be a point such that $\left|c_{j}-d_{j}\right|=\delta_{1}$, then on the line segment joining $c_{j}$ and $d_{j}$, we can find a point $o_{j}$ such that $\left|o_{j}-d_{j}\right|=\frac{\sqrt{n}}{2} \cdot 2^{-k}$. For $y \in B_{\frac{\sqrt{n}}{2} \cdot 2^{-k}}\left(o_{j}\right)$, we have that $\left|d_{\Omega}(y)-d_{\Omega}\left(o_{j}\right)\right| \leq\left|y-o_{j}\right|$. Hence $d_{\Omega}(y) \leq d_{\Omega}\left(o_{j}\right)+\left|y-o_{j}\right|<\sqrt{n} \cdot 2^{-k}<\delta_{1}$. This means that $B_{\frac{\sqrt{n}}{2} \cdot 2^{-k}}\left(o_{j}\right) \subset \Gamma_{\delta_{1}}$. Moreover,

$$
\left|c_{j}-y\right| \leq\left|c_{j}-o_{j}\right|+\left|o_{j}-y\right| \leq \delta_{1}-\frac{\sqrt{n}}{2} \cdot 2^{-k}+\frac{\sqrt{n}}{2} \cdot 2^{-k}=\delta_{1}
$$

Thus $B_{\frac{\sqrt{n}}{2} \cdot 2^{-k}}\left(o_{j}\right) \subset B_{\delta_{1}}\left(c_{j}\right)$. Denote $B_{\frac{\sqrt{n}}{2} \cdot 2^{-k}}\left(o_{j}\right)$ by $B_{j}^{*}$. We have that

$$
\int_{B_{j}}|f| d y \leq \int_{B_{\delta_{1}}\left(c_{j}\right)}\left|f-f_{B_{\delta_{1}}\left(c_{j}\right)}\right| d y+\int_{B_{\delta_{1}\left(c_{j}\right)}}\left|f_{B_{\delta_{1}}\left(c_{j}\right)}-f_{B_{j}^{*}}\right| d y+\int_{B_{\delta_{1}}\left(c_{j}\right)}\left|f_{B_{j}^{*}}\right| d y
$$

Notice that

$$
\begin{aligned}
\int_{B_{\delta_{1}}\left(c_{j}\right)}\left|f-f_{B_{\delta_{1}}\left(c_{j}\right)}\right| d y & \leq C_{n} \cdot \delta_{1}^{n} \cdot[f]_{B M O^{\mu}} \\
\int_{B_{\delta_{1}}\left(c_{j}\right)}\left|f_{B_{\delta_{1}}\left(c_{j}\right)}-f_{B_{j}^{*}}\right| d y & \leq \frac{\left|B_{\delta_{1}}\left(c_{j}\right)\right|^{2}}{\left|B_{j}^{*}\right|} \cdot[f]_{B_{M O}} \\
\int_{B_{\delta_{1}}\left(c_{j}\right)}\left|f_{B_{j}^{*}}\right| d y & \leq \frac{\left|B_{\delta_{1}}\left(c_{j}\right)\right|}{\left|B_{j}^{*}\right|} \cdot[f]_{\delta_{1}}
\end{aligned}
$$

Since $\left|B_{\delta_{1}}\left(c_{j}\right)\right|=C_{n} \cdot \delta_{1}^{n}$ and $\frac{\left|B_{\delta_{1}}\left(c_{j}\right)\right|}{\left|B_{j}^{*}\right|}=\frac{C_{n} \cdot \delta_{1}^{n}}{\left(\frac{\sqrt{n}}{2} \cdot 2^{-k}\right)^{n}} \leq \frac{C_{n} \cdot \delta_{1}^{n}}{\left(\frac{\delta_{1}}{4}\right)^{n}}=C_{n},\|f\|_{L^{1}\left(B_{j}\right)}$ is therefore controlled by $C_{\delta_{1}, n} \cdot\left([f]_{B M O^{\mu}}+[f]_{\Gamma_{\delta_{1}}}\right)$.

Next we consider $Q_{j}^{\prime} \in D_{k}(x)$ that does not intersect $\Sigma$. Suppose that $Q_{j} \in D_{k}(x)$ has a touching edge with $Q_{j}^{\prime}$. There exists a ball $B_{i}^{j}$ of radius $\frac{\sqrt{n}-1}{2} \cdot 2^{-k}$ which is contained in $B_{j} \cap B_{j}^{\prime}$ where $B_{j}, B_{j}^{\prime}$ are the smallest balls that contain $Q_{j}, Q_{j}^{\prime}$ respectively. Similar to above, as $B_{i}^{j} \subset B_{j}$,

$$
\begin{aligned}
\int_{B_{j}^{\prime}}|f| d y & \leq \int_{B_{j}^{\prime}}\left|f-f_{B_{j}^{\prime}}\right| d y+\int_{B_{j}^{\prime}}\left|f_{B_{j}^{\prime}}-f_{B_{i}^{j}}\right| d y+\int_{B_{j}^{\prime}}\left|f_{B_{i}^{j}}\right| d y \\
& \leq\left|B_{j}^{\prime}\right| \cdot[f]_{B M O^{\mu}}+\frac{\left|B_{j}^{\prime}\right|^{2}}{\left|B_{i}^{j}\right|} \cdot[f]_{B M O^{\mu}}+\frac{\left|B_{j}^{\prime}\right|}{\left|B_{i}^{j}\right|} \cdot \int_{B_{j}}|f| d y .
\end{aligned}
$$

Therefore if $\|f\|_{L^{1}\left(B_{j}\right)}$ is controlled by $C_{\delta_{1}, n} \cdot\left([f]_{B M O^{\mu}}+[f]_{\Gamma_{\delta_{1}}}\right),\|f\|_{L^{1}\left(B_{j}^{\prime}\right)}$ is also controlled by $C_{\delta_{1}, n} \cdot\left([f]_{B M O^{\mu}}+[f]_{\Gamma_{\delta_{1}}}\right)$.

Since $B_{r_{0}}(x) \cap\left(\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}}\right)$ is connected, we can estimate $\|f\|_{L^{1}\left(B_{j}\right)}$ for every $Q_{j} \in D_{k}(x)$ where $B_{j}$ is the smallest ball that contains $Q_{j}$. For each $Q_{j} \in D_{k}(x)$, there exists $y \in$
$Q_{j} \cap B_{r_{0}}(x)$, so for any $z \in B_{j},|z-x| \leq|z-y|+|y-x|<\sqrt{n} \cdot 2^{-k}+r_{0}<r_{0}+\delta_{1}$. Thus $\bigcup_{Q_{j} \in D_{k}(x)} B_{j} \subset B_{r_{0}+\delta_{1}}(x)$. Let $N\left(D_{k}(x)\right)$ be the number of cubes in $D_{k}(x)$, we have that

$$
N\left(D_{k}(x)\right) \leq \frac{\left|B_{r_{0}+\delta_{1}}(x)\right|}{2^{-k n}} \leq C_{n} \cdot\left(\frac{r_{0}+\delta_{1}}{\delta_{1}}\right)^{n} .
$$

Therefore,

$$
\begin{aligned}
\int_{B_{r_{0}}(x) \cap\left(\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}}\right)}|f| d y & \leq \sum_{B_{j} \in C_{r_{0}}(x)} \int_{B_{j}}|f| d y \\
& \leq N\left(D_{k}(x)\right) \cdot C_{\delta_{1}, n} \cdot\left([f]_{B M O^{\mu}}+[f]_{\Gamma_{\delta_{1}}}\right) \\
& \leq C_{n, \delta_{1}, r_{0}} \cdot\left([f]_{B M O^{\mu}}+[f]_{\Gamma_{\delta_{1}}}\right) .
\end{aligned}
$$

For the case where the dimension $n=1$, we let $k$ to be the smallest integer such that $2^{-k}<\frac{\delta_{1}}{2}$ and $D_{k}$ to be the set of dyadic cubes of side length $2^{-k}$ that intersects $\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}}$. Notice that the region $\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}}$ is indeed a union of intervals. Without loss of generality, we can assume $\Omega$ to be ( $0, \infty$ ) and take $\mu=\infty$ by part (i) of this proposition. Thus in this case $\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}}=\left(\delta_{1}, \delta_{2}\right)$. For $Q_{0} \in D_{k}$ such that $\delta_{1} \in Q_{0}$,

$$
\begin{aligned}
\int_{Q_{0}}|f| d y & \leq \int_{2 Q_{0}}|f| d y \leq \int_{2 Q_{0}}\left|f-f_{2 Q_{0}}\right| d y+\int_{2 Q_{0}}\left|f_{2 Q_{0}}-f_{Q_{0}^{*}}\right| d y+\int_{2 Q_{0}}\left|f_{Q_{0}^{*}}\right| d y \\
& \leq C \cdot\left([f]_{B M O^{\infty}}+[f]_{\Gamma_{\delta_{1}}}\right),
\end{aligned}
$$

where $Q_{0}^{*}=2 Q_{0} \backslash\left(Q_{0} \cup\left[\delta_{1}, \infty\right)\right)$ and $\ell\left(Q_{0}^{*}\right)=\frac{1}{2} \ell\left(Q_{0}\right)=2^{-(k+1)}$.
We then put an ordering on the elements of $D_{k}$ in the following way. For $j \in \mathbf{N}$, suppose that we have ordered intervals $Q_{0}, Q_{1}, \ldots, Q_{j-1}$, we pick $Q_{j} \in D_{k} \backslash\left\{Q_{0}, Q_{1}, \ldots, Q_{j-1}\right\}$ such that $Q_{j}$ has a touching edge with $Q_{j-1}$. For $Q_{j} \in D_{k}$, similarly we have that

$$
\begin{aligned}
\int_{Q_{j}}|f| d y & \leq \int_{2 Q_{j}}|f| d y \leq \int_{2 Q_{j}}\left|f-f_{2 Q_{j}}\right| d y+\int_{2 Q_{j}}\left|f_{2 Q_{j}}-f_{Q_{j}^{*}}\right| d y+\int_{2 Q_{j}}\left|f_{Q_{j}^{*}}\right| d y \\
& \leq C \cdot\left([f]_{B M O \infty}+[f]_{\Gamma_{\delta_{1}}}\right),
\end{aligned}
$$

where $Q_{j}^{*}=2 Q_{j-1} \cap 2 Q_{j}$ and $\ell\left(Q_{j}^{*}\right)=\ell\left(Q_{j}\right)=2^{-k}$.
Let $N\left(D_{k}\right)$ be the number of elements of $D_{k}$, we have that

$$
N\left(D_{k}\right) \leq \frac{\delta_{2}-\delta_{1}}{2^{-k}}+2 \leq \frac{4\left(\delta_{2}-\delta_{1}\right)}{\delta_{1}}+2
$$

and therefore

$$
\int_{\Gamma_{\delta_{2}} \backslash \Gamma_{\delta_{1}}}|f| d y \leq C_{\delta_{2}, \delta_{1}} \cdot\left([f]_{B M O^{\mu}}+[f]_{\Gamma_{\delta_{1}}}\right) .
$$

The proof is now complete.
By this observation, when we discuss the space $b m o_{\delta}^{\mu}$, there are only four types of spaces

$$
b m o_{\delta}^{\mu}, \quad b m o_{\delta}^{\infty}, \quad b m o_{\infty}^{\mu}, \quad b m o_{\infty}^{\infty}
$$

for finite $\mu, \delta>0$. If $\Omega$ is bounded, it is clear that these four spaces agree with each other. However, if $\Omega$ is unbounded, these four spaces may be different because they requires different growth at infinity. Indeed, if $\Omega=(0, \infty)$

$$
b m o_{\infty}^{\infty} \subsetneq b m o_{\delta}^{\infty}
$$

since $\log (x+1) \in b m o_{\delta}^{\infty}$ while it does not belong to $b m o_{\infty}^{\infty}$. Moreover, since $x \in b m o_{\delta}^{\mu}$ but it does not belong to neither $b m o_{\infty}^{\mu}$ nor $b m o_{\delta}^{\infty}$, we see that

$$
b m o_{\delta}^{\infty} \subsetneq b m o_{\delta}^{\mu}, \quad b m o_{\infty}^{\mu} \subsetneq b m o_{\delta}^{\mu} .
$$

It is possible to prove that $b m o_{\infty}^{\infty}=b m o_{\infty}^{\mu}$. Indeed, $b m o_{\infty}^{\infty}(\Omega) \subset b m o_{\infty}^{\mu}(\Omega)$ is simply by the definition of the $B M O$ seminorm. It is sufficient to show the contrary, i.e., $[f]_{B M O^{\infty}} \leq$ $C \cdot\left([f]_{B M O^{\mu}}+[f]_{\Gamma_{\infty}}\right)$. Without loss of generality, in defining the seminorm $[\cdot]_{L_{\mathrm{ul}}^{1}\left(\Gamma_{\infty}\right)}$, we set the radius of the ball to be $\frac{\sqrt{n}}{2}$. For $B_{r}(x) \subset \Omega$ with $r<\mu$,

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f-f_{B_{r}(x)}\right| d y \leq[f]_{B M O^{\mu}} .
$$

For $B_{r}(x) \subset \Omega$ with $r \geq \mu$, if $r \leq \frac{\sqrt{n}}{2}$, then

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f-f_{B_{r}(x)}\right| d y \leq \frac{2}{\left|B_{r}(x)\right|} \int_{B_{\frac{\sqrt{n}}{2}}^{2}(x) \cap \Omega}|f| d y \leq C_{\mu, n} \cdot[f]_{\Gamma_{\infty}} .
$$

If $r>\frac{\sqrt{n}}{2}, B_{r}(x)$ is contained in the cube $Q_{r}$ with center $x$ and side length $2([r]+1)$, here $[r]$ is the largest integer less than or equal to $r$. By dividing each side length of $Q_{r}$ equally into $2([r]+1)$ parts, we can divide the cube $Q_{r}$ into $(2[r]+2)^{n}$ subcubes of side length 1 . Let $S_{Q_{r}}$ be the set of these $(2[r]+2)^{n}$ subcubes of $Q_{r}$. For $Q_{r}^{i} \in S_{Q_{r}}$, let $B_{r}^{i}$ be the smallest ball that contains $Q_{r}^{i}$. Let $C_{Q_{r}}:=\left\{B_{r}^{i} \mid Q_{r}^{i} \in S_{Q_{r}}\right\}$. We have that

$$
\int_{B_{r}(x)}|f| d y \leq \sum_{i=1}^{(2[r]+2)^{n}} \int_{B_{r}^{i} \cap \Omega}|f| d y \leq(2[r]+2)^{n} \cdot[f]_{\Gamma_{\infty}}
$$

Since $r \geq \mu$,

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f-f_{B_{r}(x)}\right| d y \leq \frac{2}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}|f| d y \leq C_{\mu, n} \cdot[f]_{\Gamma_{\infty}} .
$$

Therefore $b m o_{\infty}^{\infty}=b m o_{\infty}^{\mu}$ and thus $b m o_{\infty}^{\mu} \subsetneq b m o_{\mu}^{\infty}$.
We summarize these equivalences.
Theorem 3.2.2. Let $\Omega$ be an arbitrary domain in $\mathbf{R}^{n}$. Then

$$
b m o_{\infty}^{\infty}(\Omega)=b m o_{\infty}^{\mu}(\Omega) \subset b m o_{\delta}^{\infty}(\Omega) \subset b m o_{\delta}^{\mu}(\Omega)
$$

for finite $\delta, \mu>0$. The inclusions can be strict when $\Omega$ is unbounded. If $\Omega$ is bounded, all four spaces are the same.

As a simple application of Proposition 3.2.1, we conclude that the space $B M O_{b}^{\mu, \nu}$ is included in $b m o_{\nu}^{\mu}$ since $[f]_{\nu} \leq c[f]_{b^{\nu}}(\nu<\infty)$ with $c>0$ depending only on $\nu$ and $n$.

Theorem 3.2.3. Let $\Omega$ be an arbitrary domain in $\mathbf{R}^{n}$. For $\mu \in(0, \infty]$ the inclusion

$$
B M O_{b}^{\mu, \nu}(\Omega) \subset b m o_{\nu}^{\mu}(\Omega)
$$

holds for $\nu \in(0, \infty)$.
Since $b^{\nu}$-seminorm controls boundary growth stronger than $L^{1}$ sense, this inclusion is in general strict even when $\Omega$ is bounded. Here is a simple example when $\Omega=(0,1)$. The $b^{\nu}$-seminorm of $f(x)=\log x$ is infinite but $\|f\|_{L^{1}(\Omega)}$ is finite.

We next discuss the space $v b m o_{\delta}^{\mu, \nu}$.
Remark 3.2.4. As proved in [5, Theorem 9], if $\Omega$ is a bounded Lipschitz domain, the space $B M O_{b}^{\mu, \nu}(\mu, \nu \in(0, \infty])$ agrees with the Miyachi BMO space [14] defined by

$$
\begin{aligned}
B M O^{M}(\Omega) & =\left\{f \in L_{\mathrm{loc}}^{1}(\Omega) \mid\|f\|_{B M O^{M}}<\infty\right\} \\
\|f\|_{B M O^{M}} & :=[f]_{B M O^{M}}+[f]_{b^{M}} \\
{[f]_{B M O^{M}} } & :=\sup \left\{\left.\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f-f_{B_{r}(x)}\right| d y \right\rvert\, B_{2 r}(x) \subset \Omega\right\} \\
{[f]_{b^{M}} } & :=\sup \left\{\left.\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}|f| d y \right\rvert\, B_{2 r}(x) \subset \Omega \text { and } B_{5 r}(x) \cap \Omega^{c} \neq \emptyset\right\} .
\end{aligned}
$$

Proposition 3.2.5. Let $\Omega$ be an arbitrary domain in $\mathbf{R}^{n}$. Let $0<\nu_{1} \leq \nu_{2} \leq \delta \leq \infty$. Then there exists a constant $c>0$ depending only on $n, \nu_{1}, \nu_{2}, \delta$ such that

$$
\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu_{2}}} \leq\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu_{1}}}+c[v]_{\Gamma_{\delta}}
$$

for all $v \in L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)$.
Proof. We may assume that $\nu_{1}<\infty$. Let $Q_{r}(x)$ denote a cube centered at $x$ with side length $2 r$, Since $|\nabla d|=1$ and $B_{r}(x) \subset Q_{r}(x)$, we see that

$$
\begin{aligned}
{\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu_{2}}}-\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu_{1}}} } & \leq \sup \left\{\left.\frac{1}{r^{n}} \int_{B_{r}(x) \cap \Omega}\left|\nabla d_{\Omega} \cdot v\right| d y \right\rvert\, x \in \partial \Omega, \nu_{1} \leq r<\nu_{2}\right\} \\
& \leq \sup \left\{\left.\frac{1}{r^{n}} \int_{Q_{r}(x)}|\tilde{v}| d y \right\rvert\, x \in \partial \Omega, \nu_{1} \leq r \leq \nu_{2}\right\}
\end{aligned}
$$

where $\tilde{v}$ denotes the zero extension of $v$ to $\mathbf{R}^{n}$. Since $\nu_{2} \leq \delta$ so that $Q_{r}(x) \cap \Omega \subset \Gamma_{\delta}$, we see that

$$
\sup _{x \in \partial \Omega} \int_{Q_{r}(x)}|\tilde{v}| d y \leq\|v\|_{L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)} \quad \text { for } \quad \nu_{1} \leq r \leq \nu_{2}
$$

provided that $\nu_{2}$ is finite by taking an equivalent norm of $L_{\mathrm{u}}^{1}$; in fact, we take $r_{0}=\sqrt{n} \nu_{2}$. This implies that

$$
\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu_{2}}}-\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu_{1}}} \leq \frac{1}{\nu_{1}^{n}}[v]_{\Gamma_{\delta}}
$$

If $\nu_{2}=\delta=\infty$, we may assume $r=2^{\ell} \nu_{1}$. We divide $Q_{r}(x)$ into subcube $Q_{j}, j=1, \ldots, 2^{\ell n}$ of side length $2 \nu_{1}$. Then

$$
\frac{1}{\left|Q_{r}(x)\right|} \int_{Q_{r}(x)}|\tilde{v}| d y \leq \frac{1}{2^{\ell n}\left(2 \nu_{1}\right)^{n}} \sum_{j=1}^{2^{\ell n}} \int_{Q_{j}}|\tilde{v}| d y \leq \frac{2^{\ell n}}{2^{\ell n}\left(2 \nu_{1}\right)^{n}}\|\tilde{v}\|_{L_{\mathrm{u} 1}^{1}} \leq \frac{1}{\left(2 \nu_{1}\right)^{n}}\|\tilde{v}\|_{L_{\mathrm{ul}}^{1}}
$$

where $r_{0}$ in $L_{\mathrm{ul}}^{1}$ norm is taken as $\sqrt{n} \nu_{1}$. We thus observe that

$$
[\nabla d \cdot v]_{b^{\nu_{2}}}-[\nabla d \cdot v]_{b^{\nu_{1}}} \leq c[v]_{\Gamma_{\delta}}
$$

By Proposition 3.2.1 and 3.2.5, we do not need to care about $\nu$. More precisely,
Theorem 3.2.6. Let $\Omega$ be an arbitrary domain in $\mathbf{R}^{n}$. Assume that $\mu \in(0, \infty]$ and that $\delta \in(0, \infty]$. Then norms $\|\cdot\|_{v b m o}{ }_{\delta}^{\mu, \nu_{1}}$ and $\|\cdot\|_{v b m o_{\delta}^{\mu, \nu_{2}}}$ are equivalent provided that $0<\nu_{1}<\nu_{2}<\infty$. In the case $\delta=\infty$, we may take $\nu_{2}=\infty$.

In general, different from Theorem 3.2.3, the space $v B M O^{\mu, \nu}$ may not be included in $b m o_{\nu}^{\mu}$ even for finite $\mu$ by the decomposition (3.2.1) and the fact that $B M O^{\mu}$ is not contained in $L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)$ for any $\delta$. However, if each connected component of the boundary $\Gamma$ of $\Omega$ has a curved part, we are able to compare these spaces.
Definition 3.2.7. Let $\Omega$ be a uniformly $C^{1}$ domain in $\mathbf{R}^{n}$ and $\Gamma^{0}$ be a connected component of the boundary $\Gamma$ of $\Omega$. We say that $\Gamma^{0}$ has a fully curved part if the set of all normals of $\Gamma^{0}$ spans $\mathbf{R}^{n}$. In other words, the set $\left\{\mathbf{n}(x) \in \mathbf{R}^{n} \mid x \in \Gamma^{0}\right\}$ contains $n$ linearly independent vectors, when $\mathbf{n}$ denotes the unit exterior normal of $\Gamma^{0}$.

We introduce $b^{\nu}\left(\Gamma^{0}\right)$-seminorm for convenience. Let us decompose $\Gamma$ into its connected component $\Gamma^{j}$ so that $\Gamma=\bigcup_{j=1}^{m} \Gamma^{j}$. We set

$$
[f]_{b^{\nu}\left(\Gamma^{j}\right)}:=\sup \left\{r^{-n} \int_{\Omega \cap B_{r}(x)}|f(y)| d y \mid x \in \Gamma^{j}, 0<r<\nu\right\}
$$

Evidently, $[f]_{b^{\nu}}=\max _{1 \leq j \leq m}[f]_{b^{\nu}\left(\Gamma^{j}\right)}$ at least for small $\nu>0$.
The existence of a fully curved part implies "non-degeneracy" of the seminorm $[\nabla d \cdot f]_{b^{\nu}}$.
Lemma 3.2.8. Let $\Omega$ be a uniformly $C^{2}$ domain in $\mathbf{R}^{n}$. Let $\Gamma^{j}$ be a connected component of the boundary $\Gamma$ of $\Omega$. If $c \in \mathbf{R}^{n}$ satisfies

$$
\left[\nabla d_{\Omega} \cdot c\right]_{b^{\nu}\left(\Gamma^{j}\right)}=0
$$

for some $\nu>0$, then $c=0$ provided that $\Gamma^{j}$ has a fully curved part.
Proof. If $\Omega$ is uniformly $C^{2}$, then $d_{\Omega}$ is $C^{2}$ in $\left(\Gamma^{j}\right)_{\delta}$ for sufficiently small $\delta>0$. Since $-\nabla d_{\Omega}(x)$ at $x \in \Gamma^{j}$ equals $\mathbf{n}(x)$, we see that

$$
\frac{1}{r^{n}} \int_{B_{r}(x) \cap \Omega} \nabla d_{\Omega}(y) d y \rightarrow c_{0} \mathbf{n}(x) \quad \text { as } \quad r \rightarrow 0
$$

with scalar constant $c_{0}$. Our assumption now implies that $c \cdot \mathbf{n}(x)=0$ for $x \in \Gamma^{j}$. If $\Gamma^{j}$ has a curved part, then by definition this implies that $c=0$.

Here is a few comments on examples of such domains. All connected components of the boundary of a bounded domain, exterior domain has a fully curved part. A perturbed half space

$$
\mathbf{R}_{\psi}^{n}=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n} \mid x_{n}>\psi\left(x^{\prime}\right), x^{\prime}=\left(x_{1}, \ldots, x_{n-1}\right) \in \mathbf{R}^{n-1}\right\}
$$

with $\psi \in C_{c}^{1}\left(\mathbf{R}^{n-1}\right), \psi \not \equiv 0$ is another example. However, a half-space $\mathbf{R}_{+}^{n}$, cylindrical domain $G \times \mathbf{R}^{n-k}$ with $k \geq 1, G \subset \mathbf{R}^{k}$ does not have a boundary having a fully curved part. Our goal is to show that for a domain with boundary components having a fully curved part the space $v B M O^{\mu, \nu}$ is comparable with $v b m o_{\delta}^{\mu, \nu}$ space if the boundary is compact.

Theorem 3.2.9. Let $\Omega$ be a $C^{2}$ bounded or exterior domain in $\mathbf{R}^{n}$ so that each component of the boundary has a fully curved part. For $\mu \in(0, \infty]$ and $\nu \in\left(0, R_{*}\right)$ the identity holds:

$$
v B M O^{\mu, \nu}(\Omega)=v b m o_{\nu}^{\mu, \nu}
$$

Proof. Let $\Gamma^{j}$ be a $j$-th connected component of the boundary $\Gamma=\partial \Omega$ such that $\Gamma=$ $\bigcup_{j=1}^{m} \Gamma^{j}$. Since $\Gamma^{j}$ is $C^{2}$ and compact, there is a number $r_{0} \in(0, \nu / 2)$ such that

$$
\left(\Gamma^{j}\right)_{\nu}=\bigcup_{x \in \Lambda} \operatorname{int} B_{r_{0}}(x), \quad \Lambda \subset\left(\Gamma^{j}\right)_{\nu}
$$

where $\Gamma^{j}$ is a connected component of $\Gamma$ and $\left(\Gamma^{j}\right)_{\nu}$ denotes its $\nu$-neighborhood. The next lemma shows that

$$
v B M O^{\nu, \nu}(\Omega) \subset L_{\mathrm{ul}}^{1}\left(\Gamma_{\nu}\right)
$$

which yields the desired result. Note that we may assume $\nu \leq \mu$ by Proposition 3.2.1.
Lemma 3.2.10. Under the same assumption of Theorem 3.2.9 with $\mu \leq \nu$ assume that $r_{0}<\nu / 2<R_{*} / 2$ is taken so that

$$
\left(\Gamma^{i}\right)_{\nu}=\bigcup_{x \in \Lambda} \operatorname{int} B_{r_{0}}(x)
$$

with some $\Lambda \subset\left(\Gamma^{j}\right)_{\nu}$. Then there exists $C>0$ depending only on $r_{0}, n, \Gamma^{j}, \nu$ such that

$$
\sup _{x \in \Lambda} \frac{1}{\left|B_{r_{0}}(x)\right|} \int_{B_{r_{0}}(x)}|f(y)| d y \leq C\left([f]_{B M O^{\mu}\left(\left(\Gamma^{j}\right)_{\nu}\right)}+\left[\nabla d_{\Omega} \cdot f\right]_{b^{\nu}\left(\Gamma^{j}\right)}\right)
$$

Proof. We shall suppress $r_{0}$ dependence since it is fixed. We shall prove the average $f_{B(x)}=$ $\frac{1}{|B(x)|} \int_{B(x)} f d y$ has an estimate

$$
\begin{equation*}
\sup _{x \in \Lambda}\left|f_{B(x)}\right| \leq C\left([f]_{B M O^{\mu}\left(\left(\Gamma^{j}\right)_{\nu}\right)}+[\nabla d \cdot f]_{b^{\nu}\left(\Gamma^{j}\right)}\right) \tag{3.2.2}
\end{equation*}
$$

If this is proved, applying the triangle inequality

$$
(|f|)_{B(x)} \leq \frac{1}{|B(x)|} \int_{B(x)}\left|f-f_{B(x)}\right| d y+\left|f_{B(x)}\right|
$$

yields the desired result.
We shall prove the key inequality (3.2.2) by contradiction argument. Assume the inequality (3.2.2) were false. Then, there would exist a sequence $\left\{f^{k}\right\}_{k=1}^{\infty}$ such that

$$
1=\sup _{x \in \Lambda}\left|f_{B(x)}^{k}\right| \geq k\left(\left[f^{k}\right]_{B M O^{\mu}}+\left[\nabla d_{\Omega} \cdot f^{k}\right]_{b^{\nu}}\right)
$$

Here we suppress $\left(\Gamma^{i}\right)_{\nu}$ and $\Gamma^{j}$ in the right-hand side. Since

$$
\sup _{x \in \Lambda}\left|c^{k}(x)\right|=1 \quad \text { with } \quad c^{k}(x)=f_{B(x)}^{k} \in \mathbf{R}^{n}
$$

there is a sequence $\left\{x_{k}\right\}_{k=1}^{\infty}$ in $\Lambda$ with the property

$$
1 \geq\left|c^{k}\left(x_{k}\right)\right| \geq 1 / 2
$$

By taking a subsequence, we may assume that $x_{k}$ converges to some $\hat{x} \in\left(\Gamma^{j}\right)_{\nu}$ since $\Gamma^{j}$ is compact and $d\left(x_{k}, \partial\left(\Gamma^{j}\right)_{\nu}\right) \geq r_{0}$, where $d\left(x_{k}, A\right)$ denotes the distance from a point $x_{k}$ to a set $A$. Since $\Gamma^{j}$ is connected, there is an increasing sequence $\left\{K_{\ell}\right\}_{\ell=1}^{\infty}$ of connected compact sets in $\left(\Gamma^{j}\right)_{\nu}$ such that int $K_{\ell} \ni \hat{x}$ for $\ell \geq 1$ and $\left(\Gamma^{j}\right)_{\nu}=\bigcup_{\ell=1}^{\infty} K_{\ell}$. By compactness, there is a finite subset $\Lambda_{\ell}$ of $\Lambda$ with the property that

$$
K_{\ell} \subset \bigcup_{x \in \Lambda_{\ell}} \operatorname{int} B(x), \quad \Lambda_{\ell} \subset \Lambda_{\ell+1}
$$

and the right-hand side is connected. By taking a further subsequence, we may assume that $c^{k}(x) \rightarrow c(x)$ for $x \in \Lambda_{\ell}$. However, since $\left[f^{k}\right]_{B M O^{\mu}} \rightarrow 0$ so that

$$
\int_{B(x)}\left|f^{k}-c^{k}\right| d x \rightarrow 0
$$

as $k \rightarrow \infty$, we see that $c(x)=c(y)$ if $\operatorname{int} B(x) \cap \operatorname{int} B(y) \neq \emptyset$. Since

$$
\bigcup_{x \in \Lambda_{\ell}} \operatorname{int} B(x)
$$

is connected, $c(x)$ is independent of $x \in \Lambda_{\ell}$, say $c=c_{\ell}$. By taking a further subsequence of $\left\{f^{k}\right\}$, we may assume that $c^{k}(x) \rightarrow c_{\ell}$ in $\Lambda_{\ell}$. By a diagonal argument, there is a subsequence of $\left\{f^{k}\right\}$ such that

$$
c^{k}(x) \rightarrow c \quad \text { for } \quad x \in \bigcup_{\ell=1}^{\infty} \Lambda_{\ell}=: \Lambda_{\infty} \subset \Lambda
$$

We thus observe that

$$
\int_{B(x)}\left|f^{k}(y)-c\right| d y \rightarrow 0 \quad \text { for } \quad x \in \Lambda_{\infty} \quad \text { as } \quad k \rightarrow \infty
$$

If we take $B(x)$ such that $\hat{x} \in \operatorname{int} B(x), c$ should not be equal to zero since $\left|c^{k}\left(x_{k}\right)\right| \geq 1 / 2$ and $x_{k} \rightarrow \hat{x}$ as $k \rightarrow \infty$. We now invoke the property that

$$
\left[\nabla d_{\Omega} \cdot f^{k}\right]_{b^{\nu}} \rightarrow 0 .
$$

Since

$$
\left(\Gamma^{j}\right)_{\nu}=\bigcup_{x \in \Lambda_{\infty}} B(x),
$$

we observe that $f^{k} \rightarrow c$ in $L_{\text {loc }}^{1}\left(\left(\Gamma^{j}\right)_{\nu}\right)$. By taking a subsequence we may assume that $f^{k}(x) \rightarrow c$ for a.e. $x \in\left(\Gamma^{j}\right)_{\nu}$ so that $\nabla d_{\Omega} \cdot f^{k} \rightarrow \nabla d_{\Omega} \cdot c$, a.e. By lower semicontinuity of integrals (Fatou's lemma) and supremum operation, the seminorm $b^{\nu}$ is lower semicontinuous under this convergence. We thus conclude that

$$
\left[\nabla d_{\Omega} \cdot c\right]_{b^{\nu}} \leq \lim _{k \rightarrow \infty}\left[\nabla d_{\Omega} \cdot f^{k}\right]_{b^{\nu}}=0
$$

By Lemma 3.2.8, this $c$ must be zero which leads to a contradiction. We thus proved the key estimate (3.2.2). This completes the proof of Lemma 3.2.10.

### 3.3 A variant of Jones' extension theorem

Different from $L^{\infty}$ functions, it is in general impossible to extend $B M O$ function by setting zero outside the domain. Indeed, the zero-extension of $\log \min (x, 1) \in b m o_{\infty}^{\infty}\left(\mathbf{R}_{+}^{1}\right)$ does not belong to $B M O^{\infty}(\mathbf{R})$. The goal in this section is to give a linear, extention operator of $B M O$ type function so that the support of extended function is contained in an $\varepsilon$ neighborhood of the original domain, of a function.

For this purpose we recall an extension given by P. W. Jones [15]. Since we modify the way of construction, we will give a sketch of this construction. We first recall a dyadic Whitney decomposition of a set $A$ in $\mathbf{R}^{n}$. Let $\mathcal{A}=\left\{Q_{j}\right\}_{j \in \mathbf{N}}$ be a set of dyadic closed cubes with side length $\ell\left(Q_{j}\right)$ contained in $A$ satisfying following four conditions.
(i) $A=\cup_{j} Q_{j}$,
(ii) $\operatorname{int} Q_{j} \cap \operatorname{int} Q_{k}=\emptyset$ if $j=k$,
(iii) $\sqrt{n} \leq d\left(Q_{j}, \mathbf{R}^{n} \backslash A\right) / \ell\left(Q_{j}\right) \leq 4 \sqrt{n}$ for all $j \in \mathbf{N}$,
(iv) $1 / 4 \leq \ell\left(Q_{k}\right) / \ell\left(Q_{j}\right) \leq 4$ if $Q_{j} \cap Q_{k} \neq \emptyset$.

We say that $\mathcal{A}$ is called a dyadic Whitney decomposition of $A$. Such a decomposition exists for any open sets; see [18, Chapter VI, Theorem 1]. Here $d(B, C)$ for sets $B, C$ in $\mathbf{R}^{n}$ is defined as

$$
d(B, C)=\inf \{|x-y| \mid x \in B, y \in C\}
$$

If $B$ is a point $x$, we write $d(x, C)$ instead of $d(\{x\}, C)$.
There are at least two important distance functions on $\mathcal{A}$. For $Q_{j}, Q_{k} \in \mathcal{A}$, a family $\{Q(\ell)\}_{\ell=0}^{m} \subset \mathcal{A}$ is called a Whitney chain of length $m$ if $Q(0)=Q_{j}$ and $Q(m)=Q_{k}$ such that $Q(\ell) \cap Q(\ell+1) \neq \emptyset$ for $\ell$ with $0 \leq \ell \leq m-1$. Then the length of the shortest Whitney chain connecting $Q_{j}$ and $Q_{k}$ gives a distance on $\mathcal{A}$, which is denoted by $d_{1}\left(Q_{j}, Q_{k}\right)$. The second distance for $Q_{j}, Q_{k} \in \mathcal{A}$ is defined as

$$
d_{2}\left(Q_{j}, Q_{k}\right):=\log \left|\frac{\ell\left(Q_{j}\right)}{\ell\left(Q_{k}\right)}\right|+\log \left|\frac{\ell\left(Q_{j}, Q_{k}\right)}{\ell\left(Q_{j}\right)+\ell\left(Q_{k}\right)}+1\right|
$$

Note that $d_{1}$ and $d_{2}$ are invariant under dilation as well as translation and rotation. P. W. Jones [15] gives a necessary and sufficient condition for a domain such that there exists a linear extension operator. A domain $\Omega$ is called a uniform domain if there exist constants $a, b>0$ such that for all $x, y \in \Omega$ there exists a rectifiable curve $\gamma \subset \Omega$ of length $s(\gamma) \leq$ $a|x-y|$ with $\min \{s(\gamma(x, z)), s(\gamma(y, z))\} \leq b d(z, \partial \Omega)$, where $\gamma(x, z)$ denotes the part of $\gamma$ between $x$ and $z$ on the curve; see e.g. [8]. It is equivalent to saying that there is a constant $K>0$ such that

$$
\begin{equation*}
d_{1}\left(Q_{j}, Q_{k}\right) \leq K d_{2}\left(Q_{j}, Q_{k}\right) \tag{3.3.1}
\end{equation*}
$$

for all $Q_{j}, Q_{k} \in \mathcal{A}$ and some dyadic Whitney decomposition $\mathcal{A}$ of $\Omega$.
Theorem 3.3.1. Let $A \subset \mathbf{R}^{n}$ be a uniform domain. Then there is a constant $C(K)$ depending only on $K$ in (3.3.1) such that for each $f \in B M O^{\infty}(A)$ there is an extension $\bar{f} \in B M O^{\infty}\left(\mathbf{R}^{n}\right)$ satisfying

$$
[\bar{f}]_{B M O^{\infty}\left(\mathbf{R}^{n}\right)} \leq C(K)[f]_{B M O^{\infty}(A)}
$$

The operator $f \mapsto \bar{f}$ is a bounded linear operator. Conversely, if there exists such an extension, then $A$ is a uniform domain.

A bounded Lipschitz domain is a typical example of a uniform domain. The constant $K$ in (3.3.1) depends only on the Lipschitz regularity of the domain. A Lipschitz half space $\mathbf{R}_{\psi}^{n}$ is another example of a uniform domain; here $\psi$ is a Lipschitz function on $\mathbf{R}^{n-1}$.

We next note that if we modify the construction by P. W. Jones, the support of the extension $\bar{f}$ is contained in an $\varepsilon$-neighborhood of $\bar{\Omega}$ if $f$ is also in $L_{\mathrm{ul}}^{1}$ type space.

Theorem 3.3.2. Let $\Omega \subset \mathbf{R}^{n}$ be a uniform domain. For each $\varepsilon>0$ there is a constant $\underline{C}=C(K, \varepsilon)$ with $K$ in (3.3.1) such that for each $f \in b m_{\infty}^{\infty}(\Omega)$ there is an extension $\bar{f} \in b m o_{\infty}^{\infty}\left(\Omega_{2 \varepsilon}\right)$ such that

$$
[f]_{b m o_{\infty}^{\infty}\left(\Omega_{2 \varepsilon}\right)} \leq C[f]_{b m o_{\infty}^{\infty}(\Omega)}
$$

and $\operatorname{supp} \bar{f} \subset \overline{\Omega_{\varepsilon}}$, where

$$
\Omega_{\varepsilon}:=\left\{x \in \mathbf{R}^{n} \mid d(x, \bar{\Omega})<\varepsilon\right\} .
$$

The operator $f \mapsto \bar{f}$ is a bounded linear operator.
This can be proved almost along the same way as in [15]. We shall give an explicit proof.

Proof. Let $k_{\varepsilon}$ be the smallest integer such that $2^{-k_{\varepsilon}}<\frac{\varepsilon}{5 \sqrt{n}}$. So $2^{-k_{\varepsilon}} \geq \frac{\varepsilon}{10 \sqrt{n}}$. Let $E=\left\{Q_{j}\right\}$ be the Whitney decomposition of $\Omega$ and $E^{\prime}=\left\{Q_{j}^{\prime}\right\}$ be the Whitney decomposition of $\Omega^{c}$. Let $E_{*}$ be the set of Whitney cubes in $E$ whose side length is strictly greater than $2^{-k_{\varepsilon}}$. For each $Q_{m} \in E_{*}$, we define a function $g_{m}$ on $\Omega$ by

$$
g_{m}(x):= \begin{cases}f_{Q_{m}}, & \text { if } x \in Q_{m} \\ 0, & \text { else }\end{cases}
$$

and we further define a function $g$ on $\Omega$ by

$$
g:=\sum_{Q_{m} \in E_{*}} g_{m} .
$$

Here $f_{Q_{m}}=\frac{1}{\left|Q_{m}\right|} \int_{Q_{m}} f(y) d y$ for each $Q_{m} \in E_{*}$. Let $\widetilde{g}$ be the zero extension of $g$ from $\Omega$ to $\mathbf{R}^{n}$.

Without loss of generality, we assume that the radius $r_{0}$ of the ball equals 1 in defining the space $L_{\mathrm{ul}}^{1}(\Omega)$. Notice that

$$
\left\|g_{m}\right\|_{L^{\infty}(\Omega)} \leq \frac{1}{\left|Q_{m}\right|} \cdot \int_{Q_{m}}|f| d y
$$

Let $k_{0}$ be the smallest integer such that $2^{-k_{0}}<\frac{2}{\sqrt{n}}$. If $\ell\left(Q_{m}\right) \leq 2^{-k_{0}}$, then $\|f\|_{L^{1}\left(Q_{m}\right)} \leq$ $\left.{ }_{[f}\right]_{\Gamma_{\infty}}$. In this case, as $\ell\left(Q_{m}\right)>2^{-k_{\varepsilon}}$,

$$
\left\|g_{m}\right\|_{L^{\infty}(\Omega)} \leq \frac{1}{\left|Q_{m}\right|} \cdot \int_{Q_{m}}|f| d y \leq\left(\frac{10 \sqrt{n}}{\varepsilon}\right)^{n} \cdot[f]_{\Gamma_{\infty}}
$$

If $\ell\left(Q_{m}\right)>2^{-k_{0}}$, we divide $Q_{m}$ into $\left(\frac{\ell\left(Q_{m}\right)}{2^{-k_{0}}}\right)^{n}$ small subcubes of side length $2^{-k_{0}}$. Hence,

$$
\int_{Q_{m}}|f| d y=\sum_{i=1}^{\left(\ell\left(Q_{m}\right) / 2^{-k_{0}}\right)^{n}} \int_{Q_{m}^{i}}|f| d y \leq\left(\frac{\ell\left(Q_{m}\right)}{2^{-k_{0}}}\right)^{n} \cdot[f]_{\Gamma_{\infty}} \leq\left|Q_{m}\right| \cdot n^{\frac{n}{2}} \cdot[f]_{\Gamma_{\infty}},
$$

in this case $\left\|g_{m}\right\|_{L^{\infty}(\Omega)} \leq n^{\frac{n}{2}} \cdot[f]_{\Gamma_{\infty}}$. Therefore,

$$
\|g\|_{L^{\infty}(\Omega)} \leq C_{n, \varepsilon} \cdot[f]_{\Gamma_{\infty}}
$$

and we deduce that $g \in b m o_{\infty}^{\infty}(\Omega)$ as $L^{\infty}(\Omega) \subset b m o_{\infty}^{\infty}(\Omega)$.
Let $f^{*}:=f-g \in b m o_{\infty}^{\infty}(\Omega)$. We do Jones extension to $f^{*}$. If $\Omega$ is unbounded, for each $Q_{j}^{\prime} \in E^{\prime}$, we find a nearset $Q_{j} \in E$ satisfying $\ell\left(Q_{j}\right) \geq \ell\left(Q_{j}^{\prime}\right)$. We define that $\widetilde{f^{*}}=f^{*}$ on $\Omega$ and $\widetilde{f}^{*}(x)=f_{Q_{j}}^{*}$ for $x \in Q_{j}^{\prime}$. If $\Omega$ is bounded, we pick $Q_{0} \in E$ such that $\ell\left(Q_{0}\right)=$ $\sup _{Q_{j} \in E} \ell\left(Q_{j}\right)$. We define that $\widetilde{f}^{*}=f^{*}$ on $\Omega, \widetilde{f}^{*}(x)=f_{Q_{j}}^{*}$ for $x \in Q_{j}^{\prime}$ where $\ell\left(Q_{j}^{\prime}\right) \leq \ell\left(Q_{0}\right)$ and $\tilde{f}^{*}(x)=f_{Q_{0}}^{*}$ for $x \in Q_{j}^{\prime}$ where $\ell\left(Q_{j}\right)>\ell\left(Q_{0}\right)$. By Jones [?PJ], $\tilde{f}^{*} \in B M O$ and $\left[\tilde{f}^{*}\right]_{B M O} \leq C_{K} \cdot\left[f^{*}\right]_{B M O \infty}(\Omega)$. By this extension, for $\widetilde{f}^{*}(x) \neq 0$, either $x \in \Omega$ or $x \in Q_{j}^{\prime}$ such that $\ell\left(Q_{j}^{\prime}\right) \leq 2^{-k_{\varepsilon}}$. Since $d\left(Q_{j}^{\prime}, \Omega\right) \leq 4 \sqrt{n} \cdot \ell\left(Q_{j}^{\prime}\right)$, pick $x \in \overline{Q_{j}^{\prime}}$ and $z \in \Gamma$ such that $|x-z|=d\left(Q_{j}^{\prime}, \Omega\right)$. For any $y \in Q_{j}^{\prime},|y-z| \leq|y-x|+|x-z| \leq 5 \sqrt{n} \cdot \ell\left(Q_{j}^{\prime}\right)$. So $\operatorname{int} Q_{j}^{\prime} \subset B_{5 \sqrt{n} \cdot \ell\left(Q_{j}^{\prime}\right)}(z)$ for some $z \in \Gamma$. Since $5 \sqrt{n} \cdot \ell\left(Q_{j}^{\prime}\right) \leq 5 \sqrt{n} \cdot 2^{-k_{\varepsilon}}<\varepsilon$, int $Q_{j}^{\prime} \subset \Omega_{\varepsilon}$. Let $\tilde{f}:=\tilde{f} *+\widetilde{g}$ and $\bar{f}=\left.\widetilde{f}\right|_{\Omega_{2 \varepsilon}}$, we have that $\operatorname{supp} \bar{f} \subset \overline{\Omega_{\varepsilon}}$ and by previous calculation,

$$
\begin{aligned}
{[\bar{f}]_{B M O^{\infty}\left(\Omega_{2 \varepsilon}\right)} } & \leq[\tilde{f}]_{B M O} \leq\left[\tilde{f}^{*}\right]_{B M O}+[\tilde{g}]_{B M O} \leq C_{K} \cdot\left[f^{*}\right]_{B M O^{\infty}(\Omega)}+2\|g\|_{\infty} \\
& \leq C_{K, n, \varepsilon} \cdot\left([f]_{B M O^{\infty}(\Omega)}+[f]_{\Gamma_{\infty}}\right) .
\end{aligned}
$$

Let $B(x)$ denotes the ball of radius 1 centered at $x$ and $\Gamma^{\varepsilon}:=\left\{x \in \Omega^{c} \mid d_{\Omega}(x)<\varepsilon\right\}$. For $B(x) \cap \Omega_{\varepsilon} \neq \emptyset$,

$$
\int_{B(x) \cap \Omega_{\varepsilon}}|\bar{f}| d y=\int_{B(x) \cap \Omega}|f| d y+\int_{B(x) \cap \Gamma^{\varepsilon}}|\bar{f}| d y .
$$

The first integral on the right hand side is directly estimated by $[f]_{\infty}$, so we only need to consider the second integral. Let $Q_{*}^{\prime}$ be a largest Whitney cube in $E^{\prime}$ that intersects $B(x) \cap \Gamma^{\varepsilon}$. For $Q_{j}^{\prime} \in E^{\prime},\left[15\right.$, Lemma 2.10] says that if $Q_{j} \in E$ is a nearest Whitney cube satisfying $\ell\left(Q_{j}\right) \geq \ell\left(Q_{j}^{\prime}\right)$, then $d\left(Q_{j}, Q_{j}^{\prime}\right) \leq 65 K^{2} \cdot \ell\left(Q_{j}^{\prime}\right)$. Consider $Q_{j}^{\prime} \in E^{\prime}$ such that $Q_{j}^{\prime} \cap B(x) \cap \Gamma^{\varepsilon} \neq \emptyset$, let $x_{j} \in Q_{j}$ where $Q_{j}$ is a nearest Whitney cube satisfying $\ell\left(Q_{j}\right) \geq \ell\left(Q_{j}^{\prime}\right)$, let $x_{j}^{\prime} \in Q_{j}^{\prime} \cap B(x) \cap \Gamma^{\varepsilon}$ and $x_{*}^{\prime} \in Q_{*}^{\prime} \cap B(x) \cap \Gamma^{\varepsilon}$. By choosing $K$ large such that $K^{2} \geq 2 \sqrt{n}$, we have that

$$
\left|x_{j}-x_{*}^{\prime}\right| \leq\left|x_{*}^{\prime}-x_{j}^{\prime}\right|+\left|x_{j}^{\prime}-x_{j}\right| \leq 2+2 \sqrt{n} \cdot \ell\left(Q_{j}^{\prime}\right)+65 K^{2} \cdot \ell\left(Q_{j}^{\prime}\right) \leq 2+66 K^{2} \cdot \ell\left(Q_{j}\right) .
$$

Since $\ell\left(Q_{j}\right) \leq 2 \ell\left(Q_{j}^{\prime}\right) \leq 2 \ell\left(Q_{*}^{\prime}\right) \leq 2 \ell\left(Q_{*}\right)$ where $Q_{*} \in E$ is a nearest cube satisfying $\ell\left(Q_{*}\right) \geq \ell\left(Q_{*}^{\prime}\right),\left|x_{j}-x_{*}^{\prime}\right| \leq 2+132 K^{2} \cdot \ell\left(Q_{*}\right)$.

If $B(x) \cap \Gamma \neq \emptyset$, then $\sqrt{n} \cdot \ell\left(Q_{*}^{\prime}\right) \leq d\left(Q_{*}^{\prime}, \Omega\right) \leq 2$. Hence $\ell\left(Q_{*}\right) \leq 2 \ell\left(Q_{*}^{\prime}\right) \leq \frac{4}{\sqrt{n}}$, for any $x_{j} \in Q_{j},\left|x_{j}-x_{*}^{\prime}\right|<2+133 K^{2} \cdot \frac{4}{\sqrt{n}}$. Consider the cube $\widetilde{Q_{*}^{\prime}}$ with center $x_{*}^{\prime}$ and side length $4+\frac{1064 K^{2}}{\sqrt{n}}$. For each $Q_{j}^{\prime} \in E^{\prime}$ such that $Q_{j}^{\prime} \cap B(x) \cap \Gamma^{\varepsilon} \neq \emptyset$, the corresponding nearest $Q_{j} \in E$ such that $\ell\left(Q_{j}\right) \geq \ell\left(Q_{j}^{\prime}\right)$ we choose to define $\widetilde{f^{*}}$ is contained in $\widetilde{Q_{*}^{\prime}}$, i.e., $Q_{j} \subset \widetilde{Q_{*}^{\prime}}$. Hence,

$$
\int_{B(x) \cap \Gamma^{\varepsilon}}|\bar{f}| d y=\sum_{\substack{Q_{j}^{\prime} \in E^{\prime}, Q_{j}^{\prime} \cap B(x) \cap \Gamma^{\varepsilon} \neq \emptyset}} \int_{Q_{j}^{\prime} \cap B(x) \cap \Gamma^{\varepsilon}}\left|f_{Q_{j}}^{*}\right| d y \leq \int_{{\widetilde{Q_{*}^{\prime}} \cap \Omega}\left|f^{*}\right| d y .}
$$

Let $p$ be the largest integer such that $2^{-p}>4+\frac{1064 K^{2}}{\sqrt{n}}$, so $2^{-p} \leq 8+\frac{2128 K^{2}}{\sqrt{n}}$. Let $\widetilde{Q_{*}^{\prime}}$ be contained in a larger cube $\widetilde{Q}$ where $\widetilde{Q}$ has center $x_{*}^{\prime}$ and side length $2^{-p}$. We can divide $\widetilde{Q}$ into $\left(\frac{2^{-p}}{2^{-k_{0}}}\right)^{n}$ subcubes of side length $2^{-k_{0}}$, thus

$$
\int_{\widetilde{Q_{*}^{\prime}} \cap \Omega}\left|f^{*}\right| d y \leq \sum_{i=1}^{\left(2^{-p} / 2^{-k_{0}}\right)^{n}} \int_{\widetilde{Q_{i}} \cap \Omega}\left|f^{*}\right| d y \leq\left(\frac{2^{-p}}{2^{-k_{0}}}\right)^{n} \cdot\left[f^{*}\right]_{\Gamma_{\infty}} \leq C_{K, n} \cdot\left[f^{*}\right]_{\Gamma_{\infty}}
$$

If $B(x) \cap \Gamma=\emptyset$, i.e., $B(x) \subset \bar{\Omega}^{c}$. Let $E_{1}^{\prime}:=\left\{Q_{j}^{\prime} \in E^{\prime} \mid Q_{j}^{\prime} \cap B(x) \neq \emptyset\right\}$. Let $\ell_{m}:=$ $\inf _{Q_{j}^{\prime} \in E_{1}^{\prime}} \ell\left(Q_{j}^{\prime}\right)$ and $Q_{*}^{\prime}$ be a largest $Q_{j}^{\prime} \in E_{1}^{\prime}$. If $\ell_{m}=0$, then there exists $z \in \Gamma \cap \partial B(x)$. In this case, $\sqrt{n} \cdot \ell\left(Q_{*}^{\prime}\right) \leq d\left(Q_{*}^{\prime}, \Omega\right) \leq 2$. Therefore same argument as in the case where $B(x) \cap \Gamma \neq \emptyset$ gives that $\|\bar{f}\|_{L^{1}\left(B(x) \cap \Gamma^{\varepsilon}\right)} \leq C_{K, n} \cdot\left[f^{*}\right]_{\infty}$. If $0<\ell_{m} \leq 2$, then pick $Q_{m}^{\prime} \in E_{1}^{\prime}$ such that $\ell\left(Q_{m}^{\prime}\right)=\ell_{m}$. Since $\sqrt{n} \cdot \ell\left(Q_{*}^{\prime}\right) \leq d\left(Q_{*}^{\prime}, \Omega\right) \leq 2+\sqrt{n} \cdot \ell\left(Q_{m}^{\prime}\right)+d\left(Q_{m}^{\prime}, \Omega\right) \leq 2+10 \sqrt{n}$, we have that $\ell\left(Q_{*}\right) \leq \frac{4}{\sqrt{n}}+20$. Hence $\left|x_{j}-x_{*}^{\prime}\right| \leq 2+133 K^{2} \cdot\left(\frac{4}{\sqrt{n}}+20\right)$. Following the argument as in the case where $B(x) \cap \Gamma \neq \emptyset$, we can deduce that $\|\bar{f}\|_{L^{1}\left(B(x) \cap \Gamma^{\varepsilon}\right)} \leq C_{K, n} \cdot\left[f^{*}\right]_{\Gamma_{\infty}}$. If $\ell_{m}>2$, then $B(x)$ intersects at most $2^{n}$ Whitney cubes in $E^{\prime}$. Without loss of generality, assume that $E_{1}^{\prime}$ has $2^{n}$ elements. Then

$$
\int_{B(x) \cap \Gamma^{\varepsilon}}|\bar{f}| d y \leq \sum_{Q_{i}^{\prime} \in E_{1}^{\prime}} \int_{B(x) \cap Q_{i}^{\prime}}\left|f_{Q_{i}}^{*}\right| d y \leq \sum_{Q_{i}^{\prime} \in E_{1}^{\prime}} \frac{\left|B(x) \cap Q_{i}^{\prime}\right|}{\left|Q_{i}\right|} \cdot \int_{Q_{i}}\left|f^{*}\right| d y
$$

Divide $Q_{i}$ into $\left(\frac{\ell\left(Q_{i}\right)}{2^{-k_{0}}}\right)^{n}$ subcubes of side length $2^{-k_{0}}$, we have that

$$
\int_{Q_{i}}\left|f^{*}\right| d y \leq\left(\frac{\ell\left(Q_{i}\right)}{2^{-k_{0}}}\right)^{n} \cdot\left[f^{*}\right]_{\Gamma_{\infty}} \leq\left|Q_{i}\right| \cdot n^{\frac{n}{2}} \cdot\left[f^{*}\right]_{\Gamma_{\infty}}
$$

Therefore,

$$
\int_{B(x) \cap \Gamma^{\varepsilon}}|\bar{f}| d y \leq\left(\sum_{Q_{i}^{\prime} \in E_{1}^{\prime}}\left|B(x) \cap Q_{i}^{\prime}\right|\right) \cdot n^{\frac{n}{2}} \cdot\left[f^{*}\right]_{\Gamma_{\infty}} \leq C_{n} \cdot\left[f^{*}\right]_{\Gamma_{\infty}}
$$

Since $\left[f^{*}\right]_{\Gamma_{\infty}} \leq[f]_{\Gamma_{\infty}}+[g]_{\Gamma_{\infty}}$ and $[g]_{\Gamma_{\infty}}$ is estimated by $C_{n, \varepsilon} \cdot[f]_{\Gamma_{\infty}}$, we are done.
As an application we give an estimate for the product of a Hölder function and a function in $b m o_{\infty}^{\infty}$. We first recall properties of point multipliers. It is known that for a local hardy space $h^{1}=F_{1,2}^{0}[16$, Theorem 3.18], there is a constant $C$ such that

$$
\begin{equation*}
\|\varphi g\|_{F_{1,2}^{0}} \leq C\|\varphi\|_{C^{\gamma}}\|g\|_{F_{1,2}^{0}} \quad g \in F_{1,2}^{0} \tag{3.3.2}
\end{equation*}
$$

for $\varphi \in C^{\gamma}\left(\mathbf{R}^{n}\right), \gamma \in(0,1)$, where

$$
\|\varphi\|_{C^{\gamma}}=\sup _{x \in \mathbf{R}^{n}}|\varphi(x)|+\sup _{\substack{x, y \in \mathbf{R}^{n} \\ x \neq y}}|\varphi(x)-\varphi(y)| /|x-y|^{\gamma}
$$

see e.g. [16, Remark 4.4]. Since

$$
b m o=B M O^{\infty}\left(\mathbf{R}^{n}\right) \cap L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)
$$

equals to $F_{\infty, 2}^{0}\left[16\right.$, Theorem 3.26], it is a dual space of $h^{1}=F_{1,2}^{0}[16$, Theorem 3.22]. Thus

$$
\begin{equation*}
\|\varphi f\|_{b m o} \leq C\|\varphi\|_{C^{\gamma}}\|f\|_{b m o} \tag{3.3.3}
\end{equation*}
$$

Theorem 3.3.3. Let $\Omega \subset \mathbf{R}^{n}$ be a uniform domain. Let $\varphi \in C^{\gamma}(\Omega), \gamma \in(0,1)$. For each $f \in b m o_{\infty}^{\infty}(\Omega)$, the function $\varphi f \in b m o_{\infty}^{\infty}(\Omega)$ satisfies

$$
\|\varphi f\|_{b m o_{\infty}^{\infty}(\Omega)} \leq C\|\varphi\|_{C^{\gamma}(\Omega)}\|f\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

with $C$ independent of $\varphi$ and $f$.
Proof. By [13], there exists $\bar{\varphi} \in C^{\gamma}\left(\mathbf{R}^{n}\right)$ such that $\left.\bar{\varphi}\right|_{\Omega}=\varphi$ and

$$
\|\bar{\varphi}\|_{C^{\gamma}\left(\mathbf{R}^{n}\right)} \leq\|\varphi\|_{C^{\gamma}(\Omega)}
$$

For our current purpose it suffices to set $\bar{\varphi}=\max \left\{\min \left\{\varphi_{*},\|\varphi\|_{\infty}\right\},-\|\varphi\|_{\infty}\right\}$ with

$$
\varphi_{*}(x)=\inf _{y \in \Omega}\left\{\varphi(y)+[\varphi]_{C^{\gamma}} \cdot|x-y|^{\gamma}\right\}
$$

where $\|\varphi\|_{C^{\gamma}(\Omega)}=\|\varphi\|_{L^{\infty}(\Omega)}+[\varphi]_{C^{\gamma}(\Omega)},\|\varphi\|_{L^{\infty}(\Omega)}=\sup _{x \in \Omega}|\varphi(x)|$ and $[\varphi]_{C^{\gamma}(\Omega)}=\sup _{x, y \in \Omega} \frac{|\varphi(x)-\varphi(y)|}{|x-y|^{\gamma}} ;$ we often suppress $\Omega$. By definition $\varphi_{*}(x) \leq \varphi(x)$. Moreover, since $\varphi(x) \leq \varphi(y)+[\varphi]_{C^{\gamma}}$. $|x-y|^{\gamma}$ for $x, y \in \Omega$, we see that $\varphi(x) \leq \varphi_{*}(x)$ which implies $\varphi=\varphi_{*}$ on $\Omega$. For any $x \in \mathbf{R}^{n}$ and $\varepsilon>0$ there is $y_{\varepsilon} \in \Omega$ such that

$$
\varphi\left(y_{\varepsilon}\right)+[\varphi]_{C^{\gamma}} \cdot\left|x-y_{\varepsilon}\right|^{\gamma} \leq \varphi_{*}(x)+\varepsilon
$$

For $x_{1} \in \mathbf{R}^{n}$ we observe that
$\varphi_{*}\left(x_{1}\right)-\varphi_{*}(x) \leq \varphi\left(y_{\varepsilon}\right)+[\varphi]_{C^{\gamma}} \cdot\left|x_{1}-y_{\varepsilon}\right|^{\gamma}-\left\{\varphi\left(y_{\varepsilon}\right)+[\varphi]_{C^{\gamma}} \cdot\left|x-y_{\varepsilon}\right|^{\gamma}\right\}+\varepsilon \leq[\varphi]_{C^{\gamma}} \cdot\left|x-x_{1}\right|^{\gamma}+\varepsilon$.
Since $\varepsilon$ is arbitrary, we see that $\varphi_{*}\left(x_{1}\right)-\varphi_{*}(x) \leq[\varphi]_{C^{\gamma}} \cdot\left|x-x_{1}\right|^{\gamma}$. Interchanging the role of $x_{1}$ and $x$, we conclude that

$$
\left[\varphi_{*}\right]_{C^{\gamma}\left(\mathbf{R}^{n}\right)} \leq[\varphi]_{C^{\gamma}(\Omega)}
$$

Since $\|\varphi\|_{\infty}<\infty, \bar{\varphi}=\varphi$ on $\Omega$ and $\bar{\varphi}$ is still Hölder. More precisely, $[\bar{\varphi}]_{C^{\gamma}} \leq\left[\varphi_{*}\right]_{C^{\gamma}}$. By definition $\|\bar{\varphi}\|_{\infty} \leq\|\varphi\|_{\infty}$ so we conclude that $\|\bar{\varphi}\|_{C^{\gamma}} \leq\|\varphi\|_{C^{\gamma}}$.

Extending $f \in b m o_{\infty}^{\infty}(\Omega)$ to $\bar{f} \in b m o$ by Theorem 3.3.2, we conclude from multiplication estimate (3.3.3) that

$$
\begin{aligned}
\|\varphi f\|_{b m o_{\infty}^{\infty}(\Omega)} & \leq\|\bar{\varphi} \bar{f}\|_{b m o} \\
& \leq C \cdot\|\bar{\varphi}\|_{C^{\gamma}\left(\mathbf{R}^{n}\right)} \cdot\|\bar{f}\|_{b m o} \\
& \leq C \cdot\|\varphi\|_{C^{\gamma}(\Omega)} \cdot\|f\|_{b m o_{\infty}^{\infty}(\Omega)} .
\end{aligned}
$$

Remark 3.3.4. If we prove that the extension $f \mapsto \bar{f}$ constructed in Theorem 3.3.1 is bounded from $b m o_{\infty}^{\infty}$ to $b m o=B M O \cap L_{\mathrm{ul}}^{1}$, then the support condition will follow by taking $\varphi \in C^{\gamma}\left(\mathbf{R}^{n}\right)$ in Theorem 3.3.3 as a cut off function of $\Omega$, i.e., $\varphi \equiv 1$ on $\Omega$ with $\operatorname{supp} \varphi \subset \Omega_{\varepsilon}$. In other words, we consider $f \mapsto \varphi \bar{f}$. However, the proof that $\bar{f} \in L_{\mathrm{ul}}^{1}$ needs some argument so we give a direct proof of Theorem 3.3.2.

For $B M O_{b}^{\mu, \infty}$ function in $\Omega$ it is easy to see that its zero extension is in $B M O$ space; see e.g. [5, Lemma 4].

Theorem 3.3.5. Let $\Omega$ be an arbitrary domain in $\mathbf{R}^{n}$. Assume that $\mu \in(0, \infty]$. For $f \in B M O_{b}^{\mu, \nu}(\Omega)$ with $\nu \geq 2 \mu$, let $f_{0}$ be the zero extension to $\mathbf{R}^{n}$, i.e., $f_{0}(x)=0$ for $x \in \Omega^{c}$ and $f_{0}(x)=f(x)$ for $x \in \Omega$. Then $f_{0} \in B M O^{\mu}\left(\mathbf{R}^{n}\right)$ and $\left[f_{0}\right]_{B M O^{\mu}} \leq C[f]_{B M O_{b}^{\mu, \nu}}$ with $C$ independent of $f$.
Proof. If the ball $B$ of radius $\leq \mu$ is in $\Omega$, then

$$
\frac{1}{|B|} \int_{B}\left|f_{0}-f_{0 B}\right| d y \leq[f]_{B M O^{\mu}}
$$

If $B$ is in $\Omega^{c}$, then $\int_{B}\left|f_{0}-f_{0 B}\right| d y=0$. It remains to estimate the integral if $B$ has nonempty intersection with the boundary $\Gamma=\partial \Omega$. For each $B_{r}(x) \cap \Gamma \neq \emptyset, r<\mu$, we take $x_{0} \in B_{r}(x) \cap \Gamma$. Then, $B_{r}(x) \subset B_{2 r}\left(x_{0}\right)$ and thus

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f_{0}-f_{0_{B_{r}(x)} \mid}\right| d y \leq \frac{2}{\left|B_{r}(x)\right|} \int_{B_{2 r}\left(x_{0}\right)}\left|f_{0}\right| d y \leq \frac{2^{n+1}}{\omega_{n}} \cdot[f]_{b^{2 \mu}}
$$

where $\omega_{n}$ is the volume of an $n$-dimensional ball.
Remark 3.3.6. In [5, Lemma 4], it is assumed that $\Omega=\Omega^{\prime} \times \mathbf{R}^{n-k}$ where $\Omega^{\prime}$ is a bounded Lipschitz domain in $\mathbf{R}^{k}$. However, from the proof above it is clear that we do not need this requirement. Thus we give a full proof here.

As an application of boundedness of multiplication, we give invariance of function spaces under coordinate changes. We say that $\Psi$ is a global $C^{k+\beta}$ (resp. $C^{k}$ )-diffeomorphism if $C^{k+\beta}$ (resp. $C^{k}$ )-norms of $\Psi$ and $\Psi^{-1}$ are bounded in $\mathbf{R}^{n}$, where $k \in \mathbf{N}$ and $\beta \in(0,1)$.
Proposition 3.3.7. The space bmo is invariant under bi-Lipschitz coordinate change and the space $h^{1}$ is invariant under global $C^{1+\beta}$-diffeomorphism.
Proof. For $f \in b m o$, by a simple change of variables on the equivalent definition of the seminorm $[f]_{B M O}$ where

$$
[f]_{B M O}=\sup _{B \subset \mathbf{R}^{n}} \inf _{c \in \mathbf{R}} \int_{B}|f(y)-c| d y
$$

see e.g. [9, Proposition 3.1.2], we can easily deduce that bmo is invariant under bi-Lipschitz coordinate change.

Let $g \in h^{1}\left(\mathbf{R}^{n}\right)$ and $\Psi$ be a global $C^{1+\beta}$-diffeomorphism. We have that

$$
\|g \circ \Psi\|_{h^{1}}=\sup _{\|f\|_{b m o} \leq 1}\left|\int_{\mathbf{R}^{n}} f \cdot g \circ \Psi d y\right| .
$$

By change of variable we have that

$$
\left|\int_{\mathbf{R}^{n}} f(y) \cdot g \circ \Psi(y) d y\right|=\left|\int_{\mathbf{R}^{n}} f \circ \Psi^{-1}(x) \cdot g(x) \cdot J_{\Psi^{-1}}(x) d x\right|,
$$

where $J_{\Psi^{-1}}$ is the Jacobian which is of regularity $C^{\beta}$. Then by the $b m o-h^{1}$ duality [16, Theorem 3.22] and multiplication estimate (3.3.2), we deduce that

$$
\left|\int_{\mathbf{R}^{n}} f \circ \Psi^{-1} \cdot g \cdot J_{\Psi^{-1}} d x\right| \leq\left\|f \circ \Psi^{-1}\right\|_{b m o} \cdot\left\|g J_{\Psi^{-1}}\right\|_{h^{1}} \leq\left\|f \circ \Psi^{-1}\right\|_{b m o} \cdot\left\|J_{\Psi^{-1}}\right\|_{C^{\beta}} \cdot\|g\|_{h^{1}}
$$

Since $b m o$ is independent of bi-Lipschitz coordinate change, we have that

$$
\|g \circ \Psi\|_{h^{1}} \leq C \cdot\left\|\nabla \Psi^{-1}\right\|_{L^{\infty}} \cdot\left\|J_{\Psi^{-1}}\right\|_{C^{\beta}} \cdot\|g\|_{h^{1}}
$$

for some constant $C$ independent of $g$ and $\Psi$.

Proposition 3.3.8. The space $F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$ is invariant under global $C^{1+\beta}$-diffeomorphism.
Proof. Let $g \in F_{1,2}^{1}$ and $\Psi$ be a global $C^{1+\beta}$-diffeomorphism. By multiplication estimate (3.3.2) and Proposition 3.3.7, we have that
$\|\nabla(g \circ \Psi)\|_{F_{1,2}^{0}} \leq C \cdot\|\nabla \Psi\|_{C^{\beta}} \cdot\|(\nabla g) \circ \Psi\|_{F_{1,2}^{0}} \leq C \cdot\|\nabla \Psi\|_{C^{\beta}} \cdot\left\|\nabla \Psi^{-1}\right\|_{L^{\infty}} \cdot\left\|J_{\Psi^{-1}}\right\|_{C^{\beta}} \cdot\|\nabla g\|_{F_{1,2}^{0}}$,
where $J_{\Psi^{-1}}$ is the Jacobian for $\Psi^{-1}$ and $C$ is a constant independent of $g$ and $\Psi$. Hence $\nabla(g \circ \Psi) \in F_{1,2}^{0}$ by $\|\nabla g\|_{F_{1,2}^{0}} \leq C\|g\|_{F_{1,2}^{1,2}}$ since the differentiation mapping is bounded from $F_{p, q}^{s}$ to $F_{p, q}^{s-1}$ for $p \in(0, \infty), q \in(0, \infty]$ and $s \in \mathbf{R}$, see e.g. [16, Theorem 2.12]. Since $\nabla(g \circ \Psi) \in F_{1,2}^{0}$, we also get $\Delta(g \circ \Psi) \in F_{1,2}^{-1}$. Since $F_{1,2}^{1} \hookrightarrow F_{1,2}^{0}$, Proposition 3.3.7 tells us that $g \circ \Psi \in F_{1,2}^{0} \subset F_{1,2}^{-1}$. Therefore, $(I-\Delta)(g \circ \Psi) \in F_{1,2}^{-1}$. Notice that [16, Theorem 2.12] also tells us that for $\sigma \in \mathbf{R},(I-\Delta)^{\sigma}$ is an isomorphism from $F_{p, q}^{s}$ to $F_{p, q}^{s-2 \sigma}$. Hence by letting $\sigma=-1$, we deduce that

$$
\begin{aligned}
\|g \circ \Psi\|_{F_{1,2}^{1}} & =\left\|(I-\Delta)^{-1}(I-\Delta)(g \circ \Psi)\right\|_{F_{1,2}^{1}} \\
& \leq C \cdot\|(I-\Delta)(g \circ \Psi)\|_{F_{1,2}^{-1}} \\
& \leq C \cdot\left(\|g \circ \Psi\|_{F_{1,2}^{0}}+\|\nabla(g \circ \Psi)\|_{F_{1,2}^{0}}\right) \\
& \leq C \cdot\left(1+\|\nabla \Psi\|_{C^{\beta}}\right) \cdot\left\|\nabla \Psi^{-1}\right\|_{L^{\infty}} \cdot\left\|J_{\Psi^{-1}}\right\|_{C^{\beta}} \cdot\|g\|_{F_{1,2}^{1}},
\end{aligned}
$$

where $C$ is a constant independent of $g$ and $\Psi$.
Remark 3.3.9. The proof of Proposition 3.3 .8 also says that $F_{1,2}^{1}=\left\{f \in F_{1,2}^{0} \mid \nabla f \in\right.$ $\left.\left(F_{1,2}^{0}\right)^{n}\right\}$.

### 3.4 Trace problems

In this section we show that the normal trace of a vector field in $v b m o_{\delta}^{\mu, \nu}$ is in $L^{\infty}(\Gamma)$ if its divergence is well controlled. We begin with the case that $\Omega$ is the half space $\mathbf{R}_{+}^{n}$.

We first recall that the trace operator $(\operatorname{Tr} f)\left(x^{\prime}\right)=f\left(x^{\prime}, 0\right)$ for $f \in F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$ gives a surjective bounded linear operator from $F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$ to $L^{1}\left(\mathbf{R}^{n-1}\right)$; see [19, Section 4.4.3].

Proposition 3.4.1 ([19]). The operator $\operatorname{Tr}$ from $F_{1,2}^{1}$ to $L^{1}\left(\mathbf{R}^{n-1}\right)$ is surjective for $n \geq 2$. Actually, surjectivity holds for a smaller space $B_{1,1}^{1}$. There exists an inverse operator called the extension which is a bounded linear operator.

For a $C^{2}$ domain $\Omega$ a normal trace $v \cdot \mathbf{n}$ on $\Gamma=\partial \Omega$ of $v$ is well-defined as an element of $W_{\text {loc }}^{-1 / p, p}(\Gamma)$ if $v$ and $\operatorname{div} v$ is in $L_{\text {loc }}^{p}$; see e.g. [6] or [7]. If $v \in v b m o_{\delta}^{\mu, \nu}(\Omega)$ so that $v \in L_{\text {loc }}^{1}$, then by an interpolation inequality (see e.g. [5, Theorem 11]) $v$ is in $L_{\text {loc }}^{p}$ for any $p \geq 1$. Thus if $\operatorname{div} v$ is in $L_{\mathrm{loc}}^{p}, v \cdot \mathbf{n}$ is well-defined. We derive $L^{\infty}$ estimate for $v \cdot \mathbf{n}$ when $\Omega$ is the half space.

Theorem 3.4.2. Let $\mu, \nu, \delta$ be in $(0, \infty]$ and $n \geq 2$. Then there is a constant $C=$ $C(\mu, \nu, \delta, n)$ such that

$$
\|v \cdot \mathbf{n}\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)} \leq C\left(\|v\|_{v b m o_{\delta}^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right)}+\|\operatorname{div} v\|_{L_{\mathrm{ul}}^{n}\left(\Gamma_{\delta}\right)}\right)
$$

for all $v \in v b m o_{\delta}^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right)$.

Proof. Let $v \in v b m o_{\delta}^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right)$. By definition, the $n$-th component $v_{n}$ of $v=\left(v^{\prime}, v_{n}\right)$ belongs to $B M O_{b}^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right)$. For $x_{0}^{\prime} \in \mathbf{R}^{n-1}$, we consider the region $U=B_{1}\left(x_{0}^{\prime}\right) \times(-\delta, \delta)$ where $B_{1}\left(x_{0}^{\prime}\right)$ denotes the ball in $\mathbf{R}^{n-1}$ centered at $x_{0}^{\prime}$ with radius 1 . Let $v_{\text {re }}$ denotes the restriction of $v$ on $U \cap \mathbf{R}_{+}^{n}$, i.e., $v_{\mathrm{re}}=\left.v\right|_{U \cap \mathbf{R}_{+}^{n}}$. We have that $v_{\mathrm{re}} \in b m o_{\infty}^{\infty}\left(U \cap \mathbf{R}_{+}^{n}\right)$ and

$$
\sup _{\substack{x^{\prime} \in B_{1}\left(x_{0}^{\prime}\right) \\ r<\nu}} \frac{1}{\left|B_{r}\left(\left(x^{\prime}, 0\right)\right)\right|} \int_{B_{r}\left(\left(x^{\prime}, 0\right)\right)}\left|\left(v_{\mathrm{re}}\right)_{n}\right| d y<\infty
$$

Let $\overline{\left(v_{\mathrm{re}}\right)_{n}}$ be the zero extension of $\left(v_{\mathrm{re}}\right)_{n}$ to $U$. By Theorem 3.3.5, $\overline{\left(v_{\mathrm{re}}\right)_{n}}$ is in $B M O^{\infty}(U)$. Let $\overline{v_{\mathrm{re}}^{\prime}}$ be the even extension of $v_{\mathrm{re}}^{\prime}$ to $U$ of the form

$$
\overline{v_{\mathrm{re}}^{\prime}}\left(x^{\prime}, x_{n}\right)= \begin{cases}v_{\mathrm{re}}^{\prime}\left(x^{\prime}, x_{n}\right), & x^{\prime} \in B_{1}\left(x_{0}^{\prime}\right) \text { and } x_{n}>0  \tag{3.4.1}\\ v_{\mathrm{re}}^{\prime}\left(x^{\prime},-x_{n}\right), & x^{\prime} \in B_{1}\left(x_{0}^{\prime}\right) \text { and } x_{n}<0\end{cases}
$$

and set $\widetilde{v}=\left(\overline{v_{\text {re }}^{\prime}}, \overline{\left(v_{\text {re }}\right)_{n}}\right)$. We have that $\widetilde{v} \in b m o_{\infty}^{\infty}(U)$. By Theorem 3.3.2 its Jones' extension $v_{U}$ belongs to $b m o_{\infty}^{\infty}\left(\mathbf{R}^{n}\right)$.

Integration by parts formally yields

$$
\begin{equation*}
\int_{\mathbf{R}^{n-1}} v_{U} \cdot \mathbf{n} \rho d x^{\prime}=\int_{\mathbf{R}_{+}^{n}}\left(\operatorname{div} v_{U}\right) \rho d x-\int_{\mathbf{R}_{+}^{n}} v_{U} \cdot \nabla \rho d x \tag{3.4.2}
\end{equation*}
$$

By Proposition 3.4.1 there is an extension operator Ext : $L^{1}\left(\mathbf{R}^{n-1}\right) \rightarrow F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$ such that TroExt is the identity operator on $L^{1}$. For $\varphi \in C_{c}^{\infty}\left(B_{\frac{1}{2}}\left(x_{0}^{\prime}\right)\right)$ we set $\sigma=\operatorname{Ext} \varphi$. Multiplying a cut off function $\theta \in C_{c}^{\infty}(U)$ such that $\theta \equiv 1$ in $\frac{1}{2} U$ and considering $\rho=\theta \sigma$, we still find $\rho \in F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$ by a multiplier theorem [16, Theorem 3.18], [19, Section 4.2.2]. We estimate (3.4.2) to get

$$
\begin{aligned}
\left|\int_{\mathbf{R}^{n-1}} v_{U} \cdot \mathbf{n} \rho d x^{\prime}\right| & \leq\left|\int_{U}\left(\operatorname{div} v_{U}\right) \rho d x\right|+\left|\int_{\mathbf{R}_{+}^{n}} v_{U}^{\prime} \cdot \nabla^{\prime} \rho d x\right| \\
& +\left|\int_{\mathbf{R}^{n}} v_{U^{n}} \frac{\partial \rho}{\partial x_{n}} d x\right|=I+I I+I I I
\end{aligned}
$$

We may assume that $\rho$ is even in $x_{n}$ by taking $\left(\rho\left(x^{\prime}, x_{n}\right)+\rho\left(x^{\prime},-x_{n}\right)\right) / 2$ so that the second term is estimated by bmo- $h^{1}$ duality $\left(h^{1}\right)^{*}=\left(F_{1,2}^{0}\right)^{*}=F_{\infty, 2}^{0}=b m o$ as follows

$$
\begin{aligned}
I I & =\left|\int_{\mathbf{R}_{+}^{n}} v_{U}^{\prime} \cdot \nabla^{\prime} \rho d x\right|=\frac{1}{2}\left|\int_{\mathbf{R}^{n}} v_{U}^{\prime} \cdot \nabla^{\prime} \rho d x\right| \\
& \leq C\left\|v_{U}^{\prime}\right\|_{b m o}\left\|\nabla^{\prime} \rho\right\|_{h^{1}} .
\end{aligned}
$$

The third term is estimated as

$$
\text { III } \leq C\left\|v_{U^{n}}\right\|_{b m o}\left\|\frac{\partial \rho}{\partial x_{n}}\right\|_{h^{1}}
$$

The first term is estimated by

$$
\begin{aligned}
I & \leq\left\|\operatorname{div} v_{U}\right\|_{L^{n}(U)}\|\rho\|_{L^{n /(n-1)}(U)} \\
& \leq C\|\operatorname{div} v\|_{L_{\mathrm{ul}}^{n}\left(\Gamma_{\delta}\right)}\|\nabla \rho\|_{L^{1}(U)}
\end{aligned}
$$

by the Sobolev inequality. Since $\|\nabla \rho\|_{L^{1}} \leq\|\nabla \rho\|_{h^{1}}$ and $\left.\|\nabla \rho\|_{h^{1}} \leq\|\rho\|_{F_{1,2}^{1}} \leq C\|\varphi\|_{L^{1}\left(B_{\frac{1}{2}}\left(x_{0}^{\prime}\right)\right.}\right)$, collecting these estimates yields

$$
\left|\int_{B_{\frac{1}{2}}\left(x_{0}^{\prime}\right)} v \cdot \mathbf{n} \varphi d x^{\prime}\right| \leq C\|\varphi\|_{L^{1}\left(B_{\frac{1}{2}}\left(x_{0}^{\prime}\right)\right)}\left(\|v\|_{v b m o_{\delta}^{\mu, \nu}\left(\mathbf{R}_{+}^{n}\right)}+\|\operatorname{div} v\|_{L_{\mathrm{ul}}^{n}\left(\Gamma_{\delta}\right)}\right) .
$$

This yields the desired estimate since $C_{c}^{\infty}\left(B_{\frac{1}{2}}\left(x_{0}^{\prime}\right)\right)$ is dense in $L^{1}\left(B_{\frac{1}{2}}\left(x_{0}^{\prime}\right)\right)$ and $C$ in the right-hand side is independent of $x_{0}^{\prime} \in \mathbf{R}^{n-1}$.

We now consider a curved domain. Let $\Omega$ be a uniformly $C^{2}$ domain in $\mathbf{R}^{n}$ so that the reach $R_{*}$ of $\Gamma$ is positive and $\beta \in(0,1)$.
Theorem 3.4.3. Let $\Omega$ be a uniformly $C^{2+\beta}$ domain in $\mathbf{R}^{n}$ with $n \geq 2$. Let $\mu, \nu, \delta$ be in $(0, \infty]$. Then there is a constant $C=C(\mu, \nu, \delta, \Omega)$ such that

$$
\|v \cdot \mathbf{n}\|_{L^{\infty}(\Gamma)} \leq C\left(\|v\|_{v b m o_{\delta}^{\mu, \nu}(\Omega)}+\|\operatorname{div} v\|_{L_{\mathrm{ul}}^{n}\left(\Gamma_{\delta}\right)}\right)
$$

for all $v \in v b m o_{\delta}^{\mu, \nu}(\Omega)$.
We shall prove this result by localizing the problems near the boundary and by using a normal coordinate system. Let $\Omega$ be a uniformly $C^{2+\beta}$ domain. In other words, there exist $r_{*}, \delta_{*}>0$ such that for each $z_{0} \in \Gamma$, up to translation and rotation, there exists a function $h_{z_{0}} \in C^{2+\beta}\left(B_{r_{*}}\left(0^{\prime}\right)\right)$ with

$$
\begin{aligned}
& \left|\left(\nabla^{\prime}\right)^{k} h_{z_{0}}\right| \leq L \text { in } B_{r_{*}}\left(0^{\prime}\right) \text { for } k=0,1,2, \\
& {\left[\left(\nabla^{\prime}\right)^{2} h_{z_{0}}\right]_{C^{\beta}\left(B_{r *}\left(0^{\prime}\right)\right)}<\infty, \nabla^{\prime} h_{z_{0}}\left(0^{\prime}\right)=0^{\prime}, h_{z_{0}}\left(0^{\prime}\right)=0}
\end{aligned}
$$

such that the neighborhood

$$
U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right):=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|h_{z_{0}}\left(x^{\prime}\right)-\delta_{*}<x_{n}<h_{z_{0}}\left(x^{\prime}\right)+\delta_{*},\left|x^{\prime}\right|<r_{*}\right\}\right.
$$

satisfies

$$
\Omega \cap U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|h_{z_{0}}\left(x^{\prime}\right)<x_{n}<h_{z_{0}}\left(x^{\prime}\right)+\delta_{*},\left|x^{\prime}\right|<r_{*}\right\}\right.
$$

and

$$
\partial \Omega \cap U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|x_{n}=h_{z_{0}}\left(x^{\prime}\right),\left|x^{\prime}\right|<r_{*}\right\}\right.
$$

For $x \in \Omega$, let $\pi x$ be a point on $\Gamma$ such that $|x-\pi x|=d_{\Omega}(x)$. If $x$ is within the reach of $\Gamma$, then this $\pi x$ is unique. There exist $r<r_{*}$ and $\delta<\delta_{*}$ such that

$$
U\left(z_{0}\right)=\left\{x \in \mathbf{R}^{n} \mid(\pi x)^{\prime} \in B_{r}\left(0^{\prime}\right), d_{\Gamma}(x)<\delta\right\}
$$

is contained in $U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)$. Since $d_{\Omega}$ is $C^{2+\beta}$ in $\bar{\Gamma}_{\sigma}$ for $\sigma<R_{*}$ [10, Chap. 14, Appendix] [11, §4.4], we may take $\delta$ smaller (independent of $z_{0}$ ) so that $d_{\Omega}$ is $C^{2+\beta}$ in $\overline{U\left(z_{0}\right) \cap \Omega}$.

We next consider a normal coordinate system in $U\left(z_{0}\right)$

$$
\left\{\begin{array}{l}
x^{\prime}=y^{\prime}+y_{n} \nabla^{\prime} d_{\Omega}\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right)  \tag{3.4.3}\\
x_{n}=h_{z_{0}}\left(y^{\prime}\right)+y_{n} \partial_{x_{n}} d_{\Omega}\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right)
\end{array}\right.
$$

or shortly

$$
x=\pi x-d_{\Omega}(x) \mathbf{n}(\pi x) .
$$

Let this coordinate change be denoted by $x=\psi(y), \psi \in C^{1+\beta}(V)$, where $V$ is a neighborhood defined below. Notice that $\nabla \psi(0)=I$. If we consider $r$ and $\delta$ small, this coordinate change is indeed a local $C^{1}$-diffeomorphism which maps $U\left(z_{0}\right)$ to $V$ where $\underset{\sim}{V}:=B_{r}\left(0^{\prime}\right) \underset{\sim}{x}(-\delta, \delta)$. Moreover, by [12], we extend $\psi$ to a global $C^{1}$-diffeomorphism $\widetilde{\psi}$ such that $\left.\widetilde{\psi}\right|_{V}=\psi$ and $\|\nabla \widetilde{\psi}\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}<2$. Let the inverse of $\psi$ in $V$ be denoted by $\phi$, i.e., $\phi=\psi^{-1}$.

Lemma 3.4.4. Let $W$ be a vector field with measurable coefficient in $\Gamma_{\sigma}, \sigma<R_{*}$ of the form

$$
W=\sum_{i=1}^{n} w_{i} \frac{\partial}{\partial x_{i}} .
$$

Let $y$ be the normal coordinate such that $y_{n}=d_{\Omega}(x)$. Let $\tilde{W}$ be $W$ in $y$ coordinate of the form $\bar{W}=\sum_{j=1}^{n} \tilde{w}_{j}(y) \partial / \partial y_{j}$. Then

$$
\tilde{w}_{n}(y)=\nabla d_{\Omega}(x(y)) \cdot w(x(y)) .
$$

We shall prove this lemma in Appendix which follows from a simple linear algebra.
Proof of Theorem 3.4.3. We first observe that the restriction of $v$ on $U\left(z_{0}\right) \cap \Omega$ belongs to $b m o_{\infty}^{\infty}\left(U\left(z_{0}\right) \cap \Omega\right)$. By considering the following equivalent definition of the seminorm $[f]_{B M O^{\infty}(D)}$ where

$$
[f]_{B M O \infty}(D)=\sup _{B_{r}(x) \subset D} \inf _{c \in \mathbf{R}} \frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}|f(y)-c| d y
$$

(see [9, Proposition 3.1.2]), we can deduce that the space $b m o_{\infty}^{\infty}$ on a bounded domain is independent of bi-Lipschitz coordinate change. We introduce normal coordinate for a vector field $v=\sum_{i=1}^{n} v_{i} \partial / \partial x_{i}$ with $v_{i} \in b m o_{\infty}^{\infty}\left(U\left(z_{0}\right) \cap \Omega\right)$. Let $w$ be the transformed vector field under the normal coordinate $y$. By Lemma 3.4.4, $w_{n}$ of $w=\sum_{i=1}^{n} w_{i} \partial / \partial y_{i}$ fulfills $w_{n}=\nabla d_{\Omega}(x(y)) \cdot v(x(y))$. Since $v \in v b m o_{\delta}^{\mu, \nu}(\Omega)$, this implies that $w \in b m o_{\infty}^{\infty}\left(V \cap \mathbf{R}_{+}^{n}\right)$ and moreover,

$$
\sup _{\ell<\delta, B_{\ell}(x) \subset V} \ell^{-n} \int_{B_{\ell}(x) \cap \mathbf{R}_{+}^{n}}\left|w_{n}\right| d y<\infty .
$$

Thus, as in the proof of Theorem 3.4.2, the zero extension of $w_{n}$ for $y_{n}<0$ is in $b m o_{\infty}^{\infty}(V)$, we still denote this extension by $w_{n}$. Let $J=J(y)$ denote the Jacobian of the mapping $y \mapsto x$ in $V$. For tangential part $w^{\prime}$ of $w=\left(w^{\prime}, w_{n}\right)$, we take an even extension with weight $J$ of the form

$$
\hat{w}^{\prime}\left(y^{\prime}, y_{n}\right)= \begin{cases}w^{\prime}\left(y^{\prime}, y_{n}\right), & y_{n}>0  \tag{3.4.4}\\ w^{\prime}\left(y^{\prime},-y_{n}\right) J\left(y^{\prime},-y_{n}\right) / J\left(y^{\prime}, y_{n}\right), & y_{n}<0\end{cases}
$$

and set $\tilde{w}\left(y^{\prime}, y_{n}\right)=\left(\hat{w}^{\prime}, w_{n}\right)$. Let $\bar{w}^{\prime}$ denote the unweighted even extension of $w^{\prime}$ to $V$, thus $w \in b m o_{\infty}^{\infty}\left(V \cap \mathbf{R}_{+}^{n}\right)$ implies that $\bar{w}^{\prime} \in b m o_{\infty}^{\infty}(V)$. Let $f$ be the function defined on $V$ such that $f \equiv 1$ for $y_{n} \geq 0$ and $f=J\left(y^{\prime},-y_{n}\right) / J\left(y^{\prime}, y_{n}\right)$ for $y_{n}<0$. Since $J(y)^{-1}=$ $|\operatorname{det} D \psi(y)|^{-1}=|\operatorname{det} D \phi(\psi(y))|$ for $y \in V$, we have that $f \in C^{\beta}(V)$. Notice that $\hat{w}^{\prime}(y)=$ $\bar{w}^{\prime}(y) f(y)$, therefore by Theorem 3.3.3, we can deduce that $\tilde{w}$ belongs to $b m o_{\infty}^{\infty}(V)$. By

Theorem 3.3.2, the Jones' extension $w_{U}$ of $\tilde{w}$ belongs to $b m o_{\infty}^{\infty}\left(\mathbf{R}^{r}\right)$. Its expression in $x$ coordinate is $v_{U}$ which is only defined near $\Gamma$.

If the support of $\rho$ is in $U\left(z_{0}\right)$, then integration by parts implies that

$$
\begin{equation*}
\int_{\Gamma} v_{U} \cdot \mathbf{n} \rho d \mathcal{H}^{n-1}=\int_{\Omega}\left(\operatorname{div} v_{U}\right) \rho d x-\int_{\Omega} v_{U} \cdot \nabla \rho d x \tag{3.4.5}
\end{equation*}
$$

We shall estimate the left-hand side as in the case of $\mathbf{R}_{+}^{n}$. The first integral in the righthand side can be estimated similarly as in the proof of Theorem 3.4.2. It is sufficient to only consider the second integral. Let $\Psi: B_{r}\left(0^{\prime}\right) \rightarrow \underset{\tilde{\sim}}{\Gamma} \cap U\left(z_{0}\right)$ by $\left(y^{\prime}, 0\right) \mapsto\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right)$. Extend $h_{z_{0}} \in C^{2}\left(B_{r}\left(0^{\prime}\right)\right)$ to $\tilde{h} \in C_{c}^{2}\left(\mathbf{R}^{n-1}\right)$ such that $\left.\tilde{h}\right|_{B_{r}\left(0^{\prime}\right)}=h_{z_{0}}$. Define $\widetilde{\Psi}: \mathbf{R}^{n-1} \rightarrow$ $\tilde{h}\left(\mathbf{R}^{n-1}\right)$ by $\left(y^{\prime}, 0\right) \mapsto\left(y^{\prime}, \tilde{h}\left(y^{\prime}\right)\right)$. Hence $\left.\widetilde{\Psi}\right|_{B_{r}\left(0^{\prime}\right)}=\Psi$. Extend further $\widetilde{\Psi}$ to $\widetilde{\Psi} *: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ by $\left(y^{\prime}, d\right) \mapsto \widetilde{\Psi}\left(y^{\prime}, 0\right)+\left(0^{\prime}, d\right)$. Notice that this $\widetilde{\Psi}^{*}$ is a global $C^{2}$-diffeomorphism whose derivatives are bounded in $\mathbf{R}^{n}$ up to second-order. We may assume $z_{0}=0$ by translation. Let $\zeta>0$ be a constant to be determined later. For $\varphi \in C_{c}^{1}\left(\Gamma \cap \zeta U\left(z_{0}\right)\right)$, we observe that $\varphi \circ \Psi \in C_{c}^{1}\left(B_{\zeta r}\left(0^{\prime}\right)\right)$. Let $\widetilde{\sigma}=\operatorname{Ext}(\varphi \circ \Psi)$ as in the proof of Theorem 3.4.2 and let $\sigma=\widetilde{\sigma} \circ\left(\widetilde{\Psi}^{*}\right)^{-1}$. With this choice of $\sigma$, we observe that for $\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right) \in \Gamma \cap \zeta U\left(z_{0}\right)$,

$$
\sigma\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right)=\widetilde{\sigma} \circ\left(\widetilde{\Psi}^{*}\right)^{-1}\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right)=\widetilde{\sigma}\left(y^{\prime}, 0\right)=\varphi \circ \Psi\left(y^{\prime}, 0\right)=\varphi\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right) .
$$

Thus $\varphi$ is an extension of $\sigma$. Since $\left(\widetilde{\Psi}^{*}\right)^{-1}$ is a global $C^{2}$-diffeomorphism and $\widetilde{\sigma} \in F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$, we observe that $\sigma \in F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$, see e.g. see Proposition 3.3 .8 or [19, Section 4.3.1].

For each $z_{0} \in \Gamma$, there exists $\epsilon_{z_{0}}>0$ such that we can find a cut off function $\theta_{z_{0}} \in$ $C_{c}^{\infty}\left(U\left(z_{0}\right)\right)$ for which $\theta_{z_{0}} \equiv 1$ within $\epsilon_{z_{0}} U\left(z_{0}\right)$ and

$$
\sum_{|\alpha| \leq 2}\left\|D^{\alpha} \theta_{z_{0}}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq M
$$

for some fixed universal constant $M>1$ independent of $z_{0}$. By multiplying this cut off function $\theta_{z_{0}}$, we have that $\rho=\theta_{z_{0}} \sigma \in F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$ and $\|\rho\|_{F_{1,2}^{1}\left(\mathbf{R}^{n}\right)} \leq M \cdot\|\sigma\|_{F_{1,2}^{1}\left(\mathbf{R}^{n}\right)}$. Hence we take the constant $\zeta$ above to be $\epsilon_{z_{0}}$.

By coodinate change, we observe that

$$
\int_{\Omega} v_{U} \cdot \nabla \rho d x=\int_{U\left(z_{0}\right) \cap \Omega} \sum_{i=1}^{n} v_{i} \frac{\partial}{\partial x_{i}} \rho d x=\int_{V \cap \mathbf{R}_{+}^{n}} \sum_{j=1}^{n} w_{U_{j}}(y) J(y) \frac{\partial}{\partial y_{j}}(\rho \circ \psi(y)) d y .
$$

The $n$-th component equals

$$
\int_{V \cap \mathbf{R}_{+}^{n}} w_{U_{n}}(y) J(y) \frac{\partial}{\partial y_{n}}(\rho \circ \psi(y)) d y=\int_{V} w_{U_{n}}(y) J(y) \frac{\partial}{\partial y_{n}}(\rho \circ \psi(y)) d y
$$

since $w_{U_{n}}$ equals zero for $y_{n}<0$. Considering extensions of Hölder functions [13] and local diffeomorphism [12], by the $F_{1,2}^{0}-F_{\infty, 2}^{0}$ duality [16, Theorem 3.22] and Proposition 3.3.7, we conclude that

$$
\begin{aligned}
\left|\int_{V} w_{U_{n}}(y) J(y) \frac{\partial}{\partial y_{n}}(\rho \circ \psi(y)) d y\right| & \leq C \cdot \sum_{i=1}^{n}\left\|w_{U_{n}}\right\|_{b m o} \cdot\|J\|_{C^{\beta}(V)} \cdot\left\|\partial_{y_{n}} \psi\right\|_{C^{\beta}(V)} \cdot\|\nabla \rho \circ \widetilde{\psi}\|_{h^{1}} \\
& \leq C \cdot\left\|w_{U_{n}}\right\|_{b m o} \cdot\|\nabla \rho\|_{h^{1}} .
\end{aligned}
$$

For tangential part we may assume that

$$
\begin{equation*}
(\rho \circ \psi)\left(y^{\prime}, y_{n}\right)=(\rho \circ \psi)\left(y^{\prime},-y_{n}\right) \text { for } y_{n}<0 \text {. } \tag{3.4.6}
\end{equation*}
$$

In fact, for a given $\rho$ we take

$$
g\left(y^{\prime}, y_{n}\right)=\left(\rho \circ \psi\left(y^{\prime}, y_{n}\right)+\rho \circ \psi\left(y^{\prime},-y_{n}\right)\right) / 2
$$

which satisfies evenness $g\left(y^{\prime}, y_{n}\right)=g\left(y^{\prime},-y_{n}\right)$ and

$$
g\left(y^{\prime}, 0\right)=\theta \circ \psi\left(y^{\prime}, 0\right) \cdot \sigma \circ \psi\left(y^{\prime}, 0\right)=\theta\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right) \cdot \varphi\left(y^{\prime}, h_{z_{0}}\left(y^{\prime}\right)\right) .
$$

It suffices to take $\rho$ such that $\rho \circ \psi(y)=g(y)$. Thus, we may assume that $\rho \circ \psi$ is even in $y_{n}$ so that $\partial_{y_{j}}(\rho \circ \psi)$ is also even in $y_{n}$ for $j=1,2, \ldots, n-1$. Since $w_{U_{j}} J$ is even in $y_{n}$ for $y$ in $V$, we observe that

$$
\int_{V \cap \mathbf{R}_{+}^{n}} w_{U_{j}}(y) J(y) \frac{\partial}{\partial y_{j}}(\rho \circ \psi) d y=\frac{1}{2} \int_{V} w_{U_{j}}(y) J(y) \frac{\partial}{\partial y_{j}}(\rho \circ \psi) d y
$$

for $1 \leq j \leq n-1$. Similar to the case for the $n$-th component, we thus conclude that

$$
\left|\int_{V} w_{U_{j}}(y) J(y) \frac{\partial}{\partial y_{j}}(\rho \circ \psi) d y\right| \leq C \cdot\left\|w_{U_{j}}\right\|_{b m o} \cdot\|\nabla \rho\|_{h^{1}} .
$$

Collecting these estimates, we conclude that

$$
\begin{aligned}
\left|\int_{\Gamma \cap \epsilon_{z_{0}} U\left(z_{0}\right)} v \cdot \mathbf{n} \varphi d x^{n-1}\right| & \leq C\left\|w_{U}\right\|_{b m o}\|\nabla \rho\|_{h^{1}} \\
& \leq C\|v\|_{v b m o_{\delta}^{\mu, \nu}(\Omega)}\|\varphi\|_{L^{1}\left(\Gamma \cap \epsilon_{z_{0}} U\left(z_{0}\right)\right)} .
\end{aligned}
$$

Thus $\|v \cdot \mathbf{n}\|_{L^{\infty}} \leq C\|v\|_{v b m o_{\delta}^{\mu, \nu}(\Omega)}$.
Remark 3.4.5. (i) Since $B M O_{b}^{\mu, \nu} \subset v b m o_{\delta}^{\mu, \nu}$ for $\delta<\infty$, the estimate in Theorem 3.4.3 holds if we replace $v b m o_{\delta}^{\mu, \nu}$ by $B M O_{b}^{\mu, \nu}$. Moreover, since we are able to use zero extension in this case. We can follow the proof of Theorem 3.4.3 directly without the necessity to invoke normal coordinates. We shall state a version of Theorem 3.4.3 for $B M O_{b}^{\mu, \nu}$ in the end of this section.
(ii) By Theorem 3.2.9 we may replace $v b m o_{\delta}^{\mu, \nu}$ by $v B M O^{\mu, \nu}(\Omega)$ in the estimate in Theorem 3.4.3 since we may always take $\delta \leq \nu<R_{*}$ provided that $\Omega$ is a bounded or an exterior domain.

Remark 3.4.6. If we assume that the vector field $v$ is continuous in $\bar{\Omega}$, then by Lebesgue differentiation theorem we have the natural estimate $\|v \cdot \mathbf{n}\|_{L^{\infty}(\Gamma)} \leq C\left[\nabla d_{\Omega} \cdot v\right]_{b^{\nu}}$ for some constant $C$ independent of $v$. Therefore, if we replace the space $v b m o_{\delta}^{\mu, \nu}(\Omega)$ by the $v b m o_{\delta}^{\mu, \nu}$ closure of $C_{\mathrm{c}}^{\infty}(\bar{\Omega})$, then Theorem 3.4.2 and 3.4.3 trivially hold. However, the $v b m o_{\delta}^{\mu, \nu}$ closure of $C_{\mathrm{c}}^{\infty}(\bar{\Omega})$ seems to be strictly smaller than the space $v b m o_{\delta}^{\mu, \nu}(\Omega)$ since it is known that a similar space $V M O$, the $B M O$ closure of $C_{\mathrm{c}}^{\infty}\left(\mathbf{R}^{n}\right)$, is a proper subspace of $B M O$ [17]. Thus, our trace theorems stay non-trivial. Generally speaking, we cannot directly estimate the $L^{\infty}$ norm on the boundary by the $b^{\nu}$-seminorm. Here is an example. In dimension 1 , for any $m \in \mathbf{N} \cap\{0\}$ we define $f$ in $(0,1)$ by

$$
f(x)= \begin{cases}m+1, & \text { if } x \in\left(\frac{1}{2^{m}+1}, \frac{1}{2^{m}}\right), \\ 0, & \text { otherwis. }\end{cases}
$$

A simple calculation tells us that $[f]_{b^{\nu}} \leq 2 \cdot \sum_{i=1}^{\infty} \frac{i}{2^{i}}<\infty$ but for any $M>0$ there exists $\delta_{M}>0$ such that there exists a subset $S \subset\left(0, \delta_{M}\right)$ with Lebesgue measure $|S|>0$ and $f(x)>M$ for any $x \in S$.

Theorem 3.4.7. Let $\Omega$ be a uniformly $C^{1+\beta}$ domain in $\mathbf{R}^{n}$ with $n \geq 2$. Let $\mu, \nu, \delta$ be in $(0, \infty]$. Then there is a constant $C=C(\mu, \nu, \delta, \Omega)$ such that

$$
\|v \cdot \mathbf{n}\|_{L^{\infty}(\Gamma)} \leq C\left(\|v\|_{B M O_{b}^{\mu, \nu}(\Omega)}+\|\operatorname{div} v\|_{L_{\mathrm{ul}}^{n}\left(\Gamma_{\delta}\right)}\right)
$$

for all $v \in B M O_{b}^{\mu, \nu}(\Omega)$.
Proof. For $z_{0} \in \Gamma$, let $U\left(z_{0}\right)=U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)$ with $\delta_{*} \leq R_{*}$. We then follow the proof of Theorem 3.4.3 without invoking the normal coordinates. For $v \in B M O_{b}^{\mu, \nu}(\Omega)$, let $v_{0}$ be the zero extension of $v$. We have that $v_{0} \in b m o_{\infty}^{\infty}\left(U\left(z_{0}\right)\right)$. Let $v_{U}$ be the Jones' extension of $r_{U\left(z_{0}\right)} v_{0}$ by Theorem 3.3.2 where $r_{U\left(z_{0}\right)} v_{0}$ denotes the restriction of $v_{0}$ on $U\left(z_{0}\right)$. For $\varphi \in C_{c}^{1}\left(\Gamma \cap \frac{1}{2} U\left(z_{0}\right)\right)$, we construct the function $\sigma$ in the same way as in the proof of Theorem 3.4.3. Since the boundary $\Gamma$ is uniformly $C^{1+\beta}, \widetilde{\Psi}^{*}$ is a global $C^{1+\beta}$-diffeomorphism. By Proposition 3.3.8, we have that $\sigma=\widetilde{\sigma} \circ\left(\widetilde{\Psi}^{*}\right)^{-1} \in F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$. Pick $\theta$ in $C_{c}^{\infty}\left(U\left(z_{0}\right)\right)$ such that $\theta \equiv 1$ within $\frac{1}{2} U\left(z_{0}\right)$ and let $\rho=\theta \sigma$, we deduce that $\rho \in F_{1,2}^{1}\left(\mathbf{R}^{n}\right)$ and

$$
\left|\int_{\Omega} v_{U} \cdot \nabla \rho d x\right| \leq C \cdot\left\|v_{U}\right\|_{b m o} \cdot\|\nabla \rho\|_{h^{1}} \leq C \cdot\|v\|_{B M O_{b}^{\mu, \nu}(\Omega)} \cdot\|\nabla \rho\|_{h^{1}}
$$

Therefore,

$$
\left|\int_{\Gamma \cap \frac{1}{2} U\left(z_{0}\right)} v \cdot \mathbf{n} \varphi d x^{n-1}\right| \leq C \cdot\|v\|_{B M O_{b}^{\mu, \nu}(\Omega)} \cdot\|\varphi\|_{L^{1}\left(\Gamma \cap \frac{1}{2} U\left(z_{0}\right)\right)}
$$

The proof is therefore complete.

### 3.5 Appendix

We shall prove Lemma 3.4.4. We first recall a simple property of a matrix.
Proposition 3.5.1. Let $A$ be an invertible matrix

$$
A=\left(\vec{a}_{1}, \ldots, \vec{a}_{n}\right)
$$

when $\vec{a}_{j}=^{t}\left(a_{i j}\right)_{1 \leq i \leq n}$ is a column vector. Assume that $\vec{a}_{n}$ is a unit vector and orthogonal to $\vec{a}_{j}$ with $1 \leq j \leq n-1$. Then $n$-row vector of $A^{-1}$ equals ${ }^{t} \vec{a}_{n}$. In other words, if one writes $A^{-1}=\left(b_{i j}\right)_{1 \leq i, j \leq n}$, then $b_{n j}=a_{j n}$ for $1 \leq j \leq n$.

Proof. By definition the row vector $\vec{b}=\left(b_{n j}\right)_{1 \leq j \leq n}$ must satisfies $\vec{b} \cdot \vec{a}_{j}=0(j=1, \ldots, n-1)$, $\vec{b} \cdot \vec{a}_{n}=1$. Since $\left\{\vec{a}_{j}\right\}_{j=1}^{n-1}$ spans $\mathbf{R}^{n-1}$ orthogonal to $\vec{a}_{n}$, first identities imply that $\vec{b}$ is parallel to $\vec{a}_{n}$. We thus conclude that $\vec{b}=\vec{a}_{n}$ since $\vec{b} \cdot \vec{a}_{n}=1$ and $\left|\vec{a}_{n}\right|=1$.

Proof of Lemma 3.4.4. We recall the explicit representation (4.4.1) of the normal coordinate system. The Jacobi matrix from $y \longmapsto x$ is of the form

$$
A=\left(\vec{a}_{1}, \ldots, \vec{a}_{n}\right)
$$

with $\vec{a}_{j}=^{t}\left(\delta_{i j}-y_{n} \partial_{j} \mathbf{n}_{i}\left(y^{\prime}, \psi\left(y^{\prime}\right)\right), \partial_{j} \psi\left(y^{\prime}\right)-y_{n} \partial_{j} \mathbf{n}_{n}\left(y^{\prime}, \psi\left(y^{\prime}\right)\right)\right)_{1 \leq i \leq n-1}, 1 \leq j \leq n-1$,

$$
\vec{a}_{n}=-{ }^{t} \mathbf{n}\left(y^{\prime}, \psi\left(y^{\prime}\right)\right) \quad \text { where } \quad \mathbf{n}=-\nabla d_{\Omega}
$$

Note that the vector $\left(\delta_{i j}, \partial_{j} \psi\left(y^{\prime}\right)\right)_{1 \leq i \leq n-1}$ is a tangential vector to $\Gamma$. Moreover, the vector $\left(\partial_{j} \mathbf{n}_{1}, \ldots, \partial_{j} \mathbf{n}_{n}\right)$ is also tangential since $\partial_{j} \mathbf{n} \cdot \mathbf{n}=\partial_{j}|\mathbf{n}|^{2} / 2=0$. Thus $\vec{a}_{j}$ is orthogonal to $\vec{a}_{n}$ for $1 \leq j \leq n-1$. The invertibility of $A$ is guaranteed if $y_{n}<R_{*}$.

By a chain rule we have

$$
\begin{aligned}
\bar{w} & =\sum_{j=1}^{n} \tilde{w}_{j}(y)\left(\partial / \partial y_{j}\right) \\
& =\sum_{i=1}^{n} \sum_{j=1}^{n} \tilde{w}_{j} \frac{\partial x_{i}}{\partial y_{j}} \frac{\partial}{\partial x_{i}}
\end{aligned}
$$

so that

$$
w_{i}(x(y))=\sum_{j=1}^{n} \tilde{w}_{j}(y) \frac{\partial x_{i}}{\partial y_{j}} \quad \text { i.e., } \quad w=A \tilde{w},
$$

where $A=\left(\partial x_{i} / \partial y_{j}\right)_{1 \leq i, j \leq n}, \tilde{w}=^{t}\left(\tilde{w}_{i}, \ldots, \tilde{w}_{n}\right), w=^{t}\left(w_{1}, \ldots, w_{n}\right)$. Thus

$$
\tilde{w}=A^{-1} w .
$$

By Proposition 3.5.1, the last row of $A^{-1}$ equals $\nabla d_{\Omega}$.
We thus conclude that $\tilde{w}_{n}=\nabla d_{\Omega} \cdot w$. This is what we would like to prove.

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## Chapter 4

## The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

We introduce a space of vector fields with bounded mean oscillation whose "tangential" and "normal" components to the boundary behave differently. We establish its Helmholtz decomposition when the domain is bounded. This substantially extends the authors' earlier result for a half space.

### 4.1 Introduction

The Helmholtz decomposition of a vector field is a fundamental tool to analyze the Stokes and the Navier-Stokes equations. It is formally a decomposition of a vector field $v=$ $\left(v^{1}, \ldots, v^{n}\right)$ in a domain $\Omega$ of $\mathbf{R}^{n}$ into

$$
\begin{equation*}
v=v_{0}+\nabla q \tag{4.1.1}
\end{equation*}
$$

here $v_{0}$ is a divergence free vector field satisfying supplemental conditions like boundary condition and $\nabla q$ denotes the gradient of a function (scalar field) $q$. If $v$ is in $L^{p}(1<$ $p<\infty)$ in $\Omega$, such a decomposition is well-studied. For example, a topological direct sum decomposition

$$
\left(L^{p}(\Omega)\right)^{n}=L_{\sigma}^{p}(\Omega) \oplus G^{p}(\Omega)
$$

holds for various domains including $\Omega=\mathbf{R}^{n}$, a half space $\mathbf{R}_{+}^{n}$, a bounded smooth domain [8]; see e.g. G. P. Galdi [9]. Here, $L_{\sigma}^{p}(\Omega)$ denotes the $L^{p}$-closure of the space of all div-free vector fields compactly supported in $\Omega$ and $G^{p}(\Omega)$ denotes the totality of $L^{p}$ gradient fields. It is impossible to extend this Helmholtz decomposition to $L^{\infty}$ even if $\Omega=\mathbf{R}^{n}$ since the projection $v \mapsto \nabla q$ is a composite of the Riesz operators which is not bounded in $L^{\infty}$. We have to replace $L^{\infty}$ with a class of functions of bounded mean oscillation. However, if the vector field is of bounded mean oscillation ( $B M O$ for short), such a problem is only studied when $\Omega$ is a half space $\mathbf{R}_{+}^{n}$ [10], where the boundary is flat.

Our goal is to establish the Helmholtz decomposition of $B M O$ vector fields in a smooth bounded domain in $\mathbf{R}^{n}$, which is a typical example of a domain with curved boundary.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Although the space of $B M O$ functions in $\mathbf{R}^{n}$ is well studied, the situation is less clear when one considers such a space in a domain, because there are several possible definitions. One should be careful about the behavior of a function near the boundary $\Gamma=\partial \Omega$. In this chapter we study a space of $B M O$ vector fields introduced in [11] and establish its Helmholtz decomposition when $\Omega$ is a bounded $C^{3}$ domain.

Let us recall the space $v B M O(\Omega)$ introduced in [11]. We first recall the $B M O$ seminorm for $\mu \in(0, \infty]$. For a locally integrable function $f$, i.e., $f \in L_{\text {loc }}^{1}(\Omega)$ we define

$$
[f]_{B M O^{\mu}(\Omega)}:=\sup \left\{\left.\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f(y)-f_{B_{r}(x)}\right| d y \right\rvert\, B_{r}(x) \subset \Omega, r<\mu\right\}
$$

where $f_{B}$ denotes the average over $B$, i.e.,

$$
f_{B}:=\frac{1}{|B|} \int_{B} f(y) d y
$$

and $B_{r}(x)$ denotes the closed ball of radius $r$ centered at $x$ and $|B|$ denotes the Lebesgue measure of $B$. The space $B M O^{\mu}(\Omega)$ is defined as

$$
B M O^{\mu}(\Omega):=\left\{f \in L_{\mathrm{loc}}^{1}(\Omega) \mid[f]_{\text {BMO }^{\mu}}<\infty\right\}
$$

This space may not agree with the space of restrictions $r_{\Omega} f$ of $f \in B M O^{\mu}\left(\mathbf{R}^{n}\right)$. As in [1], $[2],[3],[4]$ we introduce a seminorm controlling the boundary behavior. For $\nu \in(0, \infty]$, we set

$$
[f]_{b^{\nu}}:=\sup \left\{r^{-n} \int_{\Omega \cap B_{r}(x)}|f(y)| d y \mid x \in \Gamma, 0<r<\nu\right\}
$$

In these papers, the space

$$
B M O_{b}^{\mu, \nu}(\Omega):=\left\{f \in \operatorname{BMO}^{\mu}(\Omega) \mid[f]_{b^{\nu}}<\infty\right\}
$$

is considered. Note that this space $B M O_{b}^{\infty, \infty}(\Omega)$ is identified with Miyachi's $B M O$ introduced by [19] if $\Omega$ is a bounded Lipschitz domain or a Lipschitz half space as proved in [4]. However, unfortunately, it turns out such a boundary control for whole components of vector fields is too strict to have the Helmholtz decomposition. We separate tangential and normal components. Let $d_{\Gamma}(x)$ denote the distance from the boundary $\Gamma$, i.e.,

$$
d_{\Gamma}(x):=\inf \{|x-y|, y \in \Gamma\}
$$

For vector fields, we consider

$$
v B M O^{\mu, \nu}(\Omega):=\left\{v \in\left(B M O^{\mu}(\Omega)\right)^{n} \mid\left[\nabla d_{\Gamma} \cdot v\right]_{b^{\nu}}<\infty\right\}
$$

where . denotes the standard inner product in $\mathbf{R}^{n}$. The quantity $\left(\nabla d_{\Gamma} \cdot v\right) \nabla d_{\Gamma}$ on $\Gamma$ is the component of $v$ normal to the boundary $\Gamma$. We set

$$
[v]_{v B M O^{\mu, \nu}(\Omega)}:=[v]_{B M O^{\mu}(\Omega)}+\left[\nabla d_{\Gamma} \cdot v\right]_{b^{\nu}}
$$

If $\Omega$ is the half space, this is not a norm but a seminorm. However, if it has a fully curved part in the sense of [11, Definition 7 ], then this becomes a norm [11, Lemma 8]. In particular, when $\Omega$ is a bounded $C^{2}$ domain, this is a norm. Roughly speaking, the boundary behavior of a vector field $v$ is controlled for only normal part of $v$ if $v \in v B M O^{\mu, \nu}(\Omega)$. For
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
a bounded domain, this norm is equivalent no matter how $\mu$ and $\nu$ are taken; in other words, $v B M O^{\mu, \nu}(\Omega)=v B M O^{\infty, \infty}(\Omega)$. This is because $v B M O^{\mu, \nu}(\Omega) \subset L^{1}(\Omega)$ when $\Omega$ is bounded, which follows from the characterization of $v B M O^{\mu, \nu}(\Omega)$ in [11, Theorem 9]. We shall simply write $v B M O^{\mu, \nu}(\Omega)$ as $v B M O(\Omega)$. We are now in a position to state our main result.

Theorem 4.1.1. Let $\Omega$ be a bounded $C^{3}$ domain in $\mathbf{R}^{n}$. Then the topological direct sum decomposition

$$
\begin{equation*}
v B M O(\Omega)=v B M O_{\sigma}(\Omega) \oplus G v B M O(\Omega) \tag{4.1.2}
\end{equation*}
$$

holds with

$$
\begin{aligned}
v B M O_{\sigma}(\Omega) & :=\{v \in v B M O(\Omega) \mid \operatorname{div} v=0 \text { in } \Omega, v \cdot \mathbf{n}=0 \text { on } \Gamma\} \\
G v B M O(\Omega) & :=\left\{\nabla q \in v B M O(\Omega) \mid q \in L_{\mathrm{loc}}^{1}(\Omega)\right\}
\end{aligned}
$$

where $\mathbf{n}$ denotes the exterior unit normal vector field. In other words, for $v \in v B M O(\Omega)$, there is unique $v_{0} \in v B M O_{\sigma}(\Omega)$ and $\nabla q \in G v B M O(\Omega)$ satisfying $v=v_{0}+\nabla q$. Moreover, the mapping $v \mapsto v_{0}, v \mapsto \nabla q$ is bounded in $v B M O(\Omega)$.

As shown in [11], the norm trace $v \cdot \mathbf{n}$ is well defined as an element of $L^{\infty}(\Gamma)$ for $v \in v B M O(\Omega)$ with $\operatorname{div} v=0$. So far, the Helmholtz decomposition $B M O$ type space in a domain is only known for $v B M O^{\infty, \infty}$ when $\Omega$ is the half space

$$
\mathbf{R}_{+}^{n}=\left\{x=\left(x_{1}, \ldots, x_{n}\right) \in \mathbf{R}^{n} \mid x_{n}>0\right\}
$$

as shown in [10], where the normal trace is taken in locally $H^{-1 / 2}$ sense.
Here is our strategy to show Theorem 6.1.1. For a vector field $v$, we construct a linear map $v \longmapsto q_{1}$ such that $q_{1}$ satisfies

$$
-\Delta q_{1}=\operatorname{div} v \quad \text { in } \quad \Omega
$$

where the divergence is taken in the sense of distribution. There are many ways to construct such a map because there is no boundary condition. A naive way is to extend $v$ in a suitable way to a function $\bar{v}$ on $\mathbf{R}^{n}$ so that $v \longmapsto \bar{v}$ is linear. We next consider the volume potential of $\operatorname{div} \bar{v}$, i.e.,

$$
q_{0}(x):=\int_{\mathbf{R}^{n}} E(x-y) \operatorname{div} \bar{v}(y) d y=E * \operatorname{div} \bar{v}
$$

where $E$ is the fundamental solution of $-\Delta$ in $\mathbf{R}^{n}$, i.e.,

$$
E(x):= \begin{cases}-\log |x| / 2 \pi & (n=2) \\ |x|^{2-n} /(n(n-2) \alpha(n)) & (n \geq 3)\end{cases}
$$

where $\alpha(n)$ denotes the volume of the unit ball $B_{1}(0)$ of $\mathbf{R}^{n}$. By the famous $B M O-B M O$ estimate due to Fefferman and Stein [7], we have

$$
\left[\nabla q_{0}\right]_{B M O \infty\left(\mathbf{R}^{n}\right)} \leq C_{0}[\bar{v}]_{B M O \infty}\left(\mathbf{R}^{n}\right)
$$

with $C_{0}>0$ independent of $\bar{v}$. However, it is difficult to control $\left[\nabla d_{\Gamma} \cdot \nabla q_{0}\right]_{b^{\nu}}$ so we construct another function $q_{1}$ instead of $q_{0}$.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Although $B M O$ space does not allow the standard cut-off procedure, our space is in $L^{1}$, so we are able to decompose $v$ into two parts $v=v_{1}+v_{2}$ such that the support of $v_{2}$ is close to $\Gamma$ while the support of $v_{1}$ is away from $\Gamma$; see Proposition 6.2.4. For $v_{1}$ we just set

$$
q_{1}^{1}=E * \operatorname{div} v_{1}
$$

by extending $v_{1}$ as zero outside its support. Then, the $L^{\infty}$ bound for $\nabla q_{1}^{1}$ is well controlled near $\Gamma$, which yields a bound for $b^{\nu}$ semi-norm. To estimate $v_{2}$, we use a normal coordinate system near $\Gamma$ and reduce the problem to the half space. Let $d$ denotes the signed distance function where $d=d_{\Gamma}$ in $\Omega$ and $d=-d_{\Gamma}$ outside $\Omega$. We extend $v_{2}$ to $\mathbf{R}^{n}$ so that the normal part $\left(\nabla d \cdot \bar{v}_{2}\right) \nabla d$ is odd and the tangential part $\overline{v_{2}}-\left(\nabla d \cdot \overline{v_{2}}\right) \nabla d$ is even in the direction of $\nabla d$ with respect to $\Gamma$. In such type of coordinate system, the minus Laplacian can be transformed as

$$
L=A-B+\text { lower order terms, } A=-\Delta_{\eta}, B=\sum_{1 \leq i, j \leq n-1} \partial_{\eta_{i}} b_{i j} \partial_{\eta_{j}}
$$

where $\eta_{n}$ is the normal direction to the boundary so that $\left\{\eta_{n}>0\right\}$ is the half space. By choosing a suitable coordinate system to represent $\Gamma$ locally, we are able to arrange $b_{i j}=0$ at one point of the boundary of the local coordinate system. We use a freezing coefficient method to construct volume potential $q_{1}^{2}$ and $q_{1}^{3}$, which corresponds to the contribution from the tangential part ${\overline{v_{2}}}^{\text {tan }}$ and the normal part ${\overline{v_{2}}}^{\text {nor }}$ respectively. Since the leading term of $\operatorname{div}{\overline{v_{2}}}^{\text {nor }}$ in normal coordinate consists of the differential of $\eta_{n}$ only, if we extend the coefficient $b_{i j}$ even in $\eta_{n}, q_{1}^{3}$ is constructed so that the leading term of $\nabla d \cdot \nabla q_{1}^{3}$ is odd in the direction of $\nabla d$. On the other hand, as the leading term of div $\bar{v}_{2}^{\tan }$ in normal coordinate consists of the differential of $\eta^{\prime}=\left(\eta_{1}, \ldots, \eta_{n-1}\right)$ only, the even extension of $b_{i j}$ in $\eta_{n}$ gives rise to $q_{1}^{2}$ so that the leading term of $\nabla d \cdot \nabla q_{1}^{2}$ is also odd in the direction of $\nabla d$. Disregarding lower order terms and localization procedure, we set $q_{1}^{2}$ and $q_{1}^{3}$ of the form

$$
\begin{aligned}
& q_{1}^{2}=-L^{-1} \operatorname{div} \bar{v}_{2}^{\mathrm{tan}}=-A^{-1}\left(I-B A^{-1}\right)^{-1} \operatorname{div} \bar{v}_{2}^{\mathrm{tan}} \\
& q_{1}^{3}=-L^{-1} \operatorname{div} \bar{v}_{2}^{\text {nor }}=-A^{-1}\left(I-B A^{-1}\right)^{-1} \operatorname{div} \bar{v}_{2}^{\text {nor }}
\end{aligned}
$$

One is able to arrange $B A^{-1}$ small by taking a small neighborhood of a boundary point. Then $\left(I-B A^{-1}\right)^{-1}$ is given as the Neumann series $\sum_{m=0}^{\infty}\left(B A^{-1}\right)^{m}$. We are able to establish $B M O-B M O$ estimate for $\nabla q_{1}^{2}$ and $\nabla q_{1}^{3}$, i.e.

$$
\left[\nabla q_{1}^{2}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{0}^{\prime}\left[\bar{v}_{2}^{\mathrm{tan}}\right]_{B M O\left(\mathbf{R}^{n}\right)},\left[\nabla q_{1}^{3}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{0}^{\prime}\left[\bar{v}_{2}^{\mathrm{nor}}\right]_{B M O\left(\mathbf{R}^{n}\right)}
$$

with some constant $C_{0}^{\prime}$ independent of $\overline{v_{2}}$. Since the leading term of $\nabla d \cdot\left(\nabla q_{1}^{2}+\nabla q_{1}^{3}\right)$ is odd in the direction of $\nabla d$ with respect to $\Gamma$, the $B M O$ bound implies $b^{\nu}$ bound. Note that $\left[\bar{v}_{2}{ }^{\text {nor }}\right]_{B M O\left(\mathbf{R}^{n}\right)}$ is controlled by $\left[v_{2}\right]_{b^{\nu}}$ and $\left[v_{2}\right]_{B M O(\Omega)}$ since ${\overline{v_{2}}}^{\text {nor }}$ is odd in the direction of $\nabla d$ with respect to $\Gamma$. By the procedure sketched above, we are able to construct a suitable operator by setting $q_{1}=q_{1}^{1}+q_{1}^{2}+q_{1}^{3}$.
Theorem 4.1.2 (Construction of a suitable volume potential). Let $\Omega$ be a bounded $C^{3}$ domain in $\mathbf{R}^{n}$. Then, there exists a linear operator $v \longmapsto q_{1}$ from $v B M O(\Omega)$ to $L^{\infty}(\Omega)$ such that

$$
-\Delta q_{1}=\operatorname{div} v \quad \text { in } \quad \Omega
$$

and that there exists a constant $C_{1}=C_{1}(\Omega)$ satisfying

$$
\left\|\nabla q_{1}\right\|_{v B M O(\Omega)} \leq C_{1}\|v\|_{v B M O(\Omega)}
$$

In particular, the operator $v \longmapsto \nabla q_{1}$ is a bounded linear operator in $v B M O(\Omega)$.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

By this operator, we observe that $w=v-\nabla q_{1}$ is divergence free in $\Omega$. Unfortunately, this $w$ may not fulfill the trace condition $w \cdot \mathbf{n}=0$ on the boundary $\Gamma$. We construct another potential $q_{2}$ by solving the Neumann problem

$$
\begin{array}{ll}
\Delta q_{2}=0 & \text { in } \quad \Omega \\
\frac{\partial q_{2}}{\partial n}=w \cdot \mathbf{n} & \text { on } \quad \Gamma
\end{array}
$$

We then set $q=q_{1}+q_{2}$. Since $\partial q_{2} / \partial \mathbf{n}=\nabla q_{2} \cdot \mathbf{n}, v_{0}=v-\nabla q$ gives the Helmholtz decomposition (6.1.1). To complete the proof of Theorem 6.1.1, it suffices to prove that $\left\|\nabla q_{2}\right\|_{v B M O(\Omega)}$ is bounded by a constant multiply of $\|v\|_{v B M O(\Omega)}$.

Lemma 4.1.3 (Estimate of the normal trace). Let $\Omega$ be a bounded $C^{2+\kappa}$ domain in $\mathbf{R}^{n}$ with $\kappa \in(0,1)$. Then there is a constant $C_{2}=C_{2}(\Omega)$ such that

$$
\|w \cdot \mathbf{n}\|_{L^{\infty}(\Gamma)} \leq C_{2}\|w\|_{v B M O(\Omega)}
$$

for all $w \in v B M O(\Omega)$ with $\operatorname{div} w=0$.
This is a special case of the trace theorem established in [11]. We finally need the estimate for the Neumann problem.

Lemma 4.1.4 (Estimate for the Neumann problem). Let $\Omega$ be a bounded $C^{2}$ domain. For $g \in L^{\infty}(\Gamma)$ satisfying $\int_{\Gamma} g d \mathcal{H}^{n-1}=0$, there exists a unique (up to constant) solution $u$ to the Neumann problem

$$
\begin{array}{rlrl}
\Delta u & =0 & \text { in } \quad \Omega \\
\frac{\partial u}{\partial \mathbf{n}}=g & \text { on } \quad \Gamma \tag{4.1.3}
\end{array}
$$

such that the operator $g \longmapsto u$ is linear and that there exists a constant $C_{3}=C_{3}(\Omega)$ such that

$$
\|\nabla u\|_{v B M O(\Omega)} \leq C_{3}\|g\|_{L^{\infty}(\Gamma)}
$$

Combining these two lemmas, Theorem 6.1.2 yields

$$
\begin{aligned}
\left\|\nabla q_{2}\right\|_{v B M O(\Omega)} & \leq C_{3} C_{2}\left\|v-\nabla q_{1}\right\|_{v B M O(\Omega)} \\
& \leq C_{3} C_{2}\left(1+C_{1}\right)\|v\|_{v B M O(\Omega)}
\end{aligned}
$$

Setting $q=q_{1}+q_{2}$ and $v_{0}=v-\nabla q$, we now observe that the projections $v \longmapsto v_{0}, v \longmapsto \nabla q$ are bounded in $v B M O(\Omega)$, which yields (6.1.3) in Theorem 6.1.1.

To show Lemma 6.1.4 let $N(x, y)$ be the Neumann Green function. Then a solution of (6.1.4) is given by $\int_{\Gamma} N(x, y) g(y) \mathrm{d} \mathcal{H}^{n-1}$. It is well-known (see e.g. [12, Appendix]) that leading part of $N$ is $E(x-y)$. We have to estimate

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g\right)\right\|_{v B M O^{\infty, \nu}(\Omega)}
$$

Here $\delta_{\Gamma}$ denotes the delta function supported on $\Gamma$, i.e.,

$$
\delta_{\Gamma}: \psi \mapsto \int_{\Gamma} \psi \mathrm{d} \mathcal{H}^{n-1}
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
for $\psi \in C_{c}^{\infty}\left(\mathbb{R}^{n}\right)$. We take a $C^{2}$ cutoff function $\theta \geq 0$ such that $\theta(\sigma)=1$ for $\sigma \leq 1, \theta(\sigma)=0$ for $\sigma \geq 2$. We take $\delta$ small so that $2 \delta$ is smaller than the reach of $\Gamma$. By this choice, $\theta_{d}=\theta(d / \delta)$ is $C^{2}$ in $\mathbf{R}^{n}$, where $d$ denotes the signed distance function from $\Gamma$ so that $\nabla d=-\mathbf{n}$ on $\Gamma$. For $g \in L^{\infty}(\Gamma)$, we extend $g$ so that $\nabla d \cdot g=0$ near the $2 \delta$-neighborhood of $\Gamma$. Let $g_{e}$ denotes this extension and set $g_{e, c}=\theta_{d} g_{e}$. A key observation is that

$$
\begin{aligned}
& \delta_{\Gamma} \otimes g=\left(\nabla 1_{\Omega} \cdot \nabla d\right) g_{e, c}=\operatorname{div}\left(g_{e, c} 1_{\Omega} \nabla d\right)-1_{\Omega} \operatorname{div}\left(g_{e, c} \nabla d\right) \\
& \operatorname{div}\left(g_{e, c} \nabla d\right)=g_{e, c} \Delta d+\nabla d \cdot \nabla g_{e, c}=g_{e, c} \Delta d+\frac{\theta^{\prime}(d / \delta)}{\delta} g_{e}
\end{aligned}
$$

where $1_{\Omega}$ is the characteristic function of $\Omega$. The leading (singular) part of $\nabla E *\left(\delta_{\Gamma} \otimes g\right)$ is the term involving $\operatorname{div}\left(g_{e, c} 1_{\Omega} \nabla d\right)$. The famous $L^{\infty}-B M O$ estimate for the singular integral operator $\nabla E * \operatorname{div}$ yields

$$
\left\|\nabla E * \operatorname{div}\left(g_{e, c} 1_{\Omega} \nabla d\right)\right\|_{B M O\left(\mathbf{R}^{n}\right)} \leq C\left\|g_{e, c} \nabla d\right\|_{L^{\infty}(\Omega)} \leq C^{\prime}\|g\|_{L^{\infty}(\Gamma)}
$$

with $C$ and $C^{\prime}$ independent of $g$. All other terms can be estimated easily since the integral kernel is integrable. A direct calculation gives an $L^{\infty}$ estimate near $\Gamma$ for $\nabla d \cdot \nabla E *\left(\delta_{\Gamma} \otimes g\right)$ which yields

$$
\left[\nabla d \cdot \nabla E *\left(\delta_{\Gamma} \otimes g\right)\right]_{b^{\nu}} \leq C_{4}\|g\|_{L^{\infty}(\Gamma)}
$$

with $C_{4}$ independent of $g$, but it is impossible to estimate $b^{\nu}$-seminorm of the tangential part. This is the main reason why we use $v B M O$ instead of $B M O_{b}$-type space where $b^{\nu}$-boundedness of ALL components of vector fields is imposed; see the end of Section 6.3.2.

To extend our results to a more general domain it seems to be reasonable to consider $v B M O \cap L^{2}$. This is because $L^{p} \cap L^{2}(p>2)$ admits the Helmholtz decomposition for arbitrary uniformly $C^{2}$ domains as proved in [5], [6].

Our approach in this chapter is to derive the boundedness of the operator $v \mapsto \nabla q$ by a potential-theoretic approach. In $L^{p}$ setting there is a variational approach based on duality introduced by [21]; see also [5]. The key estimate is

$$
\|\nabla q\|_{L^{p}(\Omega)} \leq C_{5} \sup \left\{\int_{\Omega} \nabla q \cdot \nabla \varphi d x \mid\|\nabla \varphi\|_{L^{p^{\prime}}(\Omega)} \leq 1\right\}
$$

with $C_{5}$ independent of $q$, where $1 / p+1 / p^{\prime}=1,1<p<\infty$. Formally, this estimate yields the desired bound $\|\nabla q\|_{L^{p}(\Omega)} \leq C_{5}\|v\|_{L^{p}(\Omega)}$ since

$$
\int_{\Omega} \nabla q \cdot \nabla \varphi d x=\int_{\Omega} v \cdot \nabla \varphi d x
$$

At this moment, it is not clear that similar estimate holds if one replaces $L^{p}(\Omega)$ by $v B M O$ since the predual space of $v B M O$ is not clear.

For $B M O_{b}$ type solution, it is known that the Stokes semigroup is analytic [1], [3]. However, it is nontrivial to extend to the space $v B M O$ since in the half space the Stokes operator with Dirichlet boundary condition does not generate a semigroup because $[u(t)]_{v B M O}$ for the solution $u(t)$ may be non-zero for $t>0$ for initial data $u_{0}$ with $\left[u_{0}\right]_{v B M O}=0$ so that $u_{0}^{\mathrm{tan}}$ may be a non-zero constant [1, Example 6.5].

This chapter is organized as follows. In Section 4.2, to construct a volume potential of $\operatorname{div} v$, we localize the problem and reduce the problem to small neighborhoods of points on the boundary. In Section 4.3, we construct a leading part of the volume potential by a perturbation method called the freezing coefficient method. In these two sections, we complete the proof of Theorem 6.1.2. In Section 4.4, we prove Lemma 6.1.4 by estimating the single layer potential.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

### 4.2 Construction of volume potential

For $v \in v B M O(\Omega)$, we shall construct a suitable potential $q_{1}$ so that $v \longmapsto \nabla q_{1}$ is a bounded linear operator in $v B M O$ as stated in Theorem 6.1.2. In this section, as a preliminary, we reduce the problem to the case that the support of $v$ is contained in a small neighborhood of a point on the boundary and it consists of only normal part.

### 4.2.1 Localization procedure

Let $\Omega$ be a uniformly $C^{k}$ domain in $\mathbf{R}^{n}(k \geq 1)$. In other words, there exists $r_{*}, \delta_{*}>0$ such that for each $z_{0} \in \Gamma$, up to translation and rotation, there exists a function $h_{z_{0}}$ which is $C^{k}$ in a closed ball $B_{r_{*}}\left(0^{\prime}\right)$ of radius $r_{*}$ centered at the origin $0^{\prime}$ of $\mathbf{R}^{n-1}$ satisfying following properties:
(i) $K_{\Gamma}:=\sup _{B_{r *}\left(0^{\prime}\right)}\left|\left(\nabla^{\prime}\right)^{s} h_{z_{0}}\right|<\infty$ for $s=0,1,2, \ldots, k$, where $\nabla^{\prime}$ denotes the gradient in $x^{\prime} \in \mathbf{R}^{n-1} ; \nabla^{\prime} h\left(0^{\prime}\right)=0, h\left(0^{\prime}\right)=0$,

$$
\begin{align*}
\Omega \cap U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right) & =\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|h_{z_{0}}\left(x^{\prime}\right)<x_{n}<h_{z_{0}}\left(x^{\prime}\right)+\delta_{*},\left|x^{\prime}\right|<r_{*}\right\}\right. \text { for }  \tag{ii}\\
U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right) & :=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|h_{z_{0}}\left(x^{\prime}\right)-\delta_{*}<x_{n}<h_{z_{0}}\left(x^{\prime}\right)+\delta_{*},\left|x^{\prime}\right|<r_{*}\right\},\right.
\end{align*}
$$

(iii) $\Gamma \cap U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|x_{n}=h_{z_{0}}\left(x^{\prime}\right),\left|x^{\prime}\right|<r_{*}\right\}\right.$.

A bounded $C^{k}$ domain is, of course, a uniformly $C^{k}$ domain.
Let $d$ denote the signed distance function from $\Gamma$ which is defined by

$$
d(x)=\left\{\begin{array}{rrr}
\inf _{y \in \Gamma}|x-y| & \text { for } & x \in \Omega,  \tag{4.2.1}\\
-\inf _{y \in \Gamma}|x-y| & \text { for } & x \notin \Omega
\end{array}\right.
$$

so that $d(x)=d_{\Gamma}(x)$ for $x \in \Omega$. If $\Omega$ is a bounded $C^{2}$ domain, then there is $R_{*}>0$ such that if $|d(x)|<R_{*}$, there is unique point $\pi x$ such that $|x-\pi x|=|d(x)|$. The supremum of such $R_{*}$ is called the reach of $\Omega$ and $\Omega^{c}$. Moreover, $d$ is $C^{2}$ in the $R_{*}$-neighborhood of $\Gamma$, i.e., $d \in C^{2}\left(\Gamma_{R_{*}}^{\mathbf{R}^{n}}\right)$ with

$$
\Gamma_{R_{*}}^{\mathbf{R}^{n}}:=\left\{x \in \mathbf{R}^{n}| | d(x) \mid<R_{*}\right\} ;
$$

see [13, Chap. 14, Appendix], [17, §4.4]. Note that $R_{*}$ satisfies

$$
R_{*}=\min \left(R_{*}^{\Omega}, R_{*}^{\Omega c}\right),
$$

where $R_{*}^{\Omega}$ is the reach of $\Gamma$ in $\Omega$ while $R_{*}^{\Omega c}$ is the reach of $\Gamma$ in the complement $\Omega^{c}$ of $\Omega$. Let $K_{\Gamma}^{*}:=\max \left\{K_{\Gamma}, 1\right\}$. There exists $0<\rho_{0}<\min \left(r_{*}, \delta_{*}, \frac{R_{*}}{2}, \frac{1}{2 n K_{\Gamma}^{*}}\right)$ such that

$$
U_{\rho}\left(z_{0}\right):=\left\{x \in \mathbf{R}^{n}\left|(\pi x)^{\prime} \in \operatorname{int} B_{\rho}\left(0^{\prime}\right),|d(x)|<\rho\right\}\right.
$$

is contained in the coordinate chart $U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)$ for any $\rho \leq \rho_{0}$.
We always take $\rho<\rho_{0}$. Since $\Omega$ is bounded and

$$
\bigcup_{z \in \Gamma} U_{\rho}(z)
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
covers the compact set $K=\operatorname{cl}\left(\Gamma_{\rho / 2}^{\mathbf{R}^{n}}\right)$, there exists a finite subcover $\left\{U_{\rho}\left(z_{j}\right)\right\}_{j=1}^{m}$ of $K$, where the number $m$ depends on $\rho$. For $\sigma>0$, we denote that

$$
\Omega^{\sigma}=\Omega \backslash \Gamma_{\sigma}^{\mathbf{R}^{n}}, \quad U_{\sigma, j}:=U_{\sigma}\left(z_{j}\right)
$$

Observe that

$$
\bar{\Omega} \subset \bigcup_{j=1}^{m} U_{\rho, j} \cup \Omega^{\rho / 2}
$$

Let $\left\{\varphi_{j}\right\}_{j=0}^{m}$ be a partition of the unity associated with $\left\{U_{\rho, j}\right\} \cup\left\{\Omega^{\rho / 2}\right\}$ in the sense that

$$
\begin{aligned}
& \varphi_{j} \in C_{c}^{\infty}\left(U_{\rho, j} \cap \bar{\Omega}\right), \quad 0 \leq \varphi_{j} \leq 1 \quad \text { for } \quad j=1, \ldots, m \\
& \varphi_{0} \in C_{c}^{\infty}\left(\Omega^{\rho / 2}\right), \quad 0 \leq \varphi_{0} \leq 1, \quad \varphi_{0}=1 \quad \text { in } \quad \Omega^{\rho}
\end{aligned}
$$

and

$$
\sum_{j=0}^{m} \varphi_{j}=1 \quad \text { in } \quad \bar{\Omega}
$$

Here $C_{c}^{\infty}(W)$ denotes the space of all smooth function in $W$ whose support is compact in $W$.

Throughout this chapter, unless otherwise specified, the symbol $C$ in an inequality represents a positive constant independent of quantities that appeared in the inequality. For a fixed $\rho>0, C_{\rho}$ represents a constant depending only on $\rho$. $C_{n}$ represents a constant depending only on $n$ and $C_{\Omega, n}$ represents a constant depending only on $\Omega$ and $n$.

### 4.2.2 Cut-off and extension

In general, multiplication by a smooth function to $B M O$ is not bounded in $B M O$. Fortunately, our space is closed by multiplication.
Proposition 4.2.1 (Multiplication). Let $\Omega$ be a bounded $C^{2}$ domain in $\mathbf{R}^{n}$. Let $\varphi \in C^{\gamma}(\Omega)$, $\gamma \in(0,1)$. For each $v \in v B M O(\Omega)$, the function $\varphi v \in v B M O(\Omega)$ satisfies

$$
\|\varphi v\|_{v B M O(\Omega)} \leq C\|\varphi\|_{C^{\gamma}(\Omega)}\|v\|_{v B M O(\Omega)}
$$

with $C$ independent of $\varphi$ and $v$.
Proof. Since

$$
[\nabla d \cdot \varphi v]_{b^{\nu}} \leq\|\varphi\|_{L^{\infty}(\Omega)}[\nabla d \cdot v]_{b^{\nu}}
$$

it suffices to establish the estimate

$$
\begin{equation*}
[\varphi v]_{B M O(\Omega)} \leq c_{0}\|\varphi\|_{C^{\gamma}(\Omega)}\|v\|_{v B M O(\Omega)} \tag{4.2.2}
\end{equation*}
$$

with $c_{0}$ independent of $\varphi$ and $v$. Since a bounded Lipschitz domain is a uniform domain, we are able to apply [11, Theorem 13] to get

$$
[\varphi v]_{B M O(\Omega)} \leq c_{1}\|\varphi\|_{C^{\gamma}(\Omega)}\left([v]_{B M O(\Omega)}+\|v\|_{L^{1}(\Omega)}\right)
$$

This is based on the product estimate of a Hölder function and a function in $b m o\left(\mathbf{R}^{n}\right):=$ $B M O\left(\mathbf{R}^{n}\right) \cap L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)$ where

$$
L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right):=\left\{f \in L_{\mathrm{loc}}^{1}\left(\mathbf{R}^{n}\right)\left|\|f\|_{L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)}:=\sup _{x \in \mathbf{R}^{n}} \int_{B_{1}(x)}\right| f(y) \mid d y<\infty\right\}
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

The space $b m o\left(\mathbf{R}^{n}\right)$ is equipped with the norm

$$
\|f\|_{b m o\left(\mathbf{R}^{n}\right)}:=[f]_{B M O\left(\mathbf{R}^{n}\right)}+\|f\|_{L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)}
$$

for $f \in b m o\left(\mathbf{R}^{n}\right)$. The product estimate for $b m o$ follows from a similar result for a local Hardy space $h^{1}=F_{1,2}^{0}$ [20, Remark 4.4] and duality bmo $=\left(h^{1}\right)^{\prime}[20$, Theorem 3.26]. To handle a function in $\Omega$, we need an extension to conclude [11, Theorem 13]. Fortunately, by the characterization of $v B M O$ for a bounded $C^{2}$ domain [11, Theorem 9],

$$
\|v\|_{L^{1}(\Omega)} \leq c_{2}\|v\|_{v B M O(\Omega)}
$$

Here $c_{j}$ denotes a constant independent of $v$ and $\varphi$ for $j=1,2$. Combining these two estimates, we obtain (4.2.2) with $c_{0}=c_{1}\left(1+c_{2}\right)$. This yields Proposition 6.2.4.

For a bounded $C^{3}$ domain, we next consider an extension based on the normal coordinate in $U_{\rho}\left(z_{0}\right)$ for $\rho \leq \rho_{0}$ of the form

$$
\left\{\begin{array}{l}
x^{\prime}=\eta^{\prime}+\eta_{n} \nabla^{\prime} d\left(\eta^{\prime}, h_{z_{0}}\left(\eta^{\prime}\right)\right) ;  \tag{4.2.3}\\
x_{n}=h_{z_{0}}\left(\eta^{\prime}\right)+\eta_{n} \partial_{x_{n}} d\left(\eta^{\prime}, h_{z_{0}}\left(\eta^{\prime}\right)\right) .
\end{array}\right.
$$

Let $V_{\sigma}:=B_{\sigma}\left(0^{\prime}\right) \times(-\sigma, \sigma)$ for $\sigma \in\left(0, \rho_{0}\right)$. We shall write this coordinate change by $x=\psi(\eta)$ with $\psi \in C^{2}\left(V_{\rho_{0}}\right)$ and

$$
x=\pi x-d(x) \mathbf{n}(\pi x), \quad \mathbf{n}(\pi x)=-\nabla d(\pi x) .
$$

We consider the projection to the direction to $\nabla d$. For $x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}}$, we set

$$
P(x)=\nabla d(\pi x) \otimes \nabla d(\pi x)=\mathbf{n}(\pi x) \otimes \mathbf{n}(\pi x) .
$$

For later convenience, we set $Q(x)=I-P(x)$ which is the tangential projection for $x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}}$. For a function $f$ in $\Gamma_{\rho}^{\mathbf{R}^{n}} \cap \bar{\Omega}$, let $f_{\text {even }}$ (resp. $f_{\text {odd }}$ ) denote its even (odd) extension to $\Gamma_{\rho}^{\mathbf{R}^{n}}$ defined by

$$
\begin{aligned}
& f_{\text {even }}(\pi x+d(x) \mathbf{n}(\pi x))=f(\pi x-d(x) \mathbf{n}(\pi x)) \quad \text { for } \quad x \in \Gamma_{\rho}^{\mathbf{R}^{n}} \backslash \bar{\Omega}, \\
& f_{\text {odd }}(\pi x+d(x) \mathbf{n}(\pi x))=-f(\pi x-d(x) \mathbf{n}(\pi x)) \quad \text { for } \quad x \in \Gamma_{\rho}^{\mathbf{R}^{n}} \backslash \bar{\Omega} .
\end{aligned}
$$

We denote $r_{W}$ to be the restriction in $W$ for any subset $W \subset \mathbf{R}^{n}$. Let $f$ be a function (or a vector field) defined in $V_{\sigma}$ for some $\sigma \in(0, \infty]$. We set $E_{\text {even }} f$ to be the even extension of $f$ in $V_{\sigma} \cap \mathbf{R}_{+}^{n}$ to $V_{\sigma}$ with respect to the $n$-th variable, i.e.,

$$
E_{\text {even }} f\left(\eta^{\prime},-\eta_{n}\right)=f\left(\eta^{\prime}, \eta_{n}\right)
$$

for any $\left(\eta^{\prime}, \eta_{n}\right) \in V_{\sigma} \cap \mathbf{R}_{+}^{n}$.
For $v \in v B M O(\Omega)$ with supp $v \subset U_{\rho}\left(z_{0}\right) \cap \bar{\Omega}$, let $\bar{v}$ be its extension of the form

$$
\begin{equation*}
\bar{v}(x):=\left(P v_{\text {odd }}\right)(x)+\left(Q v_{\text {even }}\right)(x) \tag{4.2.4}
\end{equation*}
$$

for $x \in U_{\rho}\left(z_{0}\right)$. Notice that $\operatorname{supp} \bar{v} \subset U_{\rho}\left(z_{0}\right), \bar{v}$ is indeed defined in $\mathbf{R}^{n}$ with $\bar{v}(x)=0$ for any $x \in U_{\rho}\left(z_{0}\right)^{\text {c }}$. Define

$$
L_{*}:=\sup _{z_{0} \in \Gamma, \rho \leq \rho_{0}} \max \left\{\|\nabla \psi\|_{L^{\infty}\left(V_{\rho}\right)}+\left\|\nabla \psi^{-1}\right\|_{L^{\infty}\left(U_{\rho}\left(z_{0}\right)\right)}, 1\right\} .
$$

Since the boundary $\Gamma$ is uniformly $C^{3}, L_{*}$ is finite that depends on $\Omega$ only. We set $\rho_{0, *}=$ $\rho_{0} / 12 L_{*}$.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Proposition 4.2.2. Let $\Omega \subset \mathbf{R}^{n}$ be a bounded $C^{2}$ domain, $z_{0} \in \Gamma$ and $\rho \in\left(0, \rho_{0, *}\right)$. There exists a constant $C_{\rho}$, which depends on $\rho$ only, such that

$$
\begin{aligned}
{[\bar{v}]_{B M O\left(\mathbf{R}^{n}\right)} } & \leq C_{\rho}\|v\|_{v B M O(\Omega)}, \\
{[\nabla d \cdot \bar{v}]_{b^{\nu}(\Gamma)} } & \leq C_{\rho}\|v\|_{v B M O(\Omega)}
\end{aligned}
$$

for all $v \in v B M O(\Omega)$ with $\operatorname{supp} v \subset U_{\rho}\left(z_{0}\right) \cap \bar{\Omega}$ and $\nu>0$.
In the normal coordinate, $P \bar{v}=P v_{\text {odd }}$ is odd in $\eta_{n}$ and $Q \bar{v}=Q v_{\text {even }}$ is even in $\eta_{n}$. The key idea of proving this proposition is to reduce the problem to the case where the boundary is locally flat by invoking the normal coordinate.

Proof. Since $v B M O(\Omega) \subset L^{1}(\Omega)$, see e.g. [11, Theorem 9], by considering the normal coordinate change $y=\psi(\eta)$ in $U_{\rho}\left(z_{0}\right)$ we can deduce that $v_{\text {even }}, v_{\text {odd }} \in L^{1}\left(\mathbf{R}^{n}\right)$ satisfying

$$
\left\|v_{\text {even }}\right\|_{L^{1}\left(\mathbf{R}^{n}\right)}=\left\|v_{\text {odd }}\right\|_{L^{1}\left(\mathbf{R}^{n}\right)} \leq 2 L_{*}^{2}\|v\|_{L^{1}(\Omega)} .
$$

Hence $\bar{v} \in L^{1}\left(\mathbf{R}^{n}\right)$ satisfies the estimate $\|\bar{v}\|_{L^{1}\left(\mathbf{R}^{n}\right)} \leq C_{\Omega, n}\|v\|_{L^{1}(\Omega)}$. Since $\Omega$ is a uniform domain, by $\left[16\right.$, Theorem 1] there exists $v_{J} \in B M O\left(\mathbf{R}^{n}\right)$ with $r_{\Omega} v_{J}=v$ and

$$
\left[v_{J}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{\Omega, n}[v]_{B M O^{\infty}(\Omega)}
$$

Suppose that $B_{r}(\zeta) \subset V_{4 \rho L_{*}}^{+}:=V_{4 \rho L_{*}} \cap \mathbf{R}_{+}^{n}$. The mean value theorem implies that $\psi\left(B_{r}(\zeta)\right) \subset B_{L_{*} r}(x)$ with $x=\psi(\zeta)$. By change of variables $y=\psi(\eta)$ in $U_{4 \rho L_{*}}\left(z_{0}\right)$, we see that

$$
\begin{aligned}
\frac{1}{\left|B_{r}(\zeta)\right|} \int_{B_{r}(\zeta)}|v \circ \psi(\eta)-c| d \eta & \leq L_{*} \cdot \frac{1}{\left|B_{r}(\zeta)\right|} \int_{\psi\left(B_{r}(\zeta)\right)}|v(y)-c| d y \\
& \leq C_{n} L_{*}^{n+1} \cdot \frac{1}{\left|B_{L_{*} r}(x)\right|} \int_{B_{L_{*} r}(x)}\left|v_{J}(y)-c\right| d y
\end{aligned}
$$

for any constant vector $c \in \mathbf{R}^{n}$. By considering an equivalent definition of the $B M O-$ seminorm, see e.g. [14, Proposition 3.1.2], we deduce that

$$
[v \circ \psi]_{B M O \infty\left(V_{4 \rho L_{*}}^{+}\right)} \leq C_{\Omega, n}[v]_{B M O^{\infty}(\Omega)}
$$

By recalling the results concerning the even extension of $B M O$ functions in the half space, see [10, Lemma 3.2] and [10, Lemma 3.4], we can deduce that

$$
\begin{equation*}
\left[v_{\text {even }} \circ \psi\right]_{B M O^{\infty}\left(V_{4 \rho L_{*}}\right)} \leq C_{\Omega, n}[v]_{B M O^{\infty}(\Omega)} \tag{4.2.5}
\end{equation*}
$$

Next, we shall estimate the $B M O$-seminorm of $v_{\text {even }}$. Let $B_{r}(x)$ be a ball with radius $r \leq \frac{\rho}{2}$. If either $B_{r}(x) \cap U_{\rho}\left(z_{0}\right)=\emptyset$ or $B_{r}(x) \subset \Omega$, there is nothing to prove. It is sufficient to consider $B_{r}(x)$ that intersects both $U_{\rho}\left(z_{0}\right)$ and $\Omega^{\mathrm{c}}$. In this case we can find $x_{0} \in B_{r}(x) \cap U_{\rho}\left(z_{0}\right)$. Since $B_{r}(x) \subset B_{2 r}\left(x_{0}\right) \subset B_{4 \rho}\left(z_{0}\right) \subset U_{8 \rho}\left(z_{0}\right)$, by considering change of variables $y=\psi(\eta)$ in $U_{8 \rho}\left(x_{0}\right)$, we have that

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|v_{\mathrm{even}}(y)-c\right| d y \leq \frac{L_{*}}{\left|B_{r}(x)\right|} \int_{\psi^{-1}\left(B_{r}(x)\right)}\left|v_{\mathrm{even}} \circ \psi(\eta)-c\right| d \eta
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

For any $y \in B_{r}(x)$, we have that $\left|y-z_{0}\right|<4 \rho$. Hence $\psi^{-1}\left(B_{r}(x)\right) \subset B_{L_{*} r}(\zeta) \subset B_{4 \rho L_{*}}(0) \subset$ $V_{4 \rho L_{*}}$. By (5.4.1), we deduce that

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|v_{\mathrm{even}}(y)-\left(v_{\mathrm{even}}\right)_{B_{r}(x)}\right| d y \leq C_{\Omega, n}[v]_{B M O \infty(\Omega)} .
$$

Thus, we obtain that

$$
\left[v_{\mathrm{even}}\right]_{B M O^{\frac{\rho}{2}}\left(\mathbf{R}^{n}\right)} \leq C_{\Omega, n}[v]_{B M O^{\infty}(\Omega)} .
$$

For a ball $B$ with radius $r(B)>\frac{\rho}{2}$, a simple triangle inequality implies that

$$
\frac{1}{|B|} \int_{B}\left|v_{\mathrm{even}}(y)-\left(v_{\mathrm{even}}\right)_{B}\right| d y \leq \frac{2}{|B|} \int_{B}\left|v_{\mathrm{even}}(y)\right| d y \leq \frac{C_{n}}{\rho^{n}}\left\|v_{\mathrm{even}}\right\|_{L^{1}\left(\mathbf{R}^{n}\right)} .
$$

Therefore, we obtain the $B M O$ estimate for $v_{\text {even }}$, i.e.,

$$
\left[v_{\mathrm{even}}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq \frac{C_{\Omega, n}}{\rho^{n}}\|v\|_{v B M O(\Omega)} .
$$

We shall then give the $B M O$ estimate for $P v_{\text {odd }}$. Since $\nabla d \in C^{1}\left(\Gamma_{\rho_{0}}^{\mathbf{R}^{n}}\right)$, there exists $D_{e} \in C^{1}\left(\mathbf{R}^{n}\right)$ such that $\left\|D_{e}\right\|_{C^{1}\left(\mathbf{R}^{n}\right)} \leq\|\nabla d\|_{C^{1}\left(\Gamma_{\rho_{0}}^{\mathrm{R}^{n}}\right)}$ and $r_{\Gamma_{\rho_{0}}^{\mathrm{R}^{n}}} D_{e}=\nabla d$, see the proof of [11, Theorem 13]. By the multiplication rule for $b m o$ functions, we have that $(P v)_{E}:=$ $\left(D_{e} \cdot v_{\text {even }}\right) D_{e} \in b m o\left(\mathbf{R}^{n}\right)$, see also [11, Theorem 13]. Consider the normal coordinate change in $U_{4 \rho L_{*}}\left(z_{0}\right)$. Since $(P v)_{E}=P v$ in $U_{4 \rho L_{*}}\left(z_{0}\right) \cap \Omega$, same argument in the second paragraph implies that

$$
\left.[P v \circ \psi]_{B M O \infty\left(V_{4 \rho L}\right)}^{+}\right) \leq C_{\Omega, n}\left\|(P v)_{E}\right\|_{b m o\left(\mathbb{R}^{n}\right)} \leq \frac{C_{\Omega, n}}{\rho^{n}}\|v\|_{v B M O(\Omega)} .
$$

Let $\zeta \in V_{12 \rho L_{*}}=\psi^{-1}\left(U_{12 \rho L_{*}}\left(z_{0}\right)\right)$ with $\zeta_{n}=0$. Let $B_{r}(\zeta) \subset V_{12 \rho L_{*}}$ and $x=\psi(\zeta)$. Since $F\left(B_{r}(\zeta) \cap V_{12 \rho L_{*}}^{+}\right) \subset B_{L_{*} r}(x) \cap \Omega$, by considering change of variables $y=\psi(\eta)$ in $U_{12 \rho L_{*}}\left(z_{0}\right)$, we can deduce that

$$
\begin{equation*}
\frac{1}{\left|B_{r}(\zeta)\right|} \int_{B_{r}(\zeta) \cap V_{12 \rho L_{*}}^{+}}\left|P v_{\text {odd }} \circ \psi(\eta)\right| d \eta \leq L_{*}^{n+1}[\nabla d \cdot v]_{b^{\nu}} . \tag{4.2.6}
\end{equation*}
$$

Recall the results concerning the odd extension of $B M O$ functions in the half space, see [10, Lemma 3.1], we have the estimate

$$
\begin{equation*}
\left[P v_{\text {odd }} \circ \psi\right]_{B M O^{\infty}\left(V_{\left.4 \rho L_{*}\right)}\right.} \leq \frac{C_{\Omega, n}}{\rho^{n}}\|v\|_{v B M O(\Omega)} . \tag{4.2.7}
\end{equation*}
$$

By considering (4.2.7) and the fact that $P v_{\text {odd }}=(P v)_{E}$ in $\Omega$, same argument in the third paragraph implies the $B M O$ estimate for $P v_{\text {odd }}$, i.e.,

$$
\left[P v_{\text {odd }}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq \frac{C_{\Omega, n}}{\rho^{n}}\|v\|_{v B M O(\Omega)}
$$

Combining the $B M O$ estimates for $v_{\text {even }}$ and $P v_{\text {odd }}$, we have that

$$
[\bar{v}]_{B M O\left(\mathbf{R}^{n}\right)} \leq \frac{C_{\Omega, n}}{\rho^{n}}\|v\|_{v B M O(\Omega)} .
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Notice that $\nabla d \cdot \bar{v}=v_{\text {odd }} \cdot \nabla d$ in $\mathbf{R}^{n}$. Let $x \in \Gamma$ and $r \leq \frac{\rho}{L_{*}}$. If $B_{r}(x) \cap U_{\rho}\left(z_{0}\right)=\emptyset$, then $v_{\text {odd }}=$ 0 in $B_{r}(x)$. Suppose that $B_{r}(x) \cap U_{\rho}\left(z_{0}\right) \neq \emptyset$. Then we can find $x_{0} \in B_{r}(x) \cap U_{\rho}\left(z_{0}\right) \cap \Gamma$. Let $\zeta_{0}=\psi^{-1}\left(x_{0}\right)$, we have that $\psi^{-1}\left(B_{r}(x)\right) \subset B_{2 L_{*} r}\left(\zeta_{0}\right) \subset V_{12 \rho L_{*}}$. Hence,

$$
\begin{aligned}
r^{-n} \int_{B_{r}(x)}\left|v_{\mathrm{odd}} \cdot \nabla d\right| d y & \leq \frac{2 L_{*}}{r^{n}} \int_{B_{2 L_{*} r}\left(\zeta_{0}\right) \cap V_{12 \rho L_{*}}^{+}}|(v \cdot \nabla d) \circ \psi| d \eta \\
& \leq \frac{2 L_{*}^{2}}{r^{n}} \int_{B_{2 L_{*}^{2} r}\left(x_{0}\right) \cap \Omega}|\nabla d \cdot v| d y \leq C_{\Omega, n}[\nabla d \cdot v]_{b^{\nu}}
\end{aligned}
$$

For $r>\frac{\rho}{L_{*}}$, we simply have that

$$
r^{-n} \int_{B_{r}(x)}\left|v_{\mathrm{odd}} \cdot \nabla d\right| d y \leq \frac{C_{\Omega, n}}{\rho^{n}}\left\|v_{\mathrm{odd}}\right\|_{L^{1}\left(\mathbf{R}^{n}\right)} \leq \frac{C_{\Omega, n}}{\rho^{n}}\|v\|_{v B M O(\Omega)}
$$

### 4.2.3 Volume potentials

To construct mapping $v \mapsto q_{1}$ in Theorem 6.1.2, for some $\rho_{*}$ to be determined later in the next section, we localize $v$ by using the partition of the unity $\left\{\varphi_{j}\right\}_{j=0}^{m}$ associated with the covering

$$
\left\{U_{\rho, j}\right\}_{j=1}^{m} \cup \Omega^{\rho / 2}
$$

as in Section 6.2.1, where $\rho$ is always assumed to satisfy $\rho \leq \rho_{*} / 2$. Here and hereafter we always assumed that $\Omega$ is a bounded $C^{3}$ domain in $\mathbf{R}^{n}$.

Proposition 4.2.3. There exists a constant $C_{\rho}$, which depends on $\rho$ only, such that

$$
\begin{aligned}
{\left[\nabla q_{1}^{1}\right]_{B M O^{\infty}\left(\mathbf{R}^{n}\right)} } & \leq C_{\rho}\|v\|_{v B M O(\Omega)} \\
\left\|\nabla q_{1}^{1}(x)\right\|_{L^{\infty}\left(\Gamma_{\rho / 4}^{\mathbf{R}^{n}}\right)} & \leq C_{\rho}\|v\|_{v B M O(\Omega)}
\end{aligned}
$$

for $q_{1}^{1}=E * \operatorname{div}\left(\varphi_{0} v\right)$ and $v \in v B M O(\Omega)$. In particular,

$$
\left[\nabla q_{1}^{1}\right]_{b^{\nu}(\Gamma)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

for $\nu<\rho / 4$.
Proof. By the $B M O-B M O$ estimate [7], we have the estimate

$$
\left[\nabla q_{1}^{1}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\left[\varphi_{0} v\right]_{B M O\left(\mathbf{R}^{n}\right)}
$$

Consider $x \in \Gamma_{\rho / 4}^{\mathrm{R}^{n}}$. Since $\nabla q_{1}^{1}$ is harmonic in $\Gamma_{\rho / 2}^{\mathrm{R}^{n}}$ and $B_{\frac{\rho}{4}}(x) \subset \Gamma_{\rho / 2}^{\mathrm{R}^{n}}$, the mean value property for harmonic functions implies that

$$
\nabla q_{1}^{1}(x)=\frac{C_{n}}{\rho^{n}} \int_{B_{\frac{\rho}{4}}(x)} \nabla q_{1}^{1}(y) d y
$$

By Hölder's inequality, we can estimate $\left|\nabla q_{1}^{1}(x)\right|$ by $\frac{C_{n}}{\rho^{n / 2}}\left\|\nabla q_{1}^{1}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)}$. Since the convolution with $\nabla^{2} E$ is bounded in $L^{p}$ for any $1<p<\infty$, see e.g. [14, Theorem 5.2.7 and Theorem 5.2.10], an interpolation inequality (cf. [4, Lemma 5]) implies that

$$
\left\|\nabla q_{1}^{1}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C\left\|\varphi_{0} v\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C\left\|\varphi_{0} v\right\|_{L^{1}\left(\mathbf{R}^{n}\right)}^{\frac{1}{2}}\left[\varphi_{0} v\right]_{B M O\left(\mathbf{R}^{n}\right)}^{\frac{1}{2}}
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

View $\varphi_{0} v$ as the extension of $\varphi_{0} v$ from $\Omega$ to $\mathbf{R}^{n}$. By the extension theorem for bmo functions [11, Theorem 12], we estimate $\left[\varphi_{0} v\right]_{B M O\left(\mathbf{R}^{n}\right)}$ by $C_{\rho}\left[\varphi_{0} v\right]_{B M O \infty}(\Omega)$. Since $v B M O(\Omega) \subset$ $L^{1}(\Omega)$, see [11, Theorem 9], Proposition 6.2.4 implies that

$$
\left|\nabla q_{1}^{1}(x)\right| \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

for any $x \in \Gamma_{\rho / 4}^{\mathrm{R}^{n}}$.
We next set $v_{1}:=\varphi_{0} v$ and $v_{2}:=1-v_{1}$. For each $\varphi_{j} v_{2}(j=1, ., m)$, we extend as in Proposition 6.2.5 to get $\overline{\varphi_{j} v_{2}}$ and set

$$
\overline{v_{2}}:=\sum_{j=1}^{m} \overline{\varphi_{j} v_{2}}
$$

Indeed, this extension is independent of the choice $\varphi_{j}$ 's but we do not use this fact. We next set

$$
{\overline{v_{2}}}^{\tan }:=Q \overline{v_{2}}=\sum_{j=1}^{m} Q\left(\varphi_{j} v_{2}\right)_{\mathrm{even}}
$$

For $1 \leq j \leq m, \varphi_{j} \in C_{\mathrm{c}}^{\infty}\left(U_{\rho, j} \cap \bar{\Omega}\right)$ implies that the even extension of $\varphi_{j}$ in $U_{\rho, j}$ with respect to $\Gamma$ is Hölder continuous in the sense that $\left(\varphi_{j}\right)_{\text {even }} \in C^{0,1}\left(U_{\rho, j}\right)$. Moreover, we have that $\left(\varphi_{j}\right)_{\text {even }} \in C^{0,1}\left(\mathbf{R}^{n}\right)$ satisifes

$$
\left\|\left(\varphi_{j}\right)_{\mathrm{even}}\right\|_{C^{0,1}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|\left(\varphi_{j}\right)_{\mathrm{even}}\right\|_{C^{0,1}\left(U_{\rho, j}\right)}
$$

For simplicity of notations, we denote $Q\left(\varphi_{j} v_{2}\right)_{\text {even }}$ by $w_{j}^{\text {tan }}$ for every $1 \leq j \leq m$. Now, we are ready to construct the suitable potential corresponding to ${\overline{v_{2}}}^{\tan }$.

Proposition 4.2.4. There exists $\rho_{*}>0$ such that if $\rho<\rho_{*} / 2$, then for every $1 \leq j \leq m$, there exists a linear operator $v \longmapsto p_{j}^{\tan }$ from $v B M O(\Omega)$ to $L^{\infty}\left(\mathbf{R}^{n}\right)$ such that

$$
-\Delta p_{j}^{\tan }=\operatorname{div} w_{j}^{\tan } \text { in } U_{2 \rho, j} \cap \Omega
$$

and that there exists a constant $C_{\rho}$, independent of $v$, such that

$$
\begin{aligned}
{\left[\nabla p_{j}^{\mathrm{tan}}\right]_{B M O\left(\mathbf{R}^{n}\right)} } & \leq C_{\rho}\|v\|_{v B M O(\Omega)} \\
\sup _{x \in \Gamma, r<\rho} \frac{1}{r^{n}} \int_{B_{r}(x)}\left|\nabla d \cdot \nabla p_{j}^{\tan }\right| d y & \leq C_{\rho}\|v\|_{v B M O(\Omega)}
\end{aligned}
$$

Having the estimate for the volume potential near the boundary regarding its tangential component, we are left to handle the contribution from $\bar{v}_{2}^{\text {nor }}:=\bar{v}_{2}-\bar{v}_{2}^{\mathrm{tan}}$. We recall its decomposition

$$
\bar{v}_{2}^{\mathrm{nor}}=\sum_{j=1}^{m} P\left(\varphi_{j} v_{2}\right)_{\mathrm{odd}}
$$

For simplicity of notations, we denote $P\left(\varphi_{j} v_{2}\right)_{\text {odd }}$ by $w_{j}^{\text {nor }}$ for every $1 \leq j \leq m$. With a similar idea of proof, we can establish the suitable potential corresponding to $\bar{v}_{2}^{\text {nor }}$.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Proposition 4.2.5. There exists $\rho_{*}>0$ such that if $\rho<\rho_{*} / 2$, then for every $1 \leq j \leq m$, there exists a linear operator $v \longmapsto p_{j}^{\text {nor }}$ from $v B M O(\Omega)$ to $L^{\infty}\left(\mathbf{R}^{n}\right)$ such that

$$
-\Delta p_{j}^{\text {nor }}=\operatorname{div} w_{j}^{\text {nor }} \quad \text { in } U_{2 \rho, j} \cap \Omega
$$

and that there exists a constant $C_{\rho}$, independent of $v$, such that

$$
\begin{aligned}
{\left[\nabla p_{j}^{\mathrm{nor}}\right]_{B M O\left(\mathbf{R}^{n}\right)} } & \leq C_{\rho}\|v\|_{v B M O(\Omega)} \\
\sup _{x \in \Gamma, r<\rho} \frac{1}{r^{n}} \int_{B_{r}(x)}\left|\nabla d \cdot \nabla p_{j}^{\mathrm{nor}}\right| d y & \leq C_{\rho}\|v\|_{v B M O(\Omega)}
\end{aligned}
$$

Once these two propositions are proved, we are able to prove Theorem 6.1.2.
Theorem 6.1.2 admitting Proposition 6.2.7 and 6.2.8. Fix $1 \leq j \leq m$. Let us first consider the contribution from the tangential part. We take a cut-off function $\theta_{j} \in C_{c}^{\infty}\left(U_{2 \rho, j}\right)$ such that $\theta_{j}=1$ on $U_{\rho, j}$ and $0 \leq \theta_{j} \leq 1$. We next set

$$
q_{1, j}^{\mathrm{tan}}:=\theta_{j} p_{j}^{\mathrm{tan}}+E *\left(p_{j}^{\mathrm{tan}} \Delta \theta_{j}+2 \nabla \theta_{j} \cdot \nabla p_{j}^{\mathrm{tan}}\right)
$$

By definition, Proposition 6.2 .7 says that

$$
\begin{aligned}
-\Delta q_{1, j}^{\tan } & =-\Delta\left(\theta_{j} p_{j}^{\tan }\right)+p_{j}^{\tan } \Delta \theta_{j}+2 \nabla \theta_{j} \cdot \nabla p_{j}^{\tan } \\
& =\theta_{j} \operatorname{div} w_{j}^{\tan }=\operatorname{div} w_{j}^{\tan }
\end{aligned}
$$

in $\Omega$ as $\operatorname{supp} w_{j}^{\tan } \subset U_{\rho, j}$. By interpolation as in the proof of Proposition 6.2.7, we observe that $\left\|p_{j}^{\tan }\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)},\left\|\nabla p_{j}^{\tan }\right\|_{L^{p}\left(\mathbf{R}^{n}\right)}$ are controlled by $\|v\|_{B M O(\Omega)}$. Since $\nabla E$ is in $L^{p^{\prime}}\left(B_{R}\right)$ for $p^{\prime}<n /(n-1)$ where $R=\operatorname{diam} \Omega+4 \rho$, it follows that

$$
\sup _{\mathbf{R}^{n}}\left|\nabla E *\left(p_{j}^{\tan } \Delta \theta_{j}+2 \nabla \theta_{j} \cdot \nabla p_{j}^{\mathrm{tan}}\right)\right| \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

Thus, by Proposition 6.2.7, we conclude that the restriction of $q_{1, j}^{\tan }$ on $\Omega$, which is still denoted by $q_{1, j}^{\text {tan }}$, fulfills

$$
\begin{equation*}
\left\|\nabla q_{1, j}^{\tan }\right\|_{v B M O(\Omega)} \leq C_{\rho}\|v\|_{v B M O(\Omega)} \tag{4.2.8}
\end{equation*}
$$

By Proposition 6.2.8, a similar argument yields an estimate of type (4.2.8) for

$$
q_{1, j}^{\mathrm{nor}}:=\theta_{j} p_{j}^{\mathrm{nor}}+E *\left(p_{j}^{\mathrm{nor}} \Delta \theta_{j}+2 \nabla \theta_{j} \cdot \nabla p_{j}^{\mathrm{nor}}\right)
$$

Set

$$
q_{1}^{2}=\sum_{j=1}^{m} q_{1, j}^{\mathrm{tan}}, q_{1}^{3}=\sum_{j=1}^{m} q_{1, j}^{\mathrm{nor}}, q_{1}=q_{1}^{1}+q_{1}^{2}+q_{1}^{3}
$$

Observe that $q_{1}^{2}$ and $q_{1}^{3}$ satisfy the desired estimates in Theorem 6.1.2. Moreover, by construction we have that

$$
\begin{aligned}
-\Delta q_{1} & =-\Delta q_{1}^{1}-\Delta q_{1}^{2}-\Delta q_{1}^{3} \\
& =\operatorname{div} v_{1}+\sum_{j=1}^{m} \operatorname{div} w_{j}^{\tan }+\sum_{j=1}^{m} \operatorname{div} w_{j}^{\text {nor }} \\
& =\operatorname{div}\left(v_{1}+v_{2}\right)=\operatorname{div} v
\end{aligned}
$$

in $\Omega$.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

### 4.3 Volume potentials based on normal coordinates

Our goal in this section is to prove Proposition 6.2.7 and Proposition 6.2.8. We write the Laplace operator by a normal coordinate system and construct a volume potential keeping the parity of functions with respect to the boundary. For this purpose, we adjust a perturbation method called a freezing coefficient method which is often used to construct a fundamental solution to an operator with variable coefficients.

### 4.3.1 A perturbation method keeping parity

We consider an elliptic operator of the form

$$
L_{0}=A-B, \quad A=-\Delta_{\eta}, \quad B=\sum_{1 \leq i, j \leq n-1} \partial_{\eta_{i}} b_{i j}(\eta) \partial_{\eta_{j}}
$$

in a cylinder $V_{4 \rho}$. We assume that
(B1) (Regularity) $b_{i j} \in \operatorname{Lip}\left(V_{4 \rho}\right)(1 \leq i, j \leq n-1)$,
(B2) (Parity) $b_{i j}$ is even in $\eta_{n}$, i.e., $b_{i j}\left(\eta^{\prime}, \eta_{n}\right)=b_{i j}\left(\eta^{\prime},-\eta_{n}\right)$ for $\eta \in V_{4 \rho}$,
(B3) (Smallness) $b_{i j}(0)=0(1 \leq i, j \leq n-1)$.
For $\rho>0$, let $Y_{\rho}$ denotes the space

$$
\left\{g \in B M O\left(\mathbf{R}^{n}\right) \cap L^{2}\left(\mathbf{R}^{n}\right) \mid \operatorname{supp} g \subset V_{\rho}, g\left(\eta^{\prime}, \eta_{n}\right)=g\left(\eta^{\prime},-\eta_{n}\right) \text { for } \eta \in V_{\rho}\right\}
$$

whereas $Z_{\rho}$ denotes the space

$$
\left\{f \in B M O\left(\mathbf{R}^{n}\right) \mid \operatorname{supp} f \subset V_{\rho}, f\left(\eta^{\prime}, \eta_{n}\right)=-f\left(\eta^{\prime},-\eta_{n}\right) \text { for } \eta \in V_{\rho}\right\}
$$

The oddness condition in $Z_{\rho}$ guarantees that

$$
\frac{1}{r^{n}} \int_{B_{r}\left(\eta^{\prime}, 0\right)} f d \eta=0
$$

for any $r>0$ and $\eta^{\prime} \in \mathbf{R}^{n-1}$, which implies that

$$
\frac{1}{r^{n}} \int_{B_{r}\left(\eta^{\prime}, 0\right)}|f| d \eta \leq[f]_{B M O\left(\mathbf{R}^{n}\right)}
$$

for any $r>0$ and $\eta^{\prime} \in \mathbf{R}^{n-1}$. Hence $f$ is $L^{1}$ in $\mathbf{R}^{n}$.
Lemma 4.3.1. Assume that (B1) - (B3). Then, there exists $\rho_{*}>0$ depending only on $n$ and $b$ such that the following property holds provided that $\rho \in\left(0, \rho_{*}\right)$. There exists $a$ bounded linear operator $f \mapsto q_{o}$ from $Z_{\rho}$ to $L^{\infty}\left(\mathbf{R}^{n}\right)$ such that
(i)

$$
\left[\nabla_{\eta} q_{o}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C[f]_{B M O\left(\mathbf{R}^{n}\right)} \quad \text { for all } \quad f \in Z_{\rho}
$$

with some $C$ independent of $f$;
(ii)

$$
L_{0} q_{o}=\partial_{\eta_{n}} f \quad \text { in } \quad V_{2 \rho} ;
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
(iii) $q_{o}$ is even in $\mathbf{R}^{n}$ with respect to $\eta_{n}$, i.e. $q_{o}\left(\eta^{\prime}, \eta_{n}\right)=q_{o}\left(\eta^{\prime},-\eta_{n}\right) \forall \eta \in \mathbf{R}^{n}$;
(iv)

$$
\sup \left\{\left.\frac{1}{r^{n}} \int_{B_{r}\left(\eta^{\prime}, 0\right)}\left|\partial_{\eta_{n}} q_{o}\right| d \eta \right\rvert\, 0<r<\infty, \eta^{\prime} \in \mathbf{R}^{n-1}\right\} \leq C[f]_{B M O\left(\mathbf{R}^{n}\right)}
$$

Proof. By (B3) and (B1), we observe that

$$
\varlimsup_{\rho \downarrow 0}\left\|b_{i j}\right\|_{C^{\gamma}\left(V_{4 \rho}\right)} / \rho^{1-\gamma}<\infty
$$

for any $\gamma \in(0,1)$ and $1 \leq i, j \leq n-1$. Indeed, for $1 \leq i, j \leq n-1,(\mathrm{~B} 1)$ and (B3) imply that

$$
\begin{aligned}
\left\|b_{i j}\right\|_{L^{\infty}\left(V_{4 \rho}\right)} & \leq 8 L \rho \\
{\left[b_{i j}\right]_{C^{\gamma}\left(V_{4 \rho}\right)} } & :=\sup \left\{\left|b_{i j}(\eta)-b_{i j}(\zeta)\right| /|\eta-\zeta|^{\gamma} \mid \eta, \zeta \in V_{4 \rho}\right\} \\
& \leq L(16 \rho)^{1-\gamma}
\end{aligned}
$$

where $L$ is the maximum of Lipschitz bound for $b_{i j}$ for all $1 \leq i, j \leq n-1$. We next take a cut-off function. We take $\theta \in C_{c}^{\infty}\left(V_{4}\right)$ such that $\theta=1$ on $V_{2}$ and $0 \leq \theta \leq 1$ in $V_{4}$, we may assume $\theta$ is radial so that $\theta$ is even in $\eta_{n}$. We rescale $\theta$ by setting

$$
\theta_{\rho}(\eta)=\theta(\eta / \rho)
$$

so that $\theta_{\rho}=1$ on $V_{2 \rho}$. Since $\left\|\nabla \theta_{\rho}\right\|_{\infty} \rho$ is bounded as $\rho \rightarrow 0$, we see that

$$
\varlimsup_{\rho \downarrow 0}\left[\theta_{\rho}\right]_{C^{\gamma}\left(V_{4 \rho}\right)} \rho^{\gamma}<\infty
$$

Hence, the estimate

$$
\left[\theta_{\rho} b_{i j}\right]_{C^{\gamma}\left(V_{4 \rho}\right)} \leq\left[\theta_{\rho}\right]_{C^{\gamma}\left(V_{4 \rho}\right)}\left\|b_{i j}\right\|_{L^{\infty}\left(V_{4 \rho}\right)}+\left[b_{i j}\right]_{C^{\gamma}\left(V_{4 \rho}\right)}\left\|\theta_{\rho}\right\|_{L^{\infty}\left(V_{4 \rho}\right)}
$$

implies that

$$
\varlimsup_{\rho \downarrow 0}\left\|\theta_{\rho} b_{i j}\right\|_{C^{\gamma}\left(V_{4 \rho}\right)} / \rho^{1-\gamma}<\infty .
$$

We then set

$$
L_{1}=A-B_{1}, \quad B_{1}=\sum_{1 \leq i, j \leq n-1} \partial_{\eta_{i}} b_{i j}^{\rho} \partial_{\eta_{j}}, \quad b_{i j}^{\rho}=b_{i j} \theta_{\rho}
$$

For $1 \leq i, j \leq n-1$, notice that $b_{i j}^{\rho}$ satisfies the same property of $b_{i j}$ in (B1) $-(\mathrm{B} 3)$. Moreover,

$$
\operatorname{supp} b_{i j}^{\rho} \subset V_{4 \rho} \quad \text { and } \quad\left\|b_{i j}^{\rho}\right\|_{C^{\gamma}\left(V_{4 \rho}\right)} \leq c_{b} \rho^{1-\gamma}, \rho>0
$$

with some $c_{b}$ independent of $\rho$. Since supp $b_{i j}^{\rho} \subset V_{4 \rho}$, we actually have that $b_{i j}^{\rho} \in C^{\gamma}\left(\mathbf{R}^{n}\right)$ together with the estimate

$$
\left\|b_{i j}^{\rho}\right\|_{C^{\gamma}\left(\mathbf{R}^{n}\right)} \leq\left\|b_{i j}^{\rho}\right\|_{C^{\gamma}\left(V_{4 \rho}\right)}
$$

For a given $f \in Z_{\rho}$, we define $q_{o}$ by

$$
q_{o}:=\sum_{k=0}^{\infty} A^{-1}\left(B_{1} A^{-1}\right)^{k} \partial_{\eta_{n}} f
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
where formally for a function $h$ we mean $A^{-1} h$ by $E * h$. The parity condition (iii) is clear once $q_{o}$ is well defined as a function. Since

$$
L_{1} q_{o}=\sum_{k=0}^{\infty}\left(B_{1} A^{-1}\right)^{k} \partial_{\eta_{n}} f-\sum_{k=1}^{\infty}\left(B_{1} A^{-1}\right)^{k} \partial_{\eta_{n}} f=\partial_{\eta_{n}} f
$$

in $\mathbf{R}^{n}$, the property (ii) then follows since $L_{1}=L_{0}$ in $V_{2 \rho}$.
It remains to prove the convergence of $q_{o}$ as well as (i). For this purpose, we reinterpret $q_{o}$ in a different way. We rewrite

$$
B_{1}=\operatorname{div}^{\prime} \cdot \nabla_{B}^{\prime} \quad \text { with } \quad \nabla_{B}^{\prime}=\left(\sum_{j=1}^{n-1} b_{i j}^{\rho} \partial_{\eta_{j}}\right)_{1 \leq i \leq n-1}
$$

and observe that

$$
\begin{aligned}
& q_{o}=\sum_{k=0}^{\infty} A^{-1} \operatorname{div}^{\prime} \cdot G^{k} \cdot \nabla_{B}^{\prime} A^{-1} \partial_{\eta_{n}} f+A^{-1} \partial_{\eta_{n}} f \\
& G:=\nabla_{B}^{\prime} A^{-1} \operatorname{div}^{\prime}
\end{aligned}
$$

Denote

$$
b^{\rho}:=\left(b_{i j}^{\rho}\right)_{1 \leq i, j \leq n-1}
$$

Since $\partial_{\eta_{\alpha}} A^{-1} \partial_{\eta_{\beta}}$ is bounded in $B M O[7]$ and also in $L^{p}(1<p<\infty)$ for all $\alpha, \beta=1, \ldots, n$, see e.g. [14, Theorem 5.2.7 and Theorem 5.2.10], by a multiplication theorem we can deduce the estimates

$$
\begin{align*}
\|G h\|_{L^{p}\left(\mathbf{R}^{n}\right)} & \leq C_{p}\left\|b^{\rho}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}\|h\|_{L^{p}\left(\mathbf{R}^{n}\right)},  \tag{4.3.1}\\
{[G h]_{B M O\left(\mathbf{R}^{n}\right)} } & \leq C_{\infty}^{\prime}\left\|b^{\rho}\right\|_{C^{\gamma}\left(\mathbf{R}^{n}\right)}\left([h]_{B M O\left(\mathbf{R}^{n}\right)}+\|h\|_{L^{1}\left(\mathbf{R}^{n}\right)}\right) \tag{4.3.2}
\end{align*}
$$

provided that supp $h \subset V_{4 \rho}$ and $\rho<1$. Here $C_{p}$ and $C_{\infty}^{\prime}$ are independent of $\rho$ and $h$. Similar estimate holds for $\nabla_{B}^{\prime} A^{-1} \partial_{\eta_{n}}$. Since $\|f\|_{L^{1}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}[f]_{B M O\left(\mathbf{R}^{n}\right)}$ for $f \in Z_{\rho}$, by an interpolation (cf. [4, Lemma 5]) we see that the $L^{p}$ norm of $f$ is also controlled, i.e., $\|f\|_{L^{p}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}[f]_{B M O\left(\mathbf{R}^{n}\right)}$ for any $1 \leq p<\infty$. By the support condition, $A^{-1} \operatorname{div}^{\prime}$ and $A^{-1} \partial_{\eta_{n}}$ is bounded from $L^{p} \rightarrow L^{\infty}$ for $p>n$ with bound $K$, we see that

$$
\begin{aligned}
\left\|q_{o}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} & \leq K\left(\left\|\sum_{k=0}^{\infty} G^{k} \nabla_{B}^{\prime} A^{-1} \partial_{\eta_{n}} f\right\|_{L^{p}\left(\mathbf{R}^{n}\right)}+\|f\|_{L^{p}\left(\mathbf{R}^{n}\right)}\right) \\
& \leq K\left(\sum_{k=0}^{\infty} C_{p}^{k+1}\left\|b^{\rho}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}^{k+1}\|f\|_{L^{p}\left(\mathbf{R}^{n}\right)}+\|f\|_{L^{p}\left(\mathbf{R}^{n}\right)}\right), \quad p>n
\end{aligned}
$$

If $\rho$ is taken small so that

$$
\sum_{k=0}^{\infty}\left(C_{p} \cdot 8 L \rho\right)^{k+1}<\infty
$$

then $q_{o}$ converges uniformly in $\mathbf{R}^{n}$ and $\left\|q_{o}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}[f]_{B M O\left(\mathbf{R}^{n}\right)}$ with some $C_{\rho}$ independent of $f$.

Set

$$
\|h\|_{B M O L^{p}\left(\mathbf{R}^{n}\right)}:=[h]_{B M O\left(\mathbf{R}^{n}\right)}+\|h\|_{L^{p}\left(\mathbf{R}^{n}\right)} .
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

By estimates (4.3.1) and (4.3.2), we observe that

$$
\|G h\|_{B M O L^{p}\left(\mathbf{R}^{n}\right)} \leq C_{*}\left\|b^{\rho}\right\|_{C^{\gamma}\left(\mathbf{R}^{n}\right)}\|h\|_{B M O L^{p}\left(\mathbf{R}^{n}\right)}, \quad 1<p<\infty
$$

where $C_{*}=C_{p}+C_{\infty}^{\prime} \cdot C_{n}$ with $C_{n}$ independent of $\rho$ and $h$. We next estimate $\nabla q_{o}$. By the similar estimate for $\nabla_{B}^{\prime} A^{-1} \operatorname{div}^{\prime}$ and $\nabla_{B}^{\prime} A^{-1} \partial_{\eta_{n}}$, we have that

$$
\left\|\nabla q_{o}\right\|_{B M O L^{p}\left(\mathbf{R}^{n}\right)} \leq\left(\sum_{k=0}^{\infty} C_{*}^{k+1}\left\|b^{\rho}\right\|_{C^{\gamma}\left(\mathbf{R}^{n}\right)}^{k+1}+C_{*}\left\|b^{\rho}\right\|_{C^{\gamma}\left(\mathbf{R}^{n}\right)}\right)\|f\|_{B M O L^{p}\left(\mathbf{R}^{n}\right)}
$$

We fix $p>n$ and take $\rho<\frac{1}{8 L C_{p}}$ sufficiently small so that

$$
\sum_{k=0}^{\infty}\left(C_{*} \cdot c_{b} \rho^{1-\gamma}\right)^{k+1}<\infty
$$

Then we get our desired estimate

$$
\left\|\nabla q_{o}\right\|_{B M O L^{p}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|f\|_{B M O L^{p}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}[f]_{B M O\left(\mathbf{R}^{n}\right)}
$$

for $f \in Z_{\rho}$. This completes the proof of (i).
Since $\partial_{\eta_{n}} q_{o}$ is odd in $\eta_{n}$ so that

$$
\frac{1}{r^{n}} \int_{B_{r}\left(\eta^{\prime}, 0\right)} \partial_{\eta_{n}} q_{o} d \eta=0
$$

for any $\eta^{\prime} \in \mathbf{R}^{n-1}$, the left-hand side of (iv) is estimated by a constant multiple of $\left[\partial_{\eta_{n}} q_{o}\right]_{B M O\left(\mathbf{R}^{n}\right)}$, which is estimated by a constant multiple of $[f]_{B M O\left(\mathbf{R}^{n}\right)}$. The proof of (iv) is now complete.

Similarly, we are able to establish the following which corresponds to a version of Lemma 4.3.1 for the space $Y_{\rho}$.

Lemma 4.3.2. Assume that (B1) - (B3). Then, there exists $\rho_{*}>0$ depending only on $n$ and $b$ such that the following property holds provided that $\rho \in\left(0, \rho_{*}\right)$. For each $1 \leq i \leq n-1$, there exists a bounded linear operator $g \mapsto q_{e, i}$ from $Y_{\rho}$ to $L^{\infty}\left(\mathbf{R}^{n}\right)$ such that
(i)

$$
\left[\nabla q_{e, i}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\|g\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} \quad \text { for all } \quad g \in Y_{\rho}
$$

with some $C$ independent of $f$;
(ii)

$$
L_{0} q_{e, i}=\partial_{\eta_{i}} g \quad \text { in } \quad V_{2 \rho}
$$

(iii) $q_{e, i}$ is even in $\mathbf{R}^{n}$ with respect to $\eta_{n}$, i.e. $q_{e, i}\left(\eta^{\prime}, \eta_{n}\right)=q_{e, i}\left(\eta^{\prime},-\eta_{n}\right) \forall \eta \in \mathbf{R}^{n}$;
(iv)

$$
\sup \left\{\left.\frac{1}{r^{n}} \int_{B_{r}\left(\eta^{\prime}, 0\right)}\left|\partial_{\eta_{n}} q_{e, i}\right| d \eta \right\rvert\, 0<r<\infty, \eta^{\prime} \in \mathbf{R}^{n-1}\right\} \leq C\|g\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)}
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Proof. Fix $1 \leq i \leq n-1$. Since $g$ is even in $\mathbf{R}^{n}$ with respect to $\eta_{n}, \partial_{\eta_{i}} g$ is also even in $\mathbf{R}^{n}$ with respect to $\eta_{n}$. This means that $\partial_{\eta_{i}} g$ has the same parity with $\partial_{\eta_{n}} f$ in Lemma 4.3.1. By considering

$$
q_{e, i}:=\sum_{k=0}^{\infty} A^{-1}\left(B_{1} A^{-1}\right)^{k} \partial_{\eta_{i}} g
$$

exactly the same arguments of the proof of Lemma 4.3.1 finish the rest of the work.
We take $\rho_{*}$ in Lemma 4.3.1 and Lemma 4.3.2 to be

$$
\rho_{*}:=\min \left\{\rho_{0, *}, \frac{1}{8 L C_{p}},\left(\frac{1}{C_{*} \cdot c_{b}}\right)^{\frac{1}{1-\gamma}}\right\} .
$$

### 4.3.2 Laplacian in a normal coordinate system

Take $z_{0} \in \Gamma$. Let us recall the normal coordinate system (4.2.3) introduced in Section 6.2.1, i.e.,

$$
\left\{\begin{aligned}
x^{\prime} & =\eta^{\prime}+\eta_{n} \nabla^{\prime} d\left(\eta^{\prime}, h_{z_{0}}\left(\eta^{\prime}\right)\right) \\
x_{n} & =h_{z_{0}}\left(\eta^{\prime}\right)+\eta_{n} \partial_{\eta_{n}} d\left(\eta^{\prime}, h_{z_{0}}\left(\eta^{\prime}\right)\right)
\end{aligned}\right.
$$

in $U_{\rho_{0}}\left(z_{0}\right)$ with $\nabla^{\prime} h_{z_{0}}\left(0^{\prime}\right)=0, h_{z_{0}}\left(0^{\prime}\right)=0$ up to translation and rotation such that $z_{0}=0$ and

$$
-\mathbf{n}\left(\eta^{\prime}, h_{z_{0}}\left(\eta^{\prime}\right)\right)=\left(-\nabla^{\prime} h_{z_{0}}\left(\eta^{\prime}\right), 1\right) /\left(1+\left|\nabla_{z_{0}}^{\prime} h\left(\eta^{\prime}\right)\right|^{2}\right)^{1 / 2}, \quad \eta^{\prime} \in B_{\rho_{0}}
$$

Since $\Gamma$ is $C^{3}$, the mapping $x=\psi(\eta) \in C^{2}\left(V_{\rho_{0}}\right)$ in $U_{\rho_{0}}\left(z_{0}\right)$, it is a local $C^{2}$-diffeomorphism. Moreover, its Jacobi matrix $D \psi$ is the identity at 0, i.e.,

$$
\nabla \psi(0)=I=\nabla \psi^{-1}(0)
$$

A direct calculation shows that in $U_{\rho_{0}}\left(z_{0}\right) \cap \Omega$,

$$
\begin{aligned}
-\Delta_{x}=-\Delta_{\eta} & -\left\{\sum_{\substack{1 \leq i, j \leq n-1 \\
i \neq j}} \gamma_{i j} \partial_{\eta_{i}} \partial_{\eta_{j}}+\sum_{j=1}^{n-1}\left(\gamma_{j j}-1\right) \partial_{\eta_{j}}^{2}\right\} \\
& -\sum_{1 \leq i, j \leq n} \frac{\partial^{2} \eta_{j}}{\partial x_{i}^{2}} \partial_{\eta_{j}}, \quad \gamma_{i j}=\sum_{k=1}^{n} \frac{\partial \eta_{j}}{\partial x_{k}} \frac{\partial \eta_{i}}{\partial x_{k}}
\end{aligned}
$$

Note that $\gamma_{j j}(0)=1$ while $\gamma_{i j}(0)=0$ if $i \neq j$. Changing order of multiplication and differentiation, we conclude that

$$
\begin{aligned}
-\Delta_{x} & =\tilde{L}_{0}+\tilde{M} \\
\tilde{L}_{0} & :=A-\tilde{B}, \quad A:=-\Delta_{\eta}, \quad \tilde{B}:=\sum_{1 \leq i, j \leq n-1} \partial_{\eta_{i}} \tilde{b}_{i j}(\eta) \partial_{\eta_{j}} \\
\tilde{M} & :=\sum_{j=1}^{n} \tilde{c}_{j}(\eta) \partial_{\eta_{j}}
\end{aligned}
$$

with $\tilde{b}_{i j}=\gamma_{i j}-\delta_{i j}, \tilde{c}_{j}=-\sum_{i=1}^{n} \frac{\partial^{2} \eta_{j}}{\partial x_{i}^{2}}+\sum_{i=1}^{n} \partial_{\eta_{i}} \gamma_{i j}$. Note that if $\Gamma=\partial \Omega$ is $C^{3}, \tilde{b}_{i j} \in C^{1}\left(V_{\rho_{0}}\right)$ and $\tilde{c_{j}} \in C\left(V_{\rho_{0}}\right)$. We restrict $\tilde{b}_{i j}, \tilde{c}_{j}$ in $V_{\rho_{0}} \cap \mathbf{R}_{+}^{n}$ and extend to $V_{\rho_{0}}$ so that the extended
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
function $b_{i j}, c_{j}$ 's are even in $V_{\rho_{0}}$ with respect to $\eta_{n}$, i.e., we set $b_{i j}=E_{\text {even }} r_{V_{\rho_{0}} \cap \mathbf{R}_{+}^{n}} \tilde{b_{i j}}$ and $c_{j}=E_{\text {even }} r_{V_{\rho_{0}} \cap \mathbf{R}_{+}^{n}} \tilde{c_{j}}$. By this extension, $b_{i j}$ may not be in $C^{1}$ but still Lipschitz and $c_{j} \in C\left(V_{\rho_{0}}\right)$. We set

$$
\begin{aligned}
B & :=\sum_{1 \leq i, j \leq n-1} \partial_{\eta_{i}} b_{i j}(\eta) \partial_{\eta_{j}} \\
M & :=\sum_{j=1}^{n} c_{j}(\eta) \partial_{\eta_{j}}
\end{aligned}
$$

and

$$
L:=L_{0}+M, \quad L_{0}=A-B
$$

The operator $L$ may not agree with $-\Delta_{x}$ outside $U_{\rho_{0}}\left(z_{0}\right) \cap \Omega$. We summarize what we observe so far.

Proposition 4.3.3. Let $\Gamma=\partial \Omega$ be $C^{3}$ and $\rho_{0}$ be chosen as in Section 6.2.1. For $z_{0} \in \Gamma$, $L_{0}$ satisfies (B1) - (B3). Moreover, $-\Delta_{x}=L$ in $U_{\rho_{0}}\left(z_{0}\right) \cap \Omega$ and the coefficient of $M$ is in $C\left(V_{\rho_{0}}\right)$.

Although we do not use the explicit formula of $\Delta$ in normal coordinates, we give it for $n=2$ when we take the arc length parameter $s$ to represent $\Gamma$. The coordinate transform is of the form

$$
\begin{aligned}
& x_{1}=\phi_{1}(x)+r \phi_{2}^{\prime}(s) \\
& x_{2}=\phi_{2}(x)-r \phi_{1}^{\prime}(s)
\end{aligned}
$$

with $\phi_{1}^{\prime 2}+\phi_{2}^{\prime 2}=1$ and $r=d(x)$. A direct calculation yields

$$
-\Delta_{x}=-\Delta_{s, r}-\partial_{s}\left(\frac{1}{J^{2}}-1\right) \partial_{s}-\frac{\partial_{s} J}{J^{3}} \partial_{s}-\frac{1}{r}\left(1-\frac{1}{J}\right) \partial_{r}
$$

where $J=1+r \kappa$ and $\kappa$ is the curvature. We see that that the even extension of coefficient does not agree with $-\Delta_{x}$ outside $\Omega$.

### 4.3.3 bmo invariant under local $C^{1}$-diffeomorphism

Before we give the proofs to Proposition 6.2 .7 and 6.2 .8 , we shall first establish the fact that the bmo estimate of a compactly supported function is preserved under a local $C^{1}$ diffeomorphism. Let $V, U \subset \mathbf{R}^{n}$ be two domains, we consider a local $C^{1}$-diffeomorphism $\psi: V \mapsto U$. Suppose that

$$
\left\|\nabla_{\eta} \psi\right\|_{L^{\infty}(V)}+\left\|\nabla_{x} \psi^{-1}\right\|_{L^{\infty}(U)}<\infty
$$

Let $\rho>0$. Assume that there exist two bounded subdomains $V_{\rho} \subset V, U_{\rho} \subset U$ such that $\psi: V_{\rho} \mapsto U_{\rho}$ is also a local $C^{1}$-diffeomorphism. Set

$$
K_{*}:=\max \left\{1,\left\|\nabla_{\eta} \psi\right\|_{L^{\infty}(V)}+\left\|\nabla_{x} \psi^{-1}\right\|_{L^{\infty}(U)}\right\}
$$

We assume further that there exists a constant $c_{0}$ such that for some $\eta_{0} \in V_{\rho}$,

$$
V_{\rho} \subset B_{c_{0} \rho}\left(\eta_{0}\right) \subset B_{K_{*}\left(c_{0}+3\right) \rho}\left(\eta_{0}\right) \subset V, \quad U_{\rho} \subset B_{c_{0} \rho}\left(x_{0}\right) \subset B_{K_{*}\left(c_{0}+3\right) \rho}\left(x_{0}\right) \subset U
$$

where $x_{0}=\psi\left(\eta_{0}\right)$.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Proposition 4.3.4. Let $f \in b m o\left(\mathbf{R}^{n}\right)$ with $\operatorname{supp} f \subset V_{\rho}$, then $f \circ \psi^{-1} \in b m o\left(\mathbf{R}^{n}\right)$ satisfies

$$
\left\|f \circ \psi^{-1}\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|f\|_{b m o\left(\mathbf{R}^{n}\right)} .
$$

Proof. Since supp $f \circ \psi^{-1} \subset U_{\rho}$, we can treat $f \circ \psi^{-1}$ as a function in $\mathbf{R}^{n}$ with value zero outside $U_{\rho}$. The compactness of $V_{\rho}$ in $\mathbf{R}^{n}$ implies that $\|f\|_{b m o\left(\mathbf{R}^{n}\right)}=\|f\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)}$. Thus, the $L^{1}$ estimate

$$
\left\|f \circ \psi^{-1}\right\|_{L^{1}\left(\mathbf{R}^{n}\right)} \leq C\|f\|_{L^{1}\left(\mathbf{R}^{n}\right)}
$$

is obvious. Since $\psi \in C^{1}\left(V_{\rho}\right)$, an equivalent definition of the $B M O$-seminorm (cf. [15, Proposition 3.1.2]) implies that

$$
\left[f \circ \psi^{-1}\right]_{B M O^{\infty}\left(B_{\left(c_{0}+1\right) \rho}\left(x_{0}\right)\right)} \leq\left\|\nabla_{x} \psi^{-1}\right\|_{L^{\infty}(U)}^{n} \cdot\left\|\nabla_{\eta} \psi\right\|_{L^{\infty}(V)} \cdot[f]_{B M O\left(\mathbf{R}^{n}\right)} .
$$

As $U_{\rho} \subset B_{c_{0} \rho}\left(x_{0}\right)$, by the extension theorem of $b m o$ functions [11, Theorem 12], we obtain that

$$
\left\|f \circ \psi^{-1}\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|f \circ \psi^{-1}\right\|_{b m o_{\infty}^{\infty}\left(B_{\left(c_{0}+1\right) \rho}\left(x_{0}\right)\right)} \leq C_{\rho}\|f\|_{b m o\left(\mathbf{R}^{n}\right)} .
$$

Similarly, if $g \in b m o\left(\mathbf{R}^{n}\right)$ with $\operatorname{supp} g \subset U_{\rho}$, then we have that $g \circ \psi \in b m o\left(\mathbf{R}^{n}\right)$ satisfying

$$
\|g \circ \psi\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|g\|_{b m o\left(\mathbf{R}^{n}\right)} .
$$

Even if we are considering vector fields instead of scalar functions, similar results hold.
Proposition 4.3.5. Let $\nabla_{\eta} f \in b m o\left(\mathbf{R}^{n}\right)$ with $\operatorname{supp} \nabla_{\eta} f \subset V_{\rho}$, then $\nabla_{x}\left(f \circ \psi^{-1}\right) \in b m o\left(\mathbf{R}^{n}\right)$ satisfying

$$
\left\|\nabla_{x}\left(f \circ \psi^{-1}\right)\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|\nabla_{\eta} f\right\|_{b m o\left(\mathbf{R}^{n}\right)} .
$$

Proof. Since $\nabla_{\eta} f$ is compactly supported, the $L^{1}$ estimate

$$
\left\|\nabla_{x}\left(f \circ \psi^{-1}\right)\right\|_{L^{1}\left(\mathbf{R}^{n}\right)} \leq C\left\|\nabla_{\eta} f\right\|_{L^{1}\left(\mathbf{R}^{n}\right)}
$$

is obvious. Pick a cut-off function $\theta_{*, \rho} \in C_{c}^{\infty}\left(B_{K_{*}\left(c_{0}+3\right) \rho}\left(\eta_{0}\right)\right)$ such that $\theta_{*, \rho}=1$ in $B_{K_{*}\left(c_{0}+2\right) \rho}\left(\eta_{0}\right)$. Consider $B_{r}(x) \subset B_{\left(c_{0}+1\right) \rho}\left(x_{0}\right)$ with $r<\rho$. Let $\eta=\psi^{-1}(x)$. Since $\psi^{-1}\left(B_{r}(x)\right) \subset B_{K_{*}\left(c_{0}+2\right) \rho}\left(\eta_{0}\right)$, we have that

$$
\frac{1}{r^{n}} \int_{B_{r}(x)}\left|\partial_{x_{i}}\left(f \circ \psi^{-1}\right)-c\right| d y \leq \frac{K_{*}}{r^{n}} \int_{\psi^{-1}\left(B_{r}(x)\right)}\left|\sum_{1 \leq l \leq n} \theta_{*, \rho}\left(\frac{\partial \eta_{l}}{\partial x_{i}}\right)_{\psi} \partial_{\eta_{l}} f-c\right| d \eta
$$

for any $c \in \mathbf{R}^{n}, 1 \leq i \leq n$. By considering an equivalent definition of the $B M O$-seminorm, see e.g. [15, Proposition 3.1.2], we deduce that

$$
\begin{aligned}
{\left[\nabla_{x}\left(f \circ \psi^{-1}\right)\right]_{B M O}^{\infty}\left(B_{\left(c_{0}+1\right) \rho}\left(x_{0}\right)\right) } & \leq K_{*}^{n+1}\left[\sum_{1 \leq i, l \leq n} \theta_{*, \rho}\left(\frac{\partial \eta_{l}}{\partial x_{i}}\right)_{\psi} \partial_{\eta_{l}} f\right]_{B M O\left(\mathbf{R}^{n}\right)} \\
& \leq C_{\rho}\left\|\nabla_{\eta} f\right\|_{b m o\left(\mathbf{R}^{n}\right)} .
\end{aligned}
$$

As $U_{\rho} \subset B_{c_{0} \rho}\left(x_{0}\right)$, by the extension theorem of $b m o$ functions [11, Theorem 12], we obtain that

$$
\left\|\nabla_{x}\left(f \circ \psi^{-1}\right)\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|\nabla_{x}\left(f \circ \psi^{-1}\right)\right\|_{b m o \infty}^{\infty}\left(B_{\left(c_{0}+1\right) \rho}\left(x_{0}\right)\right) \leq C_{\rho}\left\|\nabla_{\eta} f\right\|_{b m o\left(\mathbf{R}^{n}\right)} .
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

If $\nabla_{x} g \in b m o\left(\mathbf{R}^{n}\right)$ with $\operatorname{supp} \nabla_{x} g \subset U_{\rho}$, same proof of Proposition 4.3.5 shows that $\nabla_{\eta}(g \circ \psi) \in b m o\left(\mathbf{R}^{n}\right)$ satisfying

$$
\left\|\nabla_{\eta}(g \circ \psi)\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|\nabla_{x} g\right\|_{b m o\left(\mathbf{R}^{n}\right)}
$$

Let $h$ be either a scalar function or a vector field which is compactly supported in $U_{\rho}$, for simplicity of notations we denote $h_{\psi}:=h \circ \psi$. If $h$ is a vector field, we denote $h_{\psi, i}:=h_{i} \circ \psi$ for $1 \leq i \leq n$.

### 4.3.4 Volume potential for tangential component

Let $\rho \in\left(0, \rho_{*} / 2\right)$ and fix $1 \leq j \leq m$. Since $\varphi_{j} v_{2} \in v B M O(\Omega)$ with supp $\varphi_{j} v_{2} \subset U_{\rho, j} \cap \bar{\Omega}$, Proposition 6.2.5 implies that $\left(\varphi_{j} v_{2}\right)_{\text {even }} \in B M O L^{1}\left(\mathbf{R}^{n}\right)$. By the product estimate for bmo functions [11, Theorem 13], we see that $w_{j}^{\mathrm{tan}}=Q\left(\varphi_{j} v_{2}\right) \in B M O L^{1}\left(\mathbf{R}^{n}\right)$ with $\operatorname{supp} w_{j}^{\mathrm{tan}} \subset$ $U_{\rho, j}$. For simplicity of notations, we set $v_{2, j}:=\left(\varphi_{j} v_{2}\right)_{\text {even }}$.

Let $\psi: V_{4 \rho} \mapsto U_{4 \rho, j}$ be the normal coordinate change defined by (4.2.3) in Section 6.2.1. Since $\rho<\rho_{*} / 2$, we have that

$$
V_{4 \rho} \subset B_{12 \rho}(0) \subset B_{24 L_{*} \rho}(0) \subset V_{\rho_{0}}, \quad U_{4 \rho, j} \subset B_{12 \rho}\left(z_{j}\right) \subset B_{24 L_{*} \rho}\left(z_{j}\right) \subset U_{\rho_{0}, j}
$$

By Proposition 4.3.4 and 4.3.5, we see that $\psi$, in this case, is a local $C^{2}$-diffeomorphism that preserves bmo estimates for functions or vector fields compactly supported in $V_{4 \rho}$. As a result, $\left(v_{2, j}\right)_{\psi} \in B M O L^{1}\left(\mathbf{R}^{n}\right)$ satisfies the estimate

$$
\left\|\left(v_{2, j}\right)_{\psi}\right\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|v_{2, j}\right\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)} .
$$

Note that similar conclusions hold if we consider $\psi^{-1}: U_{4 \rho, j} \mapsto V_{4 \rho}$ instead.
Proposition 6.2.7. For $1 \leq i \leq n$ and $1 \leq k \leq n-1$, we define

$$
\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{*}:=E_{\text {even }} r_{V_{4 \rho} \cap \mathbf{R}_{+}^{n}}\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{\psi} \text { and } g_{i, k}:=\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{*} \cdot\left(v_{2, j}\right)_{\psi, i} .
$$

We consider

$$
\begin{aligned}
\left(\operatorname{div}_{x} w_{j}^{\mathrm{tan}}\right)_{\psi, *} & :=\sum_{\substack{1 \leq i \leq n, 1 \leq k \leq n-1}}\left\{\partial_{\eta_{k}} g_{i, k}-\partial_{\eta_{k}}\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{\psi} \cdot\left(v_{2, j}\right)_{\psi, i}\right\} \\
& -\sum_{\substack{1 \leq i \leq n, 1 \leq k \leq n-1}}\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{\psi} \cdot\left(\sum_{1 \leq l \leq n}\left(v_{2, j}\right)_{\psi, l} \cdot\left(\frac{\partial \eta_{n}}{\partial x_{l}}\right)_{\psi}\right) \cdot \frac{\partial^{2} x_{i}}{\partial \eta_{k} \partial \eta_{n}}
\end{aligned}
$$

in $V_{4 \rho}=\psi^{-1}\left(U_{4 \rho, j}\right)$. Let $L=L_{0}+M$ be the operator in Proposition 4.3.3 and $L_{0}^{-1}$ be the operator in Lemma 4.3.2. Let $1 \leq i \leq n$ and $1 \leq k \leq n-1$. We set

$$
q_{j, 1, \psi}^{i, k}:=-\theta_{\rho} L_{0}^{-1} \partial_{\eta_{k}} g_{i, k}
$$

where $\theta_{\rho}$ is the cut-off function defined in the proof of Lemma 4.3.1. There exists $\overline{\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{*}} \in$ $C^{0,1}\left(\mathbf{R}^{n}\right)$, see e.g. [11, Theorem 13], such that the restriction of $\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{*}$ in $V_{4 \rho}$ equals $\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{*}$ and $\|\left(\overline{\left.\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{*}}\left\|_{C^{0,1}\left(\mathbf{R}^{n}\right)} \leq\right\|\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{*} \|_{C^{0,1}\left(V_{4 \rho}\right)}\right.$. By viewing $g_{i, k}$ as $\overline{\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{*}} \cdot\left(v_{2, j}\right)_{\psi, i}$, we see that
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
$g_{i, k} \in B M O L^{1}\left(\mathbf{R}^{n}\right)$. Hence, $q_{j, 1, \psi}^{i, k} \in L^{\infty}\left(\mathbf{R}^{n}\right)$ is well-defined which satisfies all conditions in Lemma 4.3.2. Let $f_{j, 1, \psi}^{i, k}:=M \theta_{\rho} L_{0}^{-1} \partial_{\eta_{k}} g_{i, k}$. We can define

$$
q_{j, 1}^{i, k}:=q_{j, 1, \psi}^{i, k} \circ \psi^{-1}, f_{j, 1}^{i, k}:=f_{j, 1, \psi}^{i, k} \circ \psi^{-1}
$$

in $U_{\rho_{0}, j}$. Notice that $\operatorname{supp} q_{j, 1}^{i, k}, \operatorname{supp} f_{j, 1}^{i, k} \subset U_{4 \rho, j}$, we can indeed treat $q_{j, 1}^{i, k}, f_{j, 1}^{i, k}$ as functions defined in $\mathbf{R}^{n}$ where their values outside $U_{4 \rho, j}$ equal zero. Proposition 4.3 .5 shows that $\nabla_{x} q_{j, 1}^{i, k} \in B M O\left(\mathbf{R}^{n}\right)$ satisfies the estimate

$$
\left[\nabla_{x} q_{j, 1}^{i, k}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|\nabla_{\eta} q_{j, 1, \psi}^{i, k}\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|g_{i, k}\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)}
$$

Let $p_{j, 1}^{i, k}:=E * f_{j, 1}^{i, k}$. By Lemma 4.3.2 again, we can prove that

$$
\left\|p_{j, 1}^{i, k}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}+\left\|\nabla_{x} p_{j, 1}^{i, k}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|f_{j, 1, \psi}^{i, k}\right\|_{L^{p}\left(V_{2 \rho}\right)} \leq C_{\rho}\left\|g_{i, k}\right\|_{L^{p}\left(\mathbf{R}^{n}\right)}
$$

with some $p>n$. Thus, $p_{j, 1}^{i, k}$ is well-defined. By Proposition 6.2.5, we have that

$$
\left\|g_{i, k}\right\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|v_{2, j}\right\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

Hence, by an interpolation (cf. [4, Lemma 5]),

$$
\left\|g_{i, k}\right\|_{L^{p}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

for any $1<p<\infty$.
For lower order term $q_{j, 2, \psi}^{i, k}:=\partial_{\eta_{k}}\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{\psi} \cdot\left(v_{2, j}\right)_{\psi, i}$, we set $q_{j, 2}^{i, k}:=q_{j, 2, \psi}^{i, k} \circ \psi^{-1}$ in $U_{\rho_{0}, j}$. Similar as $q_{j, 1}^{i, k}$, we can treat $q_{j, 2}^{i, k}$ as a function in $\mathbf{R}^{n}$ with value zero outside $U_{\rho, j}$ since $\operatorname{supp} q_{j, 2}^{i, k} \subset U_{\rho, j}$. Define $p_{j, 2}^{i, k}:=E * q_{j, 2}^{i, k}$. Since $E$ and $\nabla_{x} E$ are locally integrable, we have that

$$
\left\|p_{j, 2}^{i, k}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}+\left\|\nabla_{x} p_{j, 2}^{i, k}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|q_{j, 2, \psi}^{i, k}\right\|_{L^{p}\left(V_{\rho}\right)} \leq C_{\rho}\left\|v_{2, j}\right\|_{L^{p}\left(U_{\rho, j}\right)}
$$

for some $p>n$. By an interpolation (cf. [4, Lemma 5]) again, we deduce that

$$
\left\|p_{j, 2}^{i, k}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}+\left\|\nabla_{x} p_{j, 2}^{i, k}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

This argument also holds for lower order term

$$
q_{j, 3, \psi}^{i, k}:=\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{\psi} \cdot\left(\sum_{1 \leq l \leq n}\left(v_{2, j}\right)_{\psi, l} \cdot\left(\frac{\partial \eta_{n}}{\partial x_{l}}\right)_{\psi}\right) \cdot \frac{\partial^{2} x_{i}}{\partial \eta_{k} \partial \eta_{n}}
$$

By letting $q_{j, 3}^{i, k}:=q_{j, 3, \psi}^{i, k} \circ \psi^{-1}$ in $U_{\rho_{0}, j}$ and $p_{j, 3}^{i, k}:=E * q_{j, 3}^{i, k}$, we can show that

$$
\left\|p_{j, 3}^{i, k}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}+\left\|\nabla_{x} p_{j, 3}^{i, k}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

Set

$$
p_{j}^{\tan }:=\sum_{\substack{1 \leq i \leq n, 1 \leq k \leq n-1}}\left(q_{j, 1}^{i, k}+p_{j, 1}^{i, k}+p_{j, 2}^{i, k}+p_{j, 3}^{i, k}\right)
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Since a direct calculation implies that

$$
\begin{aligned}
\left(\operatorname{div}_{x} w_{j}^{\tan }\right)_{\psi} & =\sum_{\substack{1 \leq i \leq n, 1 \leq k \leq n-1}}\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{\psi} \cdot \partial_{\eta_{k}}\left(v_{2, j}\right)_{\psi, i} \\
& -\sum_{\substack{1 \leq i \leq n, 1 \leq k \leq n-1}}\left(\frac{\partial \eta_{k}}{\partial x_{i}}\right)_{\psi} \cdot\left(\sum_{1 \leq l \leq n}\left(v_{2, j}\right)_{\psi, l} \cdot\left(\frac{\partial \eta_{n}}{\partial x_{l}}\right)_{\psi}\right) \cdot \frac{\partial^{2} x_{i}}{\partial \eta_{k} \partial \eta_{n}}
\end{aligned}
$$

in normal coordinate in $V_{4 \rho}=\psi^{-1}\left(U_{4 \rho, j}\right)$, it is easy to see that

$$
-\Delta_{x} p_{j}^{\tan }=\operatorname{div} w_{j}^{\tan }
$$

in $U_{2 \rho, j} \cap \Omega$. Calculations above ensures that

$$
\left[\nabla_{x} p_{j}^{\mathrm{tan}}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

Since $\operatorname{supp} q_{j, 1}^{i, k} \subset U_{4 \rho, j}$, we consider $x \in \Gamma$ and $r<\rho$ such that $B_{r}(x) \cap U_{4 \rho, j} \neq \emptyset$. By change of variables $y=\psi(\eta)$ in $U_{4 \rho, j}$, we deduce that

$$
\int_{B_{r}(x) \cap U_{4 \rho, j}}\left|\nabla_{y} q_{j, 1}^{i, k} \cdot \nabla_{y} d\right| d y \leq C \int_{B_{L_{*} r}(\zeta)}\left|\partial_{\eta_{n}} q_{j, 1, \psi}^{i, k}\right| d \eta
$$

where $\zeta=\psi^{-1}(x)$ and $\zeta_{n}=0$. By Lemma 4.3.2, we see that

$$
\int_{B_{L_{*} r}(\zeta)}\left|\partial_{\eta_{n}} q_{j, 1, \psi}^{i, k}\right| d \eta \leq r^{n} C_{\rho}\|v\|_{v B M O(\Omega)}
$$

Since $\nabla_{x} p_{j, l}^{i, k} \in L^{\infty}\left(\mathbf{R}^{n}\right)$ for $l=1,2,3$, we finally obtain that

$$
\frac{1}{r^{n}} \int_{B_{r}(x)}\left|\nabla_{y} p_{j}^{\tan } \cdot \nabla_{y} d\right| d y \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

### 4.3.5 Volume potential for normal component

Consider $\rho \in\left(0, \rho_{*} / 2\right)$ and $1 \leq j \leq m$. We let $g_{j}:=\nabla d \cdot\left(\varphi_{j} v_{2}\right)_{\text {odd }}$. Since $\varphi_{j} v_{2} \in v B M O(\Omega)$ with $\operatorname{supp} \varphi_{j} v_{2} \subset U_{\rho, j} \cap \bar{\Omega}$, by Proposition 6.2 .5 we see that $g_{j} \in B M O\left(\mathbf{R}^{n}\right) \cap b^{\nu}(\Gamma)$. In particular, we have the estimate

$$
\left[g_{j}\right]_{B M O\left(\mathbf{R}^{n}\right)}+\left[g_{j}\right]_{b^{\nu}(\Gamma)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

Considering the normal coordinate in $U_{4 \rho, j}, g_{j}$ is odd in $\eta_{n}$. Note that $w_{j}^{\text {nor }}=g_{j} \nabla d$.
Proposition 6.2.8. Since $\nabla d \in C^{1}\left(U_{\rho_{0}, j}\right)$, by Proposition 6.2 .5 we have that

$$
\left[w_{j}^{\text {nor }}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\|\nabla d\|_{C^{\gamma}\left(U_{\rho_{0}, j}\right)}\left\|g_{j}\right\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

We note that

$$
\operatorname{div}_{x} w_{j}^{\mathrm{nor}}=\nabla_{x} g_{j} \cdot \nabla_{x} d+g_{j} \Delta_{x} d
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Let $g_{j, \psi}:=g_{j} \circ \psi$ in $U_{\rho_{0}, j}$. We may treat $g_{j, \psi}$ as a function in $\mathbf{R}^{n}$ with value zero outside $V_{\rho}$. By Proposition 4.3.4, we have that

$$
\left[g_{j, \psi}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|g_{j}\right\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)}
$$

In normal coordinate, $\nabla_{x} g_{j} \cdot \nabla_{x} d=\partial_{\eta_{n}} g_{j, \psi}$. We introduce the operator $L=L_{0}+M$ in Proposition 4.3.3. Since $g_{j, \psi} \in Z_{\rho}$, we set

$$
p_{1, j, \psi}:=\theta_{\rho} L_{0}^{-1} \partial_{\eta_{n}} g_{j, \psi}
$$

where $\theta_{\rho}$ is the cut-off function of $V_{2 \rho}$ in the proof of Lemma 4.3.1. $p_{1, j, \psi}$ satisfies all conditions in Lemma 4.3.1. Set $f_{j, \psi}:=-M \theta_{\rho} L_{0}^{-1} \partial_{\eta_{n}} g_{j, \psi}$. We define

$$
p_{1, j}:=p_{1, j, \psi} \circ \psi^{-1}, f_{j}:=f_{j, \psi} \circ \psi^{-1}
$$

in $U_{\rho_{0}, j}$. Notice that $p_{1, j} \in L^{\infty}\left(\mathbf{R}^{n}\right)$ and $f_{j} \in L^{p}\left(\mathbf{R}^{n}\right)$ with some $p>n$. By Proposition 4.3.5,

$$
\left[\nabla_{x} p_{1, j}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left[\nabla_{\eta} p_{1, j, \psi}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left[g_{j, \psi}\right]_{B M O\left(\mathbf{R}^{n}\right)}
$$

Set

$$
p_{j}^{\text {nor }}=p_{1, j}+p_{2, j}+p_{3, j}
$$

with $p_{2, j}=E * f_{j}$ and $p_{3, j}=E *\left(g_{j} \Delta_{x} d\right)$. This $p_{j}^{\text {nor }}$ satisfies all desired properties required. For lower order terms $p_{2, j}$ and $p_{3, j}$, we have that

$$
\left\|p_{2}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}+\left\|\nabla p_{2}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}+\left\|\nabla p_{3}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)}+\left\|p_{3}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|g_{j}\right\|_{L^{p}\left(\mathbf{R}^{n}\right)}
$$

as $E$ and $\nabla_{x} E$ are both locally integrable. By an interpolation (cf. [4, Lemma 5]), we obtain that

$$
\left[\nabla_{x} p_{j}^{\mathrm{nor}}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|g_{j}\right\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

Since $\operatorname{supp} p_{1, j} \subset U_{\rho, j}$, we consider $x \in \Gamma$ and $r<\rho$ such that $B_{r}(x) \cap U_{\rho, j} \neq \emptyset$. Set $\zeta=\psi^{-1}(x)$ with $\zeta_{n}=0$. Consider change of variable $y=\psi(\eta)$ in $U_{4 \rho, j}$, by Lemma 4.3.1 we see that

$$
\int_{B_{r}(x) \cap U_{\rho, j}}\left|\nabla_{y} d \cdot \nabla_{y} p_{1, j}\right| d y \leq C \int_{B_{L_{* r}}(\zeta)}\left|\partial_{\eta_{n}} p_{1, j, \psi}\right| d \eta \leq C_{\rho}\left[g_{j, \psi}\right]_{B M O\left(\mathbf{R}^{n}\right)}
$$

By the $L^{\infty}$-estimates of $\nabla_{y} p_{2}$ and $\nabla_{y} p_{3}$, we get that

$$
\frac{1}{r^{n}} \int_{B_{r}(x)}\left|\nabla_{y} d \cdot \nabla_{y} p_{j}^{\mathrm{nor}}\right| d y \leq C_{\rho}\|v\|_{v B M O(\Omega)}
$$

Finally, a simple substitution shows that

$$
-\Delta_{x} p_{j}^{\mathrm{nor}}=\nabla_{x} d \cdot \nabla_{x} g_{j}-f_{j}+f_{j}+g_{j} \Delta_{x} d=\operatorname{div}_{x} w_{j}^{\mathrm{nor}}
$$

in $U_{2 \rho}\left(z_{0}\right) \cap \Omega$.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

### 4.4 Neumann problem with bounded data

We consider the Neumann problem for the Laplace equation problem (6.1.4) for the Laplace equation. If $\Omega$ is a smooth bounded domain, as well-known, for $g \in H^{-1 / 2}(\Gamma)$, there is a unique (up to constant) weak solution $u \in H^{1}(\Omega)$ provided that $g$ fulfills the compatibility condition

$$
\begin{equation*}
\int_{\Gamma} g d \mathcal{H}^{n-1}=0 \tag{4.4.1}
\end{equation*}
$$

see e.g. [18]. The main goal of this section is to prove that $\nabla u$ belongs to $v B M O^{\infty, \infty}(\Omega)$ provided that $g \in L^{\infty}(\Gamma)$. In other words, we prove Lemma 6.1.4.

To prove Lemma 6.1.4, we represent the solution by using the Neumann-Green function. Let $N(x, y)$ be the Green function, i.e., a solution $v$ of

$$
\begin{aligned}
-\Delta_{x} v & =\delta(x-y)-|\Omega|^{-1} & & \text { in } \Omega \\
\frac{\partial v}{\partial \mathbf{n}_{x}} & =0 & & \text { on } \partial \Omega
\end{aligned}
$$

for $y \in \Omega$. It is easy to see that the solution $u$ of (6.1.4) satisfying $\int_{\Omega} u d x=0$ is given as

$$
u(x)=\int_{\Gamma} N(x, y) g(y) d \mathcal{H}^{n-1}(y) .
$$

The function $N$ is decomposed as

$$
N(x, y)=E(x-y)+h(x, y),
$$

where $h \in C^{\infty}(\Omega \times \Omega)$ is a milder part. We recall $h(x, y)=h(y, x)$ and

$$
\sup _{x \in \Omega} \int_{\Omega}\left|\nabla_{y}^{k} h(x, y)\right|^{1+\delta} d y<\infty
$$

for $k=0,1,2$ with some $\delta>0$; see [12, Lemma 3.1]. In particular, by applying the standard $L^{p}$ estimate for the Neumann problem in the proof of [12, Lemma 3.1] to $\nabla_{y} h(\cdot, y)$, we can deduce that

$$
\sup _{x \in \Omega} \int_{\Omega}\left|\nabla_{x} \nabla_{y} h(x, y)\right|^{1+\delta} d y<\infty .
$$

Hence, we see that $\nabla_{x} h(x, \cdot) \in W^{1,1+\delta}\left(\Omega_{y}\right)$. By the trace theorem for Sobolev space $W^{1,1+\delta}\left(\Omega_{y}\right)$, this yields

$$
\begin{equation*}
M_{0}:=\sup _{x \in \Omega} \int_{\Gamma}\left|\nabla_{x} h(x, y)\right|^{1+\delta} d \mathcal{H}^{n-1}(y)<\infty . \tag{4.4.2}
\end{equation*}
$$

We decompose $u$ as

$$
u(x)=E *\left(\delta_{\Gamma} \otimes g\right)+\int_{\Gamma} h(x, y) g(y) d \mathcal{H}^{n-1}(y)=I+I .
$$

The estimate (4.4.2) yields

$$
\|\nabla I\|_{L^{\infty}(\Omega)} \leq M_{0}\|g\|_{L^{\infty}(\Gamma)},
$$

so to prove Lemma 6.1.4 it suffices to estimate $\nabla I$. In other words, Lemma 6.1.4 follows from the next lemma.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

Lemma 4.4.1. Let $\Omega$ be a bounded domain in $\mathbf{R}^{n}$ with $C^{2}$ boundary $\Gamma=\partial \Omega$.
(i) (BMO estimate) There exists a constant $C_{1}$ such that

$$
\begin{equation*}
\left[\nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{1}\|g\|_{L^{\infty}(\Gamma)} \tag{4.4.3}
\end{equation*}
$$

for all $g \in L^{\infty}(\Gamma)$.
(ii) ( $L^{\infty}$ estimate for normal component) There exists a constant $C_{2}$ such that

$$
\begin{equation*}
\left\|\nabla d \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right\|_{L^{\infty}\left(\Gamma_{\rho_{0}}^{\left.\mathbf{R}^{n} \cap \Omega\right)}\right.} \leq C_{2}\|g\|_{L^{\infty}(\Gamma)} \tag{4.4.4}
\end{equation*}
$$

for all $g \in L^{\infty}(\Gamma)$.
Here $E *\left(\delta_{\Gamma} \otimes g\right)$ is defined as $E *\left(\delta_{\Gamma} \otimes g\right)(x):=\int_{\Gamma} E(x-y) g(y) d \mathcal{H}^{n-1}(y)$ for a function $g$ on $\Gamma$. We shall prove Lemma 6.3.3 in following subsections.

### 4.4.1 $B M O$ estimate

To see the idea, we shall prove (4.4.3) in the case where $\Gamma$ is flat. Let $\Gamma=\partial \mathbf{R}_{+}^{n}$ and $\mathbf{R}_{+}^{n}=\left\{\left(x_{1}, \ldots, x_{n}\right) \mid x_{n}>0\right\}$. In this case,

$$
\nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)=\nabla \partial_{x_{n}} E * 1_{\mathbf{R}_{+}^{n}} \widetilde{g}
$$

where $\widetilde{g} \in L^{\infty}\left(\mathbf{R}^{n}\right)$ is defined by $\widetilde{g}\left(x^{\prime}, x_{n}\right):=g\left(x^{\prime}, 0\right)$ for any $x \in \mathbf{R}^{n}$. By the $L^{\infty}-B M O$ estimate for the singular integral operator [15, Theorem 4.2.7], we obtain (4.4.3) when $\Gamma=\partial \mathbf{R}_{+}^{n}$.

Lemma 6.3.3 (i). Note that the signed distance function $d$ is $C^{2}$ in $\Gamma_{\rho_{0}}^{\mathbf{R}^{n}}$, see $[13$, Section 14.6]. Let $\delta \in \rho_{0} / 2$. We take a $C^{2}$ cut-off function $\theta \geq 0$ such that $\theta(\sigma)=1$ for $\sigma \leq 1$ and $\theta(\sigma)=0$ for $\sigma \geq 2$. By the choice of $\delta$, we see that $\theta_{d}=\theta(d / \delta)$ is $C^{2}$ in $\mathbf{R}^{n}$. We extend $g \in L^{\infty}(\Gamma)$ to $g_{e} \in L^{\infty}\left(\Gamma_{2 \delta}^{\mathbf{R}^{n}}\right)$ by setting

$$
g_{e}(x):=g(\pi x)
$$

for any $x \in \Gamma_{2 \delta}^{\mathbf{R}^{n}}$ with $\pi x$ denoting the projection of $x$ on $\Gamma$. For $x \in \Gamma_{2 \delta}^{\mathbf{R}^{n}}$, by considering the normal coordinate $x=\psi(\eta)$ in $U_{2 \delta}(\pi x)$, we have that

$$
\left(\nabla_{x} d\right)_{\psi} \cdot\left(\nabla_{x} g_{e}\right)_{\psi}=\partial_{\eta_{n}}\left(g_{e}\right)_{\psi}=0
$$

as $\left(g_{e}\right)_{\psi}\left(\eta^{\prime}, \alpha\right)=\left(g_{e}\right)_{\psi}\left(\eta^{\prime}, \beta\right)$ for any $\left|\eta^{\prime}\right|<2 \delta$ and $\alpha, \beta \in(-2 \delta, 2 \delta)$. Hence, we see that $\nabla d \cdot \nabla g_{e}=0$ in $\Gamma_{2 \delta}^{\mathbf{R}^{n}}$.

Let us consider $g_{e, c}:=\theta_{d} g_{e}$. A key observation is that

$$
\begin{aligned}
\delta_{\Gamma} \otimes g & =\left(\nabla 1_{\Omega} \cdot \nabla d\right) g_{e, c} \\
& =\operatorname{div}\left(g_{e, c} 1_{\Omega} \nabla d\right)-1_{\Omega} \operatorname{div}\left(g_{e, c} \nabla d\right) \\
\operatorname{div}\left(g_{e, c} \nabla d\right) & =g_{e, c} \Delta d+\nabla d \cdot \nabla g_{e, c}=g_{e, c} \Delta d+\frac{\theta^{\prime}(d / \delta)}{\delta} g_{e}
\end{aligned}
$$

Thus

$$
\nabla E *\left(\delta_{\Gamma} \otimes g\right)=\nabla \operatorname{div}\left(E *\left(g_{e, c} 1_{\Omega} \nabla d\right)\right)-\nabla E *\left(1_{\Omega} g_{e} f_{\theta, \delta}\right)=I_{1}+I_{2}
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
where $f_{\theta, \delta}:=\theta_{d} \Delta d+\frac{\theta^{\prime}(d / \delta)}{\delta}$. By the $L^{\infty}-B M O$ estimate for the singular integral operator [15, Theorem 4.2.7], the first term is estimated as

$$
\left[I_{1}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\left\|g_{e, c} \nabla d\right\|_{L^{\infty}(\Omega)} \leq C\|g\|_{L^{\infty}(\Gamma)} .
$$

Since

$$
A=\sup _{x \in \mathbf{R}^{n} \backslash\{0\}}|x|^{n-1}|\nabla E(x)|<\infty,
$$

for $x \in \mathbf{R}^{n}$ with $d(x, \Omega)=\inf _{y \in \Omega}|x-y|<1$ we have that

$$
\left|I_{2}(x)\right| \leq A \int_{\Omega} \frac{1}{|x-y|^{n-1}} d y\left\|f_{\theta, \delta}\right\|_{L^{\infty}\left(\Gamma_{2 \delta}^{\mathbf{R}^{n}}\right)}\left\|g_{e, c}\right\|_{L^{\infty}\left(\Gamma_{2 \delta}^{\mathbf{R}^{n}}\right)} \leq C_{\Omega, \delta}\|g\|_{L^{\infty}(\Gamma)}
$$

with $C_{\Omega, \delta}$ depending only on $\Omega$ and $\delta$. For $x \in \mathbf{R}^{n}$ with $d(x, \Omega)=\inf _{y \in \Omega}|x-y| \geq 1$, the above estimate is trivial as $|x-y|^{-(n-1)} \leq 1$ for any $y \in \Omega$. The proof of (i) is now complete.

### 4.4.2 Estimate for normal derivative

We shall estimate normal derivative of $E$.
Lemma 4.4.2. Let $\Omega$ be a bounded domain in $\mathbf{R}^{n}$ with $C^{2}$ boundary $\Gamma$. Then

$$
\begin{equation*}
\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y)=-1 \quad \text { for } \quad x \in \Omega \tag{i}
\end{equation*}
$$

(ii)

$$
\sup _{x \in \Omega} \int_{\Gamma}\left|\frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)\right| d \mathcal{H}^{n-1}(y)<\infty .
$$

Proof. (i) This follows from the Gauss divergence theorem. We observe that

$$
\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y)=\int_{\Omega} \Delta_{y} E(x-y) d y .
$$

Since $\Delta_{y} E(x-y)=-\delta(x-y)$, we obtain

$$
\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y)=-1
$$

for $x \in \Omega$.
(ii) We recall our local coordinate patches $\left\{U_{i}\right\}_{i=1}^{m}$ with $U_{i}=U_{\rho, i}$ as in Section 6.2.1. For $x \in \Omega^{\rho}$ and $y \in \Gamma$, obviously $|\nabla E(x-y)| \leq C \rho^{-(n-1)}$. Let $x \in \Gamma_{\rho}^{\mathbf{R}^{n}} \cap \Omega$. If $d\left(x, U_{i} \cap \Gamma\right) \geq \rho$, similarly $|\nabla E(x-y)| \leq C \rho^{-(n-1)}$ for $y \in U_{i} \cap \Gamma$. Hence, it is sufficient to consider $U_{i}$ such that $d\left(x, U_{i} \cap \Gamma\right)<\rho$, i.e., it suffices to prove

$$
\int_{U_{i} \cap \Gamma}\left|\frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)\right| d \mathcal{H}^{n-1}(y)<\infty .
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
for $U_{i}$ such that $d\left(x, U_{i} \cap \Gamma\right)<\rho$. Since $-\partial E / \partial \mathbf{n}_{y}(x-y)$ is invariant under translations and rotations, we can write $-\partial E / \partial \mathbf{n}_{y}(x-y)$ in the local coordinate. Let $U_{i}$ be such that $d\left(x, U_{i} \cap \Gamma\right)<\rho$ and denote $h_{z_{i}}$ by $h_{i}$ for simplicity. Let us observe that

$$
-\mathbf{n}\left(y^{\prime}, h_{i}\left(y^{\prime}\right)\right)=\left(-\nabla^{\prime} h_{i}\left(y^{\prime}\right), 1\right) / \omega_{i}\left(y^{\prime}\right)
$$

with $\omega_{i}\left(y^{\prime}\right)=\left(1+\left|\nabla^{\prime} h_{i}\left(y^{\prime}\right)\right|^{2}\right)^{1 / 2}$, where $\nabla^{\prime}$ is the gradient in $y^{\prime}$ variables. This implies that

$$
-n \alpha(n) \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)=\frac{\sigma_{i}\left(y^{\prime}\right)}{\omega_{i}\left(y^{\prime}\right)\left(\left|x^{\prime}-y^{\prime}\right|^{2}+\left(x_{n}-h_{i}\left(y^{\prime}\right)\right)^{2}\right)^{n / 2}}
$$

for $y \in \Gamma_{i}$ with

$$
\sigma_{i}\left(y^{\prime}\right):=-\nabla^{\prime} h_{i}(y) \cdot\left(x^{\prime}-y^{\prime}\right)+\left(x_{n}-h_{i}\left(y^{\prime}\right)\right) \text { where } x_{n}>h_{i}\left(x^{\prime}\right), x^{\prime} \in B_{3 \rho}\left(0^{\prime}\right)
$$

We set

$$
K_{i}\left(x^{\prime}, y^{\prime}, x_{n}\right)=\frac{\sigma_{i}\left(y^{\prime}\right)}{\left(\left|x^{\prime}-y^{\prime}\right|^{2}+\left(x_{n}-h_{i}\left(y^{\prime}\right)\right)^{2}\right)^{n / 2}}
$$

By the Taylor expansion

$$
h_{i}\left(x^{\prime}\right)=h_{i}\left(y^{\prime}\right)+\nabla^{\prime} h_{i}\left(y^{\prime}\right) \cdot\left(x^{\prime}-y^{\prime}\right)+r_{i}\left(x^{\prime}, y^{\prime}\right)
$$

with

$$
r_{i}\left(x^{\prime}, y^{\prime}\right)=\left(x^{\prime}-y^{\prime}\right)^{\mathrm{T}} \cdot \int_{0}^{1}(1-\theta) \nabla^{\prime 2} h_{i}\left(\theta x^{\prime}+(1-\theta) y^{\prime}\right) d \theta \cdot\left(x^{\prime}-y^{\prime}\right)
$$

we obtain

$$
\sigma_{i}\left(y^{\prime}\right)=x_{n}-h_{i}\left(x^{\prime}\right)+r_{i}\left(x^{\prime}, y^{\prime}\right)
$$

with an estimate

$$
\begin{equation*}
\left|r_{i}\left(x^{\prime}, y^{\prime}\right)\right| \leq\left\|\nabla^{\prime 2} h_{i}\right\|_{L^{\infty}\left(B_{3 \rho}\left(0^{\prime}\right)\right)}\left|x^{\prime}-y^{\prime}\right|^{2} \tag{4.4.5}
\end{equation*}
$$

We decompose $K_{i}$ into a leading term and a remainder term

$$
K_{i}\left(x^{\prime}, y^{\prime}, x_{n}\right)=K_{0}^{i}\left(x^{\prime}, y^{\prime}, x_{n}\right)+R_{i}\left(x^{\prime}, y^{\prime}, x_{n}\right)
$$

with

$$
\begin{aligned}
K_{0}^{i}\left(x^{\prime}, y^{\prime}, x_{n}\right) & :=\frac{x_{n}-h_{i}\left(x^{\prime}\right)}{\left(\left|x^{\prime}-y^{\prime}\right|^{2}+\left(x_{n}-h_{i}\left(y^{\prime}\right)\right)^{2}\right)^{n / 2}} \\
R_{i}\left(x^{\prime}, y^{\prime}, x_{n}\right) & :=\frac{r_{i}(x, y)}{\left(\left|x^{\prime}-y^{\prime}\right|^{2}+\left(x_{n}-h_{i}\left(y^{\prime}\right)\right)^{2}\right)^{n / 2}}
\end{aligned}
$$

The term $K_{0}^{i}$ is very singular but it is positive. The term $R_{i}$ is estimated as

$$
\left|R_{i}\left(x^{\prime}, y^{\prime}, x_{n}\right)\right| \leq\left\|\nabla^{2} h_{i}\right\|_{L^{\infty}\left(B_{3 \rho}\left(0^{\prime}\right)\right)}\left|x^{\prime}-y^{\prime}\right|^{2-n}
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
by the estimate (6.3.5). Hence,

$$
\int_{\Gamma \cap U_{i}}\left|\frac{R_{i}\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega_{i}\left(y^{\prime}\right)}\right| d \mathcal{H}^{n-1}(y) \leq C \int_{B_{\rho}\left(0^{\prime}\right)} \frac{1}{\left|x^{\prime}-y^{\prime}\right|^{n-2}} d y^{\prime} \leq C \rho
$$

with $C$ independent of $\rho$ and $i$. By (i), we observe that

$$
\begin{aligned}
n \alpha(n) & =\sum_{i: d\left(x, U_{i} \cap \Gamma\right)<\rho} \int_{B_{\rho}\left(0^{\prime}\right)} \frac{K_{i}\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega_{i}\left(y^{\prime}\right)} d y^{\prime} \\
& -n \alpha(n) \sum_{j: d\left(x, U_{j} \cap \Gamma\right) \geq \rho} \int_{U_{j} \cap \Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y) .
\end{aligned}
$$

Since $K_{0}^{i}$ is positive for any $i$ such that $d\left(x, U_{i} \cap \Gamma\right)<\rho$,

$$
\sum_{i: d\left(x, U_{i} \cap \Gamma\right)<\rho} \int_{B_{\rho}\left(0^{\prime}\right)} \frac{K_{0}^{i}\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega_{i}\left(y^{\prime}\right)} d y^{\prime} \leq n \alpha(n) \cdot\left(1+\frac{m \cdot C \cdot S(\Gamma)}{\rho^{n-1}}\right)+m \cdot C \cdot \rho
$$

where $S(\Gamma)$ denotes the surface area of $\Gamma$, which is bounded. Thus, the estimate

$$
\int_{U_{i} \cap \Gamma}\left|\frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)\right| d \mathcal{H}^{n-1}(y) \leq \frac{1}{n \alpha(n)} \int_{B_{\rho}\left(0^{\prime}\right)} \frac{K_{0}^{i}+\left|R_{i}\right|}{\omega_{i}\left(y^{\prime}\right)} d y^{\prime}<\infty
$$

holds for any $U_{i}$ such that $d\left(x, U_{i} \cap \Gamma\right)<\rho$. The proof of (ii) is now complete.

Based on Lemma 6.3.4, we are able to prove Lemma 6.3 .3 (ii).
Lemma 6.3.3 (ii). We decompose

$$
\begin{aligned}
& \nabla d(x) \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)(x)=\int_{\Gamma}(\nabla d(x)-\nabla d(y)) \cdot \nabla E(x-y) g(y) d \mathcal{H}^{n-1}(y) \\
&+\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) g(y) d \mathcal{H}^{n-1}(y)=I_{1}+I_{2} .
\end{aligned}
$$

Let $x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}}$ and $\pi x$ be the projection of $x$ on $\Gamma$. For $y \in U_{\rho_{0}}(\pi x)$, there exists a constant $L^{\prime}$, independent of $x$ and $y$, such that

$$
|\nabla d(x)-\nabla d(y)| \leq L^{\prime}|x-y| .
$$

For $y \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}} \backslash U_{\rho_{0}}(\pi x)$, we have that $|x-y| \geq \frac{\rho_{0}}{2}$. Since $\overline{\Gamma_{\rho_{0} / 2}} \overline{\mathbf{R}^{n}}$ is compact in $\mathbf{R}^{n}$, by considering a finite subcover of $\cup_{z \in \Gamma} U_{\rho_{0}}(z)$ we are able to show that there exists $M>0$ such that the estimate

$$
|\nabla d(x)-\nabla d(y)| \leq M|x-y|
$$

holds for any $x, y \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}}$. Thus,

$$
H(x, y)=(\nabla d(x)-\nabla d(y)) \cdot \nabla E(x-y)
$$

is estimated as

$$
|H(x, y)| \leq \frac{M}{|x-y|^{n-2}}
$$

4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain
in $\Gamma_{\rho_{0}}^{\mathbf{R}^{n}} \times \Gamma_{\rho_{0}}^{\mathbf{R}^{n}}$. We observe that

$$
\begin{aligned}
\sup _{x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}} \cap \Omega}\left|I_{1}(x)\right| & \leq \sup _{x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}} \cap \Omega} \int_{\Gamma} H(x, y) d \mathcal{H}^{n-1}(y)\|g\|_{L^{\infty}(\Gamma)} \\
& \leq M \sup _{x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}} \cap \Omega} \int_{\Gamma} \frac{d \mathcal{H}^{n-1}(y)}{|x-y|^{n-2}}\|g\|_{L^{\infty}(\Gamma)}
\end{aligned}
$$

Since

$$
\sup _{x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}} \cap \Omega}\left|I_{2}(x)\right| \leq \sup _{x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}} \cap \Omega} \int_{\Gamma}\left|\frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)\right| d \mathcal{H}^{n-1}(y)\|g\|_{L^{\infty}(\Gamma)},
$$

Lemma 6.3.4 (ii) now yields (4.4.4). The proof is now complete.
We wonder whether the tangential component of $\nabla E *\left(\delta_{\Gamma} \otimes g\right)$ satisfies the same estimate. Unfortunately, the estimate

$$
\left\|\nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right\|_{L^{\infty}\left(\Gamma_{\rho_{0}}^{\left.\mathbf{R}^{n} \cap \Omega\right)}\right.} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

should not hold even if $\Gamma$ is flat. Even weaker estimate

$$
\left[\nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right]_{b^{\nu}(\Gamma)} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

should not hold in general.
To illustrate the problem, we consider the case that $\Gamma$ is flat. We may assume $\Gamma=\partial \mathbf{R}_{+}^{n}$, $\mathbf{R}_{+}^{n}=\left\{x_{n}>0\right\}$.

Lemma 4.4.3. The estimate

$$
\left\|\partial_{x_{n}}\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right\|_{L^{\infty}\left(\mathbf{R}_{+}^{n}\right)} \leq \frac{1}{2}\|g\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)}
$$

holds for $g \in L^{\infty}\left(\mathbf{R}^{n-1}\right)$.
Proof. This is because $-\partial_{x_{n}}\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)$ is the half of the Poisson integral, i.e.,

$$
-\partial_{x_{n}}\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)(x)=\frac{1}{2} \int_{\mathbf{R}^{n-1}} P_{x_{n}}\left(x^{\prime}-y^{\prime}\right) g\left(y^{\prime}\right) d y^{\prime}
$$

where $P_{x_{n}}$ denotes the Poisson kernel. Thus the desired $L^{\infty}$ estimate follows from the maximum principle of the Dirichlet problem for the Laplacian or from the property that $\int_{\mathbf{R}^{n-1}} P_{x_{n}}\left(x^{\prime}\right) d x^{\prime}=1$ and $P_{x_{n}} \geq 0$.

Theorem 4.4.4. There is a bounded sequence of smooth functions $\left\{g_{\ell}\right\}_{\ell \in \mathbf{N}} \subset L^{\infty}\left(\mathbf{R}^{n-1}\right)$ such that

$$
\lim _{\ell \rightarrow \infty}\left[\partial_{x^{\prime}}\left(E *\left(\delta_{\Gamma} \otimes g_{\ell}\right)\right)\right]_{b^{\nu}}=\infty
$$

for any $\nu>0$.
Proof. If $g$ is smooth, then $E *\left(\delta_{\Gamma} \otimes g\right)$ is smooth up to the boundary. In this case, if $\left[\partial_{x^{\prime}}\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right]_{b^{\nu}}$ is bounded by $C\|g\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)},\left\|\partial_{x^{\prime}}\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right\|_{L^{\infty}(\Gamma)}$ is also bounded by $c_{0} C\|g\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)}$ with a constant $c_{0}$ depending only on $n$ since the mean value over $r$-ball around $x$ converges to its value at $x$ as $r \rightarrow 0$.
4. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a bounded domain

We consider the Neumann problem

$$
\begin{aligned}
& \Delta u=0 \text { in } \quad \mathbf{R}_{+}^{n}, \\
& \frac{\partial u}{\partial \mathbf{n}}=g \quad \text { on } \quad \Gamma=\partial \mathbf{R}_{+}^{n} .
\end{aligned}
$$

By using the tangential Fourier transform, we see that

$$
u(x, t)=\Lambda^{-1} \exp \left(-x_{n} \Lambda\right) g
$$

where $\Lambda=\left(-\Delta^{\prime}\right)^{1 / 2}$. If $\left\|\nabla^{\prime} u\right\|_{L^{\infty}(\Gamma)} \leq C\|g\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)}$ were true, sending $x_{n}>0$ to zero would imply $L^{\infty}$ boundedness of the Riesz operator $\nabla^{\prime} \Lambda^{-1}$, which is absurd.

The operator $E *\left(\delta_{\Gamma} \otimes g\right)$ is the half of the solution operator of the Neumann problem, so $L^{\infty}$ bound for $\nabla^{\prime} E *\left(\delta_{\Gamma} \otimes g\right)$ should not hold even if it is restricted to smooth functions.

Corollary 4.4.5. Assume that $\Omega=\mathbf{R}_{+}^{n}$. Let $v \mapsto \nabla q$ be the Helmholtz projection to a gradient field. Then, this projection is unbounded from $\left(L^{\infty}(\Omega)\right)^{n}$ to $\left(B M O_{b}^{\mu, \nu}(\Omega)\right)^{n}$ for any $\mu, \nu>0$.

Proof. We consider

$$
v=\left(0, \ldots, 0, v_{n}\left(x^{\prime}\right)\right)
$$

with $v_{n} \in L^{\infty}\left(\mathbf{R}^{n-1}\right)$. This evidently solves $\operatorname{div} v=0$. The normal trace equals $-v_{n}\left(x^{\prime}\right)$. If

$$
[\nabla q]_{b^{\nu}} \leq C\left\|v_{n}\right\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)}
$$

for all $v_{n} \in L^{\infty}\left(\mathbf{R}^{n-1}\right)$ with $C$ independent of $v$, then this would contradict Theorem 4.4.4.

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## Chapter 5

## Extension theorem for $b m o$ in a domain

In this chapter, we establish an extension theorem for functions defined in an arbitrary uniformly $C^{2}$ domain in the local $B M O$ space. This extension theorem results in a product estimate for the local $B M O$ space in an arbitrary uniformly $C^{2}$ domain.

### 5.1 Introduction

For a function space defined in an open domain $\Omega \subset \mathbf{R}^{n}$, it is natural to consider the problem if functions of this space can be continuously extended from $\Omega$ to $\mathbf{R}^{n}$. For example, if $f$ is in $L^{p}(\Omega)$ with $1 \leq p \leq \infty$, its zero extension $f^{z e}=f \cdot 1_{\Omega}$ naturally belongs to $L^{p}\left(\mathbf{R}^{n}\right)$ where $1_{\Omega}$ denotes the characteristic function for domain $\Omega$. Although such extension problem is trivial for $L^{p}$, the story completely changes when it comes to the space of bounded mean oscillation ( $B M O$ for short). In the case for $B M O, f \in B M O^{\infty}(\Omega)$ is not sufficient to have that $f^{z e} \in B M O\left(\mathbf{R}^{n}\right)$. In fact, there exist domains $\Omega$ where bounded linear extension operator from $B M O^{\infty}(\Omega)$ to $B M O\left(\mathbf{R}^{n}\right)$ does not exist. P. W. Jones [11] gives a necessary and sufficient condition for a domain such that there exists a bounded linear extension operator.

An open connected subset $D \subset \mathbf{R}^{n}$ is called a uniform domain if there exists constants $a, b>0$ such that for all $x, y \in D$ there exists a rectifiable curve $\gamma \subset D$ of length $s(\gamma) \leq$ $a|x-y|$ with min $\{s(\gamma(x, z)), s(\gamma(y, z))\} \leq b d(z, \partial D)$, where $\gamma(x, z)$ denotes the part of $\gamma$ between $x$ and $z$ on the curve and $d(z, \partial D)=\inf _{w \in \partial D}|z-w|$ denotes the distance from $z$ to the boundary $\partial D$; see e.g. [6]. Let $D \subset \mathbf{R}^{n}$ be a uniform domain. Jones' extension theorem guarantees that there is a constant $C_{J}$ such that for each $f \in B M O^{\infty}(D)$, there is an extension $\bar{f} \in B M O\left(\mathbf{R}^{n}\right)$ satisfying

$$
[f]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{J}[f]_{B M O^{\infty}(D)}
$$

with $C_{J}$ independent of $f$. The operator $f \mapsto \bar{f}$ is a bounded linear operator. Conversely, if there exists such an extension, then $D$ is a uniform domain.

In [8], a small modification was made to Jones' extension theorem so that we obtained an extension theorem regarding the local BMO space $b m o_{\infty}^{\infty}(D):=B M O^{\infty}(D) \cap L_{\mathrm{ul}}^{1}(D)$ where

$$
L_{\mathrm{ul}}^{1}(D):=\left\{f \in L_{\mathrm{loc}}^{1}(D)\left|\|f\|_{L_{\mathrm{ul}}^{1}(D)}:=\sup _{x \in \mathbf{R}^{n}} \int_{B_{1}(x) \cap D}\right| f(y) \mid d y<\infty\right\}
$$

If $D$ is a uniform domain, the modified Jones' extension theorem says that for $f \in b m o_{\infty}^{\infty}(D)$ there exists $\bar{f} \in b m o:=B M O \cap L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)$ satisfies

$$
\begin{equation*}
\|\bar{f}\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C_{J}\|f\|_{b m o_{\infty}^{\infty}(D)} \tag{5.1.1}
\end{equation*}
$$

with $C_{J}$ independent of $f$. Moreover, the support of $\bar{f}$ is contained in a small neighborhood of $\bar{D}$. The reason why we are interested in such local $B M O$ spaces ( $b m o$ ) is that multiplication by a Hölder function in such spaces is bounded, i.e., for $\varphi \in C^{\gamma}(D)$ with $\gamma \in(0,1)$, we have that $\varphi f \in b m o_{\infty}^{\infty}(D)$ satisfies the product estimate

$$
\begin{equation*}
\|\varphi f\|_{b m o_{\infty}^{\infty}(D)} \leq C_{J}\|\varphi\|_{C^{\gamma}(D)}\|f\|_{b m o_{\infty}^{\infty}(D)} \tag{5.1.2}
\end{equation*}
$$

with $C_{J}$ independent of $\varphi$ and $f$. Because of this multiplication principle, cut-off becomes possible in the space $b m o_{\infty}^{\infty}(D)$. The product estimate for bmo follows from the fact that such estimate holds for the local Hardy space $h^{1}$ and $b m o$ is the dual space of $h^{1}$, see e.g. [13, Section 3].

Since the extension theorem and the product estimate for $b m o_{\infty}^{\infty}(D)$ relies heavily on the original extension theorem by Jones, we don't know if these results hold or not in the case where $D$ is not a uniform domain. For instance, an aperture domain is an example for a non-uniform domain which is of special interests in fluid mechanics.

Our goal in this chapter is to establish the extension theorem for $b m o_{\infty}^{\infty}(\Omega)$ in the case where $\Omega$ is any arbitrary uniformly $C^{2}$ domain. We would like to clarify several relevant concepts before we state our main theorem. Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2$. Let $\Gamma:=\partial \Omega$ denotes the boundary of $\Omega$. Let $R_{0}$ be the reach of the boundary $\Gamma=\partial \Omega$. By considering $R_{0}$ sufficiently small, we may assume that $R_{0}$ is not only the reach of $\Gamma$ in $\Omega$ but also the reach of $\Gamma$ in $\Omega^{c}$. Let $d$ denote the signed distance function from $\Gamma$ which is defined by

$$
d(x)=\left\{\begin{array}{cc}
\inf _{y \in \Gamma}|x-y| & \text { for } \\
-\inf _{y \in \Gamma}|x-y| & \text { for } \\
x \notin \Omega,
\end{array}\right.
$$

so that $d(x)=d_{\Gamma}(x)$ for $x \in \Omega$. For $0<\rho<R_{0}$, let $\Gamma_{\rho}$ be the $\rho$-neighborhood of $\Gamma$ in $\Omega$, i.e.,

$$
\Gamma_{\rho}=\left\{x \in \Omega \mid d_{\Gamma}(x)<\rho\right\}
$$

and $\Gamma^{\rho}$ be the $\rho$-neighborhood of $\Gamma$ in $\mathbf{R}^{n}$, i.e.,

$$
\Gamma^{\rho}=\left\{x \in \mathbf{R}^{n}| | d(x) \mid<\rho\right\} .
$$

We recall the $B M O^{\mu}$-seminorm for $\mu \in(0, \infty$ ] which was defined in [1], [2], [3], [4]. For $f \in L_{\text {loc }}^{1}(\Omega)$, we define

$$
[f]_{B M O^{\mu}(\Omega)}:=\sup \left\{\left.\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f(y)-f_{B_{r}(x)}\right| d y \right\rvert\, B_{r}(x) \subset \Omega, r<\mu\right\},
$$

where $f_{B}$ denotes the average over $B$, i.e.,

$$
f_{B}:=\frac{1}{|B|} \int_{B} f(y) d y
$$

and $B_{r}(x)$ denotes the closed ball of radius $r$ centered at $x$ and $|B|$ denotes the Lebesgue measure of $B$. The space $B M O^{\mu}(\Omega)$ is defined as

$$
B M O^{\mu}(\Omega):=\left\{f \in L_{\mathrm{loc}}^{1}(\Omega) \mid[f]_{B M O^{\mu}}<\infty\right\} .
$$

As in [8], for $\delta \in(0, \infty]$ we set

$$
b m o_{\delta}^{\mu}(\Omega):=B M O^{\mu}(\Omega) \cap L_{\mathrm{ul}}^{1}\left(\Gamma_{\delta}\right)
$$

with the norm

$$
\|v\|_{b m o_{\delta}^{\mu}}:=[v]_{B M O^{\mu}(\Omega)}+[v]_{L_{\mathrm{u} 1}^{1}\left(\Gamma_{\delta}\right)} .
$$

We are now in a position to state our main result.
Theorem 5.1.1. Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2$. There exists $c_{\Omega}^{*}>0$ such that for any $\rho \in\left(0, c_{\Omega}^{*}\right)$ and $v \in b m o_{\infty}^{\infty}(\Omega)$, there is an extension $\widetilde{v} \in b m o\left(\mathbf{R}^{n}\right)$ such that

$$
\|\widetilde{v}\|_{b m o\left(\mathbf{R}^{n}\right)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

with $C$ independent of $v$ and $\rho$. Moreover, $\operatorname{supp} \widetilde{v} \subset \overline{\Omega_{2 \rho}}$ where

$$
\Omega_{2 \rho}:=\left\{x \in \mathbf{R}^{n} \mid d(x, \bar{\Omega})<2 \rho\right\}
$$

The operator $v \mapsto \widetilde{v}$ is a bounded linear operator.
Different from the construction by Jones which delicately deals with the Whitney decomposition of both $\Omega$ and $\Omega^{\mathrm{c}}$, our strategy firstly decomposes $v$ into the sum of $v_{1}$ and $v_{2}$ such that the support of $v_{1}$ is close to $\Gamma$ whereas the support of $v_{2}$ is away from $\Gamma$. Such decomposition of $v$ is achieved by the multiplication of $v$ with a cut-off function $\theta_{\rho}$ supported in a small neighborhood of $\Gamma$, i.e., $v_{1}:=\theta_{\rho} v$. Since $\Omega$ is not necessarily uniform, at this moment we cannot apply the product estimate that was established for the case of uniform domains to $v_{1}$ directly. Instead, we apply a localization argument so that we can estimate the $B M O^{\rho}$-seminorm of $v_{1}$ in $\Omega$. The key idea of the localization argument is as follow. If a ball $B$ of radius $r(B) \leq \rho$ in $\Omega$ is away from the boundary, then $v_{1}$ vanishes in this ball. If $B$ is close to the boundary, then we can find a bounded Lipschitz domain $W_{\rho}$ such that the boundary of $W_{\rho}$ coincides with $\Gamma$ for a small part and $B \subset W_{\rho}$. Since $\Gamma$ is uniformly $C^{2}$, by considering the normal coordinate change in $\Gamma^{R_{0}}$, we are able to show that the Lipschitz regularity of $\partial W_{\rho}$ can be uniformly controlled. As $r_{W_{\rho}} v_{1} \in b m o_{\infty}^{\infty}\left(W_{\rho}\right)$, we can apply the product estimate to $r_{W_{\rho}} v_{1}$ in $W_{\rho}$. Since a bounded Lipschitz domain is a typical example of a uniform domain and the constant $C_{J}$ in (5.1.1) and (5.1.2) depends only on the Lipschitz regularity of the domain, we obtain a uniform estimate for $\left[v_{1}\right]_{B M O^{\rho}(\Omega)}$.

Next, we recall the extension introduced in [9] for functions supported in a small neighborhood of $\Gamma$. We extend $v_{1}$ to $v_{1}^{e}$ in $\mathbf{R}^{n}$ so that $v_{1}^{e}$ is even in the direction of $\nabla d$ with respect to $\Gamma$. By considering the normal coordinate change, we then reduce the problem to the half space and prove that $v_{1}^{e} \in b m o_{\infty}^{\rho}\left(\mathbf{R}^{n}\right)$. Since the $B M O^{\infty}$-seminorm can be estimated by the $b m o_{\infty}^{\rho}$-norm, we thus deduce that $v_{1}^{e} \in b m o\left(\mathbf{R}^{n}\right)$. For $v_{2}$, we simply zero extend it. By a similar argument, it is not hard to show that its zero extension $v_{2}^{z e} \in b m o\left(\mathbf{R}^{n}\right)$. Setting $\widetilde{v}=v_{1}^{e}+v_{2}^{z e}$ gives us Theorem 5.1.1.

Since there exists a bounded linear extension operator from $C^{\gamma}(\Omega)$ to $C^{\gamma}\left(\mathbf{R}^{n}\right)$ for arbitrary domain $\Omega$, the product estimate for $b m o_{\infty}^{\infty}(\Omega)$ follows naturally from Theorem 5.1.1.

Theorem 5.1.2. Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2$. Let $\varphi \in C^{\gamma}(\Omega)$ with $\gamma \in(0,1)$. For each $v \in b m o_{\infty}^{\infty}(\Omega)$, the function $\varphi v \in b m o_{\infty}^{\infty}(\Omega)$ satisfies

$$
\|\varphi v\|_{b m o_{\infty}^{\infty}(\Omega)} \leq C\|\varphi\|_{C^{\gamma}(\Omega)}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

with $C$ independent of $\varphi$ and $v$.

This chapter is organized as follow. In Section 5.2, we establish several uniform estimates which are essential for our localization argument. In Section 5.3, we perform the localization argument to do the cut-off to $v$ and get $v_{1}$. In Section 5.4, we extend $v_{1}$ from $\Omega$ to $\mathbf{R}^{n}$ and prove Theorem 5.1.1 and Theorem 5.1.2. Besides, we apply a similar argument to further obtain an extension theorem for $b m o_{\delta}^{\mu}(\Omega)$ in the case where $\delta, \mu<\infty$. In Section 5.5, we give a simple application of our main extension theorem to construct an example regarding the space $B M O_{b}^{\infty, \infty}(\Omega)$. In Section 5.6, we update an extension result that is essential in establishing the Helmholtz decomposition of vector fields of $B M O$ in a domain.

### 5.2 Uniform estimates

We denote $x^{\prime}:=\left(x_{1}, x_{2}, \ldots, x_{n-1}\right)$ for $x \in \mathbf{R}^{n}$ and $\nabla^{\prime}:=\left(\partial_{1}, \partial_{2}, \ldots, \partial_{n-1}\right)$. Since $\Omega$ is a uniformly $C^{2}$ domain, there exists $r_{*}, \delta_{*}, L_{\Gamma}>0$ such that for each $w_{0} \in \Gamma$, up to translation and rotation, there exists a function $\psi_{w_{0}} \in C^{2}\left(B_{r_{*}}\left(0^{\prime}\right)\right)$ with

$$
\begin{align*}
& \left|\nabla^{k} \psi_{w_{0}}\right| \leq L_{\Gamma} \text { in } B_{r_{*}}\left(0^{\prime}\right) \text { for } k=0,1,2 \\
& \nabla^{\prime} \psi_{w_{0}}\left(0^{\prime}\right)=0^{\prime}, \psi_{w_{0}}\left(0^{\prime}\right)=0 \tag{5.2.1}
\end{align*}
$$

such that the neighborhood

$$
U_{r_{*}, \delta_{*}, \psi_{w_{0}}}\left(w_{0}\right):=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|\psi_{w_{0}}\left(x^{\prime}\right)-\delta_{*}<x_{n}<\psi_{w_{0}}\left(x^{\prime}\right)+\delta_{*},\left|x^{\prime}\right|<r_{*}\right\}\right.
$$

satisfies

$$
\Omega \cap U_{r_{*}, \delta_{*}, \psi_{w_{0}}}\left(w_{0}\right)=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|\psi_{w_{0}}\left(x^{\prime}\right)<x_{n}<\psi_{w_{0}}\left(x^{\prime}\right)+\delta_{*},\left|x^{\prime}\right|<r_{*}\right\}\right.
$$

and

$$
\partial \Omega \cap U_{r_{*}, \delta_{*}, \psi_{w_{0}}}\left(w_{0}\right)=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|x_{n}=\psi_{w_{0}}\left(x^{\prime}\right),\left|x^{\prime}\right|<r_{*}\right\}\right.
$$

For simplicity of explanation, we say that $\Omega$ is of type $\left(r_{*}, \delta_{*}, L_{\Gamma}\right)$. For $x \in \Omega$, let $\pi x$ be a point on $\Gamma$ such that $|x-\pi x|=d_{\Gamma}(x)$. If $x$ is within the reach of $\Gamma$, then this $\pi x$ is unique. There exists $0<\rho_{0}<\min \left\{r_{*}, \delta_{*}, R_{0}, 1\right\}$ such that for any $w_{0} \in \Gamma$,

$$
\begin{equation*}
U_{\rho_{0}}\left(w_{0}\right):=\left\{x \in U_{r_{*}, \delta_{*}, \psi_{w_{0}}}\left(w_{0}\right)\left|(\pi x)^{\prime} \in B_{\rho_{0}}\left(0^{\prime}\right),|d(x)|<\rho_{0}\right\}\right. \tag{5.2.2}
\end{equation*}
$$

is contained in $U_{r_{*}, \delta_{*}, \psi_{w_{0}}}\left(w_{0}\right)$.
We next consider the normal coordinate in $U_{\rho_{0}}\left(w_{0}\right)$, i.e.,

$$
x=F(\eta)=\left\{\begin{array}{l}
\eta^{\prime}+\eta_{n} \nabla^{\prime} d\left(\eta^{\prime}, \psi_{w_{0}}\left(\eta^{\prime}\right)\right)  \tag{5.2.3}\\
\psi_{w_{0}}\left(\eta^{\prime}\right)+\eta_{n} \partial_{x_{n}} d\left(\eta^{\prime}, \psi_{w_{0}}\left(\eta^{\prime}\right)\right)
\end{array}\right.
$$

or shortly

$$
x=\pi x-d(x) \mathbf{n}(\pi x)
$$

For each $w_{0} \in \Gamma, F$ is indeed a local $C^{1}$-diffeomorphism which maps $V_{\rho_{0}}$ to $U_{\rho_{0}}\left(w_{0}\right)$ where $V_{\rho_{0}}:=B_{\rho_{0}}\left(0^{\prime}\right) \times\left(-\rho_{0}, \rho_{0}\right)$. We indeed have that $F \in C^{1}\left(V_{\rho_{0}}\right)$ and $\left(\nabla_{\eta} F\right)(0)=I$. Our first uniform control is for the gradient of $F$ with respect to different $w_{0} \in \Gamma$.

Proposition 5.2.1. Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2, \varepsilon \in(0,1)$. Then there exists a constant $c_{\Omega}^{\varepsilon}>0$, depending on $\Omega$, $n$ and $\varepsilon$ only, such that for any $\rho \in\left(0, c_{\Omega}^{\varepsilon}\right]$ and $w_{0} \in \Gamma$,

$$
\begin{aligned}
\|\nabla F-I\|_{L^{\infty}\left(V_{\rho}\right)} & <\varepsilon \\
\left\|\nabla F^{-1}-I\right\|_{L^{\infty}\left(U_{\rho}\left(w_{0}\right)\right)} & <\varepsilon
\end{aligned}
$$

hold simultaneously.

Proof. Let $0<\varepsilon<1$ and fix $w_{0} \in \Gamma, \rho<\rho_{0}$. By the mean value theorem together with the upper bound of second order derivatives of $\psi_{w_{0}}$ in (5.2.1), we deduce that

$$
\begin{equation*}
\left|\nabla^{\prime} \psi_{w_{0}}\left(\eta^{\prime}\right)\right|=\left|\nabla^{\prime} \psi_{w_{0}}\left(\eta^{\prime}\right)-\nabla^{\prime} \psi_{w_{0}}\left(0^{\prime}\right)\right| \leq\left\|\nabla^{2} \psi_{w_{0}}\right\|_{L^{\infty}\left(B_{\rho}\left(0^{\prime}\right)\right)} \cdot\left|\eta^{\prime}\right| \leq L_{\Gamma} \cdot \rho \tag{5.2.4}
\end{equation*}
$$

for any $\left|\eta^{\prime}\right|<\rho$. Since

$$
\begin{aligned}
\partial_{\eta_{j}} x_{i} & =\delta_{i, j}+\eta_{n} \cdot \partial_{\eta_{j}}\left(\partial_{x_{i}} d\right) \\
& =\delta_{i, j}-\eta_{n} \cdot \frac{\partial_{\eta_{j}} \partial_{\eta_{i}} \psi_{w_{0}}}{\left(1+\left|\nabla^{\prime} \psi_{w_{0}}\right|^{2}\right)^{\frac{1}{2}}}+\eta_{n} \cdot \frac{\sum_{k=1}^{n-1} \partial_{\eta_{i}} \psi_{w_{0}} \cdot \partial_{\eta_{k}} \psi_{w_{0}} \cdot \partial_{\eta_{j}} \partial_{\eta_{k}} \psi_{w_{0}}}{\left(1+\left|\nabla^{\prime} \psi_{w_{0}}\right|^{2}\right)^{\frac{3}{2}}}
\end{aligned}
$$

in $V_{\rho}$ for $1 \leq i, j \leq n-1$, by estimates (5.2.1) and (5.2.4) we have that

$$
\left|\partial_{\eta_{j}} x_{i}(\eta)-\delta_{i, j}\right| \leq L_{\Gamma} \rho+(n-1) \cdot\left(L_{\Gamma} \rho\right)^{3}
$$

for any $\eta \in V_{\rho}$. By similar calculations, for $\eta \in V_{\rho}$ we can also deduce that

$$
\left|\partial_{\eta_{n}} x_{i}(\eta)\right| \leq L_{\Gamma} \rho
$$

for each $1 \leq i \leq n-1$ and

$$
\begin{aligned}
\left|\partial_{\eta_{j}} x_{n}(\eta)\right| & \leq L_{\Gamma} \rho+(n-1) \cdot\left(L_{\Gamma} \rho\right)^{2} \quad \text { for } \quad 1 \leq j \leq n-1, \\
\left|\partial_{\eta_{n}} x_{n}(\eta)-1\right| & \leq(n-1) \cdot\left(L_{\Gamma} \rho\right)^{2} .
\end{aligned}
$$

Notice that for an invertible matrix $A$, we have that $A^{-1}=\frac{1}{\operatorname{det}(A)} \cdot \operatorname{adj}(A)$ where $\operatorname{adj}(A)$ denotes the adjugate of matrix $A$. Since we have obtained estimates for each entry of $\nabla F$, by considering the inverse of $\nabla F$ we can deduce similar estimates for entries of $\nabla F^{-1}$. Denote $c_{L_{\Gamma} \rho}:=L_{\Gamma} \rho+(n-1) \cdot\left(L_{\Gamma} \rho\right)^{2}$. Assume that $L_{\Gamma} \rho \ll 1$, then for any $\eta \in V_{\rho}$,
$\left(1-c_{L_{\Gamma} \rho}\right)^{n}-n!\cdot c_{L_{\Gamma} \rho}^{2} \cdot\left(1+c_{L \rho}\right)^{n-2} \leq|\operatorname{det}(\nabla F)(\eta)| \leq\left(1+c_{L_{\Gamma} \rho}\right)^{n}+n!\cdot c_{L_{\Gamma} \rho}^{2} \cdot\left(1+c_{L_{\Gamma} \rho}\right)^{n-2}$.
By considering the adjugate of $\nabla F$, in $V_{\rho}$ we also have that
$\left(1-c_{L_{\Gamma} \rho}\right)^{n-1}-(n-1)!\cdot c_{L_{\Gamma} \rho}^{2} \cdot\left(1+c_{L_{\Gamma} \rho}\right)^{n-3} \leq\left|\partial_{x_{i}} \eta_{i}(\eta)\right| \leq\left(1+c_{L_{\Gamma} \rho}\right)^{n-1}+(n-1)!\cdot c_{L_{\Gamma} \rho}^{2} \cdot\left(1+c_{L_{\Gamma} \rho}\right)^{n-3}$
for every $1 \leq i \leq n$ and

$$
\left|\partial_{x_{j}} \eta_{i}(\eta)\right| \leq(n-1)!\cdot c_{L_{\Gamma} \rho} \cdot\left(1+c_{L_{\Gamma} \rho}\right)^{n-2}
$$

for every $1 \leq i, j \leq n$ with $i \neq j$. Therefore, if $\rho$ is chosen to be sufficiently small, then for each $w_{0} \in \Gamma$ we can have

$$
\begin{aligned}
\|\nabla F-I\|_{L^{\infty}\left(V_{\rho}\right)} & <\varepsilon \\
\left\|\nabla F^{-1}-I\right\|_{L^{\infty}\left(U_{\rho}\left(w_{0}\right)\right)} & <\varepsilon
\end{aligned}
$$

simultaneously.
Next we determine how small for $\rho$ is enough. It is easy to see that if $\rho<\min \left\{\frac{\varepsilon}{2 L_{\Gamma}}, \frac{1}{(n-1) L_{\Gamma}}\right\}$, we have that $\|\nabla F-I\|_{L^{\infty}\left(V_{\rho}\right)}<\varepsilon$. Suppose further that $c_{L_{\Gamma} \rho}<2 L_{\Gamma} \rho \ll 1$, then in $V_{\rho}$ we have that

$$
1-c_{L_{\Gamma} \rho} \cdot(n+1)!\cdot 2^{n}<|\operatorname{det}(\nabla F)(\eta)|<1+c_{L_{\Gamma} \rho} \cdot(n+1)!\cdot 2^{n}
$$

Hence if $2 L_{\Gamma} \rho<\frac{1}{(n+1)!\cdot 2^{n+1}}$, then

$$
1-c_{L_{\Gamma} \rho} \cdot(n+1)!\cdot 2^{n+1}<\frac{1}{|\operatorname{det}(\nabla F)(\eta)|}<1+c_{L_{\Gamma} \rho} \cdot(n+1)!\cdot 2^{n+1}
$$

in $V_{\rho}$. Since

$$
1-c_{L_{\Gamma} \rho} \cdot n!\cdot 2^{n}<\left|\partial_{x_{i}} \eta_{i}(\eta)\right| \leq 1+c_{L_{\Gamma} \rho} \cdot n!\cdot 2^{n},
$$

we deduce that

$$
\left|\frac{1}{|\operatorname{det}(\nabla F)(\eta)|} \cdot \partial_{x_{i}} \eta_{i}(\eta)-1\right|<c_{L_{\Gamma} \rho} \cdot((n+1)!)^{2} \cdot 2^{2 n+3}
$$

for every $1 \leq i \leq n$ in $V_{\rho}$. Similar calculations enable us to also obtain that

$$
\left|\frac{1}{|\operatorname{det}(\nabla F)(\eta)|} \cdot \partial_{x_{j}} \eta_{i}(\eta)\right|<c_{L_{\Gamma} \rho} \cdot n!\cdot 2^{n+1}
$$

for every $1 \leq i, j \leq n$ with $i \neq j$ in $V_{\rho}$.
Therefore, if $\rho \leq c_{\Omega}^{\varepsilon}:=\min \left\{\frac{\varepsilon}{\left.L_{\Gamma} \cdot(n+1)!\right)^{2} \cdot 2^{2 n+5}}, \frac{\rho_{0}}{2}\right\}$, we indeed have

$$
\begin{aligned}
\|\nabla F-I\|_{L^{\infty}\left(V_{\rho}\right)} & <\varepsilon, \\
\left\|\nabla F^{-1}-I\right\|_{L^{\infty}\left(U_{\rho}\left(w_{0}\right)\right)} & <\varepsilon
\end{aligned}
$$

simultaneously.
We would like to give a uniform estimate, regardless of $w_{0} \in \Gamma$, on the size of the ball centered at $w_{0}$ that is contained in $U_{\rho}\left(w_{0}\right)$.

Proposition 5.2.2. Let $\varepsilon \in(0,1)$. If $\rho<\min \left\{\frac{\varepsilon}{8 L_{\Gamma}}, \rho_{0}\right\}$, then

$$
B_{\rho\left(1-\frac{\varepsilon}{2}\right)}\left(w_{0}\right) \subset U_{\rho}\left(w_{0}\right)
$$

for any $w_{0} \in \Gamma$.
Proof. For a ball $B_{r}\left(w_{0}\right)$ to be contained in $U_{\rho}\left(w_{0}\right)$, we must have $r \leq \rho$. If $B_{r}\left(w_{0}\right)$ intersects $U_{\rho}\left(w_{0}\right)^{\mathrm{c}}$ with some $r \leq \rho$, we can find $x \in B_{r}\left(w_{0}\right)$ of the form $\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right)+\tau \nabla d\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right)$ with $\left|\eta^{\prime}\right|=\rho$ and $|\tau| \in[0, \rho)$. Notice that

$$
\left|x-w_{0}\right|^{2}=\left|\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right)\right|^{2}+\tau^{2}+2 \tau\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right) \cdot \nabla d\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right) .
$$

By the mean value theorem, we can estimate $\left|\partial_{\eta_{i}} h_{w_{0}}\left(\eta^{\prime}\right)\right|$ by $\rho L_{\Gamma}$ and $\left|h_{w_{0}}\left(\eta^{\prime}\right)\right|$ by $\rho^{2} L_{\Gamma}$ for any $\left|\eta^{\prime}\right| \leq \rho$ and $1 \leq i \leq n-1$. Thus, we deduce that

$$
\left|\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right)\right|^{2}+\tau^{2}+2 \tau\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right) \cdot \nabla d\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right) \geq \rho^{2}+\tau^{2}-4 \tau \rho^{2} L_{\Gamma}
$$

for any $\left|\eta^{\prime}\right|<\rho$. Since $\rho L_{\Gamma}<\frac{\varepsilon}{8}$, we have that

$$
\left|x-w_{0}\right| \geq \rho \sqrt{1-\frac{\varepsilon}{2}}>\rho\left(1-\frac{\varepsilon}{2}\right)
$$

for any $x$ of the form $\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right)+\tau \nabla d\left(\eta^{\prime}, h_{w_{0}}\left(\eta^{\prime}\right)\right)$ with $\left|\eta^{\prime}\right|=\rho$ and $|\tau| \in[0, \rho)$. Hence for any $w_{0} \in \Gamma$, we have that $B_{\rho\left(1-\frac{\varepsilon}{2}\right)}\left(w_{0}\right) \subset U_{\rho}\left(w_{0}\right)$.

Next, we establish a partition of unity for a small neighborhood of the boundary $\Gamma$ in which not only partition functions but also their gradients are uniformly controlled.

Proposition 5.2.3. Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2, \rho \in\left(0, \frac{\rho_{0}}{2}\right)$. There exist a countable family of points in $\Gamma$, say $S:=\left\{x_{i} \in \Gamma \mid i \in \mathbf{N}\right\}$, and a natural number $N_{*} \in \mathbf{N}$ such that

$$
\Gamma^{2 \rho}=\bigcup_{x_{i} \in S} U_{2 \rho}\left(x_{i}\right)
$$

and for any $x_{j} \in S$, there exist at most $N_{*}$ points in $S$, say $\left\{x_{j_{1}}, \ldots, x_{j_{N_{*}}}\right\} \subset S$, with

$$
U_{2 \rho}\left(x_{j}\right) \cap U_{2 \rho}\left(x_{j_{l}}\right) \neq \emptyset
$$

for each $1 \leq l \leq N_{*}$.
Proof. Let $k_{*} \in \mathbf{N}$ be the smallest integer such that $2^{-k_{*}} \leq \frac{\rho}{\sqrt{n}}$. Let $\mathscr{D}$ be the collection of all dyadic cubes of the form

$$
\left\{\left(y_{1}, \ldots, y_{n}\right) \in \mathbf{R}^{n} \mid m_{j} 2^{-k_{*}} \leq y_{j}<\left(m_{j}+1\right) 2^{-k_{*}}\right\}
$$

where $m_{j} \in \mathbf{Z}$. Since $\mathscr{D}$ covers the whole space $\mathbf{R}^{n}$, we can pick out the set of dyadic cubes in $\mathscr{D}$ that intersect the boundary $\Gamma$. Let this subset be denoted by $G=\left\{Q_{i} \in \mathscr{D} \mid i \in \mathbf{N}\right\}$ and we have that

$$
\Gamma \subset \bigcup_{i \in \mathbb{N}} Q_{i} .
$$

We choose $x_{i} \in Q_{i} \cap \Gamma$ for each $i \in \mathbf{N}$ and set $S$ to be the set of these points.
This is indeed the set of points we are seeking. For $y \in \Gamma^{2 \rho}$, there exists $y_{0} \in \Gamma$ such that $d(y)=\left|y-y_{0}\right|$. As $G$ covers the boundary $\Gamma$, we have that $y_{0} \in Q_{j}$ for some $j \in \mathbf{N}$. Hence $y \in U_{2 \rho}\left(x_{j}\right)$. We have that

$$
\Gamma^{2 \rho}=\bigcup_{x_{i} \in S} U_{2 \rho}\left(x_{i}\right) .
$$

By the mean value theorem, we can deduce that

$$
\sup _{y \in U_{2 \rho}(x)}|y-x|<5 \rho
$$

for every $x \in \Gamma$. We fix $x_{i} \in S$. For $Q_{j} \in G$ with $d\left(Q_{j}, Q_{i}\right)>10 \rho$, by the triangle inequality we obviously have that

$$
U_{2 \rho}\left(x_{j}\right) \cap U_{2 \rho}\left(x_{i}\right)=\emptyset .
$$

This means that if $U_{2 \rho}\left(x_{j}\right)$ intersects $U_{2 \rho}\left(x_{i}\right)$, we must have that $d\left(Q_{j}, Q_{i}\right) \leq 10 \rho$. If $d\left(Q_{j}, Q_{i}\right) \leq 10 \rho$, then

$$
\sup _{y \in Q_{j}, x \in Q_{i}}|y-x|<12 \rho .
$$

Denote $x_{i_{c}}$ to be the center of the cube $Q_{i}$. If $U_{2 \rho}\left(x_{j}\right)$ intersects $U_{2 \rho}\left(x_{i}\right)$, we have that $Q_{j} \subset Q_{i}^{*}$ where $Q_{i}^{*}$ is the cube of side-length $24 \rho$ with center $x_{i_{c}}$. Since elements of $S$ belong to cubes that do not intersect, we can choose $N_{*}$ to be $24^{n} \cdot n^{\frac{n}{2}}$.

Based on $\left\{U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right) \mid x_{i} \in S\right\}$, a locally finite open cover of $\Gamma^{\varepsilon_{\Omega}^{\varepsilon}}$, our desired partition of unity for $\Gamma^{c_{\Omega}^{\varepsilon}}$ can be constructed as follow.

Proposition 5.2.4. There exist $\varphi_{i} \in C^{1}\left(\Gamma^{c_{\Omega}^{\varepsilon}}\right)$ for each $i \in \mathbf{N}$ and a constant $C_{U}$ such that properties

$$
\begin{align*}
& 0 \leq \varphi_{i} \leq 1 \text { for any } i \in \mathbf{N} \\
& \operatorname{supp} \varphi_{i} \subset \overline{U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right)} \text { for any } i \in \mathbf{N}, \\
& \sum_{i=1}^{\infty} \varphi_{i}(x) \equiv 1 \text { for any } x \in \Gamma^{c_{\Omega}^{\varepsilon}}  \tag{5.2.5}\\
& \sup _{i \in \mathbf{N}}\left\|\nabla \varphi_{i}\right\|_{L^{\infty}\left(\Gamma^{c_{\Omega}^{\varepsilon}}\right)} \leq C_{U}
\end{align*}
$$

hold.
Similar proposition appears in [5]. For the completeness of the theory, we shall provide a proof here.

Proof of Proposition 6.2.3. Let us recall an empirical cutoff function that is widely used in various contents, e.g. see [12, Lemma 2.20 and Lemma 2.21]. We consider

$$
f(t)= \begin{cases}\exp \left(-\frac{1}{t}\right) & t>0 \\ 0 & t \leq 0\end{cases}
$$

and

$$
\theta(t):=\frac{f(2-t)}{f(t-1)+f(2-t)}
$$

for $t \in \mathbf{R}$. A simple calculation tells us that $\theta \in C_{\mathrm{c}}^{\infty}(\mathbf{R})$ with $\theta(t)=1$ for $|t| \leq 1$ and $\theta(t)=0$ for $|t| \geq 2$. For $i \in \mathbf{N}$, we define that

$$
\phi_{i}(x):=\theta\left(2\left|\left(F^{-1}(x)\right)^{\prime}\right| / c_{\Omega}^{\varepsilon}\right)
$$

for $x \in U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right)$ where $F$ in this case is the normal coordinate change between $V_{c_{\Omega}^{\varepsilon}}$ and $U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right)$. By Proposition 6.2.2, there exists $S_{i}:=\left\{x_{i_{1}}, x_{i_{2}}, \ldots, x_{i_{m}}\right\} \subset S$ with $m \leq N_{*}$ and $U_{c_{\Omega}^{\varepsilon}}\left(x_{i l}\right) \cap U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right) \neq \emptyset$ for any $1 \leq l \leq m$. Without loss of generality, we assume that $i_{l} \neq i$ for each $1 \leq l \leq m$. Then we define $\varphi_{i}$ in $\Gamma^{c_{\Omega}^{\varepsilon}}$ by

$$
\varphi_{i}(x):= \begin{cases}\frac{\phi_{i}(x)}{\phi_{i}(x)+\sum_{l=1}^{l n} \phi_{i_{l}}(x)} & x \in U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right), \\ 0 & x \in \Gamma_{\Omega}^{c_{\Omega}^{\varepsilon}} \backslash U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right) .\end{cases}
$$

It is trivial to see that $0 \leq \varphi_{i} \leq 1$ for any $i \in \mathbf{N}$ and

$$
\sum_{i=1}^{\infty} \varphi_{i}(x) \equiv 1 \quad \text { in } \quad \Gamma^{c_{\Omega}^{\varepsilon}} .
$$

It is sufficient to estimate the gradient of $\varphi_{i}$. Note that

$$
\partial_{j} \varphi_{i}=\frac{\partial_{j} \phi_{i}}{\phi_{i}+\sum_{l=1}^{m} \phi_{i_{l}}}-\frac{\phi \cdot\left(\partial_{j} \phi_{i}+\sum_{l=1}^{m} \partial_{j} \phi_{i_{l}}\right)}{\left(\phi+\sum_{l=1}^{m} \phi_{i_{l}}\right)^{2}} .
$$

Let $x \in U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right)$ and $\pi x$ be the projection of $x$ in $\Gamma$. By the construction of the set $S$ in the proof of Proposition 6.2.2, there exists $x_{i_{k}} \in S_{i}$ such that $\left|\pi x-x_{i_{k}}\right|<\frac{\varepsilon_{\Omega}^{\varepsilon}}{2}$. This means that $\left|\left(F^{-1}(x)\right)^{\prime}\right|<\frac{\varepsilon_{\Omega}^{\varepsilon}}{2}$, i.e., we have that $\phi_{i_{k}}(x)=1$. Hence, we deduce that

$$
\phi_{i}+\sum_{l=1}^{m} \phi_{i_{l}} \geq 1 \quad \text { in } \quad U_{c_{\Omega}^{\varepsilon}}\left(x_{i}\right) .
$$

As a result, we have the estimate

$$
\left|\partial_{j} \varphi_{i}\right| \leq 2 \cdot\left|\partial_{j} \phi_{i}\right|+\sum_{l=1}^{m}\left|\partial_{j} \phi_{i_{l}}\right| .
$$

For any $k \in \mathbf{N}$, we have that

$$
\left\|\nabla \phi_{k}\right\|_{L^{\infty}\left(U_{c_{\Omega}^{\varepsilon}}\left(x_{k}\right)\right)} \leq \frac{C_{n}}{\rho} \cdot\left\|\theta^{\prime}\right\|_{L^{\infty}(\mathbf{R})} \cdot\left\|\nabla F^{-1}\right\|_{L^{\infty}\left(U_{c_{\Omega}^{\varepsilon}}\left(x_{k}\right)\right)} .
$$

By Proposition 6.2.1, we have a uniform estimate for $\left\|\nabla F^{-1}\right\|_{L^{\infty}\left(U_{c_{\Omega}^{\varepsilon}}\left(x_{k}\right)\right)}$. Therefore, combining all estimates together, we finally obtain that

$$
\sup _{i \in \mathbf{N}}\left\|\nabla \varphi_{i}\right\|_{L^{\infty}\left(\Gamma^{c_{\Omega}^{\varepsilon}}\right)} \leq \frac{C_{n, N_{*}}}{\rho}\left\|\theta^{\prime}\right\|_{L^{\infty}(\mathbf{R})} .
$$

### 5.3 Cut-off

We consider $v \in b m o_{\infty}^{\infty}(\Omega)$. Let $0<\rho<c_{\Omega}^{\varepsilon} / 32$ be sufficiently small for which the smallness of $\rho$ will be determined later. For $x \in \Gamma_{\rho_{0}}^{\mathbf{R}^{n}}$, we set $\theta_{\rho}(x):=\theta(d(x) / \rho)$ where $\theta$ is defined in the proof of Proposition 6.2.3. Note that $\theta_{\rho} \in C^{2}\left(\mathbf{R}^{n}\right)$. We then consider $v_{1}:=\theta_{\rho} v$.

Lemma 5.3.1. $v_{1} \in b m o_{\infty}^{\rho}(\Omega)$ satisfies the estimate

$$
\left\|v_{1}\right\|_{b m o_{\infty}^{\rho}(\Omega)} \leq \frac{C}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

with $C$ independent of $v$ and $\rho$.
Since the domain $\Omega$ is not assumed to be a Jones domain, this lemma cannot be derived by applying the product estimate to bmo functions directly. To establish Lemma 5.3.1, we consider a localization argument in which we apply the product estimate to $b m o$ functions locally. For $w_{0} \in \Gamma$, we invoke the normal coordinate change $x=F(\eta)$ in $U_{32 \rho}\left(w_{0}\right)$. There exists a bounded $C^{2}$ domain $W$ such that $V_{16} \cap \mathbf{R}_{+}^{n} \subset W \subset V_{32} \cap \mathbf{R}_{+}^{n}$ and $\partial W \cap \mathbf{R}^{n-1} \times\{0\}=$ $B_{16}\left(0^{\prime}\right) \times\{0\}$. Without loss of generality, we assume that $W$ is of type ( $\alpha, \beta, L_{\partial W}$ ) with some constant $L_{\partial W}$. Let $W_{\rho}:=\{\rho x \mid x \in W\}$. A simple check tells us that $W_{\rho}$ is of type $\left(\alpha \rho, \beta \rho, L_{\partial W} / \rho\right)$.

Proposition 5.3.2. $F\left(W_{\rho}\right)$ is a bounded Lipschitz domain with Lipschitz constant depending on $L_{\partial W}$ only. Moreover, we have that $U_{16 \rho}\left(w_{0}\right) \cap \Omega \subset F\left(W_{\rho}\right) \subset U_{32 \rho}\left(w_{0}\right) \cap \Omega$ and $\partial F\left(W_{\rho}\right) \cap \Gamma=U_{16 \rho}\left(w_{0}\right) \cap \Gamma$.

Proof. Since the normal coordinate change $F$ is a $C^{1}$-diffeomorphism, we see that $F\left(W_{\rho}\right)$ is a bounded domain which satisfies $F\left(\partial W_{\rho}\right)=\partial F\left(W_{\rho}\right)$. Let $\tau_{0} \in \partial W_{\rho}$ and $\delta<\min \{\alpha \rho, \beta \rho, \rho\}$. Without loss of generality we may assume that $\delta=c_{0} \rho$ for some sufficiently small universal constant $c_{0}$. Since $\partial W_{\rho}$ is uniformly $C^{2}$, there exist a rotation $R_{\tau_{0}}$ and $h_{\tau_{0}} \in C^{2}\left(B_{\delta}\left(0^{\prime}\right)\right)$ such that $\widetilde{\eta_{0}}:=R_{\tau_{0}}\left(\eta_{0}-\tau_{0}\right)$ satisfies

$$
\left(\widetilde{\eta_{0}}\right)_{n}=h_{\tau_{0}}\left({\widetilde{\eta_{0}}}^{\prime}\right)
$$

for any $\eta_{0} \in \partial W_{\rho}$ with $\left|\widetilde{\eta}_{0}\right|<\delta$. Let $y_{0}:=F\left(\tau_{0}\right)$ and $e_{\tau_{0}}$ to be the unit normal through $\tau_{0}$ with respect to boundary $\partial W_{\rho}$. We set $\tau_{n}:=\tau_{0}+\delta e_{\tau_{0}}$ and $y_{n}:=F\left(\tau_{n}\right)$. There exists another rotation matrix $R_{y_{0}}$ such that $R_{y_{0}}\left(y_{n}-y_{0}\right)=\delta e_{n}$ where $e_{n}=\left(0^{\prime}, 1\right)$. Let $\zeta_{0} \in \partial W_{\rho}$ such that $\left|\widetilde{\zeta}_{0}\right|<\delta$ where $\widetilde{\zeta}_{0}:=R_{\tau_{0}}\left(\zeta_{0}-\tau_{0}\right)$. We set $x_{0}:=F\left(\zeta_{0}\right)$ and $z_{0}:=F\left(\eta_{0}\right)$. In the coordinate system centered at $y_{0}$ with $y_{n}$ lying on the $n$-axis in the positive direction, the coordinate of $x_{0}$ becomes $\widetilde{x_{0}}:=R_{y_{0}}\left(x_{0}-y_{0}\right)$ whereas the coordinate of $z_{0}$ becomes $\widetilde{z_{0}}:=R_{y_{0}}\left(z_{0}-y_{0}\right)$. By applying the mean value theorem, we have that

$$
\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}=R_{y_{0}, n} \cdot \int_{0}^{1}(\nabla F)\left(\eta_{0}+t\left(\zeta_{0}-\eta_{0}\right)\right) d t \cdot R_{\tau_{0}}^{-1} \cdot\left(\widetilde{\zeta_{0}}-\widetilde{\eta_{0}}\right)
$$

with $R_{y_{0}, n}$ denoting the $n$-th row of rotation matrix $R_{y_{0}}$. Since $\left(\widetilde{\zeta_{0}}\right)_{n}-\left(\widetilde{\eta_{0}}\right)_{n}=h_{\tau_{0}}\left(\widetilde{\zeta}_{0}^{\prime}\right)-$ $h_{\tau_{0}}\left({\widetilde{\eta_{0}}}^{\prime}\right)$, we deduce that

$$
\begin{equation*}
\left|\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right| \leq\|\nabla F\|_{L^{\infty}\left(V_{16 \rho}\right)} \cdot\left(1+\left\|h_{\tau_{0}}\right\|_{L^{\infty}\left(B_{\delta}\left(0^{\prime}\right)\right)}\right) \cdot\left|\widetilde{\zeta}_{0}^{\prime}-\widetilde{\eta}_{0}^{\prime}\right| \tag{5.3.1}
\end{equation*}
$$

Applying the mean value theorem again to rewrite $\widetilde{\zeta_{0}}-\widetilde{\eta_{0}}$ back to $\widetilde{x_{0}}-\widetilde{z_{0}}$, for $1 \leq i \leq n-1$ we have that

$$
\begin{equation*}
\left(\widetilde{\zeta_{0}}\right)_{i}-\left(\widetilde{\eta_{0}}\right)_{i}=R_{\tau_{0}, i} \cdot \int_{0}^{1}\left(\nabla F^{-1}\right)\left(z_{0}+t\left(x_{0}-z_{0}\right)\right) d t \cdot R_{y_{0}}^{-1} \cdot\left(\widetilde{x_{0}}-\widetilde{z_{0}}\right) \tag{5.3.2}
\end{equation*}
$$

with $R_{\tau_{0}, i}$ denoting the $i$-th row of rotation matrix $R_{\tau_{0}}$.
Fix $1 \leq i \leq n-1$. By deducting the identity matrix $I$ from $\nabla F^{-1}$ in (5.3.2) and then adding $I$ back, we have that

$$
\left|\left(\widetilde{\zeta_{0}}\right)_{i}-\left(\widetilde{\eta_{0}}\right)_{i}\right| \leq\left\|\nabla F^{-1}-I\right\|_{L^{\infty}\left(U_{32 \rho}\left(w_{0}\right)\right)} \cdot\left|\widetilde{x_{0}}-\widetilde{z_{0}}\right|+\left|R_{\tau_{0}, i} \cdot R_{y_{0}}^{-1} \cdot\left(\widetilde{x_{0}}-\widetilde{z_{0}}\right)\right|
$$

In the coordinate system centered at $\tau_{0}$, there exists $\eta_{i} \in V_{32 \rho}$ such that $R_{\tau_{0}}\left(\eta_{i}-\tau_{0}\right)=\delta e_{i}$ where $e_{i}$ denotes the vector whose $j$-th entry equals $\delta_{i, j}$ for each $1 \leq j \leq n$. Hence, $R_{\tau_{0}, i}=$ $\frac{1}{\delta}\left(\eta_{i}-\tau_{0}\right)$. Similarly, in the coordinate system centered at $y_{0}$, we can find $y_{i} \in U_{32 \rho}\left(w_{0}\right)$ such that $R_{y_{0}, i}=\frac{1}{\delta}\left(y_{i}-y_{0}\right)$ where $R_{y_{0} \cdot j}$ denotes the $j$-th row of $R_{y_{0}}$ for any $1 \leq j \leq n$. Since $R_{y_{0}}^{-1}=R_{y_{0}}^{\mathrm{T}}$, we see that

$$
R_{\tau_{0}, i} \cdot R_{y_{0}}^{-1} \cdot\left(\widetilde{x_{0}}-\widetilde{z_{0}}\right)=\left(R_{\tau_{0}, i}-R_{y_{0}, i}\right) \cdot R_{y_{0}}^{\mathrm{T}} \cdot\left(\widetilde{x_{0}}-\widetilde{z_{0}}\right)+\left(\widetilde{x_{0}}\right)_{i}-\left(\widetilde{z_{0}}\right)_{i}
$$

Focus on the term that involves $\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}$, characterizations of rows of $R_{\tau_{0}}$ and $R_{y_{0}}$ say that

$$
\left(\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right)\left(\left(R_{\tau_{0}, i}-R_{y_{0}, i}\right) \cdot R_{y_{0}, n}\right)=\frac{\left(\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right)}{\delta^{2}}\left(\left(\eta_{i}-y_{i}\right)-\left(\tau_{0}-y_{0}\right)\right) \cdot\left(y_{n}-y_{0}\right)
$$

For $\zeta \in V_{32 \rho}$,

$$
F(\zeta)-\zeta=\left(0^{\prime}, \psi_{w_{0}}\left(\zeta^{\prime}\right)-\zeta_{n}\right)+\zeta_{n} \cdot(\nabla d)\left(\zeta^{\prime}, \psi_{w_{0}}\left(\zeta^{\prime}\right)\right)
$$

An easy check gives that

$$
\left|\zeta_{n} \cdot\left(\partial_{x_{j}} d\right)\left(\zeta^{\prime}, \psi_{w_{0}}\left(\zeta^{\prime}\right)\right)\right| \leq\left|\zeta_{n} \cdot\left(\partial_{\zeta_{j}} \psi_{w_{0}}\right)\left(\zeta^{\prime}\right)\right| \leq C_{L_{\Gamma}} \rho^{2}
$$

for $1 \leq j \leq n-1$ and

$$
\left|\psi_{w_{0}}\left(\zeta^{\prime}\right)\right|+\left|\zeta_{n}\right| \cdot\left|\left(\left(\partial_{x_{n}} d\right)\left(\zeta^{\prime}, \psi_{w_{0}}\left(\zeta^{\prime}\right)\right)-1\right)\right| \leq C_{L_{\Gamma}, n} \rho^{2}
$$

Hence, for any $\zeta \in V_{32 \rho}$, we have the estimate

$$
|F(\zeta)-\zeta| \leq \frac{C_{L_{\Gamma}, n}}{c_{0}^{2}} \delta^{2}
$$

By the mean value theorem, we see that

$$
\begin{equation*}
\left|\left(y_{0}-\tau_{0}\right) \cdot\left(y_{n}-y_{0}\right)\right| \leq\left|F\left(\tau_{0}\right)-\tau_{0}\right| \cdot\left|F\left(\tau_{n}\right)-F\left(\tau_{0}\right)\right| \leq \frac{C_{L_{\Gamma}, n}}{c_{0}^{2}} \cdot\|\nabla F\|_{L^{\infty}\left(V_{32 \rho}\right)} \cdot \delta^{3} . \tag{5.3.3}
\end{equation*}
$$

On the other hand,

$$
\left|\left(\eta_{i}-y_{i}\right) \cdot\left(y_{n}-y_{0}\right)\right| \leq\left|\left(\eta_{i}-\tau_{0}\right) \cdot\left(y_{n}-y_{0}\right)\right|+\left|\left(\tau_{0}-y_{0}\right) \cdot\left(y_{n}-y_{0}\right)\right|+\left|\left(y_{0}-y_{i}\right) \cdot\left(y_{n}-y_{0}\right)\right| .
$$

By decomposing $y_{n}-y_{0}$ into $\left(y_{n}-\tau_{n}\right)+\left(\tau_{n}-\tau_{0}\right)+\left(\tau_{0}-y_{0}\right)$ and applying the estimate (5.3.3), we deduce that

$$
\begin{aligned}
\left|\left(\eta_{i}-y_{i}\right) \cdot\left(y_{n}-y_{0}\right)\right| & \leq\left|\left(\eta_{i}-\tau_{0}\right) \cdot\left(y_{n}-\tau_{n}\right)\right|+\left|\left(\eta_{i}-\tau_{0}\right) \cdot\left(\tau_{0}-y_{0}\right)\right|+\left|\left(\tau_{0}-y_{0}\right) \cdot\left(y_{n}-y_{0}\right)\right| \\
& \leq \frac{C_{L_{\Gamma}, n}}{c_{0}^{2}} \cdot\left(2+\|\nabla F\|_{L^{\infty}\left(V_{32 \rho}\right)}\right) \cdot \delta^{3} .
\end{aligned}
$$

Therefore,

$$
\left|\left(\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right)\left(\left(R_{\tau_{0}, i}-R_{y_{0}, i}\right) \cdot R_{y_{0}, n}\right)\right| \leq \frac{C_{L_{\Gamma}, n}}{c_{0}^{2}} \cdot\left(1+\|\nabla F\|_{L^{\infty}\left(V_{32 \rho}\right)}\right) \cdot \delta \cdot\left|\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right| .
$$

If $\rho<c_{\Omega}^{\varepsilon} / 32$, by Proposition 6.2 .1 we see that

$$
\left|R_{\tau_{0}, i} \cdot R_{y_{0}}^{-1} \cdot\left(\widetilde{x_{0}}-\widetilde{z_{0}}\right)\right| \leq(n+1) \cdot\left|\left(\widetilde{x_{0}}\right)^{\prime}-\left(\widetilde{z_{0}}\right)^{\prime}\right|+\frac{C_{L_{\Gamma}, n}}{c_{0}^{2}} \cdot \delta \cdot\left|\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right| .
$$

Hence,

$$
\left|\left(\widetilde{\zeta_{0}}\right)_{i}-\left(\widetilde{\eta_{0}}\right)_{i}\right| \leq(n+2) \cdot\left|\left(\widetilde{x_{0}}\right)^{\prime}-\left(\widetilde{z_{0}}\right)^{\prime}\right|+\left(\frac{C_{L_{\Gamma}, n}}{c_{0}^{2}} \cdot \delta+\varepsilon\right) \cdot\left|\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right| .
$$

Substitute this estimate back to the inequality (5.3.1), we obtain that

$$
\left|\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right| \leq C_{n, L_{\partial W}}\left|\left(\widetilde{x_{0}}\right)^{\prime}-\left(\widetilde{z_{0}}\right)^{\prime}\right|+2 n\left(1+L_{\partial W}\right) \cdot\left(\frac{C_{L_{\Gamma}, n}}{c_{0}^{2}} \cdot \delta+\varepsilon\right) \cdot\left|\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right|
$$

Therefore, if we take $\varepsilon<\frac{1}{8 n\left(1+L_{\partial W}\right)}$ and $\rho<\min \left\{\frac{c_{0}^{2}}{8 n\left(1+L_{\partial W}\right) \cdot C_{L_{\Gamma}, n}}, \frac{,_{\Omega}^{\varepsilon}}{32}\right\}$, then we have that

$$
\left|\left(\widetilde{x_{0}}\right)_{n}-\left(\widetilde{z_{0}}\right)_{n}\right| \leq 2 C_{n, L_{\partial W}}\left|\left(\widetilde{x_{0}}\right)^{\prime}-\left(\widetilde{z_{0}}\right)^{\prime}\right| .
$$

Based on this proposition, we have the tool to localize the problem and then to apply the product estimate for $b m o$ functions in a bounded domain.

Proof of Lemma 5.3.1. Obviously, the estimate $\left\|v_{1}\right\|_{L^{1}\left(B_{1}(x) \cap \Omega\right)} \leq\|v\|_{L^{1}\left(B_{1}(x) \cap \Omega\right)}$ holds for any $x \in \mathbf{R}^{n}$. It is sufficient to estimate the $B M O^{\rho}$-seminorm for $v_{1}$. Let $r \leq \rho$. For $x \in \Omega$ such that $d(x) \geq 3 \rho, v_{1} \equiv 0$ in $B_{r}(x)$ as $B_{r}(x) \subset \Omega \backslash \overline{\Gamma_{2 \rho}^{\mathbf{R}^{n}}}$, there is nothing to prove in this case. We then consider $x \in \Omega$ with $d(x)<3 \rho$ and $B_{r}(x) \subset \Omega$. Let $\pi x$ be the projection of $x$ on $\Gamma$, i.e., $d(x)=|x-\pi x|$. We have that $B_{r}(x) \subset U_{8 \rho}(\pi x) \cap \Omega$. By Proposition 5.3.2, we see that $B_{r}(x) \subset F\left(W_{\rho}\right) \subset U_{32 \rho}(\pi x) \cap \Omega$ where $F$ in this case is the normal coordinate change between $U_{32 \rho}(\pi x)$ and $V_{32 \rho}$. Since a bounded Lipschitz domain is a uniform (Jones) domain, we can apply the product estimate for bmo functions [8, Theorem 13] in $F\left(W_{\rho}\right)$, i.e., we have that

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|v_{1}(y)-\left(v_{1}\right)_{B_{r}(x)}\right| d y \leq\left\|v_{1}\right\|_{b m o_{\infty}^{\infty}\left(F\left(W_{\rho}\right)\right)} \leq C_{0}\left\|\theta_{\rho}\right\|_{C^{1}\left(F\left(W_{\rho}\right)\right)}\|v\|_{b m o_{\infty}^{\infty}\left(F\left(W_{\rho}\right)\right)}
$$

where $C_{0}$ depends only on the Lipschitz constant of $\partial F\left(W_{\rho}\right)$, which is universal by Proposition 5.3.2. Therefore, we obtain that

$$
\left[v_{1}\right]_{B M O^{\rho}(\Omega)} \leq \frac{C_{0}}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)} .
$$

Next, let us consider further cut-offs induced by the partition of unity for $\Gamma^{2 \rho}$. For $i \in \mathbf{N}$, we set $v_{1, i}:=\varphi_{i} v_{1}$ where $\varphi_{i}$ is the cut-off function defined in Proposition 6.2.3.

Lemma 5.3.3. $v_{1, i} \in b m o_{\infty}^{\rho}(\Omega)$ satisfies the estimate

$$
\left\|v_{1, i}\right\|_{b m o_{\infty}^{\rho}(\Omega)} \leq \frac{C}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

with $C$ independent of $v$ and $\rho$.
Proof. The estimate $\left\|v_{1, i}\right\|_{L^{1}\left(B_{1}(x) \cap \Omega\right)} \leq\|v\|_{L^{1}\left(B_{1}(x) \cap \Omega\right)}$ is trivial for any $x \in \mathbf{R}^{n}$. Let $r \leq \rho$. We only need to consider $x \in \Omega$ such that $d(x)<3 \rho, B_{r}(x) \subset \Omega$ and $B_{r}(x) \cap U_{2 \rho}\left(x_{i}\right) \neq \emptyset$. Proposition 5.2.2 ensures that if $\varepsilon<\frac{2}{3}$ and $\rho<\frac{1}{4 L_{\Gamma}}$, then $B_{r}(x) \subset B_{7 \rho}\left(x_{i}\right) \cap \Omega \subset U_{16 \rho}\left(x_{i}\right) \cap$ $\Omega \subset F\left(W_{\rho}\right)$ where $F$ in this case is the normal coordinate change that maps $V_{32 \rho}$ to $U_{32 \rho}\left(x_{i}\right)$. Again, by applying the product estimate for bmo functions [8, Theorem 13] in $F\left(W_{\rho}\right)$, we have that

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|v_{1, i}(y)-\left(v_{1, i}\right)_{B_{r}(x)}\right| d y \leq\left\|v_{1, i}\right\|_{b m o_{\infty}^{\infty}\left(F\left(W_{\rho}\right)\right)} \leq C_{1}\left\|\varphi_{i}\right\|_{C^{1}\left(F\left(W_{\rho}\right)\right)}\left\|v_{1}\right\|_{b m o_{\infty}^{\infty}\left(F\left(W_{\rho}\right)\right)}
$$

with $C_{1}$ depending only on the Lipschitz constant of $\partial F\left(W_{\rho}\right)$. Note that $b m o_{\infty}^{\infty}\left(F\left(W_{\rho}\right)\right)=$ $b m o_{\infty}^{\rho}\left(F\left(W_{\rho}\right)\right)$. Since $F\left(W_{\rho}\right) \subset U_{32 \rho}\left(x_{i}\right) \cap \Omega \subset \Gamma^{c_{\Omega}^{\varepsilon}}$, by Proposition 6.2.3 and Proposition 5.3.2 we can deduce that

$$
\left[v_{1, i}\right]_{B M O^{\rho}(\Omega)} \leq \frac{C_{1}\left(1+C_{U}\right)\left(1+C_{0}\right)}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)} .
$$

### 5.4 Extension

### 5.4.1 Extension to a neighborhood of $\Gamma$

We are now in a position to extend $v_{1, i}$ with respect to the boundary $\Gamma$ for $i \in \mathbf{N}$. Let us recall the extension introduced in [9]. For a function $h$ defined in $\Gamma^{\rho_{0}} \cap \bar{\Omega}$, let $h^{e}$ denote the even extension of $h$ with respect to $\Gamma$ to $\Gamma^{\rho_{0}}$ defined by

$$
h^{e}(\pi x+d(x) \mathbf{n}(\pi x))=h(\pi x-d(x) \mathbf{n}(\pi x)) \quad \text { for } \quad x \in \Gamma^{\rho_{0}} \backslash \bar{\Omega}
$$

Let $h^{o}$ denote the odd extension of $h$ with respect to $\Gamma$ to $\Gamma^{\rho_{0}}$ defined by

$$
h^{o}(\pi x+d(x) \mathbf{n}(\pi x))=-h(\pi x-d(x) \mathbf{n}(\pi x)) \quad \text { for } \quad x \in \Gamma^{\rho_{0}} \backslash \bar{\Omega}
$$

Lemma 5.4.1. Let $\rho<\frac{c_{\Omega}^{\varepsilon}}{32}$. There exists a constant $C$, independent of $v$ and $\rho$, such that the estimate

$$
\left[v_{1, i}^{e}\right]_{b m o\left(\mathbf{R}^{n}\right)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

holds for any $i \in \mathbf{N}$.
Proof. It is trivial to see that

$$
\int_{U_{2 \rho}\left(x_{i}\right)}\left|v_{1, i}^{e}\right| d y \leq 2\|\nabla F\|_{L^{\infty}\left(V_{2 \rho}\right)} \cdot\left\|\nabla F^{-1}\right\|_{L^{\infty}\left(U_{2 \rho}\left(x_{i}\right)\right)} \cdot \int_{U_{2 \rho}\left(x_{i}\right) \cap \Omega}\left|v_{1, i}\right| d y
$$

Since supp $v_{1, i} \subset U_{2 \rho}\left(x_{i}\right), \rho<\frac{c_{\Omega}^{\varepsilon}}{32}$ implies that

$$
\left\|v_{1, i}^{e}\right\|_{L^{1}\left(\mathbf{R}^{n}\right)} \leq 8\left\|v_{1, i}\right\|_{L^{1}\left(B_{1}\left(x_{i}\right) \cap \Omega\right)} \leq 8\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

Since $F\left(W_{\rho}\right)$ is a bounded Lipschitz domain and $v_{1, i} \in b m o_{\infty}^{\infty}\left(F\left(W_{\rho}\right)\right)$, by the extension theorem for $B M O$ functions [11], there exists $v_{1, i}^{J} \in B M O\left(\mathbf{R}^{n}\right)$ satisfying $r_{F\left(W_{\rho}\right)} v_{1, i}^{J}=v_{1, i}$ and

$$
\left[v_{1, i}^{J}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\left[v_{1, i}\right]_{B M O^{\infty}\left(F\left(W_{\rho}\right)\right)}
$$

where by Proposition 5.3 .2 the constant $C$ depends on $L_{\partial W}$ only. Let $c \in \mathbb{R}^{n}$ be a constant vector. For $B_{r}(\zeta) \subset V_{16 \rho}^{+}$, by change of variable $\eta=F^{-1}(y)$ in $V_{16 \rho}=F^{-1}\left(U_{16 \rho}\left(x_{i}\right)\right)$, we see that

$$
\frac{1}{\left|B_{r}(\zeta)\right|} \int_{B_{r}(\zeta)}\left|v_{1, i} \circ F(\eta)-c\right| d \eta \leq\left\|\nabla F^{-1}\right\|_{L^{\infty}\left(U_{16 \rho}\left(x_{i}\right)\right)} \cdot \frac{1}{\left|B_{r}(\zeta)\right|} \int_{F\left(B_{r}(\zeta)\right)}\left|v_{1, i}(y)-c\right| d y
$$

Let $x=F(\zeta)$. By Proposition 6.2.1, $\rho<\frac{c_{\Omega}^{\varepsilon}}{32}$ implies that $\left\|\nabla F^{-1}\right\|_{L^{\infty}\left(U_{16 \rho}\left(x_{i}\right)\right)}<2$ and $F\left(B_{r}(\zeta)\right) \subset B_{2 r}(x)$. Thus,

$$
\frac{1}{\left|B_{r}(\zeta)\right|} \int_{F\left(B_{r}(\zeta)\right)}\left|v_{1, i}(y)-c\right| d y \leq 2^{n} \cdot \frac{1}{\left|B_{2 r}(x)\right|} \int_{B_{2 r}(x)}\left|v_{1, i}^{J}(y)-c\right| d y
$$

By considering an equivalent definition of the $B M O$-seminorm, see e.g. [10, Proposition 3.1.2], we deduce that

$$
\left[v_{1, i} \circ F\right]_{B M O^{\infty}\left(V_{16 \rho}^{+}\right)} \leq C_{n}\left[v_{1, i}\right]_{B M O^{\infty}\left(F\left(W_{\rho}\right)\right)} \leq \frac{C_{n}}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

By recalling the results concerning the even extension of $B M O$ functions in the half space, see [7, Lemma 3.2] and [7, Lemma 3.4], we can deduce that

$$
\begin{equation*}
\left[v_{i, n}^{e} \circ F\right]_{B M O^{\infty}\left(V_{8 \rho}\right)} \leq \frac{C_{n}}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)} . \tag{5.4.1}
\end{equation*}
$$

Let $B_{r}(x)$ be a ball with radius $r \leq \rho$. If $B_{r}(x) \cap U_{2 \rho}\left(x_{i}\right)=\emptyset$, there is nothing to prove. It is sufficient to consider $B_{r}(x)$ that intersects $U_{2 \rho}\left(x_{i}\right)$. Proposition 5.2.2 ensures that if $\varepsilon<\frac{1}{4}$, then $B_{r}(x) \subset B_{7 \rho}\left(x_{i}\right) \subset U_{8 \rho}\left(x_{i}\right)$. By change of variable $y=F(\eta)$ in $U_{16 \rho}\left(x_{i}\right)$, we have that

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|v_{1, i}^{e}(y)-c\right| d y \leq\|\nabla F\|_{L^{\infty}\left(V_{16 \rho}\right)} \cdot \frac{1}{\left|B_{r}(x)\right|} \int_{F^{-1}\left(B_{r}(x)\right)}\left|v_{1, i}^{e} \circ F(\eta)-c\right| d \eta .
$$

Since $F^{-1}\left(B_{r}(x)\right) \subset B_{2 r}(\zeta) \subset B_{8 \rho}(0) \subset V_{8 \rho}$, by (5.4.1) we deduce that

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|v_{1, i}^{e}(y)-\left(v_{1, i}^{e}\right)_{B_{r}(x)}\right| d y \leq \frac{C_{n}}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)} .
$$

Thus, we obtain that

$$
\left[v_{1, i}^{e}\right]_{B M O^{\rho}\left(\mathbf{R}^{n}\right)} \leq \frac{C_{n}}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)} .
$$

For a ball $B$ with radius $r(B)>\rho$, a simple triangle inequality implies that

$$
\frac{1}{|B|} \int_{B}\left|v_{1, i}^{e}(y)-\left(v_{1, i}^{e}\right)_{B}\right| d y \leq \frac{2}{|B|} \int_{B}\left|v_{1, i}^{e}(y)\right| d y \leq \frac{C_{n}}{\rho^{n}}\left\|v_{1, i}^{e}\right\|_{L^{1}\left(\mathbf{R}^{n}\right)} .
$$

Therefore, we obtain the $B M O$ estimate for $v_{1, i}^{e}$, i.e.,

$$
\left[v_{1, i}^{e}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq \frac{C_{n}}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)} .
$$

Since $\left\{U_{2 \rho}\left(x_{i}\right) \mid x_{i} \in S\right\}$ is a locally finite open cover of $\Gamma^{2 \rho}$, we are able to estimate the $b m o$ norm for $v_{1}^{e}$.

Lemma 5.4.2. $v_{1}^{e} \in \operatorname{bmo}\left(\mathbf{R}^{n}\right)$ satisfies the estimate

$$
\left\|v_{1}^{e}\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

with $C$ independent of $v$ and $\rho$.
Proof. Let $r<\rho$ and consider $B_{r}(x)$ that intersects $\Gamma^{2 \rho}$. By the construction of $S$ in Proposition 6.2.2, there exists $x_{i_{0}} \in S$ such that $\left|\pi x-x_{i_{0}}\right|<\rho$. Thus, by Proposition 5.2.2 we have that $B_{r}(x) \subset B_{5 \rho}\left(x_{i_{0}}\right) \subset U_{6 \rho}\left(x_{i_{0}}\right)$ as $\varepsilon<\frac{1}{3}$. If $x_{j} \in S$ such that $U_{2 \rho}\left(x_{j}\right) \cap$ $B_{r}(x) \neq \emptyset$, then $U_{6 \rho}\left(x_{j}\right) \cap U_{6 \rho}\left(x_{i_{0}}\right) \neq \emptyset$. This means that the number of $x_{j} \in S$ such that $U_{2 \rho}\left(x_{j}\right) \cap B_{r}(x) \neq \emptyset$ is smaller than the number of $x_{j} \in S$ such that $U_{6 \rho}\left(x_{j}\right) \cap U_{6 \rho}\left(x_{i_{0}}\right) \neq \emptyset$. Same proof of Proposition 6.2.2 also shows that for any $x_{k} \in S$, the number of $x_{j} \in S$ such that $U_{6 \rho}\left(x_{j}\right) \cap U_{6 \rho}\left(x_{k}\right) \neq \emptyset$ is smaller than some $N_{*, 0} \in \mathbf{N}$ independent of $x_{k}$. Hence, we can find at most $N_{*, 0}$ points in $S$, say $\left\{x_{j_{1}}, \ldots, x_{j_{N_{*, 0}}}\right\} \subset S$, such that $U_{2 \rho}\left(x_{j_{l}}\right) \cap B_{r}(x) \neq \emptyset$ for each $1 \leq l \leq N_{*, 0}$.

The $L^{1}$ norm of $v_{1}^{e}$ in $B_{r}(x)$ is estimated as

$$
\left\|v_{1}^{e}\right\|_{L^{1}\left(B_{r}(x)\right)} \leq \sum_{l=1}^{N_{*, 0}}\left\|v_{1, j_{l}}^{e}\right\|_{L^{1}\left(B_{r}(x) \cap U_{2 \rho}\left(x_{j_{l}}\right)\right)} \leq 8 N_{*, 0}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

Since this estimate holds regardless of $x \in \mathbf{R}^{n}$, we obtain that

$$
\left\|v_{1}^{e}\right\|_{L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)} \leq 8 N_{*, 0}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

Since

$$
r_{B_{r}(x)} v_{1}^{e}=\sum_{l=1}^{N_{*, 0}} r_{B_{r}(x)} v_{1, j_{l}}^{e}
$$

we have that

$$
\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|v_{1}^{e}(y)-\left(v_{1}^{e}\right)_{B_{r}(x)}\right| d y \leq \sum_{l=1}^{N_{*, 0}} \frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|v_{1, j_{l}}^{e}(y)-\left(v_{1, j_{l}}^{e}\right)_{B_{r}(x)}\right| d y
$$

By Lemma 5.4.1, we deduce that

$$
\left[v_{1}^{e}\right]_{B M O^{\rho}\left(\mathbf{R}^{n}\right)} \leq \frac{N_{*, 0} C_{n}}{\rho}\|v\|_{b m o_{\infty}^{\infty}(\Omega)} .
$$

Let $B$ be a ball in $\mathbf{R}^{n}$ with radius $r(B)>\rho$. By the triangle inequality,

$$
\frac{1}{|B|} \int_{B}\left|v_{1}^{e}(y)-\left(v_{1}^{e}\right)_{B}\right| d y \leq \frac{2}{|B|} \int_{B}\left|v_{1}^{e}(y)\right| d y
$$

Let $M \in \mathbb{N}$ be the largest integer such that $M \rho \leq r(B)$. By definition we have that $(M+1) \rho>r(B)$. Note that the ball $B$ is contained in a cube $Q$ of side length $(M+1) \rho$ which shares the same center as $B$. Separating each side of $Q$ equally into $M+1$ parts, we can divide $Q$ equally into $(M+1)^{n}$ subcubes of side length $\rho$. Hence, we have that

$$
\int_{B}\left|v_{1}^{e}(y)\right| d y \leq \int_{Q}\left|v_{1}^{e}(y)\right| d y \leq C_{n}(M+1)^{n} \cdot\left\|v_{1}^{e}\right\|_{L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)}
$$

Since $r(B) \geq M \rho$, we deduce that

$$
\frac{2}{|B|} \int_{B}\left|v_{1}^{e}\right| d y \leq \frac{C_{n}}{\rho^{n}} \cdot\left\|v_{1}^{e}\right\|_{L_{\mathrm{u} 1}^{1}\left(\mathbf{R}^{n}\right)}
$$

Therefore, we finally obtain the estimate

$$
\left[v_{1}^{e}\right]_{b m o\left(\mathbf{R}^{n}\right)} \leq \frac{N_{*, 0} C_{n}}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)} .
$$

### 5.4.2 Extension to $\mathrm{R}^{n}$

Let $v_{2}:=v-v_{1}$. Note that $\operatorname{supp} v_{2} \subset \Omega \backslash \Gamma_{\rho}$. Let $v_{2}^{z e}$ denote the zero extension of $v_{2}$ to $\mathbf{R}^{n}$, i.e.,

$$
v_{2}^{z e}(x)=\left\{\begin{array}{rll}
v_{2}(x) & \text { for } & x \in \Omega \\
0 & \text { for } & x \notin \Omega
\end{array}\right.
$$

We next estimate the $b m o$ norm of $v_{2}^{z e}$.
Lemma 5.4.3. $v_{2}^{z e} \in b m o\left(\mathbf{R}^{n}\right)$ satisfies the estimate

$$
\left\|v_{2}^{z e}\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

with $C$ independent of $v$ and $\rho$.
Proof. Since $r_{\Omega} v_{1}^{e}=v_{1}$, Lemma 5.4.2 implies that $v_{1} \in b m o_{\infty}^{\infty}(\Omega)$ with the estimate

$$
\left\|v_{1}\right\|_{b m o_{\infty}^{\infty}(\Omega)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

Hence, $v_{2}=v-v_{1} \in b m o_{\infty}^{\infty}(\Omega)$ satisfies the estimate

$$
\left\|v_{2}\right\|_{b m o_{\infty}^{\infty}(\Omega)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

Since $v_{2}^{z e}$ is the zero extension of $v_{2}$, the estimate $\left\|v_{2}^{z e}\right\|_{L_{\mathrm{ul}}^{1}\left(\mathbf{R}^{n}\right)} \leq\left\|v_{2}\right\|_{L_{\mathrm{ul}}^{1}(\Omega)}$ is trivial. Let $B \subset \mathbf{R}^{n}$ be a ball with radius $r(B) \leq \rho / 2$. If $B$ intersects $\overline{\Omega \backslash \Gamma_{\rho}}$, then $B \subset \Omega$. In this case, we naturally have that

$$
\frac{1}{|B|} \int_{B}\left|v_{2}^{z e}(y)-\left(v_{2}^{z e}\right)_{B}\right| d y \leq\left[v_{2}\right]_{B M O^{\infty}(\Omega)}
$$

If $B \cap \overline{\Omega \backslash \Gamma_{\rho}}=\emptyset$, then $v_{2}^{z e}=0$ in $B$, there is nothing to prove in this case. Hence, we have the estimate

$$
\left[v_{2}^{z e}\right]_{B M O^{\rho / 2}\left(\mathbf{R}^{n}\right)} \leq\left[v_{2}\right]_{B M O^{\infty}(\Omega)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

Let $B \subset \mathbf{R}^{n}$ be a ball with radius $r(B)>\rho / 2$. By same argument in the proof of Lemma 5.4.2 that decomposes the smallest cube $Q$ containing $B$ into small subcubes of side-length $\rho / 2$, we deduce that

$$
\frac{1}{|B|} \int_{B}\left|v_{2}^{z e}(y)-\left(v_{2}^{z e}\right)_{B}\right| d y \leq \frac{2}{|B|} \int_{B}\left|v_{2}^{z e}(y)\right| d y \leq \frac{C}{\rho^{n}}\left\|v_{2}^{z e}\right\|_{L_{\mathrm{ul} 1}^{1}\left(\mathbf{R}^{n}\right)}
$$

Therefore, we finally obtain that

$$
\left\|v_{2}^{z e}\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

Up till here, we have gathered enough results to prove our main theorem.

Proof of Theorem 5.1.1. Let

$$
\begin{aligned}
\varepsilon & <\frac{1}{8 n\left(1+L_{\partial W}\right)}, \\
c_{\Omega}^{\varepsilon} & =\min \left\{\frac{\varepsilon}{L_{\Gamma} \cdot((n+1)!)^{2} \cdot 2^{2 n+4}}, \rho_{0}\right\}, \\
c_{\Omega}^{*} & :=\min \left\{\frac{c_{0}^{2}}{16 n\left(1+L_{\partial W}\right) \cdot C_{L_{\Gamma}, n}}, \frac{c_{\Omega}^{\varepsilon}}{64}\right\} .
\end{aligned}
$$

We set $\widetilde{v}:=v_{1}^{e}+v_{2}^{z e}$ and let $\rho<c_{\Omega}^{*}$. An easy check ensures that $\operatorname{supp} \widetilde{v} \subset \overline{\Omega_{2 \rho}}$ and $r_{\Omega} \widetilde{v}=v$. By Lemma 5.4.2 and Lemma 5.4.3, we see that $\widetilde{v}=v_{1}^{e}+v_{2}^{z e} \in b m o\left(\mathbf{R}^{n}\right)$ satisfies the estimate

$$
\|\widetilde{v}\|_{b m o\left(\mathbf{R}^{n}\right)} \leq \frac{C}{\rho^{n}}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

The product estimate for $v \in b m o_{\infty}^{\infty}(\Omega)$ follows directly from the extension theorem.
Proof of Theorem 5.1.2. Let $\gamma \in(0,1)$. By [8, Theorem 13], we see that for $\varphi \in C^{\gamma}(\Omega)$, there exists $\widetilde{\varphi} \in C^{\gamma}\left(\mathbf{R}^{n}\right)$ such that $r_{\Omega} \widetilde{\varphi}=\varphi$ and

$$
\|\widetilde{\varphi}\|_{C \gamma}\left(\mathbf{R}^{n}\right) \leq\|\varphi\|_{C \gamma}(\Omega) .
$$

Extending $v \in b m o_{\infty}^{\infty}(\Omega)$ to $\widetilde{v} \in b m o\left(\mathbf{R}^{n}\right)$ by Theorem 5.1.1, we naturally have that

$$
\|\varphi v\|_{b m o_{\infty}^{\infty}(\Omega)} \leq\|\widetilde{\varphi} \widetilde{v}\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C\|\widetilde{\varphi}\|_{C^{\gamma}\left(\mathbf{R}^{n}\right)}\|\widetilde{v}\|_{b m o\left(\mathbf{R}^{n}\right)} \leq C\|\varphi\|_{C^{\gamma}(\Omega)}\|v\|_{b m o_{\infty}^{\infty}(\Omega)}
$$

By almost the same proof of Theorem 5.1.1, we are able to further establish an extension theorem for $b m o_{\delta}^{\mu}(\Omega)$ with $\delta, \mu<\infty$. We recall that $b m o_{\infty}^{\infty}(\Omega) \subset b m o_{\delta}^{\mu}(\Omega)$ for arbitrary domain $\Omega$ and $\delta, \mu<\infty$ [8, Theorem 2].

Theorem 5.4.4. Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2$ and $\mu, \delta \in(0, \infty)$. There exists $c_{\Omega}^{*}>0$ such that for any $\rho \in\left(0, c_{\Omega}^{*}\right)$ and $v \in b m o_{\delta}^{\mu}(\Omega)$, there is an extension $\widetilde{v} \in B M O^{\mu}\left(\mathbf{R}^{n}\right) \cap L_{\mathrm{ul}}^{1}\left(\Gamma^{\delta}\right)$ such that

$$
[\widetilde{v}]_{B M O^{\mu}\left(\mathbf{R}^{n}\right)}+[\widetilde{v}]_{L_{\mathbf{u l}}^{1}\left(\Gamma^{\delta}\right)} \leq \frac{C}{\rho}\|v\|_{b m o_{\delta}^{\mu}(\Omega)}
$$

with $C$ independent of $v$ and $\rho$. Moreover, $\operatorname{supp} \widetilde{v} \subset \overline{\Omega_{2 \rho}}$ where

$$
\Omega_{2 \rho}:=\left\{x \in \mathbf{R}^{n} \mid d(x, \bar{\Omega})<2 \rho\right\} .
$$

The operator $v \mapsto \widetilde{v}$ is a bounded linear operator.
Proof. By [8, Proposition 1], we see that the space $b m o_{\delta_{1}}^{\mu_{1}}(\Omega)$ and the space $b m o_{\delta_{2}}^{\mu_{2}}(\Omega)$ are equivalent for any $0<\delta_{1}, \delta_{2}, \mu_{1}, \mu_{2}<\infty$. Without loss of generality, we may assume that $\mu, \delta>c_{\Omega}^{*}$ where $c_{\Omega}^{*}$ is defined in the proof of Theorem 5.1.1. Let $\rho \in\left(0, c_{\Omega}^{*}\right)$. Follow the proofs of Lemma 5.3.1, Lemma 5.3.3, Lemma 5.4.1 and Lemma 5.4.2, we can deduce that $v_{1}^{e} \in B M O^{\rho}\left(\mathbf{R}^{n}\right) \cap L_{\mathrm{ul}}^{1}\left(\Gamma^{\delta}\right)$ satisfies the estimate

$$
\left[v_{1}^{e}\right]_{B M O^{\rho}\left(\mathbf{R}^{n}\right)}+\left[v_{1}^{e}\right]_{L_{\mathrm{ul}}^{1}\left(\Gamma^{\delta}\right)} \leq \frac{C}{\rho}\|v\|_{b m o_{\delta}^{\mu}(\Omega)}
$$

Moreover, in this case it is trivial that $v_{2}^{z e} \in B M O^{\rho}\left(\mathbf{R}^{n}\right) \cap L_{\mathrm{ul}}^{1}\left(\Gamma^{\delta}\right)$. Still by setting $\widetilde{v}=$ $v_{1}^{e}+v_{2}^{z e}$, we finally obtain that $\widetilde{v} \in B M O^{\rho}\left(\mathbf{R}^{n}\right) \cap L_{\mathrm{ul}}^{1}\left(\Gamma^{\delta}\right)$ satisfies the estimate

$$
[\tilde{v}]_{B M O^{\rho}\left(\mathbf{R}^{n}\right)}+[\tilde{v}]_{L_{\mathrm{ul}}^{1}\left(\Gamma^{\delta}\right)} \leq \frac{C}{\rho}\|v\|_{b m o_{\delta}^{\mu}(\Omega)}
$$

with $C$ independent of $v$ and $\rho$.

### 5.5 Application of the extension theorem

As defined in [1], [2], [3], [4], we recall a seminorm that controls the boundary behavior. For $\nu \in(0, \infty]$, we set

$$
[f]_{b^{\nu}}:=\sup \left\{r^{-n} \int_{\Omega \cap B_{r}(x)}|f(y)| d y \mid x \in \Gamma, 0<r<\nu\right\} .
$$

We define the space

$$
B M O_{b}^{\mu, \nu}(\Omega):=\left\{f \in B M O^{\mu}(\Omega) \mid[f]_{b^{\nu}}<\infty\right\}
$$

with

$$
\|f\|_{B M O_{b}^{\mu, \nu}(\Omega)}:=[f]_{B M O^{\mu}(\Omega)}+[f]_{b^{\nu}} .
$$

Let $\mu_{0}, \nu_{0}<\infty$. In [4, Example 1], we see that there exist examples in $B M O_{b}^{\mu_{0}, \nu_{0}}$, $B M O_{b}^{\mu_{0}, \infty}$ and $B M O_{b}^{\infty, \nu_{0}}$. By making use of the extension theorem and the product estimate established in this chapter, we shall give an example of a function that belongs to $B M O_{b}^{\infty, \infty}$ but does not belong to $L^{\infty}$.

We consider the case where the domain $\Omega$ is the half space $\mathbf{R}_{+}^{2}$. Let $f=\log x_{2}$ defined in the layer domain $D_{L}:=\left\{0<x_{2}<1\right\}$. For a cube $Q=[a, a+1] \times[b, b+1]$ that intersects $D_{L}$, we have that

$$
\int_{Q \cap D_{L}}\left|\log x_{2}\right| d x=-\int_{0}^{b+1} \log x_{2} d x_{2} \leq 1 .
$$

Hence, we see that $f \in b m o_{\infty}^{\infty}\left(D_{L}\right)$. By Theorem 5.1.1, we can find $\tilde{f} \in b m o\left(\mathbf{R}^{2}\right)$ such that $r_{D_{L}} \tilde{f}=f$ and supp $\tilde{f} \subset\left\{-1<x_{2}<2\right\}$. Set $\widetilde{g}\left(x_{1}, x_{2}\right):=\widetilde{f}\left(x_{1}, x_{2}-2\right)$ for any $x=\left(x_{1}, x_{2}\right) \in \mathbf{R}^{2}$ and $g:=r_{\mathbf{R}_{+}^{2}} \tilde{g}$. Note that $\operatorname{supp} g \subset\left\{1<x_{2}<4\right\}$.
Proposition 5.5.1. $g \in B M O_{b}^{\infty, \infty}\left(\mathbf{R}_{+}^{2}\right)$ but $g \notin L^{\infty}\left(\mathbf{R}_{+}^{2}\right)$.
Proof. It is trivial to see that $g \in B M O^{\infty}\left(\mathbf{R}_{+}^{2}\right)$ and $g \notin L^{\infty}\left(\mathbf{R}_{+}^{2}\right)$. We only need to estimate the $b^{\infty}$-norm for $g$. Since $\operatorname{supp} g \subset\left\{1<x_{2}<4\right\}$, it is sufficient to estimate

$$
\frac{2}{\left|Q_{r}(x)\right|} \int_{Q_{r}(x) \cap \mathbf{R}_{+}^{2}}|g| d y
$$

for $r \geq 1$ and $x=\left(x_{1}, 0\right) \in \partial \mathbf{R}_{+}^{2}$ where $Q_{r}(x)$ denotes the square with center $x$ of sidelength $2 r$. Without loss of generality, we may assume that $g$ is only a function of $x_{2}$. Hence, a direct calculation shows that

$$
\frac{2}{\left|Q_{r}(x)\right|} \int_{Q_{r}(x) \cap \mathbf{R}_{+}^{2}}|g| d y=\frac{1}{2 r^{2}} \int_{x_{1}-r}^{x_{1}+r} \int_{1}^{r}|g| d y_{2} d y_{1} \leq 2 \int_{0}^{1}\left|\log z_{2}\right| d z_{2} \leq 2
$$

Remark 5.5.2. Let $\phi \in C_{\mathrm{c}}^{\infty}\left(B_{8}(0)\right)$ with $\phi \equiv 1$ in $B_{6}(0)$, by Proposition 5.5.1 we see that $\phi g \in B M O_{b}^{\infty, \infty}\left(\mathbf{R}_{+}^{2}\right) \cap L^{2}\left(\mathbf{R}_{+}^{2}\right)$ but $\phi g \notin L^{\infty}\left(\mathbf{R}_{+}^{2}\right)$.

### 5.6 Extension of vector fields in $b m o$ in a domain

Note that Lemma 5.4.1 basically coincide with [9, Proposition 2] in the statement. However, the proof of Lemma 5.4.1 involves the localization argument in this chapter, which actually improves [9, Proposition 2] in the sense that [9, Proposition 2] holds for any uniformly $C^{2}$ domain instead of just for bounded domain. Here we provide an update of [9, Proposition $2]$.

We consider the space

$$
v b m o(\Omega):=\left\{u \in b m o_{\infty}^{\infty}(\Omega) \mid[\nabla d \cdot u]_{b^{\nu}}<\infty\right\}
$$

equipped with the norm

$$
\|u\|_{v b m o(\Omega)}:=\|u\|_{b m o_{\infty}^{\infty}(\Omega)}+[\nabla d \cdot u]_{b^{\nu}} .
$$

This space is independent of $\nu \in(0, \infty]$. Let $u \in \operatorname{vbmo}(\Omega)$. We set $u_{1}=\theta_{\rho} u, u_{1, i}=\varphi_{i} u_{1}$. Let $P u_{1, i}^{o}:=\left(\nabla d \cdot u_{1, i}^{o}\right) \nabla d$ denotes the normal component of $u_{1, i}^{o}$ whereas $Q u_{1, i}^{e}:=u_{1, i}^{e}-$ $\left(\nabla d \cdot u_{1, i}^{e}\right) \nabla d$ denotes the tangential component of $u_{1, i}^{e}$.
Lemma 5.6.1. Let $\rho<\frac{c_{\Omega}^{\varepsilon}}{48}$. There exists a constant $C$, independent of $v$ and $\rho$, such that the estimates

$$
\begin{aligned}
{\left[P u_{1, i}^{o}\right]_{b m o\left(\mathbf{R}^{n}\right)} } & \leq \frac{C}{\rho^{n}}\|u\|_{v b m o(\Omega)}, \\
{\left[\nabla d \cdot P u_{1, i}^{o}\right]_{b^{\infty}(\Gamma)} } & \leq \frac{C}{\rho^{n}}\|u\|_{v b m o(\Omega)}
\end{aligned}
$$

hold for any $i \in \mathbf{N}$ and $\nu \in(0, \infty]$.
Proof. Follow the proofs of [9, Proposition 2] and Lemma 5.4.1, we are done.
Lemma 5.6.2. $P u_{1}^{o} \in b m o\left(\mathbf{R}^{n}\right)$ satisfies the estimates

$$
\begin{aligned}
\left\|P u_{1}^{o}\right\|_{b m o\left(\mathbf{R}^{n}\right)} & \leq \frac{C}{\rho^{n}}\|u\|_{v b m o(\Omega)} \\
{\left[\nabla d \cdot P u_{1}^{o}\right]_{b^{\infty}(\Gamma)} } & \leq \frac{C}{\rho^{n}}\|u\|_{v b m o(\Omega)}
\end{aligned}
$$

with $C$ independent of $u$ and $\rho$.
Proof. Follow the proof of Lemma 5.4.2, we are done.
Similar as in [9, Proposition 2], we set

$$
\overline{u_{1}}:=P u_{1}^{o}+Q u_{1}^{e} .
$$

By Lemma 5.4.2, we have that $\overline{u_{1}} \in b m o\left(\mathbf{R}^{n}\right)$. Let $u_{2}:=u-u_{1}$ and $u_{2}^{z e}$ be the zero extension of $u_{2}$ to $\mathbf{R}^{n}$. Since $\overline{u_{1}}$ coincide with $u_{1}$ in $\Omega$, following the proof of Lemma 5.4.3 we can show that $u_{2}^{z e} \in \operatorname{bmo}\left(\mathbf{R}^{n}\right)$ satisfying

$$
\left\|u_{2}^{z e}\right\|_{b m o\left(\mathbf{R}^{n}\right)} \leq \frac{C}{\rho^{n}}\|u\|_{v b m o(\Omega)}
$$

with $C$ independent of $u$ and $\rho$. Therefore, by setting $\bar{u}:=\overline{u_{1}}+u_{2}^{z e}$, we obtain an extension of $u$ whose normal component in a small neighborhood of $\Gamma$ is odd with respect to $\Gamma$ whereas the tangential component in a small neighborhood of $\Gamma$ is even with respect to $\Gamma$. We summarize the extension theorem for a vector field of bmo in a domain as follow.

Theorem 5.6.3. Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2$. There exists $c_{\Omega}^{* *}>0$ such that for any $\rho \in\left(0, c_{\Omega}^{* *}\right)$ and $u \in \operatorname{vbmo}(\Omega)$, there is an extension $\bar{u} \in b m o\left(\mathbf{R}^{n}\right)$ such that

$$
\|\bar{u}\|_{b m o\left(\mathbf{R}^{n}\right)}+[\nabla d \cdot \bar{u}]_{b \infty(\Gamma)} \leq \frac{C}{\rho^{n}}\|u\|_{v b m o(\Omega)}
$$

with $C$ independent of $u$ and $\rho$. Moreover, $\operatorname{supp} \bar{u} \subset \overline{\Omega_{2 \rho}}$ where

$$
\Omega_{2 \rho}:=\left\{x \in \mathbf{R}^{n} \mid d(x, \bar{\Omega})<2 \rho\right\} .
$$

The operator $u \mapsto \bar{u}$ is a bounded linear operator.
The constant $c_{\Omega}^{* *}$ can be taken as

$$
c_{\Omega}^{* *}:=\min \left\{\frac{c_{0}^{2}}{16 n\left(1+L_{\partial W}\right) \cdot C_{L_{\Gamma}, n}}, \frac{c_{\Omega}^{\varepsilon}}{96}\right\} .
$$

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## Chapter 6

## The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

We introduce a space of vector fields with bounded mean oscillation whose "tangential" and "normal" components to the boundary behave differently. We establish its Helmholtz decomposition when the domain is a perturbed half space with small perturbation. This substantially extends the authors' earlier results for a half space and a bounded domain.

### 6.1 Introduction

The Helmholtz decomposition of a vector field is a fundamental tool to analyze the Stokes and the Navier-Stokes equations. It is formally a decomposition of a vector field $v=$ $\left(v^{1}, \ldots, v^{n}\right)$ in a domain $\Omega$ of $\mathbf{R}^{n}$ into

$$
\begin{equation*}
v=v_{0}+\nabla q \tag{6.1.1}
\end{equation*}
$$

here $v_{0}$ is a divergence free vector field satisfying supplemental conditions like boundary condition and $\nabla q$ denotes the gradient of a function (scalar field) $q$. If $v$ is in $L^{p}(1<$ $p<\infty)$ in $\Omega$, such a decomposition is well-studied. For example, a topological direct sum decomposition

$$
\left(L^{p}(\Omega)\right)^{n}=L_{\sigma}^{p}(\Omega) \oplus G^{p}(\Omega)
$$

holds for various domains including $\Omega=\mathbf{R}^{n}$, a half space $\mathbf{R}_{+}^{n}$, a bounded smooth domain [8]; see e.g. G. P. Galdi [9]. Here, $L_{\sigma}^{p}(\Omega)$ denotes the $L^{p}$-closure of the space of all div-free vector fields compactly supported in $\Omega$ and $G^{p}(\Omega)$ denotes the totality of $L^{p}$ gradient fields. It is impossible to extend this Helmholtz decomposition to $L^{\infty}$ even if $\Omega=\mathbf{R}^{n}$ since the projection $v \mapsto \nabla q$ is a composite of the Riesz operators which is not bounded in $L^{\infty}$. We have to replace $L^{\infty}$ with a class of functions of bounded mean oscillation. If the vector field is of bounded mean oscillation ( $B M O$ for short), such a problem is studied in the cases when $\Omega$ is a half space $\mathbf{R}_{+}^{n}$ [10] and a bounded $C^{3}$ domain [12]. Our goal in this chapter is to establish the Helmholtz decomposition of $B M O$ vector fields in a perturbed $C^{3}$ half
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
space with small perturbation in $\mathbf{R}^{n}$, which is an example of a domain with curved and non-compact boundary.

Let us recall the $B M O$ space of vector fields introduced in [11] and [12]. We first recall the $B M O$ seminorm for $\mu \in(0, \infty]$. For a locally integrable function $f$, i.e., $f \in L_{\mathrm{loc}}^{1}(\Omega)$ we define

$$
[f]_{B M O^{\mu}(\Omega)}:=\sup \left\{\left.\frac{1}{\left|B_{r}(x)\right|} \int_{B_{r}(x)}\left|f(y)-f_{B_{r}(x)}\right| d y \right\rvert\, B_{r}(x) \subset \Omega, r<\mu\right\}
$$

where $f_{B}$ denotes the average over $B$, i.e.,

$$
f_{B}:=\frac{1}{|B|} \int_{B} f(y) d y
$$

and $B_{r}(x)$ denotes the closed ball of radius $r$ centered at $x$ and $|B|$ denotes the Lebesgue measure of $B$. The space $B M O^{\mu}(\Omega)$ is defined as

$$
B M O^{\mu}(\Omega):=\left\{f \in L_{\mathrm{loc}}^{1}(\Omega) \mid[f]_{\text {BMO }^{\mu}}<\infty\right\}
$$

This space may not agree with the space of restrictions $r_{\Omega} f$ of $f \in B M O^{\mu}\left(\mathbf{R}^{n}\right)$. As in [2], [3], [4], [5] we introduce a seminorm controlling the boundary behavior. For $\nu \in(0, \infty]$, we set

$$
[f]_{b^{\nu}}:=\sup \left\{r^{-n} \int_{\Omega \cap B_{r}(x)}|f(y)| d y \mid x \in \Gamma, 0<r<\nu\right\}
$$

In these papers, the space

$$
B M O_{b}^{\mu, \nu}(\Omega):=\left\{f \in B M O^{\mu}(\Omega) \mid[f]_{b^{\nu}}<\infty\right\}
$$

is considered. Note that this space $B M O_{b}^{\infty, \infty}(\Omega)$ is identified with Miyachi's $B M O$ introduced by [22] if $\Omega$ is a bounded Lipschitz domain or a Lipschitz half space as proved in [5]. Unfortunately, it turns out such a boundary control for all components of vector fields is too strict to have the Helmholtz decomposition. We separate tangential and normal components. Let $d$ denote the signed distance function from $\Gamma$ which is defined by

$$
d(x)=\left\{\begin{array}{c}
\inf _{y \in \Gamma}|x-y| \quad \text { for } \quad x \in \Omega \\
-\inf _{y \in \Gamma}|x-y| \quad \text { for } \quad x \notin \Omega
\end{array}\right.
$$

so that $d(x)=d_{\Gamma}(x)$ for $x \in \Omega$.
For vector fields of bounded mean oscillation, we consider

$$
v B M O^{\mu, \nu}(\Omega):=\left\{v \in\left(B M O^{\mu}(\Omega)\right)^{n} \mid[\nabla d \cdot v]_{b^{\nu}}<\infty\right\}
$$

where . denotes the standard inner product in $\mathbf{R}^{n}$. We call the quantity $(\nabla d \cdot v) \nabla d$ on $\Gamma$ to be the component of $v$ normal to the boundary $\Gamma$. We set

$$
[v]_{v B M O^{\mu, \nu}(\Omega)}:=[v]_{B M O^{\mu}(\Omega)}+\left[\nabla d_{\Gamma} \cdot v\right]_{b^{\nu}}
$$

In the case where $\Omega$ is the half space $\mathbf{R}_{+}^{n},[\cdot]_{v B M O^{\mu, \nu}(\Omega)}$ is not a norm but a seminorm if either $\mu$ or $\nu$ is finite. However, if the boundary $\Gamma$ has a fully curved part in the sense of [11, Definition 7], then this becomes a norm [11, Lemma 8]. In particular, when $\Omega$ is a bounded $C^{2}$ domain, this is a norm. Roughly speaking, the boundary behavior of
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
a vector field $v$ is controlled for only normal part of $v$ if $v \in v B M O^{\mu, \nu}(\Omega)$. If $\Omega$ is a bounded domain, this norm is equivalent no matter how $\mu$ and $\nu$ are taken; in other words, $v B M O^{\mu, \nu}(\Omega)=v B M O^{\infty, \infty}(\Omega)$. This is because $v B M O^{\mu, \nu}(\Omega) \subset L^{1}(\Omega)$ when $\Omega$ is bounded, which follows from the characterization of $v B M O^{\mu, \nu}(\Omega)$ in [11, Theorem 9]. Without loss of generality, we can simply write $v \operatorname{BMO}^{\mu, \nu}(\Omega)$ as $v B M O(\Omega)$ in this case. However, if $\Omega$ is an unbounded space, then $\Gamma$ does not necessarily have a fully curved part. Hence in this case, $[\cdot]_{v B M O^{\mu, \nu}(\Omega)}$ is not necessarily a norm. Moreover, the space $v B M O^{\mu, \nu}(\Omega)$ depends on the value of $\mu$ and $\nu$. As a result, instead of working with $v B M O^{\mu, \nu}(\Omega)$ directly, we consider its intersection with the $\left(L^{2}(\Omega)\right)^{n}$, i.e., we consider the space

$$
v B M O L^{2}(\Omega):=v B M O^{\mu, \nu}(\Omega) \cap\left(L^{2}(\Omega)\right)^{n}
$$

with

$$
\|v\|_{v B M O L^{2}(\Omega)}:=[v]_{v B M O O^{\mu},(\Omega)}+\|v\|_{\left(L^{2}(\Omega)\right)^{n}} .
$$

Note that this space $v B M O L^{2}(\Omega)$ is a Banach space which is independent of $\mu, \nu \in(0, \infty]$.
We denote $x^{\prime}:=\left(x_{1}, x_{2}, \ldots, x_{n-1}\right)$ for $x \in \mathbf{R}^{n}$. Let $h \in C_{0}^{3}\left(\mathbf{R}^{n-1}\right)$. We define the perturbed half space $\mathbf{R}_{h}^{n}$ to be the space

$$
\mathbf{R}_{h}^{n}:=\left\{x=\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n} \mid x_{n}>h\left(x^{\prime}\right)\right\}
$$

Without loss of generality, we may assume that $\operatorname{supp} h \subset B_{R_{h}}\left(0^{\prime}\right)$ for some $R_{h}>0$ where $B_{R_{h}}\left(0^{\prime}\right)$ denotes the ball in $\mathbf{R}^{n-1}$ with center $0^{\prime}$ and radius $R_{h}$. Let $C_{*}>0$ be a fixed constant that are going to be determined later in this chapter. We say the perturbed $C^{3}$ half space $\mathbf{R}_{h}^{n}$ is of small perturbation if the condition

$$
\begin{equation*}
\left(R_{h}^{n-1}+1\right)\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}<\frac{1}{2 C_{*}} \tag{6.1.2}
\end{equation*}
$$

holds. Now we are ready to state our main theorem.
Theorem 6.1.1. Let $\Omega$ be a perturbed $C^{3}$ half space in $\mathbf{R}^{n}$ with small perturbation. Then the topological direct sum decomposition

$$
\begin{equation*}
v B M O L^{2}(\Omega)=v B M O L_{\sigma}^{2}(\Omega) \oplus G v B M O L^{2}(\Omega) \tag{6.1.3}
\end{equation*}
$$

holds with

$$
\begin{aligned}
v B M O L_{\sigma}^{2}(\Omega) & :=\left\{v \in v B M O L^{2}(\Omega) \mid \operatorname{div} v=0 \text { in } \Omega, v \cdot \mathbf{n}=0 \text { on } \Gamma\right\}, \\
G v B M O L^{2}(\Omega) & :=\left\{\nabla q \in v B \operatorname{MOL}^{2}(\Omega) \mid q \in L_{\mathrm{loc}}^{1}(\Omega)\right\}
\end{aligned}
$$

where $\mathbf{n}$ denotes the exterior unit normal vector field. In other words, for $v \in v B M O L^{2}(\Omega)$, there is unique $v_{0} \in v B M O L_{\sigma}^{2}(\Omega)$ and $\nabla q \in G v B M O L^{2}(\Omega)$ satisfying $v=v_{0}+\nabla q$. Moreover, the mappings $v \mapsto v_{0}, v \mapsto \nabla q$ are bounded in $v B M O L^{2}(\Omega)$.

Our strategy to prove Theorem 6.1.1 follows from the strategy we used to establish the Helmholtz decomposition in a bounded $C^{3}$ domain [12]. Let $E$ be the fundamental solution of $-\Delta$ in $\mathbf{R}^{n}$, i.e.,

$$
E(x):= \begin{cases}-\log |x| / 2 \pi & (n=2) \\ |x|^{2-n} /(n(n-2) \alpha(n)) & (n \geq 3)\end{cases}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
where $\alpha(n)$ denotes the volume of the unit ball $B_{1}(0)$ of $\mathbf{R}^{n}$. By [Theorem 5.1.2, Chapter 5], we see that as long as the regularity of $\Gamma$ is of uniformly $C^{2}$, the space $B M O^{\infty}(\Omega) \cap L^{2}(\Omega)$ allows the standard cut-off, i.e., we are able to decompose $v$ into two parts $v=v_{1}+v_{2}$ with $v_{1}=\varphi v$ and $v_{2}=v-v_{1}$ with some $\varphi \in C_{0}^{\infty}(\Omega)$. Then, the support of $v_{2}$ lies in a small neighborhood of $\Gamma$ whereas the support of $v_{1}$ is away from $\Gamma$. For $v_{1}$ we just set

$$
q_{1}^{1}=E * \operatorname{div} v_{1}
$$

by extending $v_{1}$ as zero outside its support. Then, the $L^{\infty}$ bound for $\nabla q_{1}^{1}$ is well controlled near $\Gamma$, which yields a bound for $b^{\nu}$ semi-norm. To estimate $v_{2}$, we use a normal coordinate system near $\Gamma$ and reduce the problem to the half space. Let $d$ denotes the signed distance function where $d=d_{\Gamma}$ in $\Omega$ and $d=-d_{\Gamma}$ outside $\Omega$. We extend $v_{2}$ to $\mathbf{R}^{n}$ so that the normal part $\left(\nabla d \cdot \bar{v}_{2}\right) \nabla d$ is odd and the tangential part $\overline{v_{2}}-\left(\nabla d \cdot \overline{v_{2}}\right) \nabla d$ is even in the direction of $\nabla d$ with respect to $\Gamma$. In such type of coordinate system, the minus Laplacian can be transformed as

$$
L=A-B+\text { lower order terms, } A=-\Delta_{\eta}, B=\sum_{1 \leq i, j \leq n-1} \partial_{\eta_{i}} b_{i j} \partial_{\eta_{j}}
$$

where $\eta_{n}$ is the normal direction to the boundary so that $\left\{\eta_{n}>0\right\}$ is the half space. By choosing a suitable coordinate system to represent $\Gamma$ locally, we are able to arrange $b_{i j}=0$ at one point of the boundary of the local coordinate system. We use a freezing coefficient method to construct volume potential $q_{1}^{\tan }$ and $q_{1}^{\text {nor }}$, which corresponds to the contribution from the tangential part ${\overline{v_{2}}}^{\tan }$ and the normal part ${\overline{v_{2}}}^{\text {nor }}$ respectively. Since the leading term of $\operatorname{div} \bar{v}_{2}^{\text {nor }}$ in normal coordinate consists of the differential of $\eta_{n}$ only, if we extend the coefficient $b_{i j}$ even in $\eta_{n}, q_{1}^{\text {nor }}$ is constructed so that the leading term of $\nabla d \cdot \nabla q_{1}^{\text {nor }}$ is odd in the direction of $\nabla d$. On the other hand, as the leading term of div $\bar{v}_{2}{ }^{\tan }$ in normal coordinate consists of the differential of $\eta^{\prime}=\left(\eta_{1}, \ldots, \eta_{n-1}\right)$ only, the even extension of $b_{i j}$ in $\eta_{n}$ gives rise to $q_{1}^{\mathrm{tan}}$ so that the leading term of $\nabla d \cdot \nabla q_{1}^{\mathrm{tan}}$ is also odd in the direction of $\nabla d$. Disregarding lower order terms and localization procedure, we set $q_{1}^{\tan }$ and $q_{1}^{\text {nor }}$ of the form

$$
\begin{aligned}
& q_{1}^{\tan }=-L^{-1} \operatorname{div} \bar{v}_{2}^{\tan }=-A^{-1}\left(I-B A^{-1}\right)^{-1} \operatorname{div} \bar{v}_{2}^{\tan } \\
& q_{1}^{\text {nor }}=-L^{-1} \operatorname{div} \bar{v}_{2}^{\text {nor }}=-A^{-1}\left(I-B A^{-1}\right)^{-1} \operatorname{div} \bar{v}_{2}^{\text {nor }}
\end{aligned}
$$

One is able to arrange $B A^{-1}$ small by taking a small neighborhood of a boundary point. Then $\left(I-B A^{-1}\right)^{-1}$ is given as the Neumann series $\sum_{m=0}^{\infty}\left(B A^{-1}\right)^{m}$. We are able to establish $B M O-B M O$ estimate for $\nabla q_{1}^{\tan }$ and $\nabla q_{1}^{\text {nor }}$, i.e.

$$
\left[\nabla q_{1}^{\mathrm{tan}}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{0}^{\prime}\left[\bar{v}_{2}^{\mathrm{tan}}\right]_{B M O\left(\mathbf{R}^{n}\right)},\left[\nabla q_{1}^{\mathrm{nor}}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{0}^{\prime}\left[\bar{v}_{2}^{\mathrm{nor}}\right]_{B M O\left(\mathbf{R}^{n}\right)}
$$

with some constant $C_{0}^{\prime}$ independent of $\overline{v_{2}}$. Since the leading term of $\nabla d \cdot\left(\nabla q_{1}^{\mathrm{tan}}+\nabla q_{1}^{\mathrm{nor}}\right)$ is odd in the direction of $\nabla d$ with respect to $\Gamma$, the $B M O$ bound implies $b^{\nu}$ bound. Note that $\left[{\overline{v_{2}}}^{\text {nor }}\right]_{B M O\left(\mathbf{R}^{n}\right)}$ is controlled by $\left[v_{2}\right]_{b^{\nu}}$ and $\left[v_{2}\right]_{B M O \infty(\Omega)}$ since ${\overline{v_{2}}}^{\text {nor }}$ is odd in the direction of $\nabla d$ with respect to $\Gamma$. By the procedure sketched above, we are able to construct a suitable operator by setting $q_{1}=q_{1}^{1}+q_{1}^{\mathrm{tan}}+q_{1}^{\text {nor }}$. Since many steps in the construction of volume potential $q_{1}$ in this case follows exactly from the theory in [12, Section 3] and Chapter 5, for these parts we provide necessary results directly without giving their proofs.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Theorem 6.1.2 (Construction of a suitable volume potential). Let $\Omega$ be a uniformly $C^{3}$ domain in $\mathbf{R}^{n}$. Then, there exists a linear operator $v \longmapsto q_{1}$ from $v B M O L^{2}(\Omega)$ to $L^{\infty}(\Omega)$ such that

$$
-\Delta q_{1}=\operatorname{div} v \quad \text { in } \quad \Omega
$$

and that there exists a constant $C_{1}=C_{1}(\Omega)$ satisfying

$$
\left\|\nabla q_{1}\right\|_{v B M O L^{2}(\Omega)} \leq C_{1}\|v\|_{v B M O L^{2}(\Omega)}
$$

In particular, the operator $v \longmapsto \nabla q_{1}$ is a bounded linear operator in $v B M O L^{2}(\Omega)$.
By this operator, we observe that $w=v-\nabla q_{1}$ is divergence free in $\Omega$. Unfortunately, this $w$ may not fulfill the trace condition $w \cdot \mathbf{n}=0$ on the boundary $\Gamma$. We construct another potential $q_{2}$ by solving the Neumann problem

$$
\begin{array}{ll}
\Delta q_{2}=0 & \text { in } \quad \Omega \\
\frac{\partial q_{2}}{\partial n}=w \cdot \mathbf{n} & \text { on } \quad \Gamma
\end{array}
$$

We then set $q=q_{1}+q_{2}$. Since $\partial q_{2} / \partial \mathbf{n}=\nabla q_{2} \cdot \mathbf{n}, v_{0}=v-\nabla q$ gives the Helmholtz decomposition (6.1.1). To complete the proof of Theorem 6.1.1, it suffices to prove that $\left\|\nabla q_{2}\right\|_{v B M O L^{2}(\Omega)}$ is bounded by a constant multiply of $\|v\|_{v B M O L^{2}(\Omega)}$.

Lemma 6.1.3 (Estimate of the normal trace). Let $\Omega$ be a uniformly $C^{2+\kappa}$ domain in $\mathbf{R}^{n}$ with $\kappa \in(0,1)$. Then there is a constant $C_{2}=C_{2}(\Omega)$ such that

$$
\|w \cdot \mathbf{n}\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)} \leq C_{2}\|w\|_{v B M O L^{2}(\Omega)}
$$

for all $w \in v B M O L^{2}(\Omega)$ with $\operatorname{div} w=0$.
The $L^{\infty}$ estimate of $w \cdot \mathbf{n}$ follows from the trace theorem established in [11]. For the $H^{-\frac{1}{2}}$ estimate for $w \cdot \mathbf{n}$, we split the boundary into the straight part and the curved part. Since we have the $L^{\infty}$ estimate for $w \cdot \mathbf{n}$ and the curved part is compact, the contribution in the $H^{-\frac{1}{2}}$ estimate for $w \cdot \mathbf{n}$ that comes from the curved part can be estimated by the $L^{\infty}$ norm of $w \cdot \mathbf{n}$ directly. For the contribution in the $H^{-\frac{1}{2}}$ estimate of $w \cdot \mathbf{n}$ that comes from the straight part, we invoke the $H^{-\frac{1}{2}}$ estimate of $w \cdot \mathbf{n}$ in the case of the half space. Hence, we finally need the estimate for the Neumann problem.

Lemma 6.1.4 (Estimate for the Neumann problem). Let $\Omega \subset \mathbf{R}^{n}$ be a perturbed $C^{2}$ half space with small perturbation. For $g \in L^{\infty}(\Gamma)$ satisfying $\int_{\Gamma} g d \mathcal{H}^{n-1}=0$, there exists $a$ unique (up to constant) solution $u$ to the Neumann problem

$$
\begin{array}{rlr}
\Delta u=0 & \text { in } \quad \Omega \\
\frac{\partial u}{\partial \mathbf{n}}=g \quad & \text { on } \quad \Gamma \tag{6.1.4}
\end{array}
$$

such that the operator $g \longmapsto u$ is linear and that there exists a constant $C_{3}=C_{3}(\Omega)$ such that

$$
\|\nabla u\|_{v B M O L^{2}(\Omega)} \leq C_{3}\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Combining these two lemmas with Theorem 6.1.2 yields

$$
\begin{aligned}
\left\|\nabla q_{2}\right\|_{v B M O L^{2}(\Omega)} & \leq C_{3} C_{2}\left\|v-\nabla q_{1}\right\|_{v B M O L^{2}(\Omega)} \\
& \leq C_{3} C_{2}\left(1+C_{1}\right)\|v\|_{v B M O L^{2}(\Omega)}
\end{aligned}
$$

Setting $q=q_{1}+q_{2}$ and $v_{0}=v-\nabla q$, we now observe that the projections $v \longmapsto v_{0}, v \longmapsto \nabla q$ are bounded in $v B M O L^{2}(\Omega)$, which yields (6.1.3) in Theorem 6.1.1.

For $g \in L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$, we consider the single layer potential

$$
E *\left(\delta_{\Gamma} \otimes g\right)(x):=\int_{\Gamma} E(x-y) g(y) d \mathcal{H}^{n-1}(y)
$$

for $x \in \mathbf{R}^{n}$. To show Lemma 6.1.4, we firstly estimate

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g\right)\right\|_{v B M O^{\infty, \nu}(\Omega)}
$$

For the $B M O$ estimate, we set $g_{1}\left(y^{\prime}, h\left(y^{\prime}\right)\right):=1_{B_{2 R_{h}}\left(0^{\prime}\right)}\left(y^{\prime}\right) g\left(y^{\prime}, h\left(y^{\prime}\right)\right)$ for $\left(y^{\prime}, h\left(y^{\prime}\right)\right) \in \Gamma$ and $g_{2}:=g-g_{1}$. By setting $\overline{g_{2}}\left(y^{\prime}, 0\right)=0$ for $\left|y^{\prime}\right|<2 R_{h}$ and $\overline{g_{2}}\left(y^{\prime}, 0\right)=g_{2}\left(y^{\prime}, 0\right)$ for $\left|y^{\prime}\right| \geq 2 R_{h}$, we see that the equality

$$
E *\left(\delta_{\Gamma} \otimes g_{2}\right)(x)=E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)(x)
$$

holds for any $x \in \mathbf{R}^{n}$. Thus, the $B M O$ estimate of $\nabla E *\left(\delta_{\Gamma} \otimes g_{2}\right)$ follows from the $B M O$ estimate of $E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)$. Since $g_{1}(\cdot, h(\cdot))$ is compactly supported in $\mathbf{R}^{n-1}$, the $B M O$ estimate for $\nabla E *\left(\delta_{\Gamma} \otimes g_{1}\right)$ follows directly from [12, Lemma 5], which contains a similar estimate that is established in the case of a compact boundary. It is very subtle but by a direct calculation, we may deduce the estimate

$$
\sup _{x \in \Gamma_{\nu}} \int_{\Gamma}\left|\frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)\right| d \mathcal{H}^{n-1}(y)<\infty
$$

where $\Gamma_{\nu}:=\{x \in \Omega \mid d(x)<\nu\}$ denotes a small neighborhood of $\Gamma$ in $\Omega$. Let $x \in \Gamma_{\nu}$. By making use of this estimate, we can show that

$$
\left|\nabla d(x) \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g_{1}\right)\right)(x)\right| \leq C\|g\|_{L^{\infty}(\Gamma)} .
$$

Since the kernel $\left|.^{\prime}\right|^{1-n}$ is integrable in $L^{2}\left(B_{M}\left(0^{\prime}\right)^{\mathrm{c}}\right)$ for any $M>0$, we are able to prove that

$$
\left|\nabla d(x) \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g_{2}\right)\right)(x)\right| \leq C\|g\|_{H^{-\frac{1}{2}}(\Gamma)}
$$

Hence, we obtain an estimate for $\left\|\nabla d \cdot \nabla E *\left(\delta_{\Gamma} \otimes g\right)\right\|_{L^{\infty}\left(\Gamma_{\nu}\right)}$ by $\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}$. The $b^{\nu}$ estimate therefore follows.

Let $g \in L^{\infty}(\Gamma)$. The trace of the double layer potential

$$
(P g)(x)=\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) g(y) d \mathcal{H}^{n-1}(y), \quad x \in \Gamma_{\nu}
$$

is of the form

$$
(\gamma(P g))\left(x^{\prime}, h\left(x^{\prime}\right)\right)=\frac{1}{2} g\left(x^{\prime}, h\left(x^{\prime}\right)\right)-(S g)\left(x^{\prime}, h\left(x^{\prime}\right)\right)
$$

where $S$ is a bounded linear operator on $L^{\infty}(\Gamma)$ satisfying

$$
\|S\|_{L^{\infty}(\Gamma) \rightarrow L^{\infty}(\Gamma)} \leq C_{*} R_{h}^{n-1}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
for some constant $C_{*}$ independent of $h$. Moreover, we have that $S g \in L^{2}(\Gamma)$ satisfies the estimate

$$
\|S g\|_{L^{2}(\Gamma)} \leq C^{*} R_{h}^{\frac{n-1}{2}}\|g\|_{L^{\infty}(\Gamma)}
$$

with some constant $C^{*}$ independent of $h$ and $g$. Therefore, if $\Omega$ is a perturbed half space of small perturbation, the inverse of $I-2 S$ is well-defined as a bounded linear map from $L^{\infty}(\Gamma)$ to $L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$ by the Neumann series

$$
(I-2 S)^{-1}=\sum_{i=0}^{\infty}(2 S)^{i}
$$

Since $P g$ is harmonic in $\Omega$, the solution to the Neumann problem (6.1.4) is formally given by

$$
u(x)=E *\left(\delta_{\Gamma} \otimes\left(2(I-2 S)^{-1} g\right)\right)(x), \quad x \in \Omega
$$

If we can estimate the $L^{2}$ norm of $\nabla u$ in $\Omega$, then we are done. Fortunately, we indeed have this estimate. In the case of a half space, if $g \in H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)$ satisfies

$$
\int_{\partial \mathbf{R}_{+}^{n}} g(y) d \mathcal{H}^{n-1}(y)=0
$$

then the estimate

$$
\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq C\|g\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)}
$$

holds with some constant $C$ independent of $g$. This estimate holds for the reason that the single layer potential $E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)$ is exactly half of the solution to the Neumann problem in the half space, and the Neumann problem in the half space admits a unique weak solution (up to an additive constant) $u \in H^{1}\left(\mathbf{R}_{+}^{n}\right)$ which satisfies

$$
\|\nabla u\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq C\|g\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)}
$$

with $C$ independent of $g$, see e.g. [26, Remark 1.2 and Remark 1.3], [21, Section 1.7]. In the case that $\Omega$ is a perturbed $C^{2}$ half space, for $g \in L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$, we consider $g$ as a sum of $g_{1}$ and $g_{2}$. If the integral of $g$ on $\Gamma$ equals zero, then there exists a constant $I_{c} \in \mathbf{R}$ such that

$$
\int_{\partial \mathbf{R}_{+}^{n}} \overline{g_{2}}(y)+f_{s}(y) d \mathcal{H}^{n-1}(y)=0
$$

with

$$
f_{s}\left(x^{\prime}, 0\right)=\left\{\begin{array}{lll}
0 & \text { for } & \left|x^{\prime}\right| \geq 2 M_{h} \\
\frac{I_{c}}{\left|B_{2 M_{h}}\left(0^{\prime}\right)\right|} & \text { for } & \left|x^{\prime}\right|<2 M_{h}
\end{array}\right.
$$

Since $\overline{g_{2}}+f_{s} \in H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)$, by the $L^{2}$ estimate in the half space case, we deduce that

$$
\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes f_{s}\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}}+C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

In addition, if the support of $g\left(\cdot^{\prime}, h\left(\cdot^{\prime}\right)\right)$ is contained in $\overline{B_{2 R_{h}}\left(0^{\prime}\right)}$, we apply the idea in [12, Lemma 5] which extends $g \in L^{\infty}(\Gamma)$ to $g_{e} \in L^{\infty}\left(\Gamma^{2 \delta}\right)$ by letting $g_{e}(x):=g(\pi x)$ for any $x \in \Gamma^{2 \delta}$ with $\pi x$ denoting the projection of $x$ on $\Gamma$. By multiplying a cutoff
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
function $\theta_{d}$ to $g_{e}$ where $\theta_{d}(x)=1$ for $|d(x)| \leq \delta$ and $\theta_{d}(x)=0$ for $|d(x)| \geq 2$, we see that $g_{e, c}:=\theta_{d} g_{e} \in L^{\infty}\left(\mathbf{R}^{n}\right)$ is of compact support. Since

$$
\begin{aligned}
\delta_{\Gamma} \otimes g & =\left(\nabla 1_{\Omega} \cdot \nabla d\right) g_{e, c} \\
& =\operatorname{div}\left(g_{e, c} 1_{\Omega} \nabla d\right)-1_{\Omega} \operatorname{div}\left(g_{e, c} \nabla d\right) \\
\operatorname{div}\left(g_{e, c} \nabla d\right) & =g_{e, c} \Delta d+\nabla d \cdot \nabla g_{e, c}=g_{e, c} \Delta d+\left(\nabla d \cdot \nabla \theta_{d}\right) g_{e}
\end{aligned}
$$

we have that

$$
\nabla E *\left(\delta_{\Gamma} \otimes g_{1}\right)=\nabla \operatorname{div}\left(E *\left(g_{e, c} 1_{\Omega} \nabla d\right)\right)-\nabla E *\left(1_{\Omega} g_{e} f_{\theta}\right)=I_{1}+I_{2}
$$

where $f_{\theta}:=\theta_{d} \Delta d+\nabla d \cdot \nabla \theta_{d}$. Since $\nabla \operatorname{div} E$ is $L^{p}$ for any $1<p<\infty$, see e.g. [15, Theorem 5.2.7 and Theorem 5.2.10], $I_{1}$ can be estimated as

$$
\left\|I_{1}\right\|_{\left(L^{2}\left(\mathbf{R}^{n}\right)\right)^{n}} \leq C\left\|g_{e, c} 1_{\Omega} \nabla\right\|_{\left(L^{2}\left(\mathbf{R}^{n}\right)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

Since $\nabla E \sim|\cdot|^{1-n}$, the famous Hardy-Littlewood-Sobolev inequality [1, Theorem 1.7] implies that

$$
\left\|I_{2}\right\|_{\left(L^{2}\left(\mathbf{R}^{n}\right)\right)^{n}} \leq C\left\|1_{\Omega} g_{e} f_{\theta}\right\|_{\left(L^{2}\left(\mathbf{R}^{n}\right)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

Hence, it can be deduced that

$$
\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes f_{s}\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}}+\left\|\nabla E *\left(\delta_{\Gamma} \otimes g_{1}\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

Since $\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)=\nabla E *\left(\delta_{\Gamma} \otimes g_{2}\right)$, we finally obtain our desired $L^{2}$ estimate

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

If $g \in L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma) \cap L^{1}(\Gamma)$, then without assuming the integral of $g$ on $\Gamma$ to be zero, we can deduce the $L^{2}$ estimate

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma) \cap L^{1}(\Gamma)}
$$

in a similar way. Since we also have $S g \in L^{1}(\Gamma)$ for $g \in L^{\infty}(\Gamma)$, the series $\sum_{i=1}^{\infty}(2 S)^{i} g$ is well-defined in $L^{1}(\Gamma)$ as long as the smallness condition

$$
\left(R_{h}^{n-1}+1\right)\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}<\frac{1}{2 C_{*}}
$$

is satisfied. Therefore, the $L^{2}$ estimate for $\nabla u$ holds. We obtain Lemma 6.1.4.
Our approach in this chapter is to derive the boundedness of the operator $v \mapsto \nabla q$ by a potential-theoretic approach. In $L^{p}$ setting there is a variational approach based on duality introduced by [23]; see also [6]. The key estimate is

$$
\|\nabla q\|_{L^{p}(\Omega)} \leq C_{5} \sup \left\{\int_{\Omega} \nabla q \cdot \nabla \varphi d x \mid\|\nabla \varphi\|_{L^{p^{\prime}}(\Omega)} \leq 1\right\}
$$

with $C_{5}$ independent of $q$, where $1 / p+1 / p^{\prime}=1,1<p<\infty$. Formally, this estimate yields the desired bound $\|\nabla q\|_{L^{p}(\Omega)} \leq C_{5}\|v\|_{L^{p}(\Omega)}$ since

$$
\int_{\Omega} \nabla q \cdot \nabla \varphi d x=\int_{\Omega} v \cdot \nabla \varphi d x
$$

At this moment, it is not clear that similar estimate holds if one replaces $L^{p}(\Omega)$ by $v B M O$ since the predual space of $v B M O$ is not clear.

This chapter is organized as follows. In Section 6.2, we construct a volume potential corresponding to $\operatorname{div} v$. We localize the problem and reduce the problem to small neighborhoods of points on the boundary. Here we invoke the theory established in [12] and Chapter 5 to give a proof to Theorem 6.1.2. In Section 6.3, we establish Lemma 6.1.4 by estimating the single layer potential.

Throughout this chapter, unless otherwise specified, the symbol $C$ in an inequality represents a positive constant independent of quantities that appeared in the inequality. For a fixed $\rho>0, C_{\rho}$ represents a constant depending only on $\rho . C_{n}$ represents a constant depending only on $n$ and $C_{\Omega, n}$ represents a constant depending only on $\Omega$ and $n$.

### 6.2 Volume potential construction in a uniformly $C^{3}$ domain

For $v \in v B M O L^{2}(\Omega)$, we shall construct a suitable potential $q_{1}$ so that $v \longmapsto \nabla q_{1}$ is a bounded linear operator in $v B M O L^{2}$ as stated in Theorem 6.1.2. The construction in the case where $\Omega$ is a uniformly $C^{3}$ domain basically follows from the theory in [12], in which $\Omega$ is assumed to be a bounded $C^{3}$ domain.

### 6.2.1 Localization tools

Let us recall the uniform estimates established in Chapter 5. We denote $x^{\prime}=\left(x_{1}, x_{2}, \ldots, x_{n-1}\right)$ for $x \in \mathbf{R}^{n}$ and $\nabla^{\prime}:=\left(\partial_{1}, \partial_{2}, \ldots, \partial_{n-1}\right)$. Let $\Omega$ be a uniformly $C^{2}$ domain in $\mathbf{R}^{n}$. In other words, there exists $r_{*}, \delta_{*}>0$ such that for each $z_{0} \in \Gamma$, up to translation and rotation, there exists a function $h_{z_{0}}$ which is $C^{2}$ in a closed ball $B_{r_{*}}\left(0^{\prime}\right)$ of radius $r_{*}$ centered at the origin $0^{\prime}$ of $\mathbf{R}^{n-1}$ satisfying following properties:
(i) $K_{\Gamma}:=\sup _{B_{r_{*}}\left(0^{\prime}\right)}\left|\left(\nabla^{\prime}\right)^{s} h_{z_{0}}\right|<\infty$ for $s=0,1,2 ; \nabla^{\prime} h\left(0^{\prime}\right)=0, h\left(0^{\prime}\right)=0$,
(ii) $\Omega \cap U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|h_{z_{0}}\left(x^{\prime}\right)<x_{n}<h_{z_{0}}\left(x^{\prime}\right)+\delta_{*},\left|x^{\prime}\right|<r_{*}\right\}\right.$ for

$$
U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right):=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|h_{z_{0}}\left(x^{\prime}\right)-\delta_{*}<x_{n}<h_{z_{0}}\left(x^{\prime}\right)+\delta_{*},\left|x^{\prime}\right|<r_{*}\right\},\right.
$$

(iii) $\Gamma \cap U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n}\left|x_{n}=h_{z_{0}}\left(x^{\prime}\right),\left|x^{\prime}\right|<r_{*}\right\}\right.$.

We say that $\Omega$ is of type $\left(r_{*}, \delta_{*}, K_{\Gamma}\right)$.
Since $\Omega$ is a uniformly $C^{2}$ domain, there is $R_{*}>0$ such that if $|d(x)|<R_{*}$, there is unique point $\pi x$ such that $|x-\pi x|=|d(x)|$. The supremum of such $R_{*}$ is called the reach of $\Omega$ and $\Omega^{c}$. For $\delta \in\left(0, R_{*}\right]$, we set that

$$
\Gamma^{\delta}:=\left\{x \in \mathbf{R}^{n}| | d(x) \mid<\delta\right\}
$$

and

$$
\Gamma_{\delta}:=\left\{x \in \Omega \mid d_{\Gamma}(x)<\delta\right\}
$$

Moreover, $d$ is $C^{2}$ in the $R_{*}$ neighborhood of $\Gamma$, i.e., $d \in C^{2}\left(\Gamma^{R_{*}}\right)$; see [14, Chap. 14, Appendix], [20, §4.4]. Note that $R_{*}$ satisfies

$$
R_{*}=\min \left(R_{*}^{\Omega}, R_{*}^{\Omega^{c}}\right)
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
where $R_{*}^{\Omega}$ is the reach of $\Gamma$ in $\Omega$ while $R_{*}^{\Omega^{c}}$ is the reach of $\Gamma$ in the complement $\Omega^{c}$ of $\Omega$. Let $K_{\Gamma}^{*}:=\max \left\{K_{\Gamma}, 1\right\}$. There exists $0<\rho_{0}<\min \left(r_{*}, \delta_{*}, \frac{R_{*}}{2}, \frac{1}{2 n K_{\Gamma}^{*}}\right)$ such that

$$
U_{\rho}\left(z_{0}\right):=\left\{x \in \mathbf{R}^{n}\left|(\pi x)^{\prime} \in \operatorname{int} B_{\rho}\left(0^{\prime}\right),|d(x)|<\rho\right\}\right.
$$

is contained in the coordinate chart $U_{r_{*}, \delta_{*}, h_{z_{0}}}\left(z_{0}\right)$ for any $\rho \leq \rho_{0}$.
We next consider the normal coordinate in $U_{\rho_{0}}\left(z_{0}\right)$

$$
x=\psi(\eta)=\left\{\begin{array}{l}
\eta^{\prime}+\eta_{n} \nabla^{\prime} d\left(\eta^{\prime}, h_{z_{0}}\left(\eta^{\prime}\right)\right)  \tag{6.2.1}\\
h_{z_{0}}\left(\eta^{\prime}\right)+\eta_{n} \partial_{x_{n}} d\left(\eta^{\prime}, h_{z_{0}}\left(\eta^{\prime}\right)\right)
\end{array}\right.
$$

or shortly

$$
x=\pi x-d(x) \mathbf{n}(\pi x), \quad \mathbf{n}(\pi x)=-\nabla d(\pi x)
$$

For each $z_{0} \in \Gamma, \psi$ is indeed a local $C^{1}$-diffeomorphism which maps $V_{\rho_{0}}$ to $U_{\rho_{0}}\left(z_{0}\right)$ where $V_{\rho_{0}}:=B_{\rho_{0}}\left(0^{\prime}\right) \times\left(-\rho_{0}, \rho_{0}\right)$. We indeed have that $\psi \in C^{1}\left(V_{\rho_{0}}\right)$ with $\left(\nabla_{\eta} \psi\right)(0)=I$. Let $\varepsilon \in(0,1)$ and $c_{\Omega}^{\varepsilon}:=\min \left\{\frac{\varepsilon}{\left.K_{\Gamma}^{*} \cdot(n+1)!\right)^{2} \cdot 2^{2 n+5}}, \frac{\rho_{0}}{2}\right\}$. Regardless of $z_{0} \in \Gamma$, we can uniformly estimate the gradient of $\psi$ and $\psi^{-1}$ simultaneously.

Proposition 6.2.1 (Chapter 5). Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2$. Then for any $\rho \in\left(0, c_{\Omega}^{\varepsilon}\right]$ and $z_{0} \in \Gamma$, the estimates

$$
\begin{aligned}
\|\nabla F-I\|_{L^{\infty}\left(V_{\rho}\right)} & <\varepsilon \\
\left\|\nabla F^{-1}-I\right\|_{L^{\infty}\left(U_{\rho}\left(z_{0}\right)\right)} & <\varepsilon
\end{aligned}
$$

hold simultaneously.
For $\rho \in\left(0, \rho_{0} / 2\right)$, there exists a locally finite open cover of $\Gamma^{\rho}$, i.e., we have that
Proposition 6.2.2 (Chapter 5). Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain with $n \geq 2$. There exist a countable family of points in $\Gamma$, say $S:=\left\{x_{i} \in \Gamma \mid i \in \mathbf{N}\right\}$, and a natural number $N_{*} \in \mathbf{N}$ such that

$$
\Gamma^{\rho}=\bigcup_{x_{i} \in S} U_{\rho}\left(x_{i}\right)
$$

and for any $x_{j} \in S$, there exist at most $N_{*}$ points in $S$, say $\left\{x_{j_{1}}, \ldots, x_{j_{N_{*}}}\right\} \subset S$, with

$$
U_{\rho}\left(x_{j}\right) \cap U_{\rho}\left(x_{j_{l}}\right) \neq \emptyset
$$

for each $1 \leq l \leq N_{*}$.
Based on this open cover of $\Gamma^{\rho}$, a partition of unity for $\Gamma^{\rho}$ can be constructed as follow.
Proposition 6.2.3 (Chapter 5). There exist $\varphi_{i} \in C^{1}\left(\Gamma^{\rho}\right)$ for each $i \in \mathbf{N}$ and a constant $C_{U}$ such that properties

$$
\begin{align*}
& 0 \leq \varphi_{i} \leq 1 \text { for any } i \in \mathbf{N}, \\
& \operatorname{supp} \varphi_{i} \subset \overline{U_{\rho}\left(x_{i}\right)} \text { for any } i \in \mathbf{N}, \\
& \operatorname{supp} \varphi_{i} \circ \psi \subset B_{\rho}\left(0^{\prime}\right) \times[-\rho, \rho] \\
& \sum_{i=1}^{\infty} \varphi_{i}(x) \equiv 1 \quad \text { for any } \quad x \in \Gamma^{\rho}  \tag{6.2.2}\\
& \sup _{i \in \mathbf{N}}\left\|\nabla \varphi_{i}\right\|_{L^{\infty}\left(\Gamma^{\rho}\right)} \leq C_{U}
\end{align*}
$$

hold.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

### 6.2.2 Cut-off and extension

In general, multiplication by a smooth function to $B M O$ is not bounded in $B M O$. However, such multiplication is bounded in bmo.

Proposition 6.2.4 (Multiplication). Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain, $n \geq 2$. Let $\varphi \in C^{\gamma}(\Omega)$ with $\gamma \in(0,1)$. For each $v \in v B M O L^{2}(\Omega)$, the function $\varphi v \in v B M O L^{2}(\Omega)$ satisfies

$$
\|\varphi v\|_{v B M O L^{2}(\Omega)} \leq C\|\varphi\|_{C \gamma(\Omega)}\|v\|_{v B M O L^{2}(\Omega)}
$$

with $C$ independent of $\varphi$ and $v$.
Proof. Since

$$
[\nabla d \cdot \varphi v]_{b^{\nu}} \leq\|\varphi\|_{L^{\infty}(\Omega)}[\nabla d \cdot v]_{b^{\nu}}
$$

this proposition follows trivially from the product estimate [Theorem 5.1.2, Chapter 5], by which $\|\varphi v\|_{b m o_{\infty}^{\infty}(\Omega)}$ is estimated by the product of $\|\varphi\|_{C^{\gamma}(\Omega)}$ and $\|v\|_{b m o_{\infty}^{\infty}(\Omega)}$ with a constant $C$ independent of $\varphi$ and $v$.

We consider the projection to the direction to $\nabla d$. For $x \in \Gamma^{\rho_{0}}$, we set

$$
P(x)=\nabla d(\pi x) \otimes \nabla d(\pi x)=\mathbf{n}(\pi x) \otimes \mathbf{n}(\pi x)
$$

For later convenience, we set $Q(x)=I-P(x)$ which is the tangential projection for $x \in \Gamma^{\rho_{0}}$. For a function $f$ in $\Gamma^{\rho_{0}} \cap \bar{\Omega}$, let $f_{\text {even }}$ (resp. $f_{\text {odd }}$ ) denote its even (odd) extension to $\Gamma^{\rho_{0}}$ defined by

$$
\begin{aligned}
& f_{\text {even }}(\pi x+d(x) \mathbf{n}(\pi x))=f(\pi x-d(x) \mathbf{n}(\pi x)) \quad \text { for } \quad x \in \Gamma^{\rho_{0}} \backslash \bar{\Omega}, \\
& f_{\text {odd }}(\pi x+d(x) \mathbf{n}(\pi x))=-f(\pi x-d(x) \mathbf{n}(\pi x)) \quad \text { for } \quad x \in \Gamma^{\rho_{0}} \backslash \bar{\Omega} \text {. }
\end{aligned}
$$

We denote $r_{W}$ to be the restriction in $W$ for any subset $W \subset \mathbf{R}^{n}$. Let $f$ be a function (or a vector field) defined in $V_{\sigma}$ for some $\sigma \in(0, \infty]$. We set $E_{\text {even }} f$ to be the even extension of $f$ in $V_{\sigma} \cap \mathbf{R}_{+}^{n}$ to $V_{\sigma}$ with respect to the $n$-th variable, i.e.,

$$
E_{\text {even }} f\left(\eta^{\prime},-\eta_{n}\right)=f\left(\eta^{\prime}, \eta_{n}\right)
$$

for any $\left(\eta^{\prime}, \eta_{n}\right) \in V_{\sigma} \cap \mathbf{R}_{+}^{n}$.
For $v \in v B M O L^{2}(\Omega)$ with $\operatorname{supp} v \subset U_{\rho}\left(z_{0}\right) \cap \bar{\Omega}$, let $\bar{v}$ be its extension of the form

$$
\begin{equation*}
\bar{v}(x):=\left(P v_{\text {odd }}\right)(x)+\left(Q v_{\text {even }}\right)(x) \tag{6.2.3}
\end{equation*}
$$

for $x \in U_{\rho}\left(z_{0}\right)$. Notice that $\operatorname{supp} \bar{v} \subset U_{\rho}\left(z_{0}\right), \bar{v}$ is indeed defined in $\mathbf{R}^{n}$ with $\bar{v}(x)=0$ for any $x \in U_{\rho}\left(z_{0}\right)^{\mathrm{c}}$. Let $c_{\Omega}^{* *}<c_{\Omega}^{\varepsilon} / 96$ be the constant defined in Chapter 5 .

Proposition 6.2.5. Let $\Omega \subset \mathbf{R}^{n}$ be a uniformly $C^{2}$ domain, $z_{0} \in \Gamma$ and $\rho \in\left(0, c_{\Omega}^{* *}\right)$. There exists a constant $C$, independent of $v$ and $\rho$, such that

$$
\begin{aligned}
{[\bar{v}]_{B M O L^{2}\left(\mathbf{R}^{n}\right)} } & \leq \frac{C}{\rho^{n}}\|v\|_{v B M O L^{2}(\Omega)} \\
{[\nabla d \cdot \bar{v}]_{b^{\nu}(\Gamma)} } & \leq \frac{C}{\rho^{n}}\|v\|_{v B M O L^{2}(\Omega)}
\end{aligned}
$$

for all $v \in v B M O L^{2}(\Omega)$ with $\operatorname{supp} v \subset U_{\rho}\left(z_{0}\right) \cap \bar{\Omega}$ and $\nu>0$.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

This proposition is simply the $v B M O L^{2}$ version of [12, Proposition 2$]$.
Proof. By considering the normal coordinate change $y=\psi(\eta)$ in $U_{\rho}\left(z_{0}\right)$, we can deduce that $v_{\text {even }}, v_{\text {odd }} \in L^{2}\left(\mathbf{R}^{n}\right)$ satisfying

$$
\left\|v_{\text {even }}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)}=\left\|v_{\text {odd }}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq 4\|v\|_{L^{2}(\Omega)}
$$

Hence $\bar{v} \in L^{2}\left(\mathbf{R}^{n}\right)$ satisfies the estimate $\|\bar{v}\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C_{n}\|v\|_{L^{2}(\Omega)}$. Hence, this proposition follows from the estimate

$$
\|\bar{u}\|_{B M O\left(\mathbf{R}^{n}\right)}+[\nabla d \cdot \bar{u}]_{b^{\infty}(\Gamma)} \leq \frac{C}{\rho^{n}}\|u\|_{v B M O L^{2}(\Omega)}
$$

which is guaranteed by [Theorem 5.6.3, Chapter 5].

### 6.2.3 Volume potentials

In this subsection, we always assume that $\Omega$ is a uniformly $C^{3}$ domain in $\mathbf{R}^{n}$. Let $\rho \in$ $\left(0, \rho_{*} / 2\right)$ for some sufficiently small $\rho_{*}$ that is to be determined later. We consider a cut off function $\theta \in C_{\mathrm{c}}^{\infty}(\mathbf{R})$ such that $0 \leq \theta \leq 1, \theta(t)=1$ for any $0<|t| \leq 1 / 2$ and $\theta(t)=0$ for any $|t| \geq 1$. Set $\theta_{\rho}:=\theta(d(x) / \rho)$. Note that $\theta_{\rho} \in C^{3}\left(\mathbf{R}^{n}\right)$. We then let $v_{2}:=\theta_{\rho} v$ and $v_{1}:=\left(1-\theta_{\rho}\right) v$. Same proof of [Theorem 5.1.1, Chapter 5] implies that $v_{1} \in B M O L^{2}\left(\mathbf{R}^{n}\right)$ and $v_{2} \in B M O L^{2}\left(\mathbf{R}^{n}\right) \cap b^{\nu}(\Gamma)$.

To construct the mapping $v \mapsto q_{1}$ in Theorem 6.1.2, we localize $v_{2}$ by using the partition of the unity $\left\{\varphi_{i}\right\}_{i=1}^{\infty}$ associated with the covering $\left\{U_{\rho, i}\right\}_{i=1}^{\infty}$ of $\Gamma^{\rho}$. Here for each $i \in \mathbf{N}$, $U_{\rho, i}$ denote $U_{\rho}\left(x_{i}\right)$ in Proposition 6.2.3. The corresponding volume potential to $v_{1}$ can be estimated directly.
Proposition 6.2.6. There exists a constant $C_{\rho}$, which depends on $\rho$ only, such that

$$
\begin{aligned}
\left\|\nabla q_{1}^{1}\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} & \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)} \\
\left\|\nabla q_{1}^{1}\right\|_{L^{\infty}\left(\Gamma_{\rho / 4}^{\mathbf{R}^{n}}\right)} & \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)}
\end{aligned}
$$

for $q_{1}^{1}=E * \operatorname{div} v_{1}$ and $v \in v B M O L^{2}(\Omega)$. In particular,

$$
\left[\nabla q_{1}^{1}\right]_{b^{\nu}(\Gamma)} \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)}
$$

for $\nu<\rho / 4$.
Proof. By the $B M O-B M O$ estimate [7] and Proposition 6.2.4, we have the estimate

$$
\left[\nabla q_{1}^{1}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\left[v_{1}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)}
$$

Consider $x \in \Gamma_{\rho / 4}^{\mathrm{R}^{n}}$. Since $\nabla q_{1}^{1}$ is harmonic in $\Gamma_{\rho / 2}^{\mathrm{R}^{n}}$ and $B_{\frac{\rho}{4}}(x) \subset \Gamma_{\rho / 2}^{\mathrm{R}^{n}}$, the mean value property for harmonic functions implies that

$$
\nabla q_{1}^{1}(x)=\frac{C_{n}}{\rho^{n}} \int_{B_{\frac{\rho}{4}}(x)} \nabla q_{1}^{1}(y) d y
$$

By Hölder's inequality, we can estimate $\left|\nabla q_{1}^{1}(x)\right|$ by $\frac{C_{n}}{\rho^{n / 2}}\left\|\nabla q_{1}^{1}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)}$. Since the convolution with $\nabla^{2} E$ is bounded in $L^{p}$ for any $1<p<\infty$, see e.g. [15, Theorem 5.2.7 and Theorem 5.2.10], we have that

$$
\left\|\nabla q_{1}^{1}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C\left\|v_{1}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C\|v\|_{L^{2}\left(\mathbf{R}^{n}\right)}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Therefore, the estimate

$$
\left|\nabla q_{1}^{1}(x)\right| \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)}
$$

holds for any $x \in \Gamma_{\rho / 4}^{\mathrm{R}^{n}}$.
For $i \in \mathbf{N}$, we extend $\left(r_{\Omega} \varphi_{i}\right) v_{2}$ as in Proposition 6.2 .5 to get $\overline{\left(r_{\Omega} \varphi_{i}\right) v_{2}}$ and set

$$
\overline{v_{2}}:=\sum_{i=1}^{\infty} \overline{\left(r_{\Omega} \varphi_{i}\right) v_{2}}
$$

Indeed, this extension is independent of the choice of $\left\{\varphi_{i}\right\}_{i=1}^{\infty}$ as long as $\left\{\varphi_{i}\right\}_{i=1}^{\infty}$ is a partition of unity for $\Gamma^{\rho}$. We next set

$$
{\overline{v_{2}}}^{\tan }:=Q \overline{v_{2}}=\sum_{i=1}^{\infty} Q\left(\varphi_{i}\left(v_{2}\right)_{\text {even }}\right)
$$

For $i \in \mathbf{N}$, we have that $\varphi_{i} \in C^{2}\left(U_{\rho, i}\right)$. For simplicity of notation, we denote $\varphi_{i}\left(v_{2}\right)_{\text {even }}$ by $v_{2, i}$. Proposition 6.2 .3 and the construction of $v_{2}$ imply that $v_{2, i} \in B M O L^{2}\left(\mathbf{R}^{n}\right)$ with $\operatorname{supp} v_{2, i} \subset U_{\rho, i}$. In addition, we denote $Q v_{2, i}$ by $w_{i}^{\mathrm{tan}}$. Now, we are ready to construct the suitable potential corresponding to

$$
{\overline{v_{2}}}^{\tan }=\sum_{i=1}^{\infty} Q v_{2, i}
$$

Proposition 6.2.7 ([12]). There exists $\rho_{*}>0$ such that if $\rho<\rho_{*} / 2$, then for every $i \in \mathbf{N}$, there exist bounded linear operators $v \longmapsto p_{i, 1}^{\tan }$ and $v \longmapsto p_{i, 2}^{\tan }$ from $v B M O L^{2}(\Omega)$ to $L^{\infty}\left(\mathbf{R}^{n}\right)$ such that

$$
-\Delta p_{i}^{\tan }=\operatorname{div} w_{i}^{\tan } \quad \text { in } U_{2 \rho, i} \cap \Omega
$$

with $p_{i}^{\tan }:=p_{i, 1}^{\mathrm{tan}}+p_{i, 2}^{\mathrm{tan}}, \operatorname{supp} p_{i, 1}^{\mathrm{tan}} \subset U_{2 \rho, i}$. Moreover, there exists a constant $C_{\rho}$, independent of $v$, such that

$$
\begin{aligned}
\left\|\nabla p_{i, 1}^{\tan }\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} & \leq C_{\rho}\left\|v_{2, i}\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} \\
\left\|\nabla p_{i, 2}^{\tan }\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} & \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)} \\
\sup _{x \in \Gamma, r<\rho} \frac{1}{r^{n}} \int_{B_{r}(x)}\left|\nabla d \cdot \nabla p_{i}^{\tan }\right| d y & \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)}
\end{aligned}
$$

This proposition is simply a rewrite of [12, Proposition 4]. Having the estimate for the volume potential near the boundary regarding its tangential component, we are left to handle the contribution from $\bar{v}_{2}^{\text {nor }}:=\bar{v}_{2}-\bar{v}_{2}^{\tan }$. We recall its decomposition

$$
\bar{v}_{2}^{\mathrm{nor}}=\sum_{i=1}^{\infty} P\left(\varphi_{i}\left(v_{2}\right)_{\mathrm{odd}}\right)
$$

For simplicity of notations, we denote $\nabla d \cdot\left(\varphi_{i}\left(v_{2}\right)_{\text {odd }}\right)$ by $g_{i}$ and $P\left(\varphi_{i}\left(v_{2}\right)_{\text {odd }}\right)$ by $w_{i}^{\text {nor }}$ for every $i \in \mathbf{N}$. By this notation $w_{i}^{\text {nor }}=g_{i} \nabla d$. With a similar idea of proof, we can establish the suitable potential corresponding to $\bar{v}_{2}^{\text {nor }}$.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Proposition 6.2.8 ([12]). There exists $\rho_{*}>0$ such that if $\rho<\rho_{*} / 2$, then for every $i \in \mathbf{N}$, there exist bounded linear operators $v \longmapsto p_{i, 1}^{\text {nor }}$ and $v \longmapsto p_{i, 2}^{\text {nor }}$ from $v B M O L^{2}(\Omega)$ to $L^{\infty}\left(\mathbf{R}^{n}\right)$ such that

$$
-\Delta p_{i}^{\text {nor }}=\operatorname{div} w_{i}^{\text {nor }} \text { in } U_{2 \rho, i} \cap \Omega
$$

with $p_{i}^{\text {nor }}:=p_{i, 1}^{\text {nor }}+p_{i, 2}^{\text {nor }}, \operatorname{supp} p_{i, 1}^{\text {nor }} \subset U_{2 \rho, i}$. Moreover, there exists a constant $C_{\rho}$, independent of $v$, such that

$$
\begin{aligned}
\left\|\nabla p_{i, 1}^{\mathrm{nor}}\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} & \leq C_{\rho}\left\|g_{i}\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)}, \\
\left\|\nabla p_{i, 2}^{\text {nor }}\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} & \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)} \\
\sup _{x \in \Gamma, r<\rho} \frac{1}{r^{n}} \int_{B_{r}(x)}\left|\nabla d \cdot \nabla p_{i}^{\text {nor }}\right| d y & \leq C_{\rho}\|v\|_{v B M O L^{2}(\Omega)} .
\end{aligned}
$$

Similarly, this proposition is just a rewrite of [12, Proposition 5]. By these two propositions, we are now ready to prove Theorem 6.1.2.

Proof of Theorem 6.1.2 admitting Proposition 6.2.7 and 6.2.8. Let $i \in \mathbf{N}$. We first consider the contribution from the tangential part. We take a cut-off function $\theta_{i} \in C_{c}^{\infty}\left(U_{2 \rho, i}\right)$ such that $\theta_{i}=1$ on $U_{\rho, i}$ and $0 \leq \theta_{i} \leq 1$. We next set

$$
q_{1, i}^{\tan }:=\theta_{i} p_{i}^{\tan }+E *\left(p_{i}^{\tan } \Delta \theta_{i}+2 \nabla \theta_{i} \cdot \nabla p_{i}^{\tan }\right) .
$$

By definition, Proposition 6.2.7 says that

$$
\begin{aligned}
-\Delta q_{1, i}^{\tan } & =-\Delta\left(\theta_{i} p_{i}^{\tan }\right)+p_{i}^{\tan } \Delta \theta_{i}+2 \nabla \theta_{i} \cdot \nabla p_{i}^{\tan } \\
& =\theta_{i} \operatorname{div} w_{i}^{\tan }=\operatorname{div} w_{i}^{\tan }
\end{aligned}
$$

in $\Omega$ as supp $w_{i}^{\tan } \subset U_{\rho, i}$. We then set

$$
q_{1}^{\tan }:=\sum_{i=1}^{\infty} q_{1, i}^{\tan } .
$$

Since supp $p_{i, 1}^{\text {tan }} \subset U_{2 \rho, i}$, by Proposition 6.2.7 we see that

$$
\sum_{i=1}^{\infty}\left\|\nabla\left(\theta_{i} p_{i, 1}^{\mathrm{tan}}\right)\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C_{\rho} \sum_{i=1}^{\infty}\left\|v_{2, i}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} .
$$

Since our partition of unity for $\Gamma^{\rho}$ is locally finite according to Proposition 6.2.2 and 6.2.3, we can deduce that

$$
\sum_{i=1}^{\infty}\left\|v_{2, i}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq 8 N_{*}\left\|v_{2}\right\|_{L^{2}(\Omega)} \leq 8 N_{*}\|v\|_{L^{2}(\Omega)}
$$

with the constant $N_{*}$ defined in Proposition 6.2.2. Suppose that $B$ is a ball of radius $r(B)<\rho$. If $B$ does not intersect $\Gamma^{2 \rho}$, then

$$
\frac{1}{|B|} \int_{B}\left|\nabla\left(\theta_{i} p_{i, 1}^{\tan }\right)-\left(\nabla\left(\theta_{i} p_{i, 1}^{\tan }\right)\right)_{B}\right| d y=0
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
for each $i \in \mathbf{N}$. If $B$ intersects $\Gamma^{2 \rho}$, then by the proof of [Lemma 5.4.2, Chapter 5], we see that $B$ intersects at most $N_{*}$ neighborhoods of $\left\{U_{2 \rho}\left(x_{i}\right) \mid x_{i} \in S\right\}$. Hence in this case, we have that

$$
\begin{aligned}
\frac{1}{|B|} \int_{B}\left|\sum_{i=1}^{\infty} \nabla\left(\theta_{i} p_{i, 1}^{\mathrm{tan}}\right)-\left(\sum_{i=1}^{\infty} \nabla\left(\theta_{i} p_{i, 1}^{\mathrm{tan}}\right)\right)_{B}\right| d y & \leq \sum_{l=1}^{N_{*}}\left[\nabla\left(\theta_{i_{l}} p_{i_{l}, 1}^{\mathrm{tan}}\right)\right]_{B M O\left(\mathbf{R}^{n}\right)} \\
& \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
\end{aligned}
$$

Thus, we deduce that

$$
\left\|\sum_{i=1}^{\infty} \nabla\left(\theta_{i} p_{i, 1}^{\tan }\right)\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
$$

Since $\operatorname{supp} \theta_{i} p_{i, 2}^{\tan } \subset U_{2 \rho, i}$, by Proposition 6.2.7 and 6.2 .2 we have that

$$
\left[\sum_{i=1}^{\infty} \nabla\left(\theta_{i} p_{i, 2}^{\mathrm{tan}}\right)\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq 2\left\|\sum_{i=1}^{\infty} \nabla\left(\theta_{i} p_{i, 2}^{\mathrm{tan}}\right)\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
$$

In addition, as

$$
\left\|\nabla\left(\theta_{i} p_{i, 2}^{\tan }\right)\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq\left|U_{2 \rho, i}\right|^{1 / 2}\left\|\nabla\left(\theta_{i} p_{i, 2}^{\tan }\right)\right\|_{L^{\infty}\left(\mathbf{R}^{n}\right)} \leq C_{\rho}\left\|v_{2, i}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)},
$$

similar argument as above implies that

$$
\left\|\sum_{i=1}^{\infty} \nabla\left(\theta_{i} p_{i, 2}^{\tan }\right)\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq \sum_{i=1}^{\infty}\left\|\nabla\left(\theta_{i} p_{i, 2}^{\tan }\right)\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C_{\rho} \sum_{i=1}^{\infty}\left\|v_{2, i}\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C_{\rho} N_{*}\|v\|_{L^{2}(\Omega)}
$$

Hence, we obtain that

$$
\begin{equation*}
\left\|\sum_{i=1}^{\infty} \nabla\left(\theta_{i} p_{i}^{\tan }\right)\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)} \tag{6.2.4}
\end{equation*}
$$

Let $f_{i}^{\mathrm{tan}}=p_{i}^{\mathrm{tan}} \Delta \theta_{i}+2 \nabla \theta_{i} \cdot \nabla p_{i}^{\mathrm{tan}}$. Since $\operatorname{supp} f_{i}^{\mathrm{tan}} \subset U_{2 \rho, i}$, we actually have that

$$
\left\|f_{i}^{\tan }\right\|_{L^{1}\left(U_{2 \rho, i}\right)} \leq\left|U_{2 \rho, i}\right|^{1 / 2} \cdot\left\|f_{i}^{\tan }\right\|_{L^{2}\left(U_{2 \rho, i}\right)}
$$

By the same argument in the above paragraph which proves the estimate (6.2.4), we can show that

$$
\left[\sum_{i=1}^{\infty} f_{i}^{\tan }\right]_{B M O\left(\mathbf{R}^{n}\right)}+\sum_{i=1}^{\infty}\left\|f_{i}^{\tan }\right\|_{L^{1}\left(\mathbf{R}^{n}\right)} \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
$$

By an interpolation (cf. [5, Lemma 5], [19, Theorem 2.2], [18, Theorem 1 and Remark 1]), we see that the estimate

$$
\begin{align*}
\left\|\sum_{i=1}^{\infty} f_{i}^{\tan }\right\|_{L^{s}\left(\mathbf{R}^{n}\right)} & \leq C_{n}\left\|_{i=1}^{\infty} f_{i}^{\tan }\right\|_{L^{1}\left(\mathbf{R}^{n}\right)}^{\frac{1}{s}}\left[\sum_{i=1}^{\infty} f_{i}^{\tan }\right]_{B M O\left(\mathbf{R}^{n}\right)}^{1-\frac{1}{s}}  \tag{6.2.5}\\
& \leq C_{n}\left\|\sum_{i=1}^{\infty} f_{i}^{\tan }\right\|_{B M O L^{1}\left(\mathbf{R}^{n}\right)}
\end{align*}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
holds for any $1<s<\infty$. Since $\nabla E$ is in $L^{p^{\prime}}\left(B_{6 \rho}(0)\right)$ for $1<p^{\prime}<n /(n-1)$, it follows that

$$
\sup _{\mathbf{R}^{n}}\left|\nabla E *\left(\sum_{i=1}^{\infty} f_{i}^{\tan }\right)\right| \leq C_{\rho}\left\|\sum_{i=1}^{\infty} f_{i}^{\tan }\right\|_{L^{p}\left(\mathbf{R}^{n}\right)}
$$

Thus, we deduce that

$$
\sup _{\mathbf{R}^{n}}\left|\nabla E *\left(\sum_{i=1}^{\infty} f_{i}^{\tan }\right)\right| \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
$$

By the well-known Hardy-Littlewood-Sobolev inequality, see e.g. [1, Theorem 1.7], the estimate

$$
\left\|\nabla E *\left(\sum_{i=1}^{\infty} f_{i}^{\mathrm{tan}}\right)\right\|_{L^{2}\left(\mathbf{R}^{n}\right)} \leq C\left\|\sum_{i=1}^{\infty} f_{i}^{\mathrm{tan}}\right\|_{L^{r}\left(\mathbf{R}^{n}\right)}
$$

holds with $r=\frac{2 n}{n+2}$. Hence by (6.2.5), we get that

$$
\left\|\nabla E *\left(\sum_{i=1}^{\infty} f_{i}^{\tan }\right)\right\|_{B M O L^{2}\left(\mathbf{R}^{n}\right)} \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
$$

Combine with (6.2.4), we finally obtain that

$$
\left\|\nabla q_{1}^{\tan }\right\|_{B M O L^{2}(\Omega)} \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
$$

By Proposition 6.2.7, the control on the boundary with respect to $q_{1}^{\tan }$ is estimated by

$$
\sup _{x \in \Gamma, r<\rho} \frac{1}{r^{n}} \int_{B_{r}(x)}\left|\nabla d \cdot \nabla q_{1}^{\tan }\right| d y \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
$$

as the partition $\left\{U_{\rho}\left(x_{i}\right) \mid x_{i} \in S\right\}$ is a locally finite open cover of $\Gamma^{\rho}$ according to Proposition 6.2.2.

Set

$$
q_{1, i}^{\mathrm{nor}}:=\theta_{i} p_{i}^{\mathrm{nor}}+E *\left(p_{i}^{\mathrm{nor}} \Delta \theta_{i}+2 \nabla \theta_{i} \cdot \nabla p_{i}^{\mathrm{nor}}\right)
$$

and

$$
q_{1}^{\mathrm{nor}}:=\sum_{i=1}^{\infty} q_{1, i}^{\mathrm{nor}}
$$

By making use of Proposition 6.2.8 and repeating the whole argument above that treats the case for $q_{1}^{\mathrm{tan}}$, we can prove that

$$
\left\|\nabla q_{1}^{\mathrm{nor}}\right\|_{v B M O L^{2}(\Omega)} \leq C_{\rho} N_{*}\|v\|_{v B M O L^{2}(\Omega)}
$$

in the same way. Then we set

$$
q_{1}:=q_{1}^{1}+q_{1}^{\mathrm{tan}}+q_{1}^{\mathrm{nor}}
$$

By our construction we have that

$$
\begin{aligned}
-\Delta q_{1} & =-\Delta q_{1}^{1}-\Delta q_{1}^{\tan }-\Delta q_{1}^{\mathrm{nor}} \\
& =\operatorname{div} v_{1}+\sum_{i=1}^{\infty} \operatorname{div} w_{i}^{\mathrm{tan}}+\sum_{i=1}^{\infty} \operatorname{div} w_{i}^{\mathrm{nor}} \\
& =\operatorname{div}\left(v_{1}+v_{2}\right)=\operatorname{div} v
\end{aligned}
$$

in $\Omega$. We are done.

### 6.3 Neumann problem with bounded data in a perturbed $C^{2}$ half space with small perturbation

We consider the Neumann problem for the Laplace equation in a perturbed $C^{2}$ half space in $\mathbf{R}^{n}$ with $L^{\infty}$-initial data. We shall begin with the half space. Let $E$ be the fundamental solution of $-\Delta$ in $\mathbf{R}^{n}$. A solution of the Neumann problem

$$
\begin{align*}
& \Delta u=0 \text { in } \quad \mathbf{R}_{+}^{n} \\
& \frac{\partial u}{\partial \mathbf{n}}=g \quad \text { on } \quad \partial \mathbf{R}_{+}^{n} \tag{6.3.1}
\end{align*}
$$

is formally given by

$$
\begin{equation*}
u(x)=\int_{\partial \mathbf{R}_{+}^{n}} N(x, y) g(y) d \mathcal{H}^{n-1} \tag{6.3.2}
\end{equation*}
$$

where $N$ denotes the Neumann-Green function. In the case of a half space, it is well-known that

$$
N(x, y)=E(x-y)+E\left(x^{\prime}-y^{\prime}, x_{n}+y_{n}\right)
$$

Its exterior normal derivative $\partial N / \partial \mathbf{n}_{x}$ for $y_{n}=0$ is nothing but the Poisson kernel with the parameter $x_{n}$. By symmetry we observe that

$$
-\frac{\partial}{\partial x_{n}} \int_{\mathbf{R}^{n-1}} E\left(x^{\prime}-y^{\prime}, x_{n}\right) g\left(y^{\prime}\right) d y^{\prime} \rightarrow \frac{1}{2} g\left(x^{\prime}\right)
$$

as $x_{n}>0$ tends to zero. Thus $u$ gives a solution of (6.3.1) formally. The function

$$
E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right):=\int_{\partial \mathbf{R}_{+}^{n}} E\left(x^{\prime}-y^{\prime}, x_{n}\right) g\left(y^{\prime}\right) d y^{\prime}
$$

is called the single layer potential of $g$. For $g \in L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)$, we let $\widetilde{g}\left(x^{\prime}, x_{n}\right):=g\left(x^{\prime}, 0\right)$ for any $x \in \mathbf{R}^{n}$. Natrually, $\widetilde{g} \in L^{\infty}\left(\mathbf{R}^{n}\right)$. Let $1_{\mathbf{R}_{+}^{n}}$ be the characteristic function associated with the half space $\mathbf{R}_{+}^{n}$. In this case, we have that

$$
\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)=\nabla \partial_{x_{n}} E * 1_{\mathbf{R}_{+}^{n}} \tilde{g}
$$

Hence by the $L^{\infty}-B M O$ estimate for the singular integral operator [16, Theorem 4.2.7], we recall the following.
Proposition 6.3.1 ([12]). There exists a constant $C$, independent of $g$, such that

$$
\left[\nabla\left(E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)\right)\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\|g\|_{L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)}
$$

Since $-\partial_{x_{n}}\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)$ is the half of the Poisson integral, i.e.,

$$
-\partial_{x_{n}}\left(E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)\right)=\frac{1}{2} \int_{\mathbf{R}^{n-1}} P_{x_{n}}\left(x^{\prime}-y^{\prime}\right) g\left(y^{\prime}\right) d y^{\prime}
$$

we also have the following.
Proposition 6.3.2 ([12]). The estimate

$$
\left\|\partial_{x_{n}}\left(E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)\right)\right\|_{L^{\infty}\left(\mathbf{R}_{+}^{n}\right)} \leq \frac{1}{2}\|g\|_{L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)}
$$

holds for $g \in L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)$.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

We then seek to establish these estimates for the case where $\Omega$ is a perturbed $C^{2}$ half space with small perturbation. Here and hereafter, we set

$$
\Omega=\mathbf{R}_{h}^{n}=\left\{\left(x^{\prime}, x_{n}\right) \in \mathbf{R}^{n} \mid x_{n}>h\left(x^{\prime}\right)\right\}
$$

with $h \in C_{\mathrm{c}}^{2}\left(\mathbf{R}^{n-1}\right)$ satisfying smallness condition (6.1.2) and $\Gamma=\partial \mathbf{R}_{h}^{n}$. Let $1_{B_{2 R_{h}}\left(0^{\prime}\right)}^{\prime}$ be the characteristic function associated with $B_{2 R_{h}}\left(0^{\prime}\right)$ in $\mathbf{R}^{n-1}$. We define $g_{1}, g_{2} \in L^{\infty}(\Gamma)$ by setting $g_{1}\left(x^{\prime}, h\left(x^{\prime}\right)\right):=1_{B_{2 R_{h}}\left(0^{\prime}\right)}^{\prime}\left(x^{\prime}\right) g\left(x^{\prime}, h\left(x^{\prime}\right)\right)$ and $g_{2}\left(x^{\prime}, h\left(x^{\prime}\right)\right):=g\left(x^{\prime}, h\left(x^{\prime}\right)\right)-g_{1}\left(x^{\prime}, h\left(x^{\prime}\right)\right)$ for any $x^{\prime} \in \mathbf{R}^{n-1}$.

Lemma 6.3.3. Let $\Omega=\mathbf{R}_{h}^{n}$ be a perturbed $C^{2}$ half space in $\mathbf{R}^{n}$ with boundary $\Gamma=\partial \mathbf{R}_{h}^{n}$.
(i) (BMO estimate) There exists a constant $C_{1}$ such that

$$
\begin{equation*}
\left[\nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C_{1}\|g\|_{L^{\infty}(\Gamma)} \tag{6.3.3}
\end{equation*}
$$

for all $g \in L^{\infty}(\Gamma)$.
(ii) ( $L^{\infty}$ estimate for normal component) There exists a constant $C_{2}$ such that

$$
\begin{equation*}
\left\|\nabla d \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)\right\|_{L^{\infty}\left(\Gamma^{\rho_{0}} \cap \Omega\right)} \leq C_{2}\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)} \tag{6.3.4}
\end{equation*}
$$

for all $g \in L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$.
Here $E *\left(\delta_{\Gamma} \otimes g\right)$ is defined as $E *\left(\delta_{\Gamma} \otimes g\right)(x):=\int_{\Gamma} E(x-y) g(y) d \mathcal{H}^{n-1}(y)$ for a function $g$ on $\Gamma$. We shall prove Lemma 6.3.3 in following subsections.

### 6.3.1 $B M O$ estimate

Lemma 6.3.3 (i). We define $\overline{g_{2}} \in L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)$ by setting

$$
\overline{g_{2}}\left(x^{\prime}, 0\right)=\left\{\begin{array}{ll}
g_{2}\left(x^{\prime}, 0\right) & \text { for } \quad\left|x^{\prime}\right| \geq 2 R_{h} \\
0 & \text { for }
\end{array}\left|x^{\prime}\right|<2 R_{h}\right.
$$

By Proposition 6.3.1, the estimate

$$
\left[\nabla\left(E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)\right)\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\left\|\overline{g_{2}}\right\|_{L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

holds with $C$ independent of $g$.
Note that the signed distance function $d$ is $C^{2}$ in $\Gamma^{\rho_{0}}$, see [14, Section 14.6]. Let $\delta<\rho_{0} / 2$. We take a $C^{2}$ cut-off function $\theta \geq 0$ such that $\theta(\sigma)=1$ for $\sigma \leq 1$ and $\theta(\sigma)=0$ for $\sigma \geq 2$. By the choice of $\delta$, we see that $\theta_{d}=\theta(d / \delta)$ is $C^{2}$ in $\mathbf{R}^{n}$. We extend $g_{1} \in L^{\infty}(\Gamma)$ to $g_{1}^{e} \in L^{\infty}\left(\Gamma^{2 \delta}\right)$ by setting

$$
g_{1}^{e}(x):=g_{1}(\pi x)
$$

for any $x \in \Gamma^{2 \delta}$ with $\pi x$ denoting the projection of $x$ on $\Gamma$. For $x \in \Gamma^{2 \delta}$, by considering the normal coordinate $x=\psi(\eta)$ in $U_{2 \delta}(\pi x)$, we have that

$$
\left(\nabla_{x} d\right)_{\psi} \cdot\left(\nabla_{x} g_{1}^{e}\right)_{\psi}=\partial_{\eta_{n}}\left(g_{1}^{e}\right)_{\psi}=0
$$

as $\left(g_{1}^{e}\right)_{\psi}\left(\eta^{\prime}, \alpha\right)=\left(g_{1}^{e}\right)_{\psi}\left(\eta^{\prime}, \beta\right)$ for any $\left|\eta^{\prime}\right|<2 \delta$ and $\alpha, \beta \in(-2 \delta, 2 \delta)$. Hence, we see that $\nabla d \cdot \nabla g_{1}^{e}=0$ in $\Gamma^{2 \delta}$.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Let us consider $g_{1, c}^{e}:=\theta_{d} g_{1}^{e}$. A key observation is that

$$
\begin{aligned}
\delta_{\Gamma} \otimes g_{1} & =\left(\nabla 1_{\Omega} \cdot \nabla d\right) g_{1, c}^{e} \\
& =\operatorname{div}\left(g_{1, c}^{e} 1_{\Omega} \nabla d\right)-1_{\Omega} \operatorname{div}\left(g_{1, c}^{e} \nabla d\right) \\
\operatorname{div}\left(g_{1, c}^{e} \nabla d\right) & =g_{1, c}^{e} \Delta d+\nabla d \cdot \nabla g_{1, c}^{e}=g_{1, c}^{e} \Delta d+\frac{\theta^{\prime}(d / \delta)}{\delta} g_{1}^{e}
\end{aligned}
$$

Thus

$$
\nabla E *\left(\delta_{\Gamma} \otimes g_{1}\right)=\nabla \operatorname{div}\left(E *\left(g_{1, c}^{e} 1_{\Omega} \nabla d\right)\right)-\nabla E *\left(1_{\Omega} g_{1}^{e} f_{\theta, \delta}\right)=I_{1}+I_{2}
$$

where $f_{\theta, \delta}:=\theta_{d} \Delta d+\frac{\theta^{\prime}(d / \delta)}{\delta}$. By the $L^{\infty}-B M O$ estimate for the singular integral operator [16, Theorem 4.2.7], the first term is estimated as

$$
\left[I_{1}\right]_{B M O\left(\mathbf{R}^{n}\right)} \leq C\left\|g_{1, c}^{e} \nabla d\right\|_{L^{\infty}(\Omega)} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

Let $U_{\mathrm{c}}:=\left\{x \in \Gamma^{2 \delta}| |(\pi x)^{\prime} \mid<2 R_{h}\right\}$. Since

$$
A=\sup _{x \in \mathbf{R}^{n} \backslash\{0\}}|x|^{n-1}|\nabla E(x)|<\infty,
$$

for $x \in \mathbf{R}^{n}$ with $d(x, \Omega)=\inf _{y \in \Omega}|x-y|<1$ we have that

$$
\left|I_{2}(x)\right| \leq A \int_{U_{\mathrm{c}}} \frac{1}{|x-y|^{n-1}} d y\left\|f_{\theta, \delta}\right\|_{L^{\infty}\left(U_{\mathrm{c}}\right)}\left\|g_{1}^{e}\right\|_{L^{\infty}\left(U_{\mathrm{c}}\right)} \leq C_{R_{h}, \delta}\|g\|_{L^{\infty}(\Gamma)}
$$

with $C_{R_{h}, \delta}$ depending only on $R_{h}$ and $\delta$. For $x \in \mathbf{R}^{n}$ with $d\left(x, U_{\mathrm{c}}\right)=\inf _{y \in U_{\mathrm{c}}}|x-y| \geq 1$, the above estimate holds trivially as $|x-y|^{-(n-1)} \leq 1$ for any $y \in U_{\mathrm{c}}$. The proof of the first part of Lemma 6.3.3 is now complete.

### 6.3.2 Estimate for normal derivative

We shall estimate normal derivative of $E$.
Lemma 6.3.4. Let $\Omega$ be a perturbed $C^{2}$ half space in $\mathbf{R}^{n}$ with $\Gamma=\partial \Omega, \nu<\rho_{0}$. Then

$$
\begin{equation*}
\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y)=-\frac{1}{2} \quad \text { for } \quad x \in \Gamma_{\nu} \tag{i}
\end{equation*}
$$

(ii)

$$
\sup _{x \in \Gamma_{\nu}} \int_{\Gamma}\left|\frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)\right| d \mathcal{H}^{n-1}(y)<\infty
$$

Proof. (i) This follows from the Gauss divergence theorem. For a bounded smooth domain $D$, we have that

$$
\int_{\partial D} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y)=\int_{D} \Delta_{y} E(x-y) d y
$$

Since $\Delta_{y} E(x-y)=-\delta(x-y)$, we obtain that

$$
\int_{\partial D} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y)=-1
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
for $x \in D$. We take the domain $D_{R}$ as

$$
D_{R}:=\mathbf{R}_{h}^{n} \cap\left\{\left(y, y_{n}\right) \mid y_{n}<\|h\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)}+\epsilon\right\} \cap\left\{\left|y^{\prime}\right|<R\right\}
$$

with $\epsilon>0$. Suppose that $R>R_{h}$. By applying the Gauss divergence theorem in $D_{R}$, we deduce that

$$
\begin{aligned}
-1 & =\int_{\substack{y_{n}=\|h\|_{\infty}+\epsilon,\left|y^{\prime}\right|<R}} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y)+\int_{\substack{y \in \Gamma,\left|y^{\prime}\right|<R}} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y) \\
& +\int_{\substack{0<y_{n}<\|h\|_{\infty}+\epsilon,\left|y^{\prime}\right|=R}} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) d \mathcal{H}^{n-1}(y) .
\end{aligned}
$$

The last term tends to zero naturally as $R \rightarrow \infty$. In the first term, since $\mathbf{n}_{y}$ is pointing upward but $x$ is located below $\left\{\left(y^{\prime}, y_{n}\right) \mid y_{n}=\|h\|_{\infty}+\epsilon\right\}$, the kernel is exactly the half of the Poisson kernel. Hence, the first term tends to $-\frac{1}{2}$ as $R \rightarrow \infty$. We obtain (i).
(ii) Let us observe that

$$
-\mathbf{n}\left(y^{\prime}, h\left(y^{\prime}\right)\right)=\left(-\nabla^{\prime} h\left(y^{\prime}\right), 1\right) / \omega\left(y^{\prime}\right)
$$

with $\omega\left(y^{\prime}\right)=\left(1+\left|\nabla^{\prime} h\left(y^{\prime}\right)\right|^{2}\right)^{1 / 2}$, where $\nabla^{\prime}$ is the gradient in $y^{\prime}$ variables. This implies that

$$
-n \alpha(n) \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)=\frac{\sigma\left(y^{\prime}\right)}{\omega\left(y^{\prime}\right)\left(\left|x^{\prime}-y^{\prime}\right|^{2}+\left(x_{n}-h\left(y^{\prime}\right)\right)^{2}\right)^{n / 2}}
$$

for $y \in \Gamma$ with

$$
\sigma\left(y^{\prime}\right):=-\nabla^{\prime} h\left(y^{\prime}\right) \cdot\left(x^{\prime}-y^{\prime}\right)+\left(x_{n}-h\left(y^{\prime}\right)\right) \text { where } x_{n}>h\left(x^{\prime}\right), x^{\prime}, y^{\prime} \in \mathbf{R}^{n-1}
$$

We set

$$
K\left(x^{\prime}, y^{\prime}, x_{n}\right)=\frac{\sigma\left(y^{\prime}\right)}{\left(\left|x^{\prime}-y^{\prime}\right|^{2}+\left(x_{n}-h\left(y^{\prime}\right)\right)^{2}\right)^{n / 2}}
$$

By the Taylor expansion, for $\left|x^{\prime}-y^{\prime}\right|<1$ we have that

$$
h\left(x^{\prime}\right)=h\left(y^{\prime}\right)+\nabla^{\prime} h\left(y^{\prime}\right) \cdot\left(x^{\prime}-y^{\prime}\right)+r\left(x^{\prime}, y^{\prime}\right)
$$

with

$$
r\left(x^{\prime}, y^{\prime}\right)=\left(x^{\prime}-y^{\prime}\right)^{\mathrm{T}} \cdot \int_{0}^{1}(1-\theta) \nabla^{2} h\left(\theta x^{\prime}+(1-\theta) y^{\prime}\right) d \theta \cdot\left(x^{\prime}-y^{\prime}\right)
$$

We obtain that

$$
\sigma\left(y^{\prime}\right)=x_{n}-h\left(x^{\prime}\right)+r\left(x^{\prime}, y^{\prime}\right)
$$

with an estimate

$$
\begin{equation*}
\left|r\left(x^{\prime}, y^{\prime}\right)\right| \leq\left\|\nabla^{\prime 2} h\right\|_{L^{\infty}\left(B_{1}\left(x^{\prime}\right)\right)}\left|x^{\prime}-y^{\prime}\right|^{2} . \tag{6.3.5}
\end{equation*}
$$

We decompose $K$ into a leading term and a remainder term

$$
K\left(x^{\prime}, y^{\prime}, x_{n}\right)=K_{0}\left(x^{\prime}, y^{\prime}, x_{n}\right)+R\left(x^{\prime}, y^{\prime}, x_{n}\right)
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
with

$$
\begin{aligned}
K_{0}\left(x^{\prime}, y^{\prime}, x_{n}\right) & :=\frac{x_{n}-h\left(x^{\prime}\right)}{\left(\left|x^{\prime}-y^{\prime}\right|^{2}+\left(x_{n}-h\left(y^{\prime}\right)\right)^{2}\right)^{n / 2}} \\
R\left(x^{\prime}, y^{\prime}, x_{n}\right) & :=\frac{r(x, y)}{\left(\left|x^{\prime}-y^{\prime}\right|^{2}+\left(x_{n}-h\left(y^{\prime}\right)\right)^{2}\right)^{n / 2}} .
\end{aligned}
$$

The term $R$ is estimated as

$$
\left|R\left(x^{\prime}, y^{\prime}, x_{n}\right)\right| \leq\left\|\nabla^{\prime 2} h\right\|_{L^{\infty}\left(B_{1}\left(x^{\prime}\right)\right)}\left|x^{\prime}-y^{\prime}\right|^{2-n}
$$

for $\left|x^{\prime}-y^{\prime}\right|<1$ by (6.3.5). Hence,

$$
\int_{\substack{y \in \Gamma,\left|x^{\prime}<y^{\prime}\right|<1}}\left|\frac{R\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega\left(y^{\prime}\right)}\right| d \mathcal{H}^{n-1}(y) \leq C_{n}\left\|\nabla^{2} h\right\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)} .
$$

Since

$$
\left|\sigma\left(y^{\prime}\right)\right| \leq\left|\nabla^{\prime} h\left(y^{\prime}\right)\right| \cdot\left|x^{\prime}-y^{\prime}\right|+\left|x_{n}\right|+\left|h\left(y^{\prime}\right)\right|
$$

for any $y^{\prime} \in \mathbf{R}^{n-1}$, we have that

$$
\begin{align*}
\int_{\substack{y \in \Gamma,\left|y^{\prime}-x^{\prime}\right| \geq 1}}\left|\frac{K\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega\left(y^{\prime}\right)}\right| d \mathcal{H}^{n-1}(y) & \leq \int_{\left|y^{\prime}-x^{\prime}\right| \geq 1}\left|\nabla^{\prime} h\left(y^{\prime}\right)\right| d y^{\prime}+\int_{\left|y^{\prime}-x^{\prime}\right| \geq 1}\left|h\left(y^{\prime}\right)\right| d y^{\prime} \\
& +\int_{\left|y^{\prime}-x^{\prime}\right| \geq 1} \frac{\left|x_{n}\right|}{\left|x^{\prime}-y^{\prime}\right|^{n}} d y^{\prime} . \tag{6.3.6}
\end{align*}
$$

Since the support of $h$ is contained in $\overline{B_{R_{h}}\left(0^{\prime}\right)}$, the first two terms of (6.3.6) can be estimated by $C_{R_{h}, n}\|h\|_{C^{1}\left(\mathbf{R}^{n-1}\right)}$. Note that there exists a constant $C$, independent of $x \in \Gamma_{\nu}$, such that the estimate

$$
\left|x_{n}-h\left(x^{\prime}\right)\right| \leq C \nu
$$

holds for any $x \in \Gamma_{\nu}$. The third term of (6.3.6) is estimated by $C\left(\nu+\|h\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)}\right)$. By (i), we observe that

$$
\begin{aligned}
\frac{n \alpha(n)}{2} & =\int_{\substack{\left|y \in \Gamma,\left|y^{\prime} \in x^{\prime}\right| \geq 1\right.}} \frac{K\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega\left(y^{\prime}\right)} d \mathcal{H}^{n-1}(y)+\int_{\substack{y \in \Gamma \\
\left|y^{\prime}-x^{\prime}\right|<1}} \frac{K_{0}\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega\left(y^{\prime}\right)} d \mathcal{H}^{n-1}(y) \\
& +\int_{\substack{y \in \Gamma,\left|y^{\prime}-x^{\prime}\right|<1}} \frac{R\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega\left(y^{\prime}\right)} d \mathcal{H}^{n-1}(y) .
\end{aligned}
$$

The term $K_{0}$ is very singular but it is positive for $x \in \Gamma_{\nu}$. Hence, we have that

$$
\int_{\substack{y \in \Gamma,\left|y^{\prime}-x^{\prime}\right|<1}} \frac{K_{0}\left(x^{\prime}, y^{\prime}, x_{n}\right)}{\omega\left(y^{\prime}\right)} d \mathcal{H}^{n-1}(y) \leq \frac{n \alpha(n)}{2}+C_{R_{h}, n} \cdot\left(\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}+\nu\right) .
$$

Therefore, we finally obtain the estimate

$$
\int_{\Gamma}\left|\frac{\partial E}{\partial \mathbf{n}_{y}}(x-y)\right| d \mathcal{H}^{n-1}(y) \leq \frac{n \alpha(n)}{2}+C_{R_{h}, n} \cdot\left(\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}+\nu\right),
$$

which holds for any $x \in \Gamma_{\nu}$. The proof of (ii) is now complete.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

### 6.3.3 Review of boundary integral equation

For $g \in L^{\infty}(\Gamma)$, we define the double layer potential

$$
(P g)(x)=\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) g(y) d \mathcal{H}^{n-1}(y), \quad x \in \Gamma_{\nu}
$$

where $\partial / \partial \mathbf{n}_{y}$ denotes the exterior normal derivative with respect to $y$-variable.
Theorem 6.3.5. Assume that $\nu<\rho_{0}$.
(i) There exists a constant $C_{h}$, depending only on $h$, such that

$$
\|P g\|_{L^{\infty}\left(\Gamma_{\nu}\right)} \leq C_{h}\|g\|_{L^{\infty}(\Gamma)}
$$

(ii) The boundary trace is of the form

$$
(\gamma(P g))\left(x^{\prime}, h\left(x^{\prime}\right)\right)=\frac{1}{2} g\left(x^{\prime}, h\left(x^{\prime}\right)\right)-(S g)\left(x^{\prime}, h\left(x^{\prime}\right)\right)
$$

for $g \in L^{\infty}(\Gamma)$, where $S$ is a bounded linear operator on $L^{\infty}(\Gamma)$ satisfying

$$
\|S\|_{L^{\infty}(\Gamma) \rightarrow L^{\infty}(\Gamma)} \leq C_{*}\left(R_{h}^{n-1}+1\right)\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}
$$

with some constant $C_{*}$ independent of $h$ and $g$.
Proof. (i) This follows from the second part of Lemma 6.3.4 directly.
(ii) Suppose that $x \in \Gamma_{\nu}$ with $\left|x^{\prime}\right| \geq 2 R_{h}$. By decomposing $g$ into a straight part and a curved part, we see that

$$
\begin{aligned}
(P g)(x) & =\int_{\left\{y \in \Gamma| | y^{\prime} \mid \geq 2 R_{h}\right\}} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) g_{2}(y) d \mathcal{H}^{n-1}(y) \\
& +\int_{\left\{y \in \Gamma| | y^{\prime} \mid<2 R_{h}\right\}} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) g_{1}(y) d \mathcal{H}^{n-1}(y)=I_{1}(x)+I_{2}(x)
\end{aligned}
$$

Note that

$$
I_{1}(x)=-\int_{\left|y^{\prime}\right| \geq 2 R_{h}} P_{x_{n}}\left(x^{\prime}-y^{\prime}\right) g_{2}\left(y^{\prime}\right) d y^{\prime}=-\int_{\mathbf{R}^{n-1}} P_{x_{n}}\left(x^{\prime}-y^{\prime}\right) \overline{g_{2}}\left(y^{\prime}\right) d y^{\prime}
$$

Let $x$ tends $x_{0}$ on the boundary, in this case we have that $I_{1}$ tends to $\frac{1}{2} \overline{g_{2}}\left(x_{0}\right)$, which is indeed $\frac{1}{2} g\left(x_{0}\right)$. Recall the proof of the second part of Lemma 6.3.4, if $\left|x_{0}^{\prime}\right| \geq 2 R_{h}$ then we have that

$$
\left|I_{2}\left(x_{0}\right)\right| \leq C_{n} R_{h}^{n-1}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}\left(B_{2 R_{h}}\left(0^{\prime}\right)\right)}
$$

For $x_{0} \in \Gamma$ with $\left|x_{0}^{\prime}\right| \geq 2 R_{h}$, by setting

$$
\left(T_{s} g\right)\left(x_{0}\right)=\int_{\left\{y \in \Gamma| | y^{\prime} \mid<2 R_{h}\right\}} \frac{\partial E}{\partial \mathbf{n}_{y}}\left(x_{0}-y\right) g(y) d \mathcal{H}^{n-1}(y)
$$

we get that

$$
(\gamma(P g))\left(x_{0}\right)=\frac{1}{2} g\left(x_{0}\right)+\left(T_{s} g\right)\left(x_{0}\right)
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
with

$$
\left\|T_{s}\right\|_{\mathrm{op}} \leq C_{n} R_{h}^{n-1}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}
$$

Suppose that $x \in \Gamma_{\nu}$ with $\left|x^{\prime}\right|<2 R_{h}$. There exists a bounded $C^{2}$ domain $D_{c} \subset \Omega$ such that $\partial D_{c} \cap \Gamma=\left\{y \in \Gamma| | y^{\prime} \mid<2 R_{h}\right\}$. Let us recall a standard result concerning the double layer potential, see e.g. [17, Lemma 6.17]. Let $f \in L^{\infty}\left(\partial D_{c}\right)$, then the boundary trace of the double layer potential

$$
(Q f)(z)=\int_{\partial D_{c}} \frac{\partial E}{\partial \mathbf{n}_{y}}(z-y) f(y) d \mathcal{H}^{n-1}(y), \quad z \in D_{c}
$$

is of the form

$$
(\gamma(Q f))(w)=\frac{1}{2} f(w)+\int_{\partial D_{c}} \frac{\partial E}{\partial \mathbf{n}_{y}}(w-y) f(y) d \mathcal{H}^{n-1}(y)
$$

for $w \in \partial D_{c}$. We define $g_{c} \in L^{\infty}\left(\partial D_{c}\right)$ by letting

$$
g_{c}(w)= \begin{cases}g_{1}(w) & \text { for } \quad w \in \partial D_{c} \cap \Gamma \\ 0 & \text { for } \quad w \in \partial D_{c} \backslash \Gamma\end{cases}
$$

Without loss of generality, we may assume that $\left\{x \in \Gamma_{\nu}| | x^{\prime} \mid<2 R_{h}\right\} \subset D_{c}$. Thus, for $x \in \Gamma_{\nu}$ with $\left|x^{\prime}\right|<2 R_{h}$, we have that

$$
\left(Q g_{c}\right)(x)=\left(P g_{1}\right)(x)
$$

Let $x$ tends to $x_{0}$ on the boundary, we see that

$$
\left(\gamma\left(P g_{1}\right)\right)\left(x_{0}\right)=\left(\gamma\left(Q g_{c}\right)\right)\left(x_{0}\right)=\frac{1}{2} g\left(x_{0}\right)+\left(T_{c} g\right)\left(x_{0}\right)
$$

where $\left(T_{c} g\right)\left(x_{0}\right)$ is defined as

$$
\left(T_{c} g\right)\left(x_{0}\right)=\int_{\left\{y \in \Gamma| | y^{\prime} \mid<2 R_{h}\right\}} \frac{\partial E}{\partial \mathbf{n}_{y}}\left(x_{0}-y\right) g(y) d \mathcal{H}^{n-1}(y)
$$

Again, the proof of the second part of Lemma 6.3.4 tells us that

$$
\left|T_{c} g\left(x_{0}\right)\right| \leq C_{n} R_{h}^{n-1}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}\left(B_{2 R_{h}}\left(0^{\prime}\right)\right)}
$$

Note that in this case,

$$
\left(\gamma\left(P g_{2}\right)\right)\left(x_{0}\right)=-\int_{\left|y^{\prime}\right| \geq 2 R_{h}} P_{h\left(x_{0}^{\prime}\right)}\left(x_{0}^{\prime}-y^{\prime}\right) g_{2}\left(y^{\prime}\right) d y^{\prime}
$$

By the argument in proof of Lemma 6.3.4 (ii), we can deduce that

$$
\begin{aligned}
\left|\left(\gamma\left(P g_{2}\right)\right)\left(x_{0}\right)\right| & \leq \int_{\left|y^{\prime}-x_{0}^{\prime}\right|<1} \frac{\left\|\nabla^{\prime 2} h\right\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)}}{\left|x_{0}^{\prime}-y^{\prime}\right|^{n-2}} d y^{\prime}+\int_{\left|y^{\prime}-x_{0}^{\prime}\right| \geq 1} \frac{\|h\|_{L^{\infty}\left(\mathbf{R}^{n-1}\right)}}{\left|x_{0}^{\prime}-y^{\prime}\right|^{n}} d y^{\prime} \\
& \leq C_{n}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}(\Gamma)}
\end{aligned}
$$

Therefore, by setting

$$
(S g)\left(x_{0}\right)=-\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}\left(x_{0}-y\right) g(y) d \mathcal{H}^{n-1}(y)
$$

for $x_{0} \in \Gamma$ with $\left|x_{0}^{\prime}\right|<2 R_{h}$ and

$$
(S g)\left(x_{0}\right)=-\int_{\left\{y \in \Gamma| | y^{\prime} \mid<2 R_{h}\right\}} \frac{\partial E}{\partial \mathbf{n}_{y}}\left(x_{0}-y\right) g(y) d \mathcal{H}^{n-1}(y)
$$

for $x_{0} \in \Gamma$ with $\left|x_{0}^{\prime}\right| \geq 2 R_{h}$, we obtain the second part of Theorem 6.3.5.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

### 6.3.4 Solution to the Neumann Problem

We would like to give an essential tool for proving Lemma 6.3.3 (ii). Let us recall that for $f \in H^{\frac{1}{2}}(\Gamma)$ we mean that the norm

$$
\|f\|_{H^{\frac{1}{2}}(\Gamma)}:=\left(\|f\|_{L^{2}(\Gamma)}^{2}+\int_{\Gamma} \int_{\Gamma} \frac{|f(x)-f(y)|^{2}}{|x-y|^{n}} d \mathcal{H}^{n-1}(x) d \mathcal{H}^{n-1}(y)\right)^{\frac{1}{2}}
$$

is finite, see e.g. [24, Section I.3.6]. Our essential tool is a similar result to [13, Lemma 3.2].
Proposition 6.3.6. Let $n \geq 3$. Suppose that $f \in C^{1}\left(\mathbf{R}^{n-1}\right)$ satisfies

$$
\operatorname{supp} f \subset B_{1}\left(0^{\prime}\right)^{\mathrm{c}}, \quad\left|f\left(x^{\prime}\right)\right| \cdot\left|x^{\prime}\right|^{n-1} \leq c_{1}, \quad\left|\nabla^{\prime} f\left(x^{\prime}\right)\right| \cdot\left|x^{\prime}\right|^{n} \leq c_{2}
$$

with some constants $c_{1}$ and $c_{2}$ independent of $x^{\prime} \in \mathbf{R}^{n-1}$. Then the quantity

$$
\|f\|_{L^{2}\left(\mathbf{R}^{n-1}\right)}^{2}+\int_{\mathbf{R}^{n-1}} \int_{\mathbf{R}^{n-1}} \frac{\left|f\left(x^{\prime}\right)-f\left(y^{\prime}\right)\right|^{2}}{\left|x^{\prime}-y^{\prime}\right|^{n}} d x^{\prime} d y^{\prime}
$$

is finite which depends on $n, c_{1}$ and $c_{2}$ only.
Proof. By a direct calculation, we see that

$$
\|f\|_{L^{2}\left(\mathbf{R}^{n-1}\right)}^{2} \leq c_{1} \int_{B_{1}\left(0^{\prime}\right)^{\mathrm{c}}} \frac{1}{\left|y^{\prime}\right|^{2 n-2}} d y^{\prime} \leq C_{n} c_{1}
$$

It is sufficient to estimate

$$
I=\int_{\mathbf{R}^{n-1}} \int_{\mathbf{R}^{n-1}} \frac{\left|f\left(x^{\prime}\right)-f\left(y^{\prime}\right)\right|^{2}}{\left|x^{\prime}-y^{\prime}\right|^{n}} d x^{\prime} d y^{\prime}
$$

We follow the argument that proves [13, Lemma 3.2].
Assume that $\left|x^{\prime}\right| \leq\left|y^{\prime}\right|$ and connect $x^{\prime}$ and $y^{\prime}$ by a geodesic curve in $B_{\left|x^{\prime}\right|}\left(0^{\prime}\right)^{\text {c }}$. Since the curve length is less than $(\pi / 2)\left|x^{\prime}-y^{\prime}\right|$, by a fundamental theorem of calculus, we observe that

$$
\begin{aligned}
\left|f\left(x^{\prime}\right)-f\left(y^{\prime}\right)\right| & \leq(\pi / 2)\left|x^{\prime}-y^{\prime}\right| \cdot \sup \left\{\left|\nabla^{\prime} f\left(z^{\prime}\right)\right| \mid z^{\prime} \in B_{\left|x^{\prime}\right|}\left(0^{\prime}\right)^{\mathrm{c}}\right\} \\
& \leq(\pi / 2) c_{2}\left|x^{\prime}-y^{\prime}\right| \cdot\left|x^{\prime}\right|^{-n}
\end{aligned}
$$

Since the integrand of $I$ is symmetric with respect to $x^{\prime}$ and $y^{\prime}$, we now estimate

$$
\frac{I}{2}=\iint_{D_{1}}+\iint_{D_{2}} \frac{\left|f\left(x^{\prime}\right)-f\left(y^{\prime}\right)\right|^{2}}{\left|x^{\prime}-y^{\prime}\right|^{n}} d x^{\prime} d y^{\prime}=I_{1}+I_{2}
$$

with

$$
\begin{aligned}
& D_{1}=\left\{\left(x^{\prime}, y^{\prime}\right)\left|1 \leq\left|x^{\prime}\right| \leq\left|y^{\prime}\right|,\left|x^{\prime}-y^{\prime}\right| \leq\left|x^{\prime}\right|\right\}\right. \\
& D_{2}=\left\{\left(x^{\prime}, y^{\prime}\right)\left|1 \leq\left|x^{\prime}\right| \leq\left|y^{\prime}\right|,\left|x^{\prime}-y^{\prime}\right| \geq\left|x^{\prime}\right|\right\}\right.
\end{aligned}
$$

To estimate $I_{1}$, we observe that

$$
\begin{aligned}
\frac{\left|f\left(x^{\prime}\right)-f\left(y^{\prime}\right)\right|^{2}}{\left|x^{\prime}-y^{\prime}\right|^{n}} & \leq(\pi / 2) c_{2}\left|x^{\prime}\right|^{-2 n}\left|x^{\prime}-y^{\prime}\right|^{-(n-2)} \\
& \leq(\pi / 2) c_{2}\left|x^{\prime}\right|^{-2 n+1+\delta}\left|x^{\prime}-y^{\prime}\right|^{-(n-2)-1-\delta}
\end{aligned}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
for $0<\delta<1$ since $\left|x^{\prime}-y^{\prime}\right| \leq\left|x^{\prime}\right|$. Thus,

$$
\begin{aligned}
I_{1} & \leq(\pi / 2) c_{2} \int_{B_{1}\left(0^{\prime}\right)^{\mathrm{c}}} \int_{B_{1}\left(x^{\prime}\right)}\left|y^{\prime}-x^{\prime}\right|^{-(n-2)} d y^{\prime}\left|x^{\prime}\right|^{-2 n} d x^{\prime} \\
& +(\pi / 2) c_{2} \int_{B_{1}\left(0^{\prime}\right)^{c}} \int_{B_{1}\left(x^{\prime}\right)^{c}}\left|y^{\prime}-x^{\prime}\right|^{-(n-2)-1-\delta} d y^{\prime}\left|x^{\prime}\right|^{-2 n+1+\delta} d x^{\prime}<\infty .
\end{aligned}
$$

To estimate $I_{2}$, we observe that

$$
\frac{\left|f\left(x^{\prime}\right)-f\left(y^{\prime}\right)\right|^{2}}{\left|x^{\prime}-y^{\prime}\right|^{n}} \leq 2 \frac{\left|f\left(x^{\prime}\right)\right|^{2}+\left|f\left(y^{\prime}\right)\right|^{2}}{\left|x^{\prime}-y^{\prime}\right|^{n}} \leq 4 c_{1}\left|x^{\prime}-y^{\prime}\right|^{-n}\left|x^{\prime}\right|^{-(2 n-2)}
$$

since $\left|x^{\prime}\right| \leq\left|y^{\prime}\right|$. Since $\left|x^{\prime}-y^{\prime}\right| \geq\left|x^{\prime}\right|$ in this case, we have that

$$
\left|x^{\prime}-y^{\prime}\right|^{-n}\left|x^{\prime}\right|^{-(2 n-2)} \leq\left|x^{\prime}-y^{\prime}\right|^{-(n-2)}\left|x^{\prime}\right|^{-2 n} .
$$

and

$$
\left|x^{\prime}-y^{\prime}\right|^{-n}\left|x^{\prime}\right|^{-(2 n-2)} \leq\left|x^{\prime}-y^{\prime}\right|^{-(n-\delta)}\left|x^{\prime}\right|^{-(2 n-2)-\delta}
$$

for $0<\delta<1$. Hence,

$$
\begin{aligned}
I_{2} & \leq 4 c_{1} \int_{B_{1}\left(0^{\prime}\right)^{\mathrm{c}}} \int_{B_{1}\left(x^{\prime}\right)}\left|y^{\prime}-x^{\prime}\right|^{-(n-2)} d y^{\prime}\left|x^{\prime}\right|^{-2 n} d x^{\prime} \\
& +4 c_{1} \int_{B_{1}\left(0^{\prime}\right)^{\mathrm{c}}} \int_{B_{1}\left(x^{\prime}\right)^{c}}\left|y^{\prime}-x^{\prime}\right|^{-(n-\delta)} d y^{\prime}\left|x^{\prime}\right|^{-(2 n-2)-\delta} d x^{\prime}<\infty .
\end{aligned}
$$

Now we are ready to give a proof to Lemma 6.3.3 (ii).
Proof of Lemma 6.3.3 (ii). Let $x \in \Gamma_{\rho_{0}}$. Suppose that $\left|x^{\prime}\right| \geq R_{h}$. In this case, we decompose

$$
\begin{aligned}
\nabla d(x) \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)(x) & =\partial_{x_{n}}\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)(x) \\
& =\partial_{x_{n}}\left(E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)\right)(x)+\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) g_{1}(y) d \mathcal{H}^{n-1}(y) .
\end{aligned}
$$

By Proposition 6.3.2, we see that

$$
\left|\partial_{x_{n}}\left(E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)\right)(x)\right| \leq \frac{1}{2}\left\|\overline{g_{2}}\right\|_{L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)} \leq \frac{1}{2}\|g\|_{L^{\infty}(\Gamma)} .
$$

By Lemma 6.3.4 (ii), we have that

$$
\left|\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) g_{1}(y) d \mathcal{H}^{n-1}(y)\right| \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

Thus for $x \in \Gamma_{\rho_{0}}$ with $\left|x^{\prime}\right| \geq R_{h}$, we show that

$$
\left|\nabla d(x) \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g\right)\right)(x)\right| \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

with $C$ independent of $g$.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Suppose that $\left|x^{\prime}\right|<R_{h}$. We decompose

$$
\begin{aligned}
\nabla d(x) \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g_{1}\right)\right)(x)=\int_{\Gamma}(\nabla d(x)- & \nabla d(y)) \cdot \nabla E(x-y) g_{1}(y) d \mathcal{H}^{n-1}(y) \\
& +\int_{\Gamma} \frac{\partial E}{\partial \mathbf{n}_{y}}(x-y) g_{1}(y) d \mathcal{H}^{n-1}(y)=I_{1}+I_{2}
\end{aligned}
$$

For $\left|y^{\prime}\right|<2 R_{h}$, there exists a constant $M$, independent of $x$ and $y$, such that the estimate

$$
|\nabla d(x)-\nabla d(y)| \leq M|x-y|
$$

holds. In this case, we have that
$\left|\int_{\Gamma}(\nabla d(x)-\nabla d(y)) \cdot \nabla E(x-y) g_{1}(y) d \mathcal{H}^{n-1}(y)\right| \leq C_{n} M \int_{\left|y^{\prime}\right|<2 R_{h}} \frac{1}{\left|x^{\prime}-y^{\prime}\right|^{n-2}} d y^{\prime}\|g\|_{L^{\infty}(\Gamma)}$.
Thus, $\left|I_{1}(x)\right|$ is estimated by $C_{n} M R_{h}\|g\|_{L^{\infty}(\Gamma)}$. By Lemma 6.3 .4 (ii), $\left|I_{2}(x)\right|$ is estimated by $C\|g\|_{L^{\infty}(\Gamma)}$.

We define that

$$
H_{x}\left(y^{\prime}\right):=\left(\nabla d(x) \cdot \nabla E\left(\left(y^{\prime}, h\left(y^{\prime}\right)\right)-x\right)\right) 1_{B_{R_{h}}\left(x^{\prime}\right)^{\mathrm{c}}}\left(y^{\prime}\right)
$$

for $y^{\prime} \in \mathbf{R}^{n-1}$. With this notation, we have that

$$
\left|\nabla d(x) \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g_{2}\right)\right)(x)\right| \leq \int_{\mathbf{R}^{n-1}}\left|H_{x}\left(y^{\prime}\right) g\left(y^{\prime}, h\left(y^{\prime}\right)\right)\right| d y^{\prime}
$$

Note that $H_{x}\left(\cdot^{\prime}\right) \in C^{1}\left(\mathbf{R}^{n-1}\right)$ satisfies

$$
\operatorname{supp} H_{x}\left(\cdot^{\prime}\right) \subset B_{R_{h}}\left(x^{\prime}\right)^{\mathrm{c}}, \quad\left|H_{x}\left(y^{\prime}\right)\right| \cdot\left|x^{\prime}-y^{\prime}\right|^{n-1} \leq c_{1}, \quad\left|\nabla_{y^{\prime}}^{\prime} H_{x}\left(y^{\prime}\right)\right| \cdot\left|x^{\prime}-y^{\prime}\right|^{n} \leq c_{2}
$$

with some constant $c_{1}$ and $c_{2}$ independent of $x^{\prime}, y^{\prime} \in \mathbf{R}^{n-1}$. By Proposition 6.3.6, we deduce that $H_{x}\left(\cdot^{\prime}\right) \in H^{\frac{1}{2}}(\Gamma)$. By the duality relation, we see that

$$
\left|\nabla d(x) \cdot \nabla\left(E *\left(\delta_{\Gamma} \otimes g_{2}\right)\right)(x)\right| \leq\left\|H_{x}\left(\cdot^{\prime}\right)\right\|_{H^{\frac{1}{2}}(\Gamma)}\|g\|_{H^{-\frac{1}{2}}(\Gamma)} \leq C_{n}\|g\|_{H^{-\frac{1}{2}}(\Gamma)} .
$$

Combining all estimates above regarding different $x^{\prime} \in \mathbf{R}^{n-1}$, we are done.
Finally, if we can show that $S g \in H^{-\frac{1}{2}}(\Gamma)$ for $g \in L^{\infty}(\Gamma)$ with the operator norm

$$
\|S\|_{L^{\infty}(\Gamma) \rightarrow H^{-\frac{1}{2}}(\Gamma)}
$$

sufficiently small, then we solve Neumann problem (6.1.4). Fortunately, we have an affirmative answer to this question.

Lemma 6.3.7. For $g \in L^{\infty}(\Gamma)$, we have that $S g \in L^{2}(\Gamma)$ satisfies the estimate

$$
\|S g\|_{L^{2}(\Gamma)} \leq C^{*}\left(\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}+1\right)\left(R_{h}^{n-1}+1\right) R_{h}^{\frac{n-1}{2}}\|g\|_{L^{\infty}(\Gamma)}
$$

with some constant $C^{*}$ independent of $h$ and $g$.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Proof. Let $x \in \Gamma$ with $\left|x^{\prime}\right|<3 R_{h}$. Since

$$
\|S g\|_{L^{\infty}(\Gamma)} \leq C_{*}\left(R_{h}^{n-1}+1\right)\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}(\Gamma)}
$$

by Theorem 6.3.5 (ii), we have that

$$
\left(\int_{\left\{x \in \Gamma| | x^{\prime} \mid<3 R_{h}\right\}}|S g(z)|^{2} d \mathcal{H}^{n-1}(z)\right)^{\frac{1}{2}} \leq C_{*, h}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}(\Gamma)} \mu\left(\left\{x \in \Gamma| | x^{\prime} \mid<3 R_{h}\right\}\right)^{\frac{1}{2}}
$$

where $\mu\left(\left\{x \in \Gamma\left|\left|x^{\prime}\right|<3 R_{h}\right\}\right)\right.$ denotes the surface area of $\left\{x \in \Gamma\left|\left|x^{\prime}\right|<3 R_{h}\right\}\right.$ and $C_{*, h}:=$ $C_{*}\left(R_{h}^{n-1}+1\right)$. Thus,

$$
\left(\int_{\left\{x \in \Gamma| | x^{\prime} \mid<3 R_{h}\right\}}|S g(z)|^{2} d \mathcal{H}^{n-1}(z)\right)^{\frac{1}{2}} \leq C_{*, h} R_{h}^{\frac{n-1}{2}}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}(\Gamma)} .
$$

Suppose that $x \in \Gamma$ with $\left|x^{\prime}\right| \geq 3 R_{h}$. For $y \in \Gamma$ with $\left|y^{\prime}\right|<2 R_{h}$, the triangle inequality implies that $\left|x^{\prime}-y^{\prime}\right| \geq\left|x^{\prime}\right|-2 R_{h}$. In this case, we have that

$$
|S g(x)| \leq \int_{\left\{\left|y^{\prime}\right|<2 R_{h}\right\}} \frac{1}{\left|x^{\prime}-y^{\prime}\right|^{n-1}} d y^{\prime}\|g\|_{L^{\infty}(\Gamma)} \leq \frac{\left|B_{2 R_{h}}\left(0^{\prime}\right)\right| \cdot\|g\|_{L^{\infty}(\Gamma)}}{\left(\left|x^{\prime}\right|-2 R_{h}\right)^{n-1}} .
$$

Hence,

$$
\int_{\left\{x \in \Gamma| | x^{\prime} \mid \geq 3 R_{h}\right\}}|S g(x)|^{2} d \mathcal{H}^{n-1}(x) \leq C R_{h}^{2(n-1)}\|g\|_{L^{\infty}(\Gamma)}^{2} \cdot \int_{\left\{\left|x^{\prime}\right| \geq 3 R_{h}\right\}} \frac{1}{\left(\left|x^{\prime}\right|-2 R_{h}\right)^{2(n-1)}} d x^{\prime}
$$

Assume that $R_{h}<1$. We have that

$$
\int_{\left\{\left|x^{\prime}\right| \geq 3 R_{h}\right\}} \frac{1}{\left(\left|x^{\prime}\right|-2 R_{h}\right)^{2(n-1)}} d x^{\prime} \leq C \int_{R_{h}}^{\infty} \frac{\left(r+2 R_{h}\right)^{n-2}}{r^{2 n-2}} d r \leq C \sum_{i=0}^{n-2} R_{h}^{n-2-i} \int_{R_{h}}^{\infty} \frac{r^{i}}{r^{2 n-2}} d r .
$$

Therefore, we obtain that

$$
\left(\int_{\left\{x \in \Gamma| | x^{\prime} \mid \geq 3 R_{h}\right\}}|S g(x)|^{2} d \mathcal{H}^{n-1}(x)\right)^{\frac{1}{2}} \leq C R_{h}^{\frac{n-1}{2}}\|g\|_{L^{\infty}(\Gamma)} .
$$

Since $L^{2}(\Gamma) \subset H^{-\frac{1}{2}}(\Gamma)$ is a natural embedding, for $g \in L^{\infty}(\Gamma)$ we have that $S g \in$ $H^{-\frac{1}{2}}(\Gamma)$ satisfies the estimate

$$
\|S g\|_{H^{-\frac{1}{2}}(\Gamma)} \leq C^{*}\left(\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}+1\right)\left(R_{h}^{n-1}+1\right) R_{h}^{\frac{n-1}{2}}\|g\|_{L^{\infty}(\Gamma)}
$$

with some constant $C^{*}$ independent of $h$ and $g$.
Proof of Lemma 6.1.4. For $i \in \mathbf{N}$, we have that

$$
\begin{aligned}
\left\|(2 S)^{i} g\right\|_{H^{-\frac{1}{2}}(\Gamma)} & \leq 2 C^{*}\left(\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}+1\right)\left(R_{h}^{n-1}+1\right) R_{h}^{\frac{n-1}{2}}\left\|(2 S)^{i-1} g\right\|_{L^{\infty}(\Gamma)} \\
& \leq\left(2 C^{*}\left(\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}+1\right) R_{h}^{\frac{n-1}{2}}\right) 2^{i-1} C_{*}^{i-1}\left(R_{h}^{n-1}+1\right)^{i}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}^{i-1}\|g\|_{L^{\infty}(\Gamma)}
\end{aligned}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
and

$$
\left\|(2 S)^{i} g\right\|_{L^{\infty}(\Gamma)} \leq 2^{i} C_{*}^{i}\left(R_{h}^{n-1}+1\right)^{i}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}^{i}\|g\|_{L^{\infty}(\Gamma)}
$$

Let the perturbation $h$ be sufficiently small so that

$$
\left(R_{h}^{n-1}+1\right)\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}<\frac{1}{2 C_{*}}
$$

with $C_{*}$ defined in Theorem 6.3 .5 (ii). Then the operator $I-2 S$, which is bounded linear from $L^{\infty}(\Gamma)$ to $L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$, has a bounded inverse by a standard Neumann series argument. The inverse of $I-2 S$ can be constructed as

$$
(I-2 S)^{-1}=\sum_{i=0}^{\infty}(2 S)^{i}
$$

which is well-defined as a bounded linear map from $L^{\infty}(\Gamma)$ to $L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$ since the operator norm

$$
\|2 S\|_{L^{\infty}(\Gamma) \rightarrow L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}<1 .
$$

Therefore, for $g \in L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$, the solution to the Neumann problem (6.1.4) is formally given by

$$
u(x)=E *\left(\delta_{\Gamma} \otimes\left(2(I-2 S)^{-1} g\right)\right)(x), \quad x \in \Omega
$$

since $P g$ is harmonic in $\Omega$.
If the $L^{2}$ estimate

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes\left(2(I-2 S)^{-1} g\right)\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\left\|2(I-2 S)^{-1} g\right\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

holds, then we are done. Fortunately, we indeed have this $L^{2}$ estimate, we shall give a proof to this estimate in the next subsection. Combine this estimate with Lemma 6.3.3, we obtain our desired estimate

$$
\|\nabla u\|_{v B M O L^{2}(\Omega)} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

with a constant $C$ independent of $g$.

### 6.3.5 $L^{2}$ estimate to the solution of the Neumann problem

Firstly, we start with the half space case.
Proposition 6.3.8. For $g \in H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)$ satisfying

$$
\int_{\partial \mathbf{R}_{+}^{n}} g(y) d \mathcal{H}^{n-1}(y)=0
$$

the estimate

$$
\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq C\|g\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)}
$$

holds with some constant $C$ independent of $g$.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Proof. Since

$$
E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)=\int_{\mathbf{R}^{n-1}} E\left(x^{\prime}-y^{\prime}, x_{n}\right) g\left(y^{\prime}\right) d y^{\prime}
$$

the single layer potential $E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)$ is exactly half of the solution to the Neumann problem (6.3.1). Since $g \in H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)$ satisfying

$$
\int_{\partial \mathbf{R}_{+}^{n}} g(y) d \mathcal{H}^{n-1}(y)=0
$$

there exists a unique weak solution (up to an additive constant) $u_{*} \in H^{1}\left(\mathbf{R}_{+}^{n}\right)$ to the Neumann problem (6.3.1) which satisfies

$$
\left\|\nabla u_{*}\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq C\|g\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)}
$$

with $C$ independent of $g$, see e.g. [26, Remark 1.2 and Remark 1.3], [21, Section 1.7]. Therefore, the single layer potential $2 E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)$ indeed differs from $u_{*}$ by an additive constant. We do have that

$$
\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes g\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}}=\frac{1}{2}\left\|\nabla u_{*}\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq C\|g\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)} .
$$

We then generalize this result to any perturbed half space $\mathbf{R}_{h}^{n}$.
Lemma 6.3.9. Let $\Omega=\mathbf{R}_{h}^{n}$ be a perturbed $C^{2}$ half space with $\Gamma=\partial \Omega$. For any $g \in$ $L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$ that satisfies

$$
\int_{\Gamma} g(y) d \mathcal{H}^{n-1}(y)=0
$$

the estimate

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

holds with some constant $C$ independent of $g$.
Proof. Without loss of generality, we may assume that $\operatorname{supp} h \subset B_{M_{h}}\left(0^{\prime}\right)$ for some $M_{h}>0$. We set

$$
g_{1}\left(y^{\prime}, h\left(y^{\prime}\right)\right):=1_{B_{2 M_{h}}\left(0^{\prime}\right)}\left(y^{\prime}\right) g\left(y^{\prime}, h\left(y^{\prime}\right)\right), \quad g_{2}\left(y^{\prime}, h\left(y^{\prime}\right)\right):=g\left(y^{\prime}, h\left(y^{\prime}\right)\right)-g_{1}\left(y^{\prime}, h\left(y^{\prime}\right)\right)
$$

for any $y^{\prime} \in \mathbf{R}^{n-1}$. Since $g \in L^{\infty}(\Gamma)$, it is trivial to see that $g_{1} \in L^{2}(\Gamma) \subset H^{-\frac{1}{2}}(\Gamma)$. Hence, we deduce that $g_{1}, g_{2} \in L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)$. Since $\operatorname{supp} g_{1}\left(.^{\prime}, h\left(\cdot^{\prime}\right)\right) \subset B_{2 M_{h}}\left(0^{\prime}\right)$, there exists a constant $I_{c} \in \mathbf{R}$ such that

$$
I_{c}=\int_{\Gamma} g_{1}(y) d \mathcal{H}^{n-1}(y)=-\int_{\Gamma} g_{2}(y) d \mathcal{H}^{n-1}
$$

Let $\overline{g_{2}} \in L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)$ be defined by

$$
\overline{g_{2}}\left(x^{\prime}, 0\right)=\left\{\begin{array}{lll}
g_{2}\left(x^{\prime}, 0\right) & \text { for } & \left|x^{\prime}\right| \geq 2 M_{h} \\
0 & \text { for } & \left|x^{\prime}\right|<2 M_{h}
\end{array}\right.
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Note that $T: \eta \mapsto \zeta$ with $\zeta\left(y^{\prime}, h\left(y^{\prime}\right)\right)=\eta\left(y^{\prime}, 0\right)$ for any $y^{\prime} \in \mathbf{R}^{n-1}$ is an isomorphism between $H^{\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)$ and $H^{\frac{1}{2}}(\Gamma)$. For any $\eta \in H^{\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)$, we have that

$$
\int_{\partial \mathbf{R}_{+}^{n}} \overline{g_{2}}(y) \eta(y) d \mathcal{H}^{n-1}(y)=\int_{\Gamma} g_{2}(y) \zeta(y) d \mathcal{H}^{n-1}(y)
$$

By considering

$$
\left\|\overline{g_{2}}\right\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)}=\sup _{\|\eta\|_{H^{\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)} \leq 1}\left|\int_{\partial \mathbf{R}_{+}^{n}} \overline{g_{2}}(y) \eta(y) d \mathcal{H}^{n-1}(y)\right|
$$

we can deduce that $\overline{g_{2}} \in H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)$ satisfies the estimate

$$
\left\|\overline{g_{2}}\right\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)} \leq C\left\|g_{2}\right\|_{H^{-\frac{1}{2}}(\Gamma)} \leq C\|g\|_{H^{-\frac{1}{2}}(\Gamma)}
$$

with $C$ independent of $g$. Let $f_{s} \in L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right) \cap H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)$ be defined by

$$
f_{s}\left(x^{\prime}, 0\right)=\left\{\begin{array}{lll}
0 & \text { for } & \left|x^{\prime}\right| \geq 2 M_{h} \\
\frac{I_{c}}{\left|B_{2 M_{h}}\left(0^{\prime}\right)\right|} & \text { for } & \left|x^{\prime}\right|<2 M_{h}
\end{array}\right.
$$

where $\left|B_{2 M_{h}}\left(0^{\prime}\right)\right|$ denotes the size of the ball $B_{2 M_{h}}\left(0^{\prime}\right)$ in $\mathbf{R}^{n-1}$. Note that

$$
\int_{\partial \mathbf{R}_{+}^{n}} \overline{g_{2}}(y)+f_{s}(y) d \mathcal{H}^{n-1}(y)=0
$$

Let us recall an argument from the proof of Lemma 6.3 .3 (i). Let $\delta<\rho_{0} / 2<R_{*} / 2$. We take a $C^{2}$ cut-off function $\theta \geq 0$ such that $\theta(\sigma)=1$ for $\sigma \leq 1$ and $\theta(\sigma)=0$ for $\sigma \geq 2$. By the choice of $\delta$, we see that $\theta_{d}=\theta(d / \delta)$ is $C^{2}$ in $\mathbf{R}^{n}$. We extend $g_{1} \in L^{\infty}(\Gamma)$ to $g_{1}^{e} \in L^{\infty}\left(\Gamma^{2 \delta}\right)$ by setting

$$
g_{1}^{e}(x):=g_{1}(\pi x)
$$

for any $x \in \Gamma^{2 \delta}$ with $\pi x$ denoting the projection of $x$ on $\Gamma$. As explained in the proof of Lemma 6.3.3 (i), we have that $\nabla d \cdot \nabla g_{1}^{e}=0$ in $\Gamma^{2 \delta}$. Set $g_{1, c}^{e}:=\theta_{d} g_{1}^{e}$. Since

$$
\begin{aligned}
\delta_{\Gamma} \otimes g_{1} & =\left(\nabla 1_{\Omega} \cdot \nabla d\right) g_{1, c}^{e} \\
& =\operatorname{div}\left(g_{1, c}^{e} 1_{\Omega} \nabla d\right)-1_{\Omega} \operatorname{div}\left(g_{1, c}^{e} \nabla d\right) \\
\operatorname{div}\left(g_{1, c}^{e} \nabla d\right) & =g_{1, c}^{e} \Delta d+\nabla d \cdot \nabla g_{1, c}^{e}=g_{1, c}^{e} \Delta d+\frac{\theta^{\prime}(d / \delta)}{\delta} g_{1}^{e}
\end{aligned}
$$

for any $x \in \mathbf{R}^{n}$ we have that

$$
\nabla E *\left(\delta_{\Gamma} \otimes g_{1}\right)(x)=\nabla \operatorname{div}\left(E *\left(g_{1, c}^{e} 1_{\Omega} \nabla d\right)\right)(x)-\nabla E *\left(1_{\Omega} g_{1}^{e} f_{\theta, \delta}\right)(x)=I_{1}(x)+I_{2}(x)
$$

where $f_{\theta, \delta}:=\theta_{d} \Delta d+\frac{\theta^{\prime}(d / \delta)}{\delta}$. Since $\nabla \operatorname{div} E$ is bounded in $L^{p}$ for $1<p<\infty$, see e.g. [15, Theorem 5.2.7 and Theorem 5.2.10], we deduce that

$$
\left\|I_{1}\right\|_{\left(L^{2}\left(\mathbf{R}^{n}\right)^{n}\right.} \leq C\left\|g_{1, c}^{e} 1_{\Omega} \nabla d\right\|_{\left(L^{2}\left(\mathbf{R}^{n}\right)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

as $\operatorname{supp} g_{1, c}^{e} \subset\left\{x \in \mathbf{R}^{n}| | d(x)\left|<2 \delta,\left|(\pi x)^{\prime}\right|<2 M_{h}\right\}\right.$. Since $\left.\nabla E \sim|\cdot|\right|^{1-n}$, by the famous Hardy-Littlewood-Sobolev inequality, see e.g. [1, Theorem 1.7], we have that

$$
\left\|I_{2}\right\|_{\left(L^{2}\left(\mathbf{R}^{n}\right)\right)^{n}} \leq C\left\|1_{\Omega} g_{1}^{e} f_{\theta, \delta}\right\|_{L^{r}\left(\mathbf{R}^{n}\right)}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation
where $r=\frac{2 n}{n+2}$. As supp $g_{1}^{e} f_{\theta, \delta} \subset\left\{x \in \mathbf{R}^{n}| | d(x)\left|<2 \delta,\left|(\pi x)^{\prime}\right|<2 M_{h}\right\}\right.$, the estimate

$$
\left\|1_{\Omega} g_{1}^{e} f_{\theta, \delta}\right\|_{L^{r}\left(\mathbf{R}^{n}\right)} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

holds. Hence, we obtain the $L^{2}$ estimate for $g_{1}$, i.e., it holds that

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g_{1}\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

By Proposition 6.3.8, we have the estimate

$$
\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes\left(\overline{g_{2}}+f_{s}\right)\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq C\left(\left\|\overline{g_{2}}\right\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)}+\left\|f_{s}\right\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)}\right)
$$

with some $C$ independent of $g$. Since $f_{s} \in L^{2}\left(\partial \mathbf{R}_{+}^{n}\right)$, we have that

$$
\left\|f_{s}\right\|_{H^{-\frac{1}{2}}\left(\partial \mathbf{R}_{+}^{n}\right)} \leq \frac{C}{M_{h}^{\frac{n-1}{2}}} \cdot\left|I_{c}\right| \leq \frac{C}{M_{h}^{\frac{n-1}{2}}} \cdot S_{c} \cdot\|g\|_{L^{\infty}(\Gamma)}
$$

where $S_{c}:=\mu\left(\left\{y \in \Gamma| | y^{\prime} \mid<2 M_{h}\right\}\right)$ denotes the surface area of the curved part $\{y \in$ $\Gamma\left|\left|y^{\prime}\right|<2 M_{h}\right\}$. Hence, we get that

$$
\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes f_{s}\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}}+C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)} .
$$

Since $f_{s} \in L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)$ and supp $f_{s} \subset B_{2 M_{h}}\left(0^{\prime}\right)$, by the argument in the above paragraph, we can deduce that

$$
\left\|\nabla E *\left(\delta_{\partial \mathbf{R}^{n}} \otimes f_{s}\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq C\left\|f_{s}\right\|_{L^{\infty}\left(\partial \mathbf{R}_{+}^{n}\right)} \leq \frac{C}{M_{h}^{n-1}} \cdot\left|I_{c}\right|
$$

Note that for any $x \in \Omega$, it holds that

$$
\nabla E *\left(\delta_{\Gamma} \otimes g_{2}\right)(x)=\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)(x)
$$

In addition, for $x=\left(x^{\prime}, x_{n}\right) \in \mathbf{R}_{+}^{n}$, we have that

$$
\left|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)\left(x^{\prime},-x_{n}\right)\right|=\left|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)\left(x^{\prime}, x_{n}\right)\right|
$$

Hence, we deduce that

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g_{2}\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq 2\left\|\nabla E *\left(\delta_{\partial \mathbf{R}_{+}^{n}} \otimes \overline{g_{2}}\right)\right\|_{\left(L^{2}\left(\mathbf{R}_{+}^{n}\right)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

Combine with the $L^{2}$ estimate for $\nabla E *\left(\delta_{\Gamma} \otimes g_{1}\right)$, we finally obtain our desired $L^{2}$ estimate

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

with some constant $C$ independent of $g$.
If $g \in L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma) \cap L^{1}(\Gamma)$, then we obtain a similar lemma to Lemma 6.3 .9 which does not need to require the integral of $g$ on $\Gamma$ to be zero.

Lemma 6.3.10. Let $\Omega=\mathbf{R}_{h}^{n}$ be a perturbed $C^{2}$ half space with $\Gamma=\partial \Omega$. For any $g \in$ $L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma) \cap L^{1}(\Gamma)$, the estimate

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes g\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma) \cap L^{1}(\Gamma)}
$$

holds with some constant $C$ independent of $g$.
6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

Proof. Since $\|g\|_{L^{1}(\Gamma)}$ is finite, there exists a constant $I_{c} \in \mathbf{R}$ such that

$$
\int_{\Gamma} g_{2}(y) d \mathcal{H}^{n-1}(y)=I_{c}
$$

where $g_{2}\left(y^{\prime}, h\left(y^{\prime}\right)\right):=1_{B_{2 M_{h}}\left(0^{\prime}\right)^{\mathrm{c}}}\left(y^{\prime}\right) g\left(y^{\prime}, h\left(y^{\prime}\right)\right)$. Since we can estimate $\left|I_{c}\right|$ by $\|g\|_{L^{1}(\Gamma)}$ directly, following the proof of Lemma 6.3.9 gives us Lemma 6.3.10.

For $g \in L^{\infty}(\Gamma)$, by Lemma 6.3 .7 we see that $S g \in L^{2}(\Gamma)$. Actually, we can also estimate the $L^{1}$ norm of $S g$.

Lemma 6.3.11. For $g \in L^{\infty}(\Gamma)$, we have that $S g \in L^{1}(\Gamma)$ satisfying the estimate

$$
\|S g\|_{L^{1}(\Gamma)} \leq C\left(\left(R_{h}^{n-1}+1\right)\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}+1\right) R_{h}^{n-1}\|g\|_{L^{\infty}(\Gamma)}
$$

with some constant $C$ independent of $g$ and $h$.
Proof. Let $x \in \Gamma$ with $\left|x^{\prime}\right|<3 R_{h}$. Since

$$
\|S g\|_{L^{\infty}(\Gamma)} \leq C_{*}\left(R_{h}^{n-1}+1\right)\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}(\Gamma)}
$$

by Theorem 6.3 .5 (ii), we have that

$$
\int_{\left\{x \in \Gamma| | x^{\prime} \mid<3 R_{h}\right\}}|S g(z)| d \mathcal{H}^{n-1}(z) \leq C_{*, h}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}(\Gamma)} \cdot \mu\left(\left\{x \in \Gamma| | x^{\prime} \mid<3 R_{h}\right\}\right)
$$

where $\mu\left(\left\{x \in \Gamma\left|\left|x^{\prime}\right|<3 R_{h}\right\}\right)\right.$ denotes the surface area of $\left\{x \in \Gamma\left|\left|x^{\prime}\right|<3 R_{h}\right\}\right.$ and $C_{*, h}:=$ $C_{*}\left(R_{h}^{n-1}+1\right)$. Thus,

$$
\int_{\left\{x \in \Gamma| | x^{\prime} \mid<3 R_{h}\right\}}|S g(z)| d \mathcal{H}^{n-1}(z) \leq C_{*, h} R_{h}^{n-1}\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}\|g\|_{L^{\infty}(\Gamma)}
$$

Suppose that $x \in \Gamma$ with $\left|x^{\prime}\right| \geq 3 R_{h}$. Then we have that

$$
\int_{\left|x^{\prime}\right| \geq 3 R_{h}}\left|S g\left(x^{\prime}, 0\right)\right| d x^{\prime} \leq \int_{\left\{y \in \Gamma| | y^{\prime} \mid<2 R_{h}\right\}}\left|g_{1}\left(y^{\prime}, h\left(y^{\prime}\right)\right)\right| \cdot\left(\int_{\left|x^{\prime}\right| \geq 3 R_{h}} \frac{1}{\left|x^{\prime}-y^{\prime}\right|^{n-1}} d x^{\prime}\right) d y^{\prime}
$$

By Hölder's inequality, we deduce that

$$
\int_{\left|x^{\prime}\right| \geq 3 R_{h}}\left|S g\left(x^{\prime}, 0\right)\right| d x^{\prime} \leq A_{c}^{1 / 2}\|g\|_{L^{\infty}(\Gamma)} \cdot\left(\int_{\left|y^{\prime}\right|<2 R_{h}}\left(\int_{\left|x^{\prime}\right| \geq 3 R_{h}} \frac{1}{\left|x^{\prime}-y^{\prime}\right|^{n-1}} d x^{\prime}\right)^{2} d y^{\prime}\right)^{1 / 2}
$$

where $A_{c}:=\mu\left(\left\{y \in \Gamma| | y^{\prime} \mid<3 R_{h}\right\}\right)$ denotes the surface area of the curved part $\{y \in$ $\Gamma\left|\left|y^{\prime}\right|<2 R_{h}\right\}$. By Minkowski's inequality for integrals, see e.g. [25, Appendices A.1], we see that

$$
\begin{aligned}
& \left(\int_{\left|y^{\prime}\right|<2 R_{h}}\left(\int_{\left|x^{\prime}\right| \geq 3 R_{h}} \frac{1}{\left|x^{\prime}-y^{\prime}\right|^{n-1}} d x^{\prime}\right)^{2} d y^{\prime}\right)^{1 / 2} \\
& \leq \int_{\left|y^{\prime}\right|<2 R_{h}}\left(\int_{\left|x^{\prime}\right| \geq 3 R_{h}} \frac{1}{\left|x^{\prime}-y^{\prime}\right|^{2(n-1)}} d x^{\prime}\right)^{1 / 2} d y^{\prime}
\end{aligned}
$$

6. The Helmholtz decomposition of a space of vector fields with bounded mean oscillation in a perturbed half space with small perturbation

For $y \in \Gamma$ with $\left|y^{\prime}\right|<2 R_{h}$, the triangle inequality implies that $\left|x^{\prime}-y^{\prime}\right| \geq\left|x^{\prime}\right|-2 R_{h}$. In this case,

$$
\int_{\left|x^{\prime}\right| \geq 3 R_{h}} \frac{1}{\left|x^{\prime}-y^{\prime}\right|^{2(n-1)}} d x^{\prime} \leq \int_{\left|x^{\prime}\right| \geq 3 R_{h}} \frac{1}{\left(\left|x^{\prime}\right|-2 R_{h}\right)^{2(n-1)}} d x^{\prime}
$$

Recall the calculation in the proof of Lemma 6.3.7, it can be deduced that

$$
\int_{\left|x^{\prime}\right| \geq 3 R_{h}} \frac{1}{\left(\left|x^{\prime}\right|-2 R_{h}\right)^{2(n-1)}} d x^{\prime} \leq \frac{C}{R_{h}^{n-1}}
$$

Therefore,

$$
\int_{\left|x^{\prime}\right| \geq 3 R_{h}}\left|S g\left(x^{\prime}, 0\right)\right| d x^{\prime} \leq A_{c}^{1 / 2} C R_{h}^{\frac{n-1}{2}}\|g\|_{L^{\infty}(\Gamma)}
$$

Combine with the $L^{1}$ estimate of $|S g|$ on $\left\{x \in \Gamma\left|\left|x^{\prime}\right|<3 R_{h}\right\}\right.$, we are done.
Proof of Lemma 6.1.4 (Continued). If

$$
\left(R_{h}^{n-1}+1\right)\|h\|_{C^{2}\left(\mathbf{R}^{n-1}\right)}<\frac{1}{2 C_{*}}
$$

then Theorem 6.3.5, Lemma 6.3.7 and Lemma 6.3 .11 together imply that

$$
\left\|\sum_{i=1}^{\infty}(2 S)^{i} g\right\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma) \cap L^{1}(\Gamma)} \leq C\|g\|_{L^{\infty}(\Gamma)}
$$

with some constant $C$ independent of $g$. Let us view $\nabla E *\left(\delta_{\Gamma} \otimes\left(2(I-2 S)^{-1} g\right)\right.$ as

$$
\begin{equation*}
\nabla E *\left(\delta_{\Gamma} \otimes 2 g\right)+\nabla E *\left(\delta_{\Gamma} \otimes\left(2 \sum_{i=1}^{\infty}(2 S)^{i} g\right)\right) \tag{6.3.7}
\end{equation*}
$$

Since the integral of $g$ on $\Gamma$ is zero, by applying Lemma 6.3.9 to the first term of (6.3.7), we obtain that

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes 2 g\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)} .
$$

Since

$$
\sum_{i=1}^{\infty}(2 S)^{i} g \in L^{1}(\Gamma) \cap L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)
$$

by applying Lemma 6.3 .10 to the second term of (6.3.7) and estimating the $L^{1}$ norm of $\sum_{i=1}^{\infty}(2 S)^{i} g$ by $\|g\|_{L^{\infty}(\Gamma)}$, we get that

$$
\left\|\nabla E *\left(\delta_{\Gamma} \otimes\left(2 \sum_{i=1}^{\infty}(2 S)^{i} g\right)\right)\right\|_{\left(L^{2}(\Omega)\right)^{n}} \leq C\|g\|_{L^{\infty}(\Gamma) \cap H^{-\frac{1}{2}}(\Gamma)}
$$

This completes the proof of Lemma 6.1.4.

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