

*On the existence of holomorphic solutions of the  
Cauchy problem for nonlinear first order  
partial differential equations\**

By Raymond GÉRARD and Hidetoshi TAHARA

**Abstract.** The paper deals with the Cauchy problem for general nonlinear first order partial differential equations, and gives a sufficient condition on the following assertion: if the problem has a formal power series solution, it has a holomorphic solution.

In 1968, M. Artin [1] has proved that if a system of analytic equations has a formal power series solution, then it has a convergent power series solution. In this note we are proving similar results for the Cauchy problem for nonlinear first order partial differential equations.

**§ 1. Notations and Definitions.**

Let  $(t, x) \in \mathbb{C}^2$ ,  $X_i \in \mathbb{C}$  ( $i=1, 2, 3$ ), let  $F(t, x, X_1, X_2, X_3)$  be a holomorphic function in  $(t, x, X_1, X_2, X_3)$  defined in a neighborhood of  $(0, 0, a_1, a_2, a_3) \in \mathbb{C}^5$  satisfying  $F(0, 0, a_1, a_2, a_3) = 0$ , and let  $u_0(x)$  be a holomorphic function defined near  $x=0$  satisfying  $u_0(0) = a_1$  and  $(\partial u_0 / \partial x)(0) = a_3$ . In this paper we are dealing with the following Cauchy problem:

$$(E) \quad \begin{cases} F\left(t, x, u, \frac{\partial u}{\partial t}, \frac{\partial u}{\partial x}\right) = 0, \\ u(0, x) = u_0(x) \quad \text{and} \quad \frac{\partial u}{\partial t}(0, 0) = a_2, \end{cases}$$

where  $u = u(t, x)$  is an unknown function.

We denote by  $C[[t, x]]$  the ring of formal power series in  $(t, x)$ , and by  $C\{t, x\}$  the subring of convergent power series in  $(t, x)$ . Note that

---

1991 *Mathematics Subject Classification.* Primary 35F25; Secondary 35A10, 35A07.

\* This joint work was done during the first author's stay at the University of Tokyo in July, 1991.

any  $f(t, x) \in C[[t, x]]$  can be expressed in the form

$$f(t, x) = \sum_{i=0}^{\infty} f_i(x)t^i, \quad f_i(x) \in C[[x]] \quad (i \geq 0).$$

DEFINITION 1. The valuation  $v_t(f)$  of  $f(t, x)$  in  $t$  is defined as follows:

- (i) When  $f \equiv 0$ , then  $v_t(f) = \infty$ ;
- (ii) When  $f \not\equiv 0$ , then  $v_t(f) = \min\{i; f_i(x) \not\equiv 0\}$ .

DEFINITION 2. The Borel transform  $B_t(f)$  of  $f(t, x)$  in  $t$  is defined by

$$B_t(f) = \sum_{i=0}^{\infty} \frac{1}{i!} f_i(x)t^i.$$

For simplicity, we write  $Du = \left(u, \frac{\partial u}{\partial t}, \frac{\partial u}{\partial x}\right)$ . For any  $u(t, x) \in C[[t, x]]$  we put

$$q_i(u) = v_t\left(\frac{\partial F}{\partial X_i}(t, x, Du)\right), \quad i = 1, 2;$$

$$q_i(u, 0) = v_t\left(\frac{\partial F}{\partial X_i}(t, 0, Du(t, 0))\right), \quad i = 1, 2;$$

$$\rho(u; t) = -\frac{t\left(\frac{\partial F}{\partial X_1}(t, 0, Du(t, 0))\right)}{\frac{\partial F}{\partial X_2}(t, 0, Du(t, 0))}.$$

Note that  $q_i(u)$ ,  $q_i(u, 0)$ ,  $\rho(u; t)$  are determined depending only on  $u \in C[[t, x]]$ . If  $q_2(u, 0) < \infty$  and  $q_2(u, 0) \leq q_1(u, 0) + 1$  hold, then  $\rho(u; 0) = \rho(u; t)|_{t=0}$  is well defined.

Now let us introduce new variables  $y_1, y_2, \dots, z_1, z_2, \dots$  and put

$$Y = \sum_{i=1}^{\infty} y_i t^i, \quad Z = \sum_{i=1}^{\infty} z_i t^i.$$

Then, by using the formal Taylor expansion in  $t$  we define  $p_i(\mathbf{E})$  ( $i=0, 1, 2$ ) by

$$p_0(\mathbf{E}) = v_i \left( F \left( t, x, u_0(x) + Y, \frac{\partial Y}{\partial t}, \frac{\partial u_0(x)}{\partial x} + Z \right) - F \left( t, x, u_0(x) + Y, \frac{\partial Y}{\partial t}, \frac{\partial u_0(x)}{\partial x} \right) \right)$$

and for  $i=1, 2$

$$p_i(\mathbf{E}) = v_i \left( \frac{\partial F}{\partial X_i} \left( t, x, u_0(x) + Y, \frac{\partial Y}{\partial t}, \frac{\partial u_0(x)}{\partial x} + Z \right) - \frac{\partial F}{\partial X_i} \left( t, x, u_0(x) + Y, \frac{\partial Y}{\partial t}, \frac{\partial u_0(x)}{\partial x} \right) \right).$$

LEMMA 1. *Let  $p_i(\mathbf{E})$  ( $i=0, 1, 2$ ) be as above. Then we have:*

- (1)  $p_i(\mathbf{E}) \geq 1$  ( $i=0, 1, 2$ );
- (2)  $p_1(\mathbf{E}) \geq p_0(\mathbf{E}) - 2$ ;
- (3)  $p_2(\mathbf{E}) \geq p_0(\mathbf{E}) - 1$ ;
- (4)  $v_i \left( \frac{\partial F}{\partial X_i} \left( t, x, u_0(x) + Y, \frac{\partial Y}{\partial t}, \frac{\partial u_0(x)}{\partial x} + Z \right) \right) \geq p_0(\mathbf{E}) - 1$ .

The proof of this lemma will be given in § 3.

§ 2. Results.

By using the above notations, we have the following Artin's type theorem:

THEOREM 1. *If (E) has a formal power series solution  $\hat{u}(t, x) \in C[[t, x]]$  and if the conditions*

- i)  $q_2(\hat{u}) = q_2(\hat{u}, 0) < \infty$ ,
- ii)  $q_2(\hat{u}) \leq \min \left\{ q_1(\hat{u}) + 1, \frac{p_0(\mathbf{E}) - 1}{2} \right\}$ ,
- iii)  $\rho(\hat{u}; 0) - q_2(\hat{u}) \notin \{2, 3, 4, \dots\}$

*are satisfied, then (E) has a convergent solution  $w(t, x) \in C\{t, x\}$ .*

REMARK 1. When  $(\partial F / \partial X_2)(0, 0, a_1, a_2, a_3) \neq 0$  holds, the Cauchy-Kowalewski theorem says that (E) has a unique holomorphic solution  $u(t, x)$ . In this case, we have  $q_2(u) = q_2(u, 0) = 0$  and  $\rho(u; 0) = 0$ ; therefore the conditions i), ii), iii) in Theorem 1 are trivially satisfied.

When  $q_1(\hat{u}) + 1 < q_2(\hat{u})$ , (E) has not a convergent solution in general (see Example 4 given below). Though, still we have:

**THEOREM 2.** *If (E) has a formal power series solution  $\hat{u}(t, x) \in C[[t, x]]$  and if the conditions*

- i)  $q_1(\hat{u}) = q_1(\hat{u}, 0) < \infty$ ,
- ii)  $q_1(\hat{u}) + 1 \leq \min\left\{q_2(\hat{u}) - 1, \frac{p_0(\mathbf{E}) - 1}{2}\right\}$

are satisfied, then (E) has a formal solution  $w(t, x) = \sum_{i=0}^{\infty} w_i(x)t^i$ ,  $w_i(x) \in C\{x\}$  ( $i \geq 0$ ), such that the Borel transform  $B_i(w)$  of  $w(t, x)$  in  $t$  is convergent near the origin of  $C^2$ .

*Example 1.* Let us consider

$$(2.1) \quad \begin{cases} t^2 \left( \frac{\partial u}{\partial t} \right)^2 - u^2 + t^2 \left( \frac{\partial u}{\partial x} \right)^3 = 0, \\ u(0, x) = 0. \end{cases}$$

By a calculation we can see that for any  $\phi(x) \in C[[x]]$  satisfying  $\phi(0) \neq 0$  (2.1) has a unique formal solution  $u(\phi)$  of the form  $u(\phi) = \phi(x)t + t^2U(t, x)$ ,  $U(t, x) \in C[[t, x]]$ . In this case we have  $p_0 = 5$ ,  $q_1(u(\phi)) = 1$ ,  $q_2(u(\phi)) = q_2(u(\phi), 0) = 2$ ,  $\rho(u(\phi); 0) = 1$  and therefore we can apply Theorem 1 to this case. Note that  $u(\phi)(t, x)$  is convergent if we take  $\phi(x) \in C\{x\}$ .

*Example 2.* Let us consider

$$(2.2) \quad \begin{cases} t^2 \left( \frac{\partial u}{\partial t} \right)^2 - 3u^2 + t^2 \left( \frac{\partial u}{\partial x} \right)^3 + (1+x)^2 t^2 = 0, \\ u(0, x) = 0. \end{cases}$$

By a calculation we can see that for any  $\phi(x) \in C[[x]]$  (2.2) has two formal solution  $u(\phi, \pm)$  of the form

$$u(\phi, \pm) = \pm(1+x)t + \phi(x)t^3 + t^4U(t, x), \quad U(t, x) \in C[[t, x]].$$

In this case we have  $p_0 = 5$ ,  $q_1(u(\phi, \pm)) = 1$ ,  $q_2(u(\phi, \pm)) = q_2(u(\phi, \pm), 0) = 2$ ,  $\rho(u(\phi, \pm); 0) = 3$  and therefore we can apply Theorem 1 to this case.

*Example 3.* Let us consider

$$(2.3) \quad \begin{cases} xt \frac{\partial u}{\partial t} - u + t + t^2 \frac{\partial u}{\partial x} = 0, \\ u(0, x) = 0. \end{cases}$$

By a calculation we can see that (2.3) has a unique formal solution  $\hat{u}(t, x) \in C[[t, x]]$  and that it is divergent. In this case we have  $p_0=3$ ,  $q_1(\hat{u})=q_1(\hat{u}, 0)=0$ ,  $q_2(\hat{u})=1$ ,  $q_2(\hat{u}, 0)=\infty$ . Note that ii) in Theorem 1 is satisfied but i) in Theorem 1 is not satisfied.

*Example 4.* Let us consider

$$(2.4) \quad \begin{cases} t^2 \frac{\partial u}{\partial t} - u + t + t^2 \frac{\partial u}{\partial x} = 0, \\ u(0, x) = 0. \end{cases}$$

By a calculation we can see that (2.4) has a unique formal solution  $\hat{u}(t, x) \in C[[t, x]]$  and it is given by  $\hat{u} = \sum_{k=1}^{\infty} ((k-1)!)t^k$ . In this case we have  $p_0=3$ ,  $q_1(\hat{u})=q_1(\hat{u}, 0)=0$ ,  $q_2(\hat{u})=2$  and therefore we can apply Theorem 2 to this case.

*Example 5.* Let us consider

$$(2.5) \quad \begin{cases} \left( t \frac{\partial u}{\partial t} - u \right) \left( t^2 \frac{\partial u}{\partial t} - u + t^2 \right) + t^3 \left( \frac{\partial u}{\partial x} \right)^2 = 0 \\ u(0, x) = 0. \end{cases}$$

By a calculation we can see that for any  $\phi(x) \in C[[x]]$  satisfying  $\phi(0) \neq 0$  (2.5) has a unique formal solution  $u(\phi)$  of the form  $u(\phi) = \phi(x)t + t^2U(t, x)$ ,  $U(t, x) \in C[[t, x]]$ . In this case we have  $p_0=5$ ,  $q_1(u(\phi))=1$ ,  $q_2(u(\phi))=q_2(u(\phi), 0)=2$ ,  $\rho(u(\phi); 0)=1$  and therefore we can apply Theorem 1 to this case. Note that the equation (2.5) is not regular singular in  $t$ , since (2.5) has a divergent formal solution  $\hat{u} = \sum_{k=2}^{\infty} ((k-2)!)t^k$ .

In this paper, we are discussing only the case of two independent variables. Though, we can also deal with the case of  $n+1$  independent variables  $(t, x_1, \dots, x_n)$  by the same argument as in this paper.

### § 3. Proof of Lemma 1.

For simplicity, we write

$$\eta(t, x, Y, Z) = \left( t, x, u_0(x) + Y, \frac{\partial Y}{\partial t}, \frac{\partial u_0(x)}{\partial x} + Z \right).$$

Since  $Z|_{t=0} = 0$  holds, we have

$$(F(\eta(t, x, Y, Z)) - F(\eta(t, x, Y, 0)))|_{t=0} \equiv 0$$

which implies  $p_0(\mathbf{E}) \geq 1$ . The condition  $p_i(\mathbf{E}) \geq 1$  ( $i=1, 2$ ) may be proved in the same way.

Let us show (2) and (3). By the definition of  $p_0(\mathbf{E})$  we have

$$(3.1) \quad F(\eta(t, x, Y, Z)) \equiv F(\eta(t, x, Y, 0)) \pmod{t^{p_0(\mathbf{E})}}.$$

Applying  $\partial/\partial y_i$  ( $i=1, 2$ ) on both sides of (3.1) we obtain

$$\begin{aligned} & \frac{\partial F}{\partial X_1}(\eta(t, x, Y, Z))t^i + \frac{\partial F}{\partial X_2}(\eta(t, x, Y, Z))it^{i-1} \\ & \equiv \frac{\partial F}{\partial X_1}(\eta(t, x, Y, 0))t^i + \frac{\partial F}{\partial X_2}(\eta(t, x, Y, 0))it^{i-1} \pmod{t^{p_0(\mathbf{E})}}, \end{aligned}$$

that is, we obtain

$$\begin{aligned} & \frac{\partial F}{\partial X_1}(\eta(t, x, Y, Z))t^2 \equiv \frac{\partial F}{\partial X_1}(\eta(t, x, Y, 0))t^2 \pmod{t^{p_0(\mathbf{E})}}, \\ & \frac{\partial F}{\partial X_2}(\eta(t, x, Y, Z))t \equiv \frac{\partial F}{\partial X_2}(\eta(t, x, Y, 0))t \pmod{t^{p_0(\mathbf{E})}}, \end{aligned}$$

which imply (2) and (3) respectively.

Similarly, by applying  $\partial/\partial z_1$  on both sides of (3.1) we have

$$\frac{\partial F}{\partial X_3}(\eta(t, x, Y, Z))t \equiv 0 \pmod{t^{p_0(\mathbf{E})}},$$

which implies (4). Thus, (4) is also proved.

#### § 4. Proof of Theorem 1.

Assume that (E) has a formal solution  $\hat{u}(t, x) \in C[[t, x]]$  satisfying the conditions i), ii), iii) in Theorem 1. Set  $\hat{u} = \sum_{i=0}^{\infty} \hat{u}_i(x)t^i$  with  $\hat{u}_0(x) = u_0(x)$  and  $\hat{u}_i(x) \in C[[x]]$  ( $i \geq 1$ ).

Case:  $q_2(\hat{u}) = 0$ . By i) we have  $q_2(\hat{u}, 0) = 0$  and this is equivalent to

the condition  $(\partial F/\partial X_2)(0, 0, a_1, a_2, a_3) \neq 0$ : hence by the Cauchy-Kowalewski theorem we obtain the convergent solution  $w(t, x) \in \mathcal{C}\{t, x\}$ .

Case:  $q_2(\hat{u}) \geq 1$ . Put  $q_2 = q_2(\hat{u})$ ,  $\rho = \rho(\hat{u}; 0)$  and

$$\hat{\phi} = \sum_{i=0}^{q_2+1} \hat{u}_i(x) t^i.$$

Then, it is easy to see that

$$(4.1) \quad \frac{\partial F}{\partial X_i}(t, x, D\hat{u}) \equiv \frac{\partial F}{\partial X_i}(t, x, D\hat{\phi}) \pmod{t^{q_2+1}}$$

and therefore by i), ii) we have

$$(4.2) \quad \begin{cases} q_2 = q_2(\hat{\phi}) = q_2(\hat{\phi}, 0), \\ q_2 - 1 \leq q_1(\hat{\phi}), \end{cases}$$

which is equivalent to

$$(4.3) \quad \begin{cases} \frac{\partial F}{\partial X_1}(t, x, D\hat{\phi}) \equiv 0 \pmod{t^{q_2-1}}, \\ \frac{\partial F}{\partial X_2}(t, x, D\hat{\phi}) \equiv 0 \pmod{t^{q_2}}, \\ \left( t^{-q_2} \frac{\partial F}{\partial X_2}(t, 0, D\hat{\phi}(t, 0)) \right) \Big|_{t=0} \neq 0. \end{cases}$$

Moreover, by (4.1), (4.2) and the definition of  $\rho(\hat{u}; 0)$  we have

$$(4.4) \quad \rho(\hat{\phi}; 0) = \rho.$$

Put  $\hat{U} = t^{-q_2-1}(\hat{u} - \hat{\phi})$ . Then  $\hat{u} = \hat{\phi} + t^{q_2+1}\hat{U}$  and  $\hat{U}(0, x) \equiv 0$ . Since  $\hat{u}$  is a formal solution of (E), by using Taylor expansion we get the equality

$$(4.5) \quad \begin{aligned} 0 &= F(t, x, D\hat{\phi}) + \frac{\partial F}{\partial X_1}(t, x, D\hat{\phi})t^{q_2+1}\hat{U} \\ &+ \frac{\partial F}{\partial X_2}(t, x, D\hat{\phi})t^{q_2} \left( t \frac{\partial}{\partial t} + q_2 + 1 \right) \hat{U} + \frac{\partial F}{\partial X_3}(t, x, D\hat{\phi})t^{q_2+1} \left( \frac{\partial \hat{U}}{\partial x} \right) \\ &+ \sum_{|\alpha| \geq 2} \frac{1}{\alpha!} \left( \frac{\partial}{\partial X} \right)^\alpha F(t, x, D\hat{\phi}) t^{|\alpha|(q_2+1) - \alpha_2} \hat{U}^{\alpha_1} \left( \left( t \frac{\partial}{\partial t} + q_2 + 1 \right) \hat{U} \right)^{\alpha_2} \left( \frac{\partial \hat{U}}{\partial x} \right)^{\alpha_3}, \end{aligned}$$

where  $\alpha = (\alpha_1, \alpha_2, \alpha_3)$ ,  $|\alpha| = \alpha_1 + \alpha_2 + \alpha_3$  and  $\left( \frac{\partial}{\partial X} \right)^\alpha = \left( \frac{\partial}{\partial X_1} \right)^{\alpha_1} \left( \frac{\partial}{\partial X_2} \right)^{\alpha_2} \left( \frac{\partial}{\partial X_3} \right)^{\alpha_3}$ .

Since

$$\begin{aligned} v_t\left(\frac{\partial F}{\partial X_1}(t, x, D\hat{\varphi})t^{q_2+1}\right) &= q_1(\hat{\varphi}) + q_2 + 1 \geq 2q_2, \\ v_t\left(\frac{\partial F}{\partial X_2}(t, x, D\hat{\varphi})t^{q_2}\right) &= q_2(\hat{\varphi}) + q_2 = 2q_2, \\ v_t\left(\frac{\partial F}{\partial X_3}(t, x, D\hat{\varphi})t^{q_2+1}\right) &\geq (p_0(\mathbb{E}) - 1) + q_2 + 1 \geq 3q_2 + 1, \end{aligned}$$

$|\alpha|(q_2+1) - \alpha_2 \geq |\alpha|q_2 \geq 2q_2$  and  $v_t(\hat{U}) \geq 1$  hold, by comparing the valuation in each term of (4.5) we get

$$(4.6) \quad F(t, x, D\hat{\varphi}) \equiv 0 \pmod{t^{2q_2+1}},$$

and after simplification by  $t^{2q_2}$  (4.5) is reduced to the form

$$(4.7) \quad \begin{aligned} a(t, x, D\hat{\varphi})\hat{U} + b(t, x, D\hat{\varphi})\left(t\frac{\partial}{\partial t} + q_2 + 1\right)\hat{U} \\ = th(t, x, D\hat{\varphi}) + G\left(t, x, D\hat{\varphi}; \hat{U}, \left(t\frac{\partial}{\partial t} + q_2 + 1\right)\hat{U}, \frac{\partial \hat{U}}{\partial x}\right), \end{aligned}$$

where

$$\begin{aligned} a(t, x, D\hat{\varphi}) &= t^{1-q_2} \frac{\partial F}{\partial X_1}(t, x, D\hat{\varphi}), \\ b(t, x, D\hat{\varphi}) &= t^{-q_2} \frac{\partial F}{\partial X_2}(t, x, D\hat{\varphi}), \\ h(t, x, D\hat{\varphi}) &= -t^{-2q_2-1} F(t, x, D\hat{\varphi}), \\ G(t, x, D\hat{\varphi}; Y_1, Y_2, Y_3) &= -t^{1-q_2} \frac{\partial F}{\partial X_3}(t, x, D\hat{\varphi}) Y_3 \\ &\quad - \sum_{|\alpha| \geq 2} \frac{1}{\alpha!} \left(\frac{\partial}{\partial X}\right)^\alpha F(t, x, D\hat{\varphi}) t^{|\alpha|(q_2+1) - \alpha_2 - 2q_2} (Y_1)^{\alpha_1} (Y_2)^{\alpha_2} (Y_3)^{\alpha_3}. \end{aligned}$$

Note that  $q_2 = q_2(\hat{\varphi}, 0)$  implies  $b(0, 0, D\hat{\varphi}(0, 0)) \neq 0$  and that  $\rho = \rho(\hat{\varphi}; 0) = -(a/b)(0, 0, D\hat{\varphi}(0, 0))$  holds.

Now, let us find a convergent solution  $w(t, x) \in \mathcal{C}\{t, x\}$  of (E) in the following form:

$$\begin{cases} w = \varphi + t^{q_2+1}W, \\ \varphi = u_0(x) + \sum_{i=1}^{q_2+1} w_i(x)t^i, \quad w_i(x) \in C\{x\}, \\ W(t, x) \in C\{t, x\}, \quad W(0, x) \equiv 0, \end{cases}$$

where  $w_1(x), \dots, w_{q_2+1}(x)$  and  $W(t, x)$  are unknown functions.

To do so, let us first consider the following system of equations with respect to  $w_1(x), \dots, w_{q_2+1}(x)$ :

$$(4.8) \quad \begin{cases} F(t, x, D\varphi) \equiv 0 \pmod{t^{2q_2+1}}, \\ \frac{\partial F}{\partial X_1}(t, x, D\varphi) \equiv 0 \pmod{t^{q_2-1}}, \\ \frac{\partial F}{\partial X_2}(t, x, D\varphi) \equiv 0 \pmod{t^{q_2}}. \end{cases}$$

Since  $2q_2 + 1 \leq p_0(\mathbb{E})$  is assumed, by Lemma 1 we have  $q_2 - 1 \leq p_0(\mathbb{E}) - 2 \leq p_1(\mathbb{E})$  and  $q_2 \leq p_0(\mathbb{E}) - 1 \leq p_2(\mathbb{E})$ ; therefore it follows from the definition of  $p_i(\mathbb{E})$  ( $i=0, 1, 2$ ) that the system (4.8) is nothing but a system of analytic equations with respect to  $w_1(x), \dots, w_{q_2+1}(x)$ . Moreover, by (4.3) and (4.6) we know that (4.8) has a formal power series solution  $\hat{w}_1(x), \dots, \hat{w}_{q_2+1}(x)$ . Hence, by Artin's theorem we obtain a convergent solution  $w_i(x) \in C\{x\}$  ( $i=1, \dots, q_2+1$ ) of (4.8). In addition we may assume

$$(4.9) \quad (D\varphi)(t, 0) = (D\hat{\varphi})(t, 0)$$

(see Artin [1]).

Then, by (4.8) and (4.9) it is easy to see that

$$\begin{cases} q_2 = q_2(\varphi) = q_2(\varphi, 0), \\ q_2 - 1 \leq q_1(\varphi), \\ \rho = \rho(\varphi; 0) = -(a/b)(t, x, D\varphi) \Big|_{\substack{t=0 \\ x=0}} \end{cases}$$

holds and therefore by the same argument as in (4.7) the equation (E) is reduced to the following equation with respect to  $W(t, x)$

$$(4.10) \quad \begin{aligned} & a(t, x, D\varphi)W + b(t, x, D\varphi)\left(t\frac{\partial}{\partial t} + q_2 + 1\right)W \\ & = th(t, x, D\varphi) + G\left(t, x, D\varphi; W, \left(t\frac{\partial}{\partial t} + q_2 + 1\right)W, \frac{\partial W}{\partial x}\right), \end{aligned}$$

which is a partial differential equation of Briot-Bouquet type in  $t$  discussed in [2, 3]. Since iii) implies  $\rho - q_2 - 1 \notin \{1, 2, 3, \dots\}$ , by the result given in [2, 3] we see that (4.10) has a unique holomorphic solution  $W(t, x)$  satisfying  $W(0, x) \equiv 0$ .

Thus, we have proved that (E) has a convergent solution  $w(t, x) \in C\{t, x\}$ .

### § 5. Proof of Theorem 2.

Assume that (E) has a formal solution  $\hat{u}(t, x) \in C[[t, x]]$  satisfying the conditions i), ii) in Theorem 2. Put  $q_1 = q_1(\hat{u})$ . Then, the formal solution  $w(t, x)$  desired in Theorem 2 is obtained in the following way.

First, we put

$$\begin{cases} w = \varphi + t^{q_1+2}W, \\ \varphi = u_0(x) + \sum_{i=1}^{q_1+2} w_i(x)t^i, \quad w_i(x) \in C\{x\}, \\ W(t, x) \in C[[t, x]], \quad W(0, x) \equiv 0. \end{cases}$$

Next, by applying Artin's theorem to the system of analytic equations with respect to  $w_1(x), \dots, w_{q_1+2}(x)$ :

$$(5.1) \quad \begin{cases} F(t, x, D\varphi) \equiv 0 & (\text{mod } t^{2q_1+3}), \\ \frac{\partial F}{\partial X_1}(t, x, D\varphi) \equiv 0 & (\text{mod } t^{q_1}), \\ \frac{\partial F}{\partial X_2}(t, x, D\varphi) \equiv 0 & (\text{mod } t^{q_1+2}), \\ D\varphi(t, 0) \equiv D\hat{u}(t, 0) & (\text{mod } t^{q_1+2}), \end{cases}$$

we get a solution  $w_i(x) \in C\{x\}$  ( $i=1, \dots, q_1+2$ ).

Then, the equation (E) is reduced to the following equation with respect to  $W(t, x)$ :

$$(5.2) \quad \begin{aligned} & A(t, x, D\varphi)W \\ &= tH(t, x, D\varphi) + R\left(t, x, D\varphi; W, \left(t\frac{\partial}{\partial t} + q_1 + 2\right)W, \frac{\partial W}{\partial x}\right), \end{aligned}$$

where

$$A(t, x, D\varphi) = t^{-q_1} \frac{\partial F}{\partial X_1}(t, x, D\varphi),$$

$$\begin{aligned}
 H(t, x, D\varphi) &= -t^{-2q_1-3}F(t, x, D\varphi), \\
 R(t, x, D\varphi; Y_1, Y_2, Y_3) \\
 &= -t^{-q_1-1} \frac{\partial F}{\partial X_2}(t, x, D\varphi) Y_2 - t^{-q_1} \frac{\partial F}{\partial X_3}(t, x, D\varphi) Y_3 \\
 &\quad - \sum_{|\alpha| \geq 2} \frac{1}{\alpha!} \left( \frac{\partial}{\partial X} \right)^\alpha F(t, x, D\varphi) t^{|\alpha|(q_1+2) - \alpha_2 - 2q_1 - 2} (Y_1)^{\alpha_1} (Y_2)^{\alpha_2} (Y_3)^{\alpha_3}.
 \end{aligned}$$

Since  $A(0, 0, D\varphi(0, 0)) \neq 0$  is assumed by i) and since

$$\begin{aligned}
 v_i \left( t^{-q_1-1} \frac{\partial F}{\partial X_2}(t, x, D\varphi) \right) &\geq q_2 - q_1 - 1 \geq 1, \\
 v_i \left( t^{-q_1} \frac{\partial F}{\partial X_3}(t, x, D\varphi) \right) &\geq (p_0(\mathbb{E}) - 1) - q_1 \geq 2q_1 + 2 - q_1 \geq 2, \\
 |\alpha|(q_1+2) - \alpha_2 - 2q_1 - 2 &\geq |\alpha|(q_1+1) - 2q_1 - 2 \geq 0
 \end{aligned}$$

hold, by the Maillet's type result in [4, 5] we see that (5.2) has a unique formal solution  $W(t, x) \in C[[t, x]]$  such that  $W(0, x) \equiv 0$  and  $B_i(W) \in C\{t, x\}$  hold.

Since the argument is quite parallel to that in §4, the justification of the above construction of  $w(t, x)$  may be left to readers.

#### References

- [1] Artin, M., On the solution of analytic equations, *Invent. Math.* **5** (1968), 277-291.
- [2] Gérard, R. and H. Tahara, Nonlinear singular first order partial differential equations of Briot-Bouquet type, *Proc. Japan Acad.* **66A** (1990), 72-74.
- [3] Gérard, R. and H. Tahara, Holomorphic and singular solutions of nonlinear singular first order partial differential equations, *Publ. Res. Inst. Math. Sci.* **26** (1990), 979-1000.
- [4] Gérard, R. and H. Tahara, Théorème du type Maillet pour une classe d'équations aux dérivées partielles analytiques singulières, *C. R. Acad. Sci. Paris* **312** (1991), 499-502.
- [5] Gérard, R. and H. Tahara, Maillet's type theorems for non linear singular partial differential equations, to appear in *J. Math. Pures Appl.*

(Received August 6, 1991)

Raymond Gérard  
 Institute de Recherche Mathématique Avancée  
 Université Louis Pasteur  
 10, rue du Général Zimmer  
 67084 Strasbourg  
 France

Hidetoshi Tahara  
Department of Mathematics  
Sophia University  
Kioicho, Chiyoda-ku, Tokyo  
102 Japan