

On the conditional stability of non-minimal solutions of $w'' + e^w = 0$

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1. Introduction and Theorem.

In general it seems to be difficult to know whether or not a given initial value is on a stable manifold. The purpose of the present paper is to give a comprehensive example of initial values on the stable manifold through the well-known equation (1.1) below (I. M. Gel'fand [3], H. Fujita [2]).

In the preceding paper [4], the author showed that non-minimal¹⁾ solutions w of $\frac{d^2w}{dx^2} + e^w = 0$ ($-l < x < l$) with $w(-l) = w(l) = 0$ are conditionally stable as a stationary solution of

$$(1.1) \quad \begin{cases} \frac{\partial v}{\partial t} = \frac{\partial^2 v}{\partial x^2} + e^v & (-l < x < l, t > 0), \\ v(x, 0) = a(x) & (-l < x < l), \\ v(-l, t) = v(l, t) = 0 & (t > 0), \end{cases}$$

where l is a positive constant. That is to say, there exists a manifold S_w in $\dot{W}_{\frac{1}{2}}(-l, l)$, called a stable manifold, having the following property: if $a \in S_w$, then the solution v of (1.1) converges to w as $t \rightarrow +\infty$, where $\dot{W}_{\frac{1}{2}}(-l, l)$ is the subspace of the usual Sobolev space $W_{\frac{1}{2}}(-l, l)$ with norm $\| \cdot \|_1$ which consists of elements satisfying the homogeneous Dirichlet boundary condition. On the other hand, we know that w is unstable in the sense: if $a \leq w$ ($a \neq w$) then v of (1.1) converges to the minimal stationary solution w_{\min} as $t \rightarrow +\infty$ uniformly in x , and if $a \geq w$ ($a \neq w$) then v grows up or blows up, where we write simply $a \underset{(\leq)}{\geq} w$ for $a(x) \underset{(\leq)}{\geq} w(x)$ ($-l < x < l$) (Fujita [2]). Thus we immediately see that initial values on S_w must cross w . We shall describe the set S_w more precisely later.

In order to state our theorem, we recall a famous result by Gel'fand [3]:

1) w_{\min} is said to be minimal if $w(x) \geq w_{\min}(x)$ ($-l < x < l$) for any solution w of the equation.

There exists $l_0 (=0.93\dots)$ such that, when $l < l_0$ (1.1) has two stationary solutions, when $l = l_0$ it has only one stationary solution, and when $l > l_0$ it has no stationary solution. These solutions are given by

$$(1.2) \quad w_\alpha(x) = \alpha - 2 \log \cosh(2e^\alpha)^{1/2} x \quad (-l < x < l),$$

where α is a positive root of the equation

$$(1.3) \quad e^{\alpha/2} = \cosh(2e^\alpha)^{1/2} l.$$

[Note: When $l < l_0$ (1.3) has two solutions α_1, α_2 ($0 < \alpha_1 < \alpha_2$), when $l = l_0$ it has only one solution $\alpha_0 > 0$, and when $l > l_0$ it has no solution.] Since we are interested in the non-minimal solution, we confine our consideration to w_{α_2} in the case $l < l_0$. In what follows, we simply write w, α for w_{α_2}, α_2 respectively.

Note that $\frac{dw}{dx} < 0$ for $0 < x < l$.

Our theorem now follows.

THEOREM. Assume that $l < l_0$. Let w be as above. Suppose that given $a_0, a_1 \in \dot{W}_2^1(-l, l)$ satisfy

$$(1.4) \quad a_0 \leq w \leq a_1.$$

Then, there exists a γ in $0 \leq \gamma \leq 1$ such that the solution of (1.1) with the

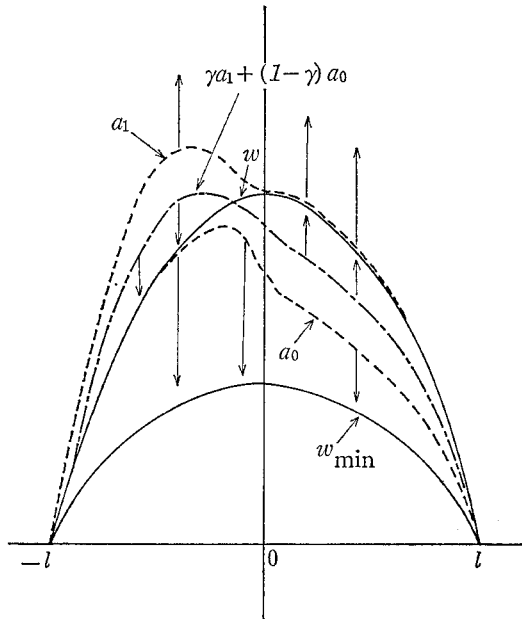


Fig. 1

initial value $\gamma a_1 + (1-\gamma)a_0$ converges exponentially to w as $t \rightarrow +\infty$ in the norm $\| \cdot \|_1$, if $\|a_0 - w\|_1, \|a_1 - w\|_1$ are sufficiently small. (See Fig. 1.)

Note: If $a_i \neq w$ ($i=0, 1$), then solutions v_i of (1.1) with $v_i(x, 0) = a_i(x)$ never converge to w as $t \rightarrow +\infty$ (Fujita's result).

In the next section, we prove this theorem by showing that $\gamma a_1 + (1-\gamma)a_0$ lies on the stable manifold S_w constructed in [4].

2. Proof of Theorem.

In the work [4], S_w was defined as

$$(2.1) \quad S_w = \{a \in \dot{W}_2^1(-l, l) : a - w \in S\},$$

where S is a stable manifold for the trivial solution $u \equiv 0$ of

$$(2.2) \quad \begin{cases} \frac{\partial u}{\partial t} = \left(\frac{\partial^2}{\partial x^2} + e^w \right) u + e^w (e^u - 1 - u) & (-l < x < l, t > 0), \\ u(x, 0) = a(x) - w(x) & (-l < x < l), \\ u(-l, t) = u(l, t) = 0 & (t > 0). \end{cases}$$

This S has the following property: If $a - w \in S$, then the solution u of (2.2) decays exponentially as $t \rightarrow +\infty$ in the norm $\| \cdot \|_1$. (See Theorem 2 in [4].) For the proof of Theorem, therefore, it is sufficient to show that $\gamma a_1 + (1-\gamma)a_0 - w \in S$. To show this, we prepare some notations and lemmas.

Let X be $\dot{W}_2^1(-l, l)$ with the norm $\| \cdot \| = \| (A_0 + \beta_0)^{1/2} \cdot \|_{L^2(-l, l)}$, where A_0 is the operator $-\left(\frac{d^2}{dx^2} + e^w \right)$ with Dirichlet boundary condition in $L^2(-l, l)$, and β_0 is a positive constant such that $A_0 + \beta_0$ is positive. We note that $\| \cdot \|$ is equivalent to $\| \cdot \|_1$, and that X can be endowed with the inner product $(\cdot, \cdot) = ((A_0 + \beta_0)^{1/2} \cdot, (A_0 + \beta_0)^{1/2} \cdot)_{L^2}$. Let Y be the subspace generated by the eigenspace corresponding to non-positive eigenvalues of $-\left(\frac{d^2}{dx^2} + e^w \right)$ in X , and Z be the complementary subspace of Y . Let P, Q be projections onto Y, Z respectively.

LEMMA 2.1. *The above S may be represented by*

$$(2.3) \quad S = \{\theta(b) : b \in B\},$$

where $B = \{b \in Z : \|b\| < r\}$ (r is some positive constant), and θ is a continuous map: $B \rightarrow X$, with $Q\theta(b) = b$ for $b \in B$.

(For the proof, see the proof of Theorem 2 in [4].)

LEMMA 2.2. Let λ_1, λ_2 be the smallest eigenvalue and the second smallest one, respectively, of the eigenvalue problem

$$(2.4) \quad \begin{cases} \left(\frac{d^2}{dx^2} + e^w\right)\phi + \lambda\phi = 0 & (-l < x < l), \\ \phi(-l) = \phi(l) = 0. \end{cases}$$

Then

$$(2.5) \quad \lambda_1 \leq 0 < \lambda_2.$$

Also, let ϕ_1, ϕ_2 be eigenfunctions corresponding to λ_1, λ_2 , respectively. Then, ϕ_1 does not change its sign in $(-l, l)$, and ϕ_2 has only one zero in it.

(We shall give the proof of Lemma 2.2 later.)

We show that $\gamma a_1 + (1-\gamma)a_0 - w \in S$ for some $0 < \gamma < 1$. We may assume $\phi_1 > 0$. By Lemma 2.1 and Lemma 2.2, S may be expressed as

$$S = \{f(b)\phi_1 + b : b \in B\},$$

where $f(b) = (\theta(b), \phi_1)$. This f is a continuous functional on B . Set $C^+ = \{u \in X : u \geq 0, u \neq 0\}$, $C^- = \{u \in X : u \leq 0, u \neq 0\}$. Then C^+ and C^- are convex cones in X with the origin as their vertices, and they satisfy

$$(2.6) \quad \{\mu\phi_1 : \mu > 0\} \subset C^+ \subset \{\mu\phi_1 + z : \mu > 0, z \in Z\},$$

$$(2.7) \quad \{\mu\phi_1 : \mu < 0\} \subset C^- \subset \{\mu\phi_1 + z : \mu < 0, z \in Z\}.$$

The first inclusion of (2.6) (or (2.7)) is trivial. For any $u \in X$,

$$\begin{aligned} (u, \phi_1) &= ((A_0 + \beta_0)^{1/2}u, (A_0 + \beta_0)^{1/2}\phi_1)_{L^2} \\ &= (u, (A_0 + \beta_0)\phi_1)_{L^2} = (\lambda_1 + \beta_0)(u, \phi_1)_{L^2}. \end{aligned}$$

Since $A_0 + \beta_0$ is positive definite, $\lambda_1 + \beta_0 > 0$. Hence, $(u, \phi_1) > 0$ if $u \in C^+$, and $(u, \phi_1) < 0$ if $u \in C^-$. This shows the second inclusion of (2.6) (or (2.7)).

By Fujita's instability results about w , $C^+ \cap S = \emptyset$ and $C^- \cap S = \emptyset$. Furthermore we have

$$(2.8) \quad C^+ \cap \{\mu\phi_1 + b : \mu \in \mathbf{R}\} \subset \{\mu\phi_1 + b : \mu > f(b)\} \quad (b \in B),$$

$$(2.9) \quad C^- \cap \{\mu\phi_1 + b : \mu \in \mathbf{R}\} \subset \{\mu\phi_1 + b : \mu < f(b)\} \quad (b \in B).$$

Indeed, if there exists $\mu \leq f(b)$ with $\mu\phi_1 + b \in C^+$, then $0 < \mu \leq f(b)$. Thus, by (2.6) and the fact that C^+ is a convex cone,

$$f(b)\phi_1 + b = (f(b) - \mu)\phi_1 + (\mu\phi_1 + b) \in C^+.$$

This contradicts the fact $C^+ \cap S = \emptyset$. Thus (2.8) has been proved. Similarly (2.9)

can be proved.

Let $\|a_i - w\| < r$ ($i=0, 1$). We may represent $a_i - w$ as

$$(2.10) \quad a_i - w = \mu_i \phi_1 + b_i \quad (i=0, 1),$$

where $\mu_i = (a_i - w, \phi_1)$, $b_i = a_i - w - \mu_i \phi_1 \in B$. By (1.4), $a_1 - w \in C^+$, $a_0 - w \in C^-$. Hence, by (2.8) and (2.9), we have $\mu_0 < f(b_0)$ and $\mu_1 > f(b_1)$. Setting

$$g(\xi) = f(\xi b_1 + (1-\xi)b_0) - (\xi \mu_1 + (1-\xi)\mu_0) \quad (0 \leq \xi \leq 1)$$

and noting that f is continuous, we see that g is a continuous function on $[0, 1]$ such that

$$\begin{aligned} g(0) &= f(b_0) - \mu_0 > 0, \\ g(1) &= f(b_1) - \mu_1 < 0. \end{aligned}$$

Hence, there exists $0 < \gamma < 1$ such that $g(\gamma) = 0$. By (2.10),

$$\begin{aligned} \gamma a_1 + (1-\gamma)a_0 - w &= (\gamma \mu_1 + (1-\gamma)\mu_0)\phi_1 + \gamma b_1 + (1-\gamma)b_0 \\ &= f(\gamma b_1 + (1-\gamma)b_0)\phi_1 + \gamma b_1 + (1-\gamma)b_0 \\ &\in S. \end{aligned}$$

Thus Theorem has been shown except for the proof of Lemma 2.2.

3. Proof of Lemma 2.2.

Since w is unstable in Fujita's sense, so is w in the usual Lyapunov sense (in the norm $\| \cdot \|$). By Theorem 1 in [4], therefore, we see that $\lambda_1 \leq 0$. The claim about ϕ_1, ϕ_2 is well-known (R. Courant & D. Hilbert [1]).

We show that $0 < \lambda_2$. We first note that the symmetry of w yields that $x=0$ is the only zero of ϕ_2 . We may assume that $\phi_2(x) > 0$ for $0 < x < l$. By (2.4) and the fact that $\phi_2(0) = 0$, λ_2 is an eigenvalue of the eigenvalue problem

$$(3.1) \quad \begin{cases} \left(\frac{d}{dx} + e^w \right) \phi + \lambda \phi = 0 & (0 < x < l), \\ \phi(0) = \phi(l) = 0, \end{cases}$$

and the restriction of ϕ_2 on $[0, l]$ is the eigenfunction corresponding to λ_2 .

LEMMA 3.1. Let $\varphi \in C^2[0, l]$, and $\varphi(x) > 0$ for all $0 \leq x \leq l$. Then

$$(3.2) \quad \inf_{0 \leq x \leq l} \left[- \frac{\varphi''(x) + e^{w(x)} \varphi(x)}{\varphi(x)} \right] \leq \lambda_2.$$

where $\lambda = \frac{d^2}{dx^2}$.

PROOF OF LEMMA 3.1. Since λ_2 and ϕ_2 satisfy (3.1), we have, noting $\phi_2(0) = \phi_2(l) = 0$, $\phi_2'(0) \geq 0$ and $\phi_2'(l) \leq 0$,

$$\begin{aligned} 0 &= \int_0^l (\phi_2'' + e^w \phi_2 + \lambda_2 \phi_2) \varphi dx \\ &= [\phi_2' \varphi - \phi_2 \varphi']_0^l + \int_0^l \phi_2 (\varphi'' + e^w \varphi + \lambda_2 \varphi) dx \\ &\leq \int_0^l \phi_2 (\varphi'' + e^w \varphi + \lambda_2 \varphi) dx. \end{aligned}$$

Hence

$$\begin{aligned} \lambda_2 \int_0^l \phi_2 \varphi dx &\geq - \int_0^l \phi_2 (\varphi'' + e^w \varphi) dx \\ &\geq \inf_{0 \leq x \leq l} \left[- \frac{\varphi'' + e^w \varphi}{\varphi} \right] \int_0^l \phi_2 \varphi dx. \end{aligned}$$

Since $\int_0^l \phi_2 \varphi dx > 0$, we obtain (3.2).

Let us construct a function φ satisfying assumptions in Lemma 3.1, and $\inf_{0 \leq x \leq l} [-(\varphi'' + e^w \varphi)/\varphi] > 0$.

Set

$$\varphi(x) = -w'(x) + (\varepsilon - w'(x)) \cos \frac{\pi(x+\rho)}{2(l+\rho)},$$

where ρ is an arbitrary positive constant, and ε is a positive constant to be determined later. By (1.2), $\varphi \in C^2[0, l]$ and $\varphi > 0$ (since $w'(x) < 0$ for $0 < x < l$).

Moreover, $0 \leq w \leq \alpha$, and $(\frac{d^2}{dx^2} + e^w)w' = 0$. Hence if we take ε so that it satisfies

$$\left[e^\alpha - \left(\frac{\pi}{2(l+\rho)} \right)^2 \right] \varepsilon < \frac{\pi}{l+\rho} \sin \frac{\pi \rho}{2(l+\rho)},$$

then we have

$$\begin{aligned} \varphi'' + e^w \varphi &= \left(\frac{d^2}{dx^2} + e^w \right) \left[(\varepsilon - w') \cos \frac{\pi(x+\rho)}{2(l+\rho)} \right] \\ &= \left[\varepsilon \left[e^w - \left(\frac{\pi}{2(l+\rho)} \right)^2 \right] + \left(\frac{\pi}{2(l+\rho)} \right)^2 w' \right] \cos \frac{\pi(x+\rho)}{2(l+\rho)} \end{aligned}$$

$$\begin{aligned}
 & -\frac{\pi}{l+\rho} e^w \sin \frac{\pi(x+\rho)}{2(l+\rho)} \\
 & \leq \varepsilon \left[e^\alpha - \left(\frac{\pi}{2(l+\rho)} \right)^2 \right] - \frac{\pi}{l+\rho} \sin \frac{\pi\rho}{2(l+\rho)} \\
 & < 0.
 \end{aligned}$$

Therefore, we have

$$0 < \inf_{0 \leq x \leq l} \left[-\frac{\varphi'' + e^w}{\varphi} \right] \leq \lambda_2.$$

This completes the proof of Lemma 2.2.

REMARK. The stable manifold S_w belongs to the "lower half space" $\{a \in X : (a-w, \phi_1) \leq 0\}$.

PROOF. Since $A_0 + \beta_0$ is positive, it is sufficient to show that $(a-w, \phi_1)_{L^2} \leq 0$ for any $a \in S_w$. Let $a \in S_w$ and v be the solution of (1.1) with the initial value a . Then v converges to w in $\| \cdot \|$ as $t \rightarrow +\infty$. On the other hand,

$$\begin{aligned}
 \frac{d}{dt} (v-w, \phi_1)_{L^2} &= \left(\frac{\partial v}{\partial t}, \phi_1 \right)_{L^2} \\
 &= \left(\frac{\partial^2}{\partial x^2} (v-w) + (e^v - e^w), \phi_1 \right)_{L^2},
 \end{aligned}$$

(by the mean value theorem and integration by parts)

$$\begin{aligned}
 &= \left(v-w, \left(\frac{d^2}{dx^2} + e^w \right) \phi_1 \right)_{L^2} \\
 &\quad + (e^{w+\sigma(v-w)} (v-w)^2, \phi_1)_{L^2} \quad (0 \leq \sigma \leq 1) \\
 &\geq -\lambda_1 (v-w, \phi_1)_{L^2}.
 \end{aligned}$$

Therefore, $(v-w, \phi_1)_{L^2} \geq e^{-\lambda_1 t} (a-w, \phi_1)_{L^2}$ if $(a-w, \phi_1)_{L^2} > 0$. Since $-\lambda_1 \geq 0$, this contradicts the fact that $\|v-w\| \rightarrow 0$ as $t \rightarrow +\infty$. This completes the proof.

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